

under Graduate Homework In Mathematics

RiemannGeometry 1

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PROBLEM I Assume $\mathcal{A}_0 = \{(U_\alpha, \phi_\alpha) : \alpha \in I\}$ is a C^r -compatible coordinate cover of a m -dimensional manifold M , let

$$\mathcal{A} := \{(U, \phi) : (U, \phi) \text{ is chart of } M, \wedge \forall (V, \psi) \in \mathcal{A}_0, (U, \phi) \text{ is compatible with } (V, \psi)\}$$

. Then \mathcal{A} is unique C^r -differential structure on M contains \mathcal{A}_0 .

SOLUTION. First, easily $\mathcal{A}_0 \subset \mathcal{A}$ by definition of \mathcal{A}_0 . Now we should prove \mathcal{A} is differential structure on M . Let $(U, \phi), (V, \psi) \in \mathcal{A}$. If $(U, \phi) \in \mathcal{A}_0$, then by definition of \mathcal{A}_0 we know (U, ϕ) is compatible to (V, ψ) . If $(U, \phi), (V, \psi) \notin \mathcal{A}_0$, then consider $U \cap V$. If $U \cap V = \emptyset$, then (U, ϕ) is compatible with (V, ψ) . Now assume $W = U \cap V \neq \emptyset$. Consider $\gamma := \psi \circ \phi^{-1} : \phi(W) \rightarrow \psi(W)$. For any $x \in W$, since \mathcal{A}_0 is cover of M , we know $\exists (T, \tau) \in \mathcal{A}_0, x \in T$. Then by the definition of \mathcal{A} , we know (T, τ) is compatible locally on x with both (U, ϕ) and (V, ψ) . So (U, ϕ) is locally compatible with (V, ψ) on x . Since x is arbitrary, we know (U, ϕ) is compatible with (V, ψ) . So \mathcal{A} is differential structure of M .

Now we assume \mathcal{B} is another differential structure of M contains \mathcal{A}_0 . Since \mathcal{B} is compatible, we get $\mathcal{B} \subset \mathcal{A}$. Since \mathcal{B} is maximal, we get $\mathcal{B} = \mathcal{A}$. So \mathcal{A} is unique. \square

PROBLEM II Assume $(U, \phi; x^i), (V, \psi; y^i), (W, \chi; z^i)$ are three local coordinate on an m -dimensional smooth manifold M , and $W \cap V \cap U \neq \emptyset$. Prove that on $\phi(U \cap V \cap W)$, we have:

$$\left(\frac{\partial z^i}{\partial x^j} \right) = \left(\frac{\partial z^i}{\partial y^k} \right) \left(\frac{\partial y^k}{\partial x^j} \right)$$

SOLUTION. For fixed $1 \leq i, j \leq m$, we have

$$\frac{\partial z^i}{\partial x^j} = \sum_{k=1}^m \frac{\partial z^i}{\partial y^k} \frac{\partial y^k}{\partial x^j}$$

. So easily to get that

$$\left(\frac{\partial z^i}{\partial x^j} \right) = \left(\frac{\partial z^i}{\partial y^k} \right) \left(\frac{\partial y^k}{\partial x^j} \right)$$

. We let $(W, \chi; z^i) = (U, \phi; x^i)$, then we get:

$$I_m = \left(\frac{\partial x^i}{\partial y^k} \right) \left(\frac{\partial y^k}{\partial x^j} \right)$$

. So both terms on the right side are invertible, thus non-singular. \square

PROBLEM III Assume M is orientable and connected, prove that M has exactly two different orientation.

SOLUTION. Since M is orientable, we can assume that $\mathcal{B} \subset \mathcal{A}$ is an orientation of M , where \mathcal{A} is all local coordinate of M . Now consider $\mathcal{C} := \{(U; -x^i) : (U; x^i) \in \mathcal{B}\}$. Easily to check that \mathcal{C} is an orientation of M , too. And obviously $\mathcal{B} \cap \mathcal{C} = \emptyset$, thus $\mathcal{B} \neq \mathcal{C}$. So there is two orientation. Now we need to prove there is no other orientation.

Assume \mathcal{D} is an orientation of M . We will define a function $\text{sgn} : M \rightarrow \{1, -1\}$ by

$$\text{sgn}(p) = 1 \iff \exists(U_0, x_0^i) \in \mathcal{B}, \exists(V_0, y_0^i) \in \mathcal{D}, p \in U_0 \cap V_0, J_{x_0, y_0}(p) > 0$$

. We will prove that

$$\text{sgn}(p) = 1 \implies \forall(U, x^i) \in \mathcal{B}, \forall(V; y^i) \in \mathcal{D}, p \in U \cap V \implies J_{x, y}(p) > 0$$

. It's easy because $J_{x, y} = J_{x, x_0} J_{x_0, y_0} J_{y_0, y}$, and $J_{x, x_0} > 0, J_{y, y_0} > 0$ by definition of orientation. So

$$\text{sgn}(p) = -1 \iff \exists(U_0, x_0^i) \in \mathcal{C}, \exists(V_0, y_0^i) \in \mathcal{D}, p \in U_0 \cap V_0, J_{x_0, y_0}(p) > 0$$

$$\iff \forall(U, x^i) \in \mathcal{B}, \forall(V; y^i) \in \mathcal{D}, p \in U \cap V \implies J_{x, y}(p) > 0$$

. Noting that if $\text{sgn}(p) = 1$, we have $\forall q \in U_0 \cap V_0, \text{sgn}(q) = 1$, and so is $\text{sgn}(p) = -1$. So sgn is continuous. So sgn is constant because M is connected. Easy to check that $\text{sgn}(p) = 1 \iff \mathcal{B} = \mathcal{D}$, and $\text{sgn}(p) = -1 \iff \mathcal{C} = \mathcal{D}$. So there is only two orientation of M . \square

PROBLEM IV Let

$$S^n(a) := \{(x^{(1)}, \dots, x^{(n+1)}) \in \mathbb{R}_1^{n+1} : \sum_{k=1}^{n+1} (x^{(k)})^2 = a^2\}$$

be the ball in \mathbb{R}^{n+1} with radius $a > 0$. Let $S := (0, \dots, -a), N := (0, \dots, a)$ be the South Pole and North Pole respectively. Let $U_+ = S^n(a) \setminus \{S\}, U_- = S^n(a) \setminus \{N\}$. Let $\phi_+ : U_+ \rightarrow \mathbb{R}^n, \phi_- : U_- \rightarrow \mathbb{R}^n$.

$$(\xi^{(1)}, \dots, \xi^{(n)}) = \phi_+(x^{(1)}, \dots, x^{(n+1)}) := \left(\frac{ax^{(1)}}{a + x^{(n+1)}}, \dots, \frac{ax^{(n)}}{a + x^{(n+1)}} \right)$$

.

$$(\eta^{(1)}, \dots, \eta^{(n)}) = \phi_-(x^{(1)}, \dots, x^{(n+1)}) := \left(\frac{ax^{(1)}}{a - x^{(n+1)}}, \dots, \frac{ax^{(n)}}{a - x^{(n+1)}} \right)$$

. Calculate the inverses of ϕ_+ and ϕ_- , thus prove $\{(U_+, \phi_+), (U_-, \phi_-)\}$ gives a smooth structuaction of $S^n(a)$.

SOLUTION. Noting

$$\xi^{(i)} = \frac{ax^{(i)}}{a + x^{(n+1)}}$$

, so

$$x^{(i)} = \frac{\xi^{(i)}(a + x^{(n+1)})}{a}$$

. And

$$\sum_{k=1}^{n+1} (x^{(k)})^2 = a^2$$

, so

$$\sum_{k=1}^n \frac{(\xi^{(i)})^2 (a + x^{(n+1)})^2}{a^2} + (x^{(n+1)})^2 = a^2$$

.

\square

PROBLEM V