

## camera

*dimensions:* {instrument}

*storage class:* Camera

## raw

*dimensions:* {detector, exposure}

*storage class:* Exposure

## cpBiasIsr

lsst.ip.isr.isrTask.IsrTask

*dimensions:* {detector, exposure}

## cpBiasIsrExp

*dimensions:* {detector, exposure}

*storage class:* Exposure