

camera

dimensions: {instrument}
storage class: Camera

cpFlatStatistics

dimensions: {detector, exposure}
storage class: PropertyList

cpFlatNormalize

`lsst.cp.pipe.cpFlatMeasure.CpFlatNormalizationTask`
dimensions: {physical_filter}

cpFlatNormalizeScales

dimensions: {physical_filter}
storage class: StructuredDataDict