

## camera

*dimensions:* {instrument}

*storage class:* Camera

## cpFlatStatistics

*dimensions:* {detector, exposure}

*storage class:* PropertyList

## cpFlatNormalize

lsst.cp.pipe.cpFlatMeasure.CpFlatNormalizationTask

*dimensions:* {physical\_filter}

## cpFlatNormalizeScales

*dimensions:* {physical\_filter}

*storage class:* StructuredDataDict