# CS2020 Data Structures and Algorithms

Welcome!

# Coding Quiz

- Date: March 10 / 11 / 13
  - Administered during your Discussion Group
  - Location: iCube 3-45/3-47
  - Do not skip Discussion Group next week.

- Practice problems:
  - See posted sample problems
  - See last year's Coding Quiz
  - Talk to your tutor.
  - If you want more practice problems, ask.

#### Advice:

- Coding under time pressure is hard.
  - Don't rush: read the problem carefully.
  - Don't rush: plan before you code.
  - Document your code as you go.
  - Don't get stuck if something doesn't work.

Use your time wisely.

#### Advice:

- Test your solution
  - Working code is important.
  - Test "corner-cases."

- Several possible solutions
  - First, ignore efficiency.
  - Develop a solution that works.
  - Test it. Test it. Test it.
  - Then, improve the efficiency.

#### Advice:

- Use good coding style
  - Deductions for code that is badly formatted

- Explain your solution
  - Credit for well-documented code.

#### Advice:

Don't submit code that does not even compile!

If you can not solve the problem correctly, then submit simple code that solves the problem simply.

# Today: Data Structures

### Last time...

Binary search trees

Dictionaries (Abstract Data Type)

Balanced search trees

**AVL** trees

## **Dynamic Data Structures**

1. Maintain a set of items

2. Modify the set of items

3. Answer queries.

## **Dynamic Data Structures**

- Operations that create a data structure
  - build (preprocess)

- Operations that modify the structure
  - insert
  - delete

- Query operations
  - search, select, etc.

## Example: QuestionTree

- Operations that create a data structure
  - buildTree(Objects[])

- Operations that modify the structure
  - insert
  - delete

- Query operations
  - findQuery

# What are trees good for?

- Symbol tables
  - insert, delete, search

- Dictionaries
  - insert, delete, search, successor, predecessor

• Bags, Heaps, etc.

### Augmented Data Structures

Many problems require storing additional data in a standard data structure.

Augment more frequently than invent...

# Today

Three examples of augmenting balanced BSTs

1. Order Statistics

2. Interval Queries

3. Orthogonal Range Searching

### Augmenting data structures

### Basic methodology:

- 1. Choose underlying data structure (tree, hash table, linked list, stack, etc.)
- 2. Determine additional info needed.
- 3. Verify that the additional info can be maintained as the data structure is modified.

(subject to insert/delete/etc.)

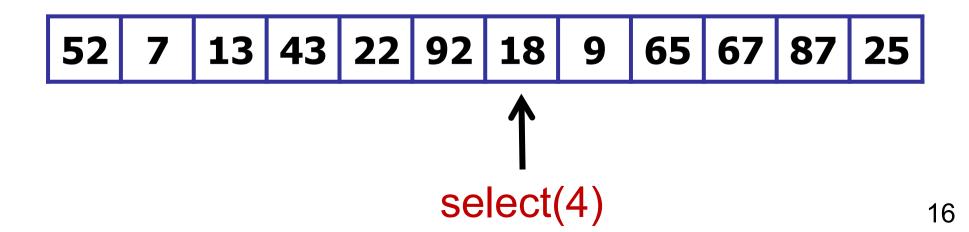
4. Develop new operations using the new info.

### Input

A set of integers.

Output: select(k)

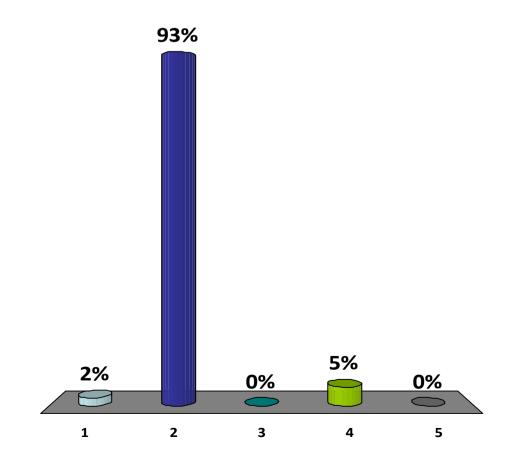
The kth item in the set.



### select(1) returns:

<b>52</b>	7	13	43	22	92	18	9	65	67	87	25	
-----------	---	----	----	----	----	----	---	----	----	----	----	--

- 1. 52
- **√**2. 7
  - 3. 13
  - 4. 43
  - 5. 25

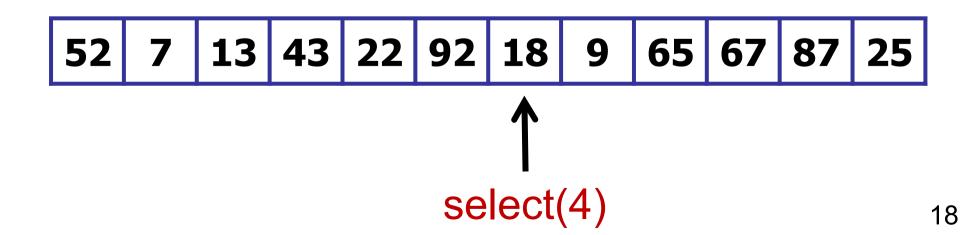


### Input

A set of integers.

Output: select(k)

The kth item in the set.

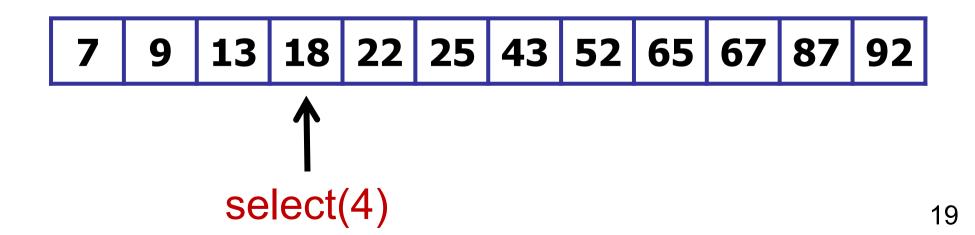


### Input

A set of integers.

Output: select(k)

The kth item in the set.

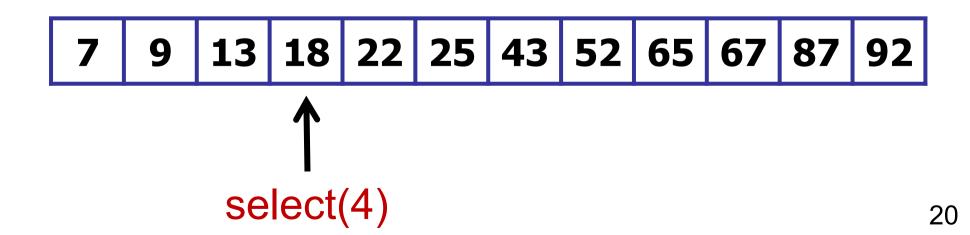


### Input

A set of integers.

Output:  $select(k) \longrightarrow Sort: O(n log n)$ 

The k<sup>th</sup> item in the set.

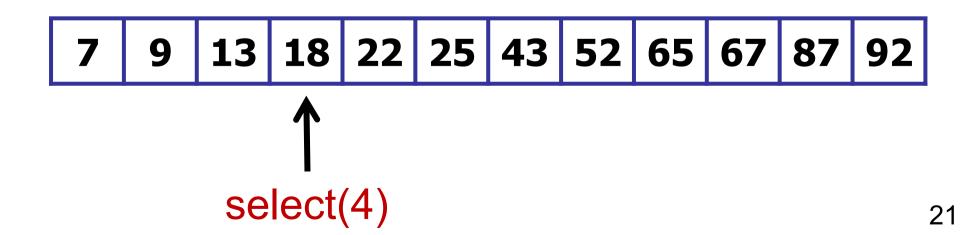


### Input

A set of integers.

Output: select(k) ———— QuickSelect: O(n)

The k<sup>th</sup> item in the set.

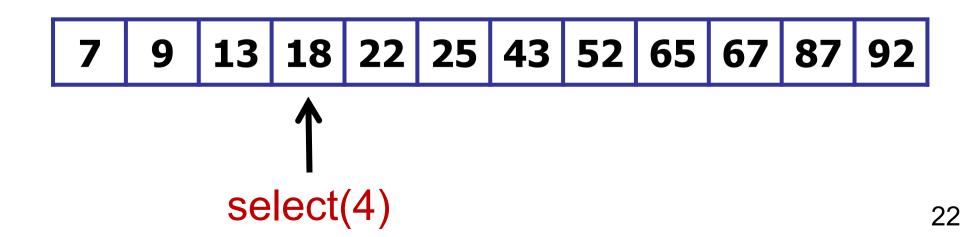


#### Solution 1:

Sort: O(n log n)

#### Solution 2:

QuickSelect: O(n)



#### Solution 1:

Preprocess: sort --- O(n log n)

Select: O(1)

#### Solution 2:

Preprocess: nothing --- O(1)

QuickSelect: O(n)

## **Dynamic Data Structures**

- Operations that create a data structure
  - build (preprocess)

- Operations that modify the structure
  - insert
  - delete

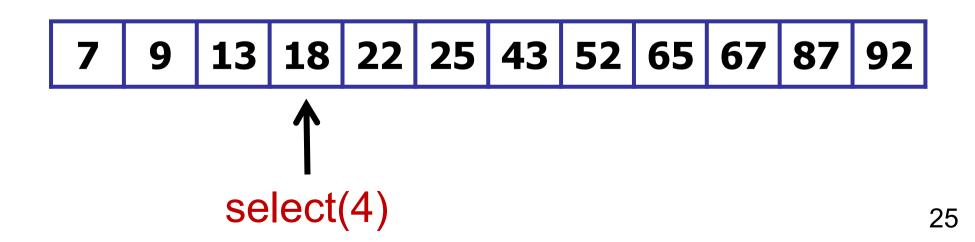
- Query operations
  - search, select, etc.

#### Implement a data structure that supports:

- insert(int key)
- delete(int key)

#### and also:

select(int k)



#### Solution 1:

Basic structure: sorted array A.

insert(int item): add item to sorted array A.

select(int k): return A[k]

7 9 13 18 22 25 43 52 65 67 87 92

#### Solution 1:

Basic structure: sorted array A.

insert(int item): add item to sorted array A.

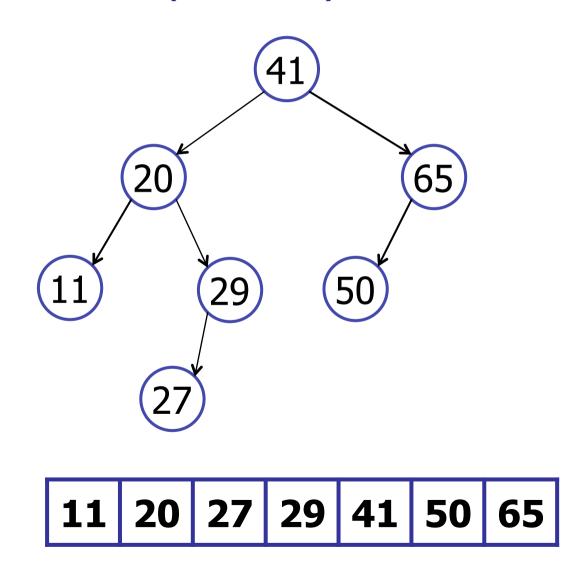
O(n) time

select(int k): return A[k]

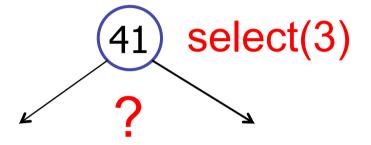
• O(1) time

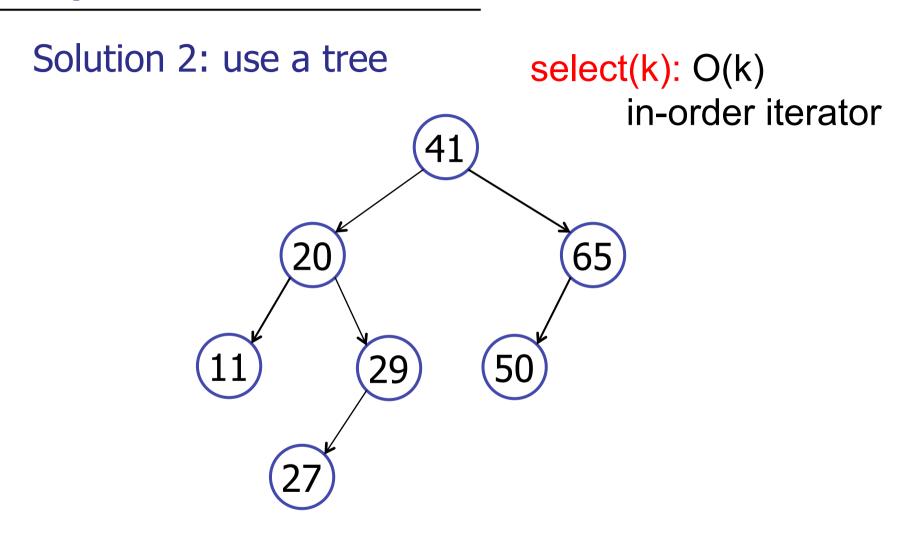
7 9 13 18 22 25 43 52 65 67 87 92

Solution 2: use a (balanced) tree



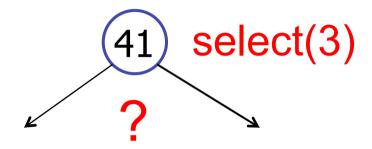
Solution 2: use a tree



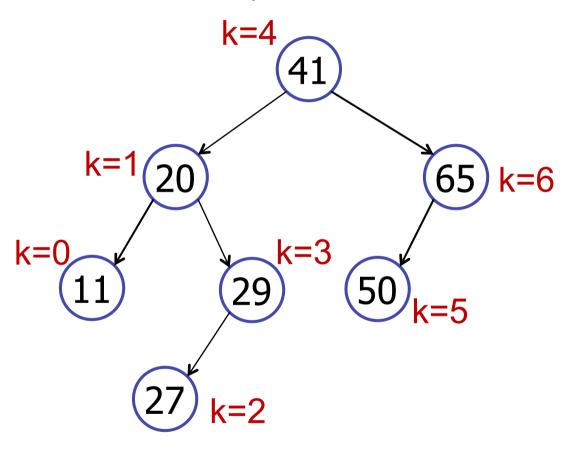


 11
 20
 27
 29
 41
 50
 65

Solution 2: Augment! What to store in each node?

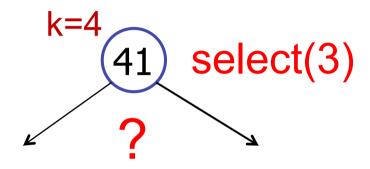


Solution 2: use a tree, store rank in every node

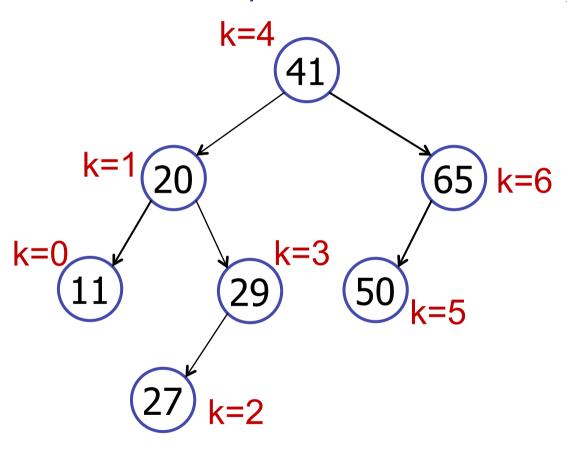




Solution 2: use a tree, store rank in every node

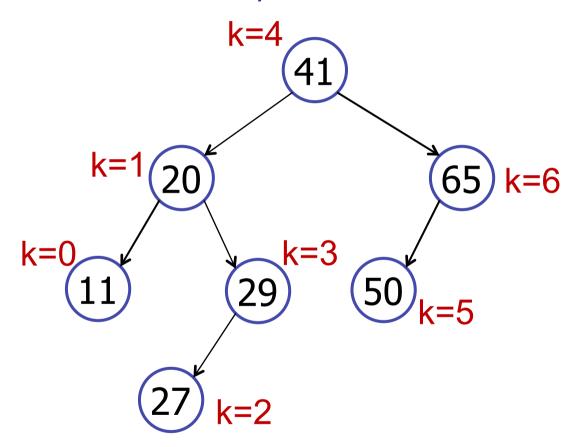


Solution 2: use a tree, store rank in every node



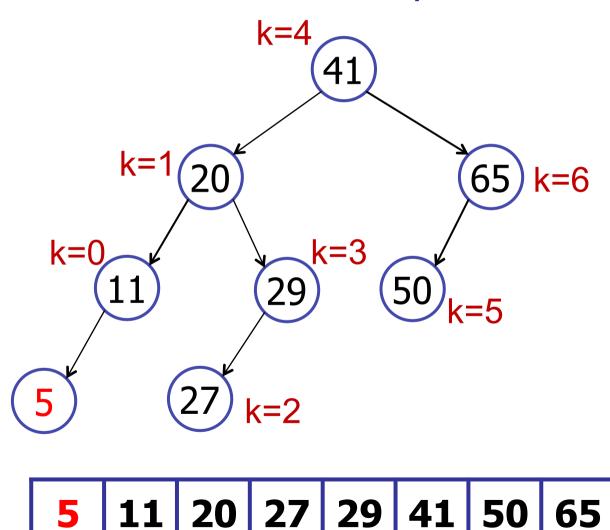


Solution 2: use a tree, store rank in every node

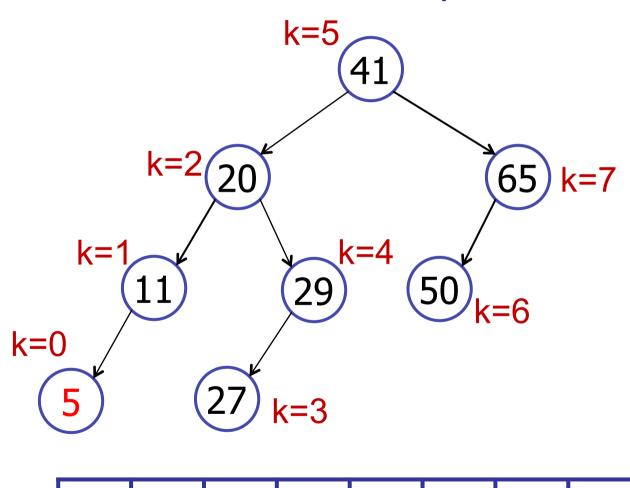


Problem: insert(5) requires updating all the ranks!

Solution 2: store rank in every node



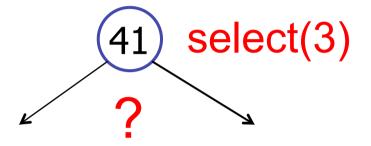
Solution 2: store rank in every node



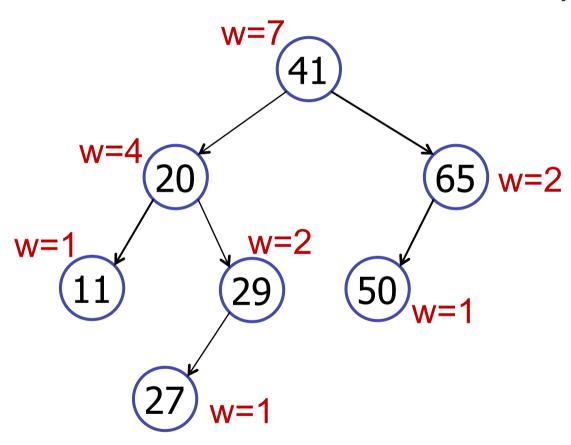
**27** 

29

What should we store in each node?



Solution 3: store size of sub-tree in every node



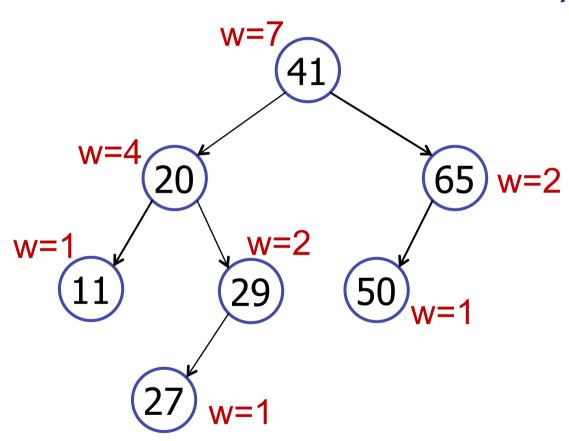
Solution 3: store size of sub-tree in every node

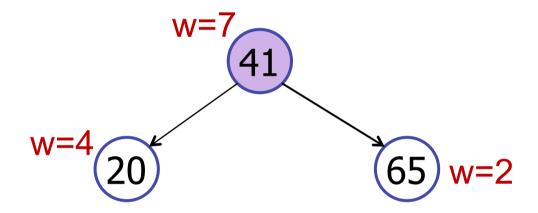
The weight of a node is the size of the tree rooted at that node.

#### Define weight:

```
w(leaf) = 1
 w(v) = w(v.left) + w(v.right) + 1
```

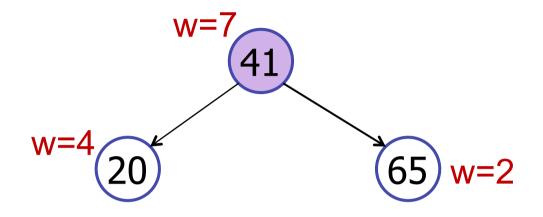
Solution 3: store size of sub-tree in every node

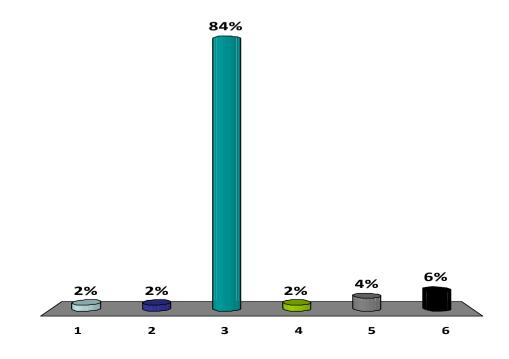


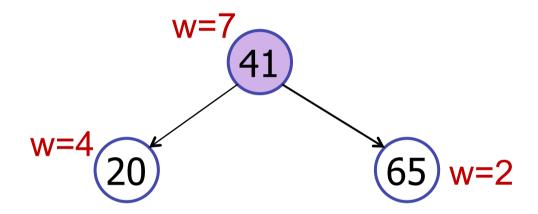


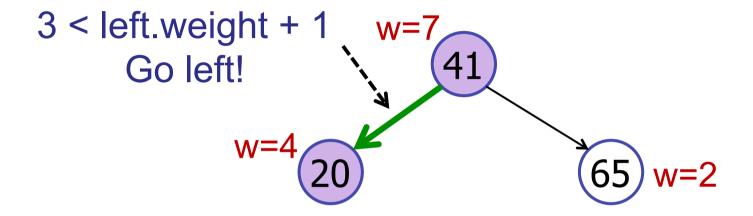
#### What is the rank of 41?

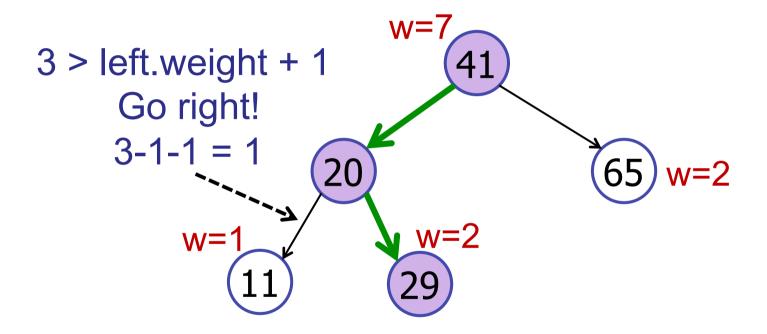
- 1. 1
- 2. 3
- **√**3. 5
  - 4. 7
  - 5. 9
  - 6. Can't tell.

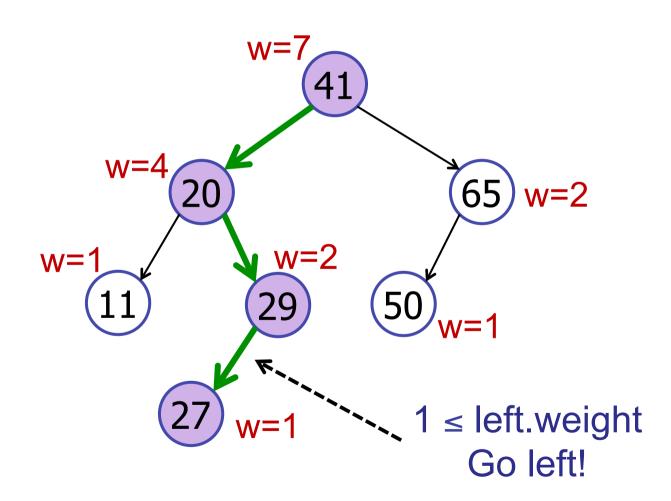


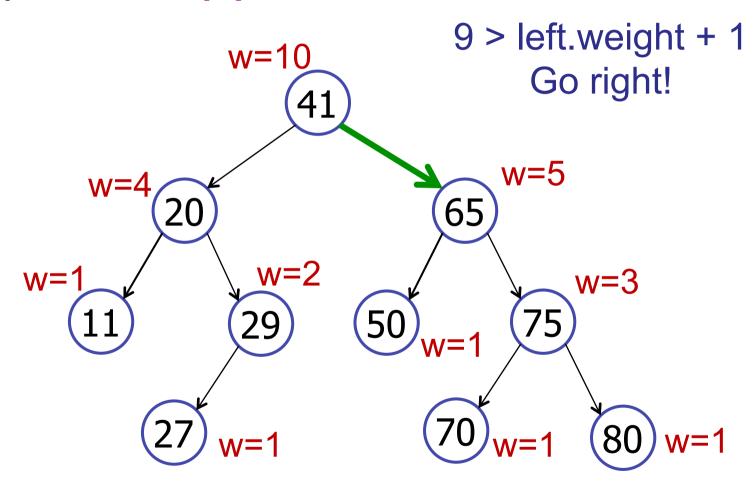




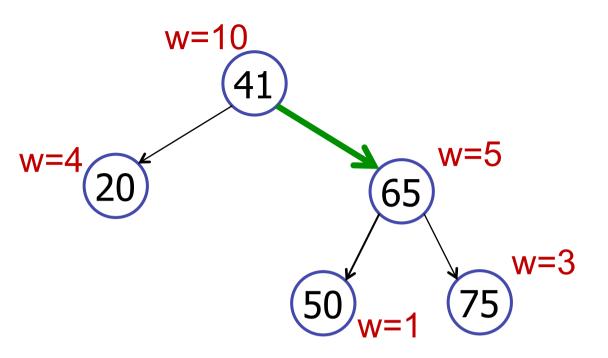


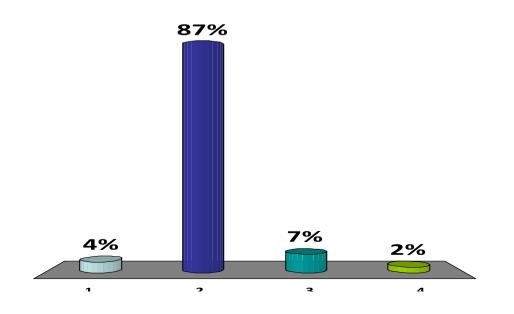


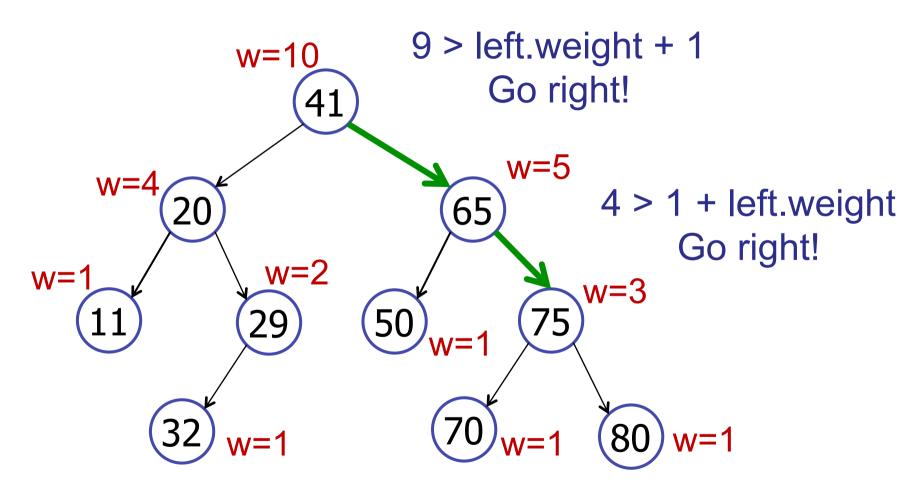




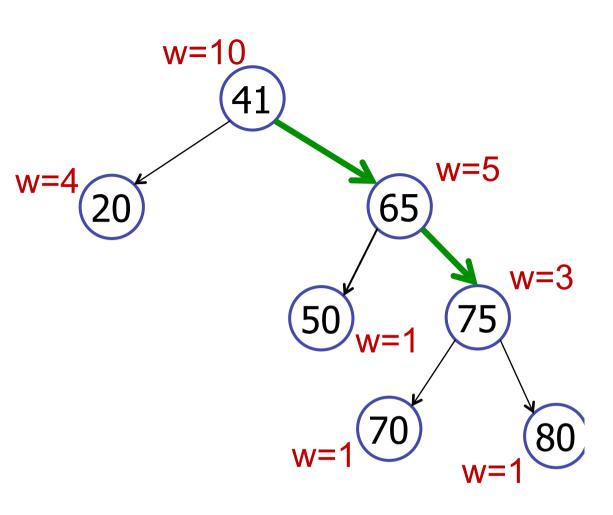
- 1. Go left at 65
- 2. Go right at 65
- 3. Stop at 65
- 4. I'm confused

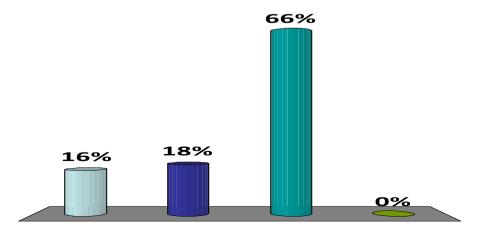


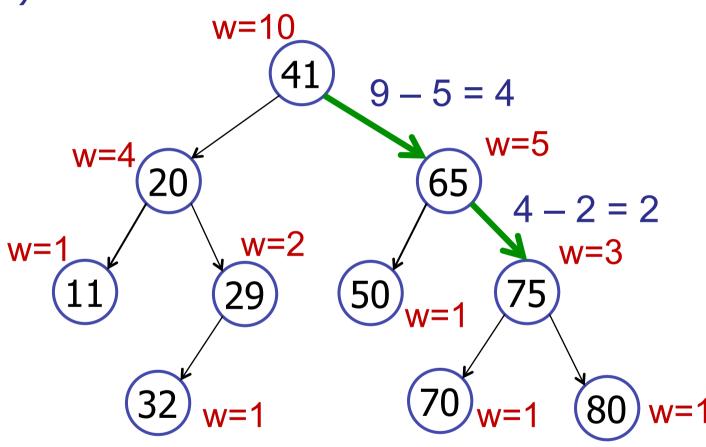




- 1. Go left at 75
- 2. Go right at 75
- 3. Stop at 75
- 4. I'm confused







#### select(k)

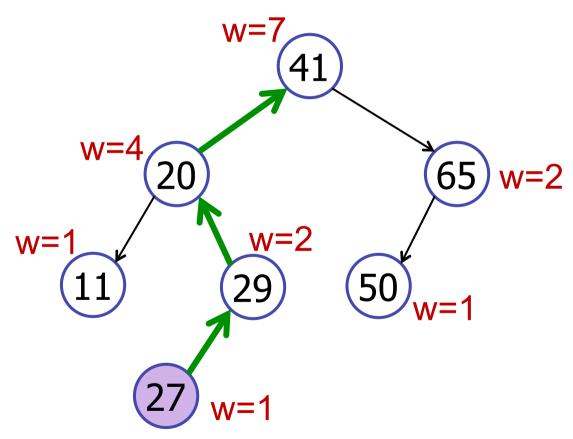
```
r = m left.weight + 1;
if (k == r) then
    return v;
else if (k < r) then
    return m left.select(k);
else if (k > r) then
    return m right.select(k-r);
```

select(k): finds the node with rank k

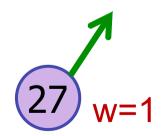
Example: find the 10th tallest student in the class.

rank(v): computes the rank of a node v

Example: determine the percentile of Johnny's height. Is Johnny in the 10<sup>th</sup> percentile or the 90<sup>th</sup> percentile?

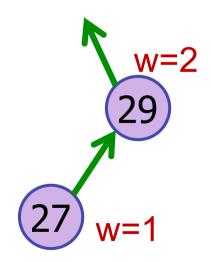


Example: rank(27)

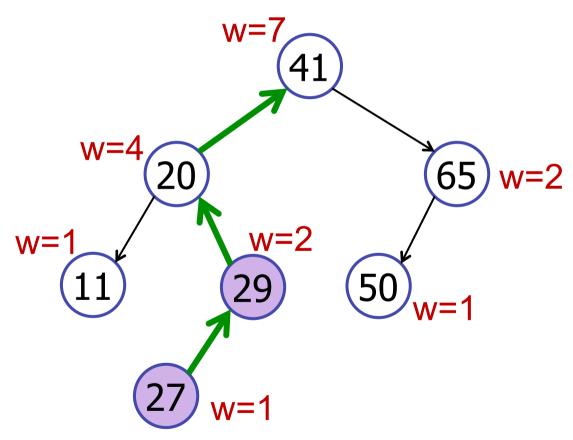


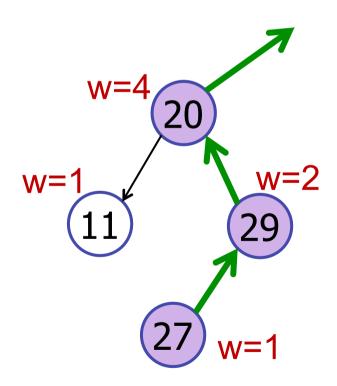
rank = 1

Example: rank(27)

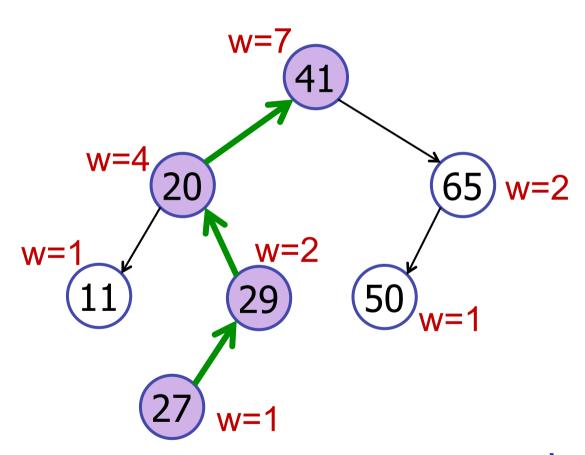


rank = 1





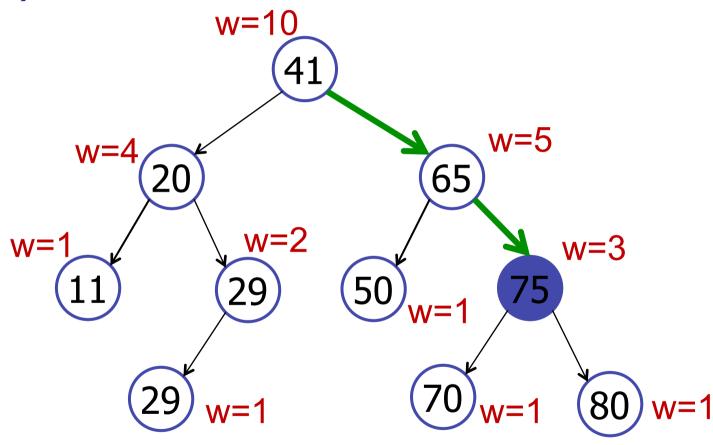
$$rank = 1 + 2$$



rank = 
$$1 + 2 = 3$$

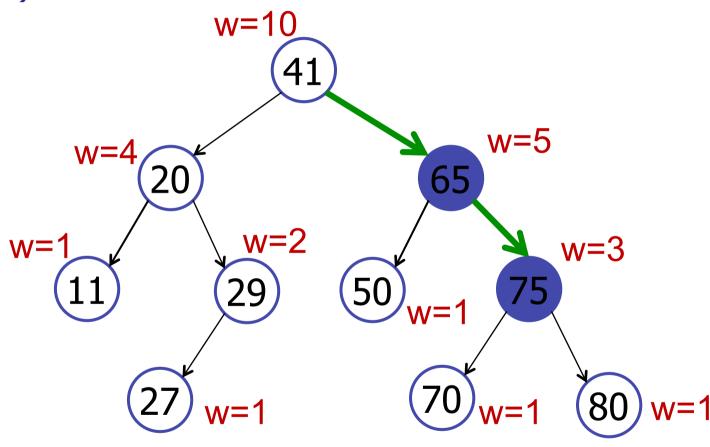
```
Rank(v): computes the rank of a node v
rank()
    r = left.weight + 1;
    node = this;
    while (node != null) do
         if node is right child then
              r += node.parent.left.weight + 1;
         node = node.parent;
    return r;
```

rank(75)



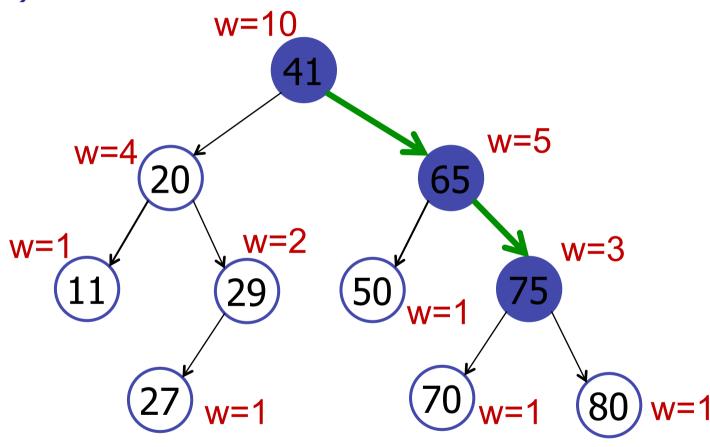
rk = 2

rank(75)



$$rk = 2 + 2$$

rank(75)



$$rk = 2 + 2 + 5 = 9$$

```
Rank(v): computes the rank of a node v
rank()
    r = left.weight + 1;
    node = this;
    while (node != null) do
         if node is right child then
              r += node.parent.left.weight + 1;
         node = node.parent;
    return r;
```

#### Augmenting data structures

#### Basic methodology:

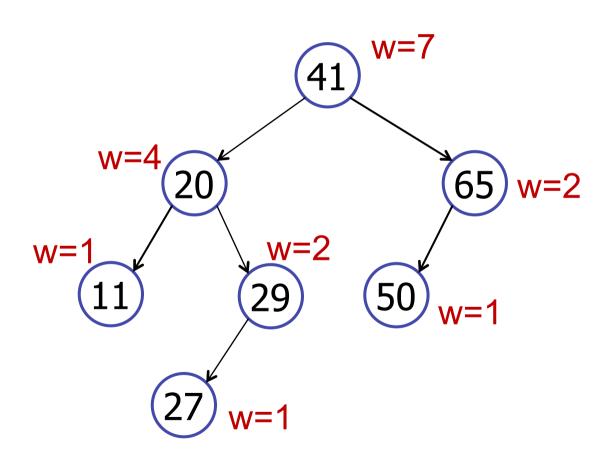
1. Choose underlying data structure:

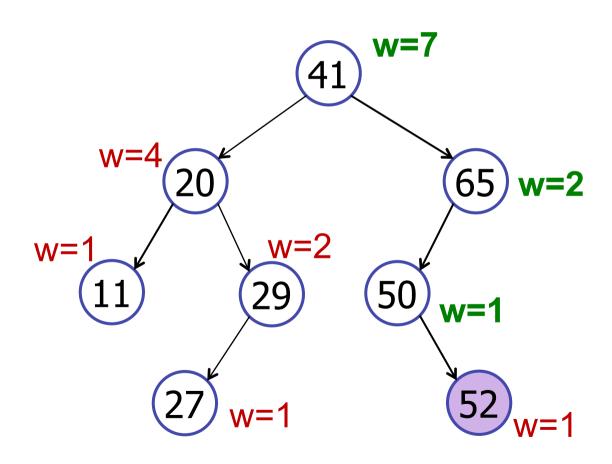
**AVL** tree

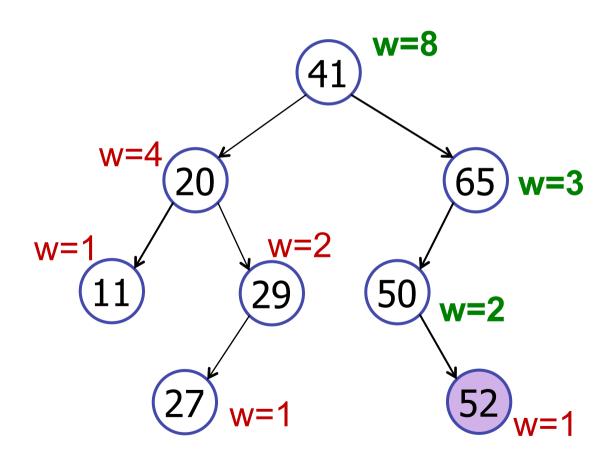
- 2. Determine additional info needed: Weight of each node
- 3. Maintained info as data structure is modified.

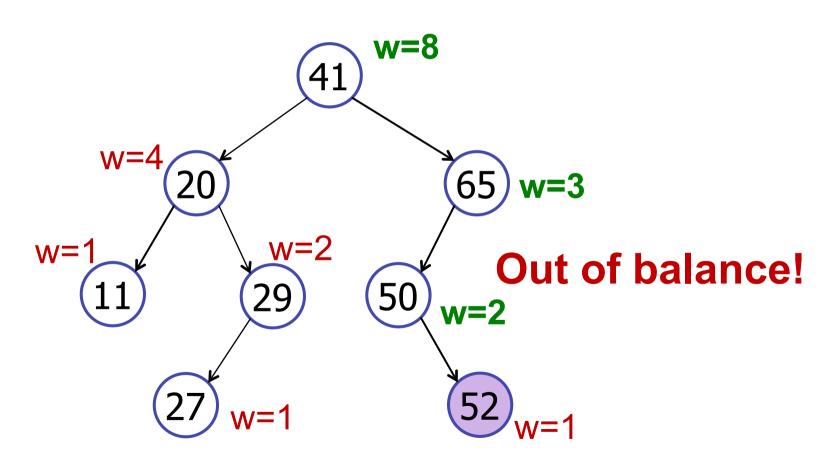
  Update weights as needed
- 4. Develop new operations using the new info.

Select and Rank

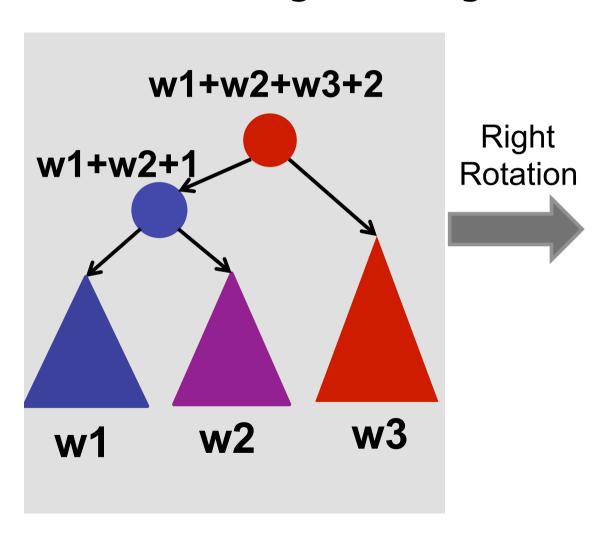


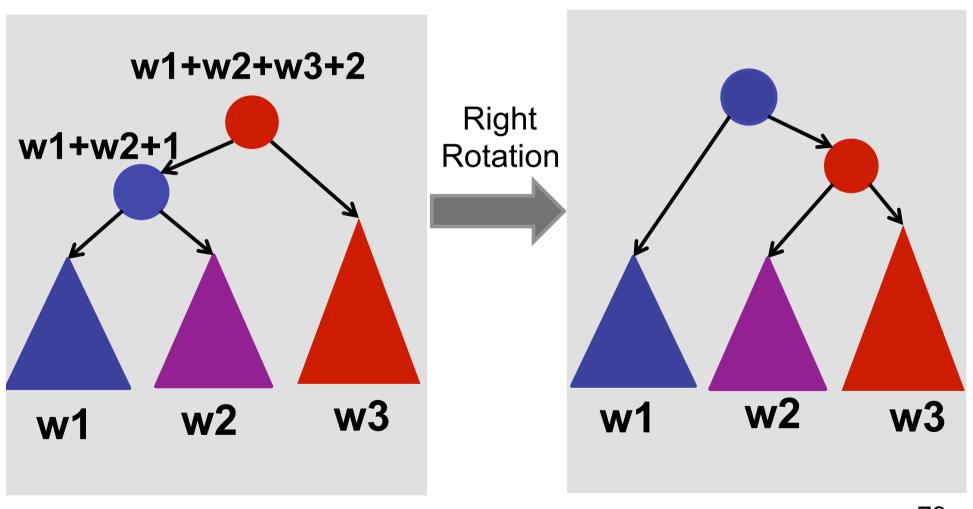


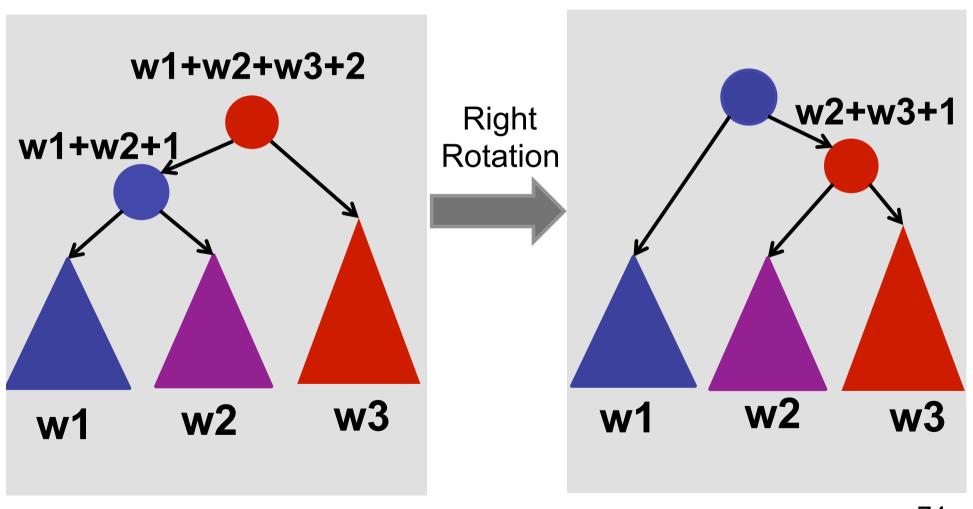


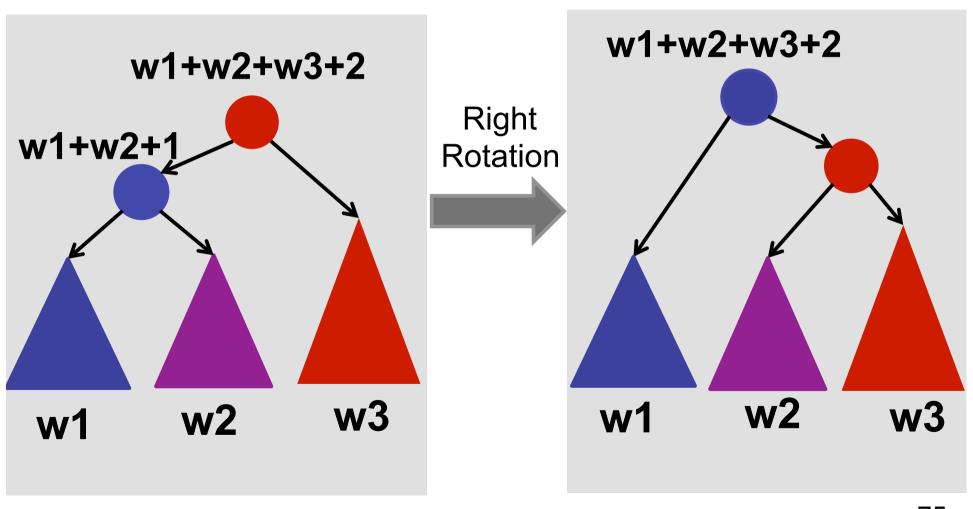


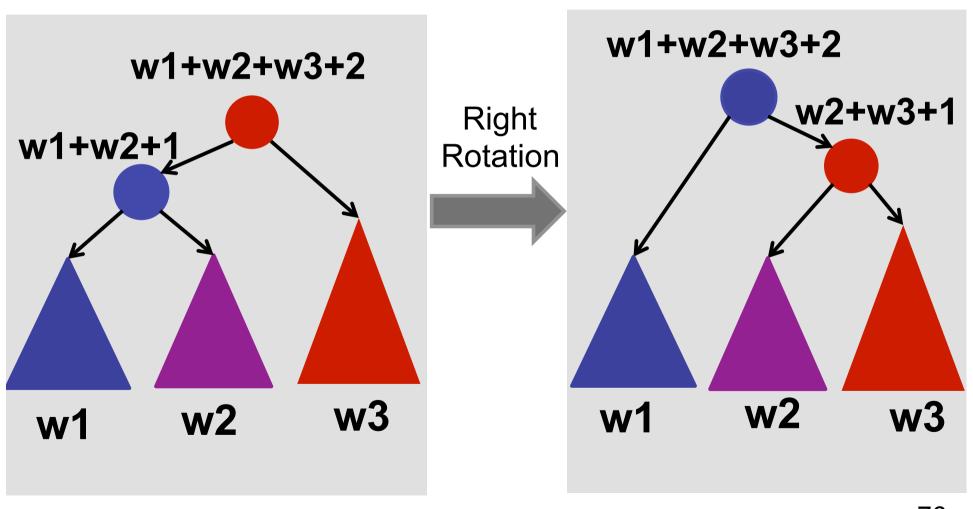
#### Maintain weight during rotations:





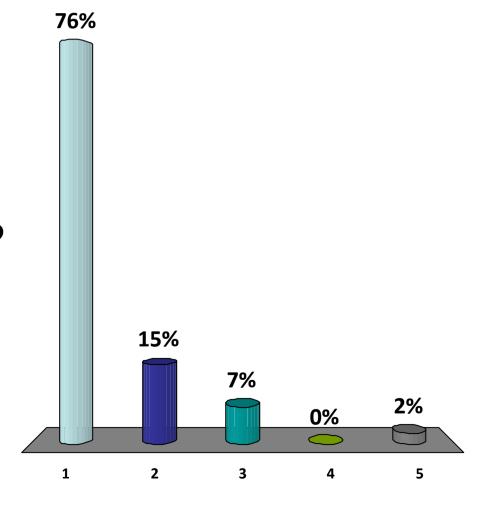


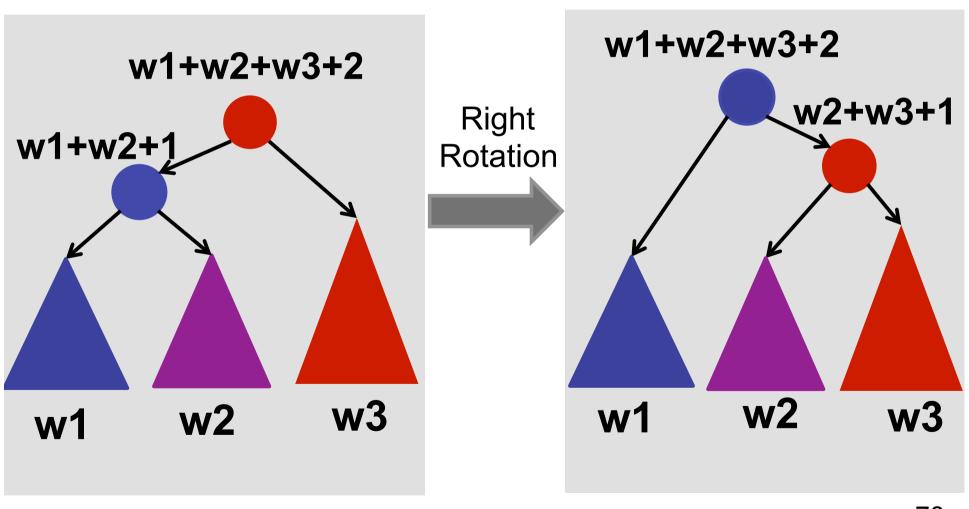




# How long does it take to update the weights during a rotation?

- 1. O(1)
- 2. O(log n)
- 3. O(n)
- 4.  $O(n^2)$
- 5. What is a rotation?





# Augmenting data structures

#### Basic methodology:

- 1. Choose underlying data structure (tree, hash table, linked list, stack, etc.)
- 2. Determine additional info needed.
- 3. Verify that the additional info can be maintained as the data structure is modified.

(subject to insert/delete/etc.)

4. Develop new operations using the new info.

# Today

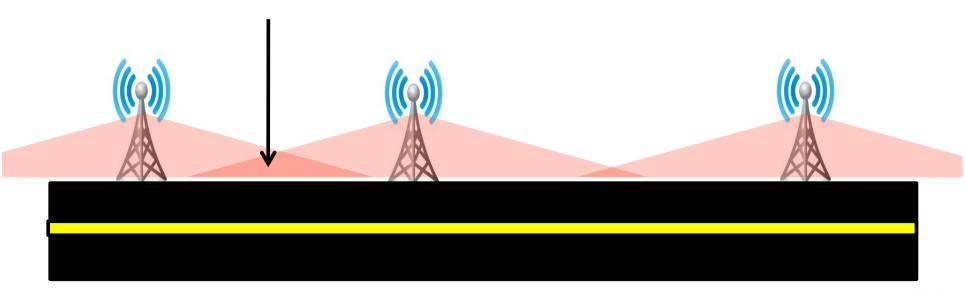
Three examples of augmenting balanced BSTs

1. Order Statistics

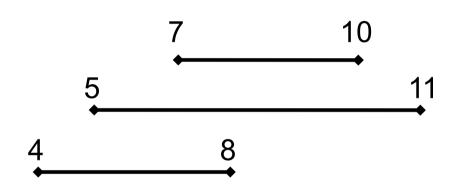
2. Intervals

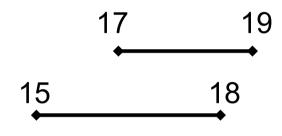
3. Orthogonal Range Searching

Find a tower that covers my location.



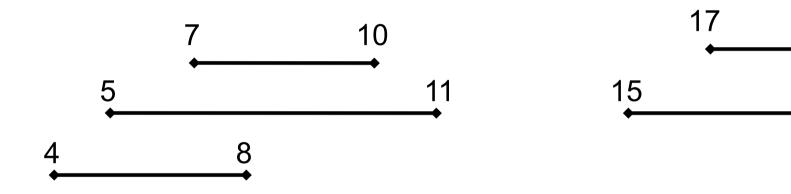
Find a tower that covers my location.





insert(begin, end) delete(begin, end)

Find a tower that covers my location.

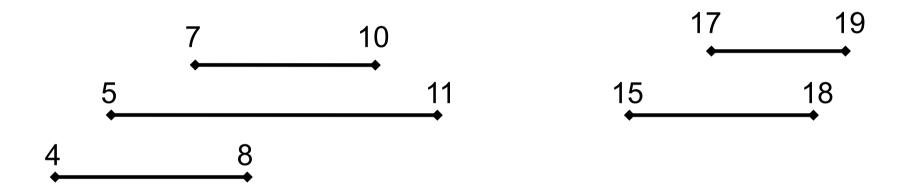


insert(begin, end) delete(begin, end)

Query: find an interval that overlaps x.

19

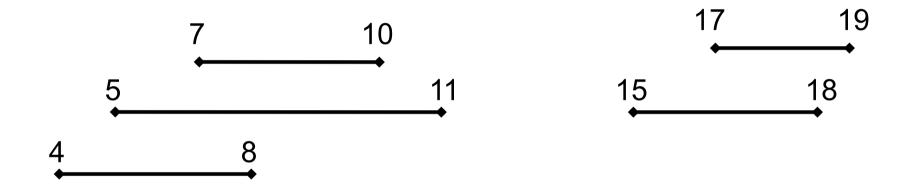
Find a tower that covers my location.



Solution 1: Keep intervals in a list.

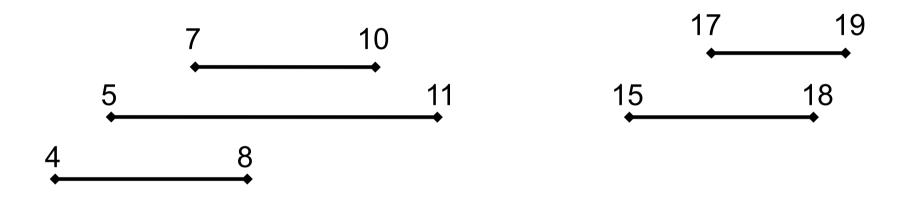
Query: scan entire list.

Find a tower that covers my location.

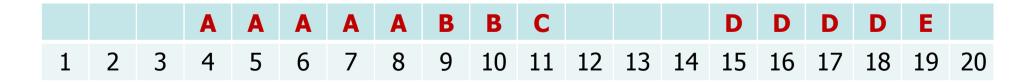


Solution 2: O(1) queries??

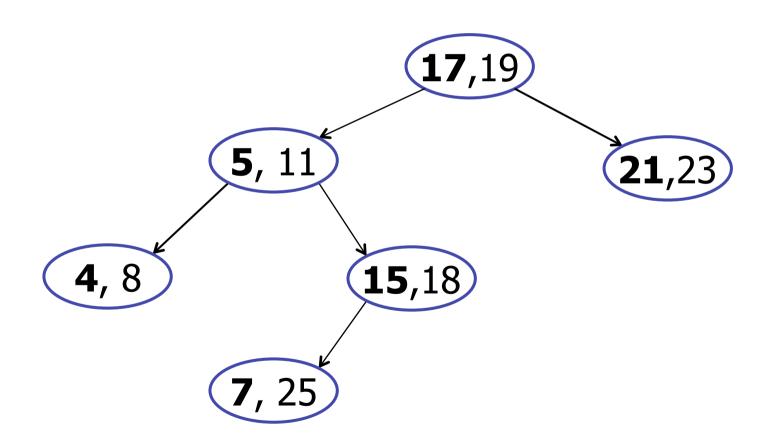
Find a tower that covers my location.



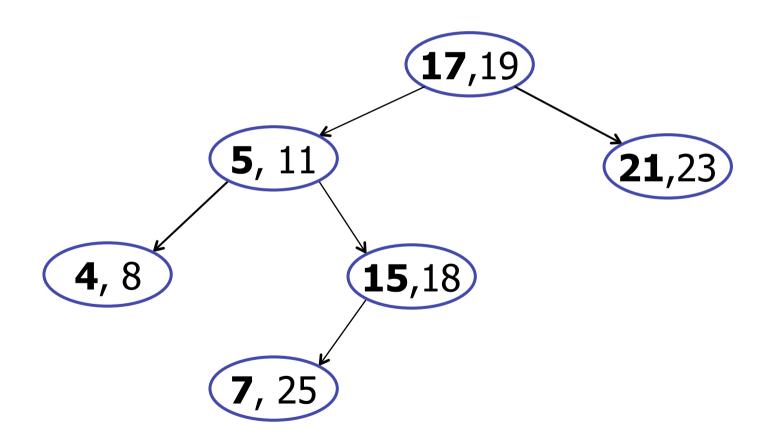
Solution 2: O(1) queries??



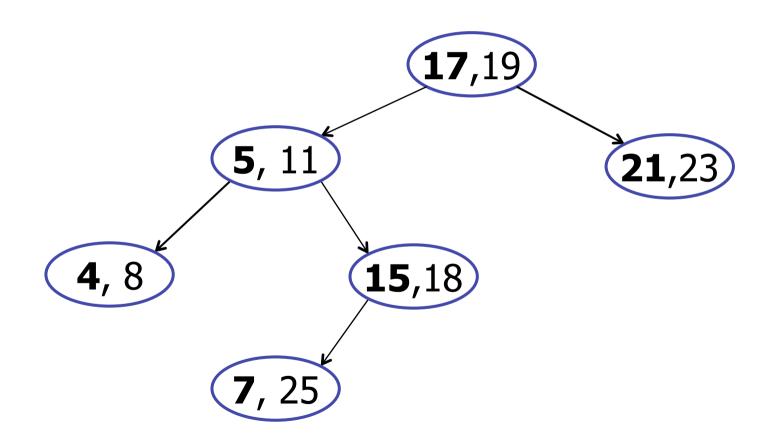
#### Sorted by left endpoint



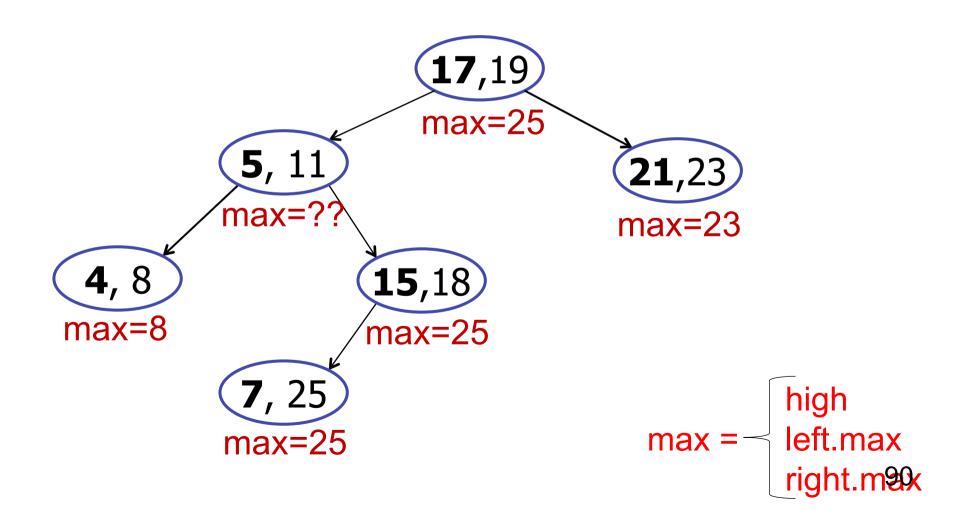
search-interval(25) = ?

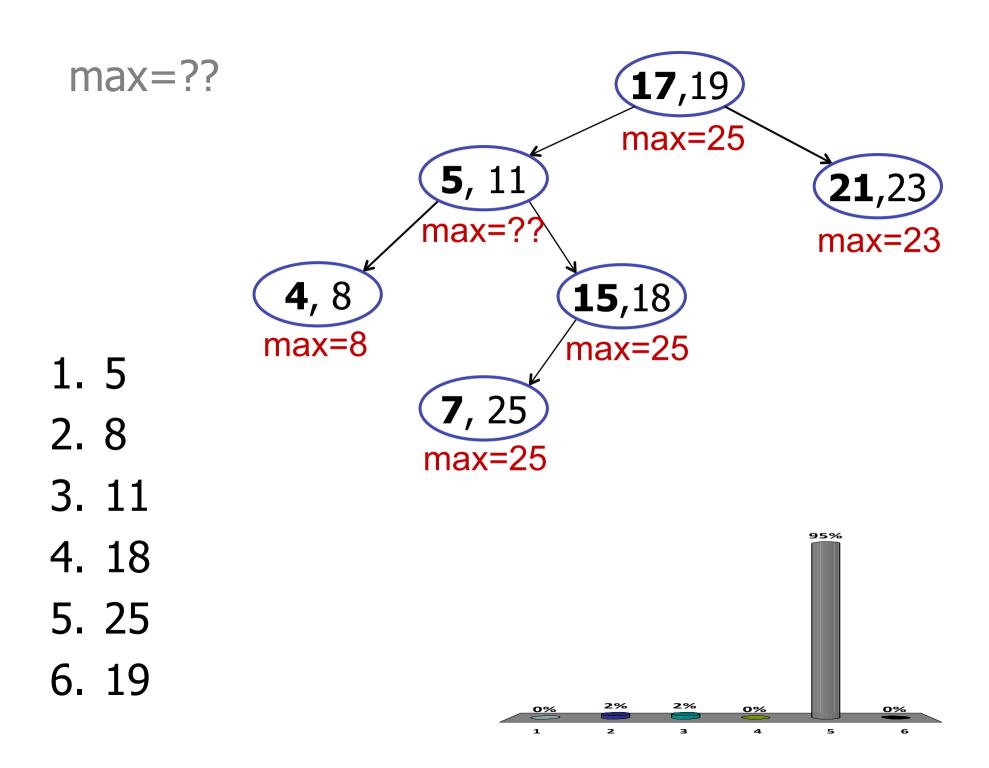


Augment: ??

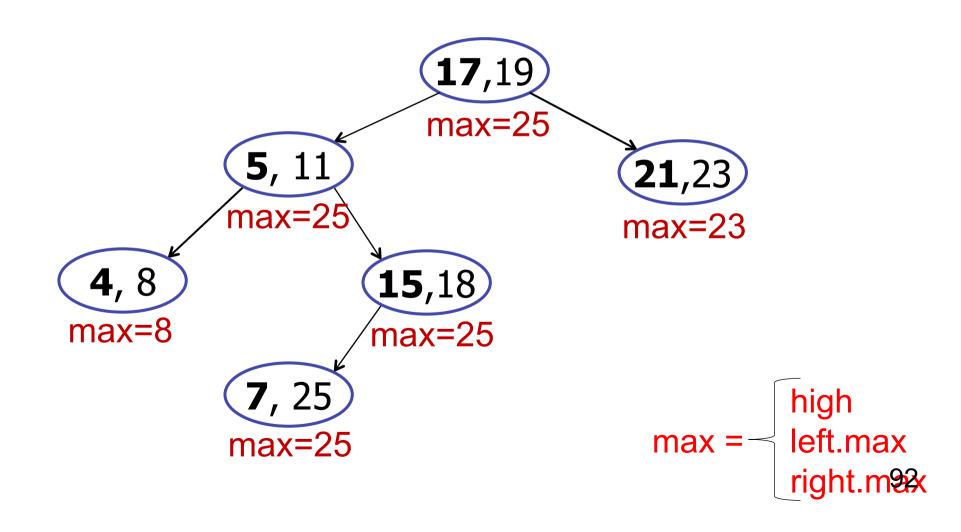


Augment: maximum endpoint in subtree

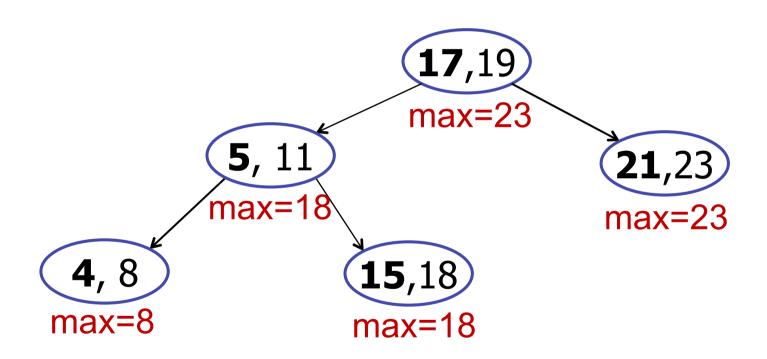




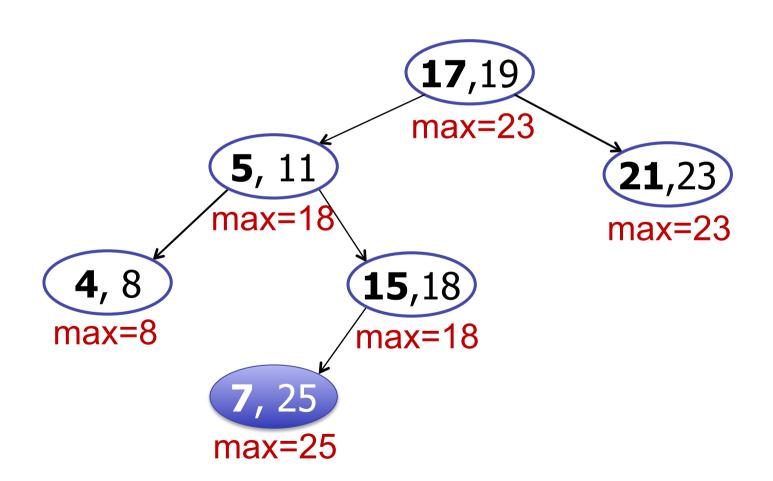
Augment: maximum endpoint in subtree



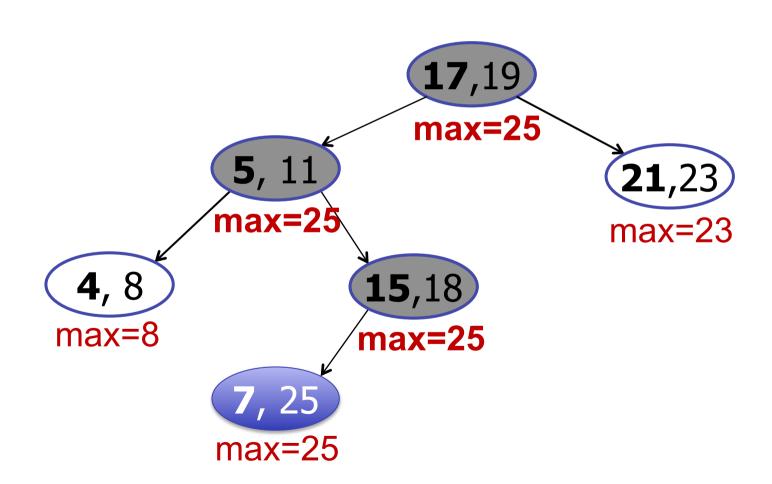
Insertion: example – insert(7, 25)



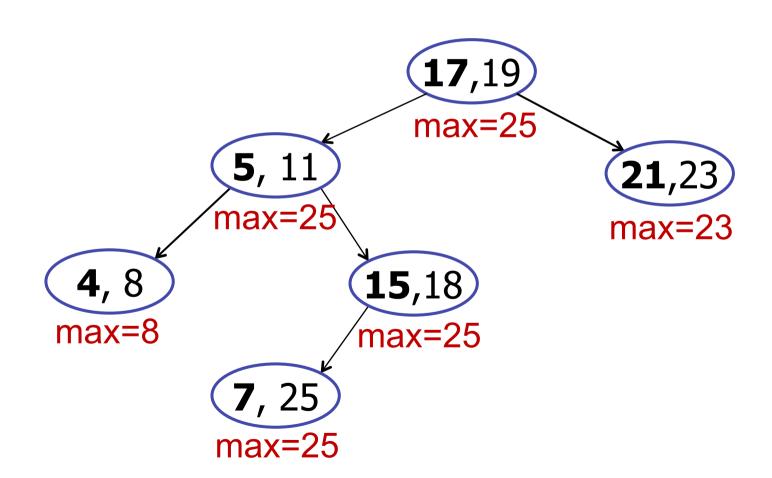
Insertion: example – insert(7, 25)



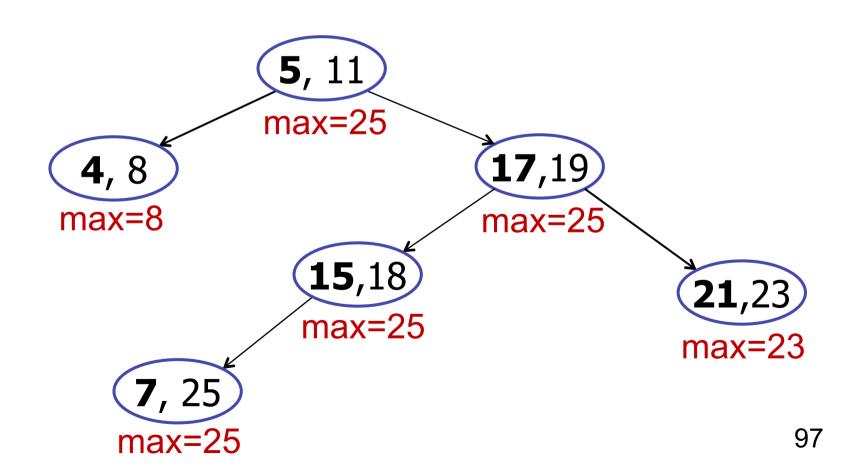
Insertion: *example* – **insert(7, 25)** 



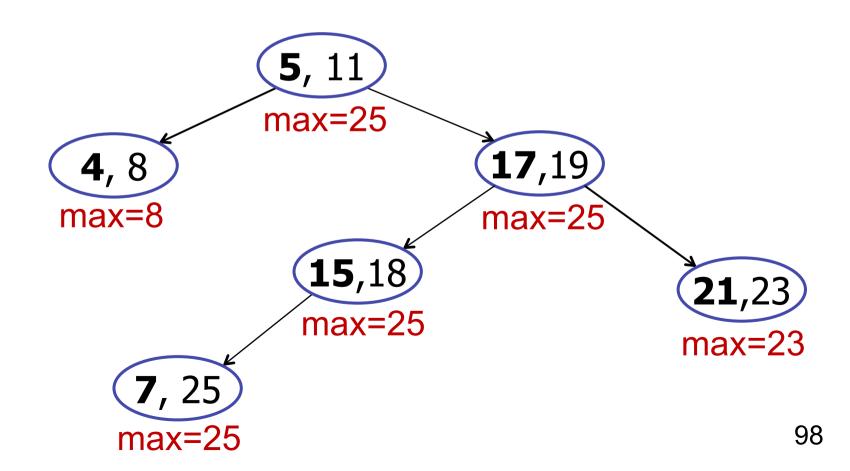
Insertion: out-of-balance



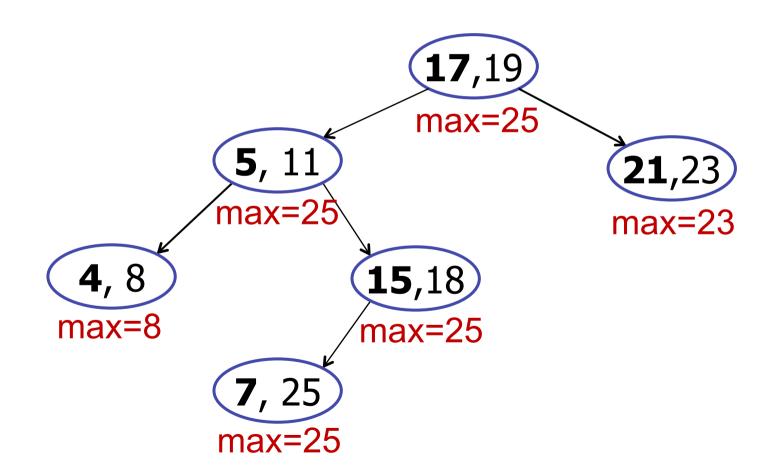
Insertion: right-rotate (17, 19)



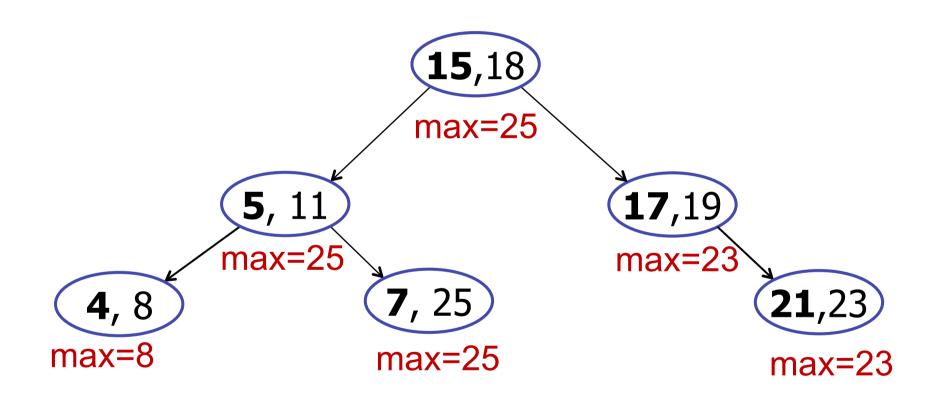
Insertion: right-rotate (17, 19), OOPS!



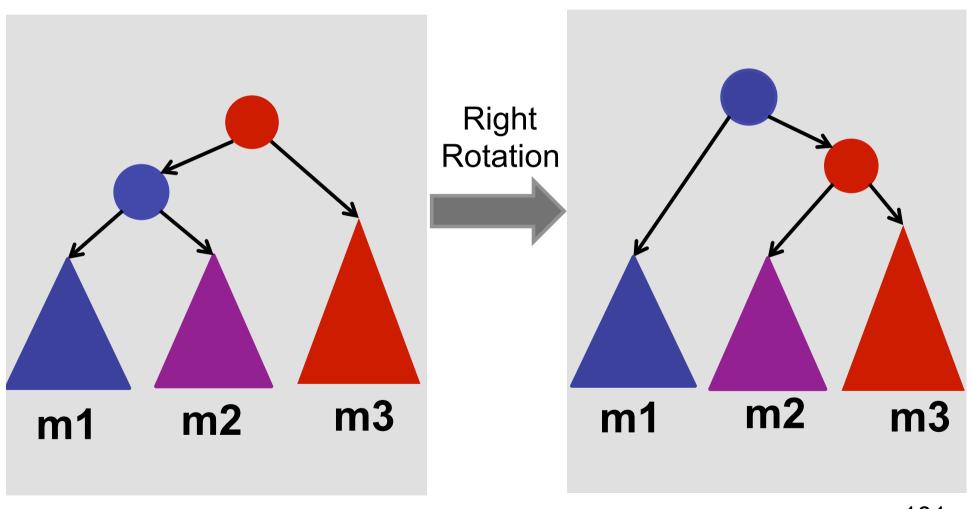
Insertion: out-of-balance



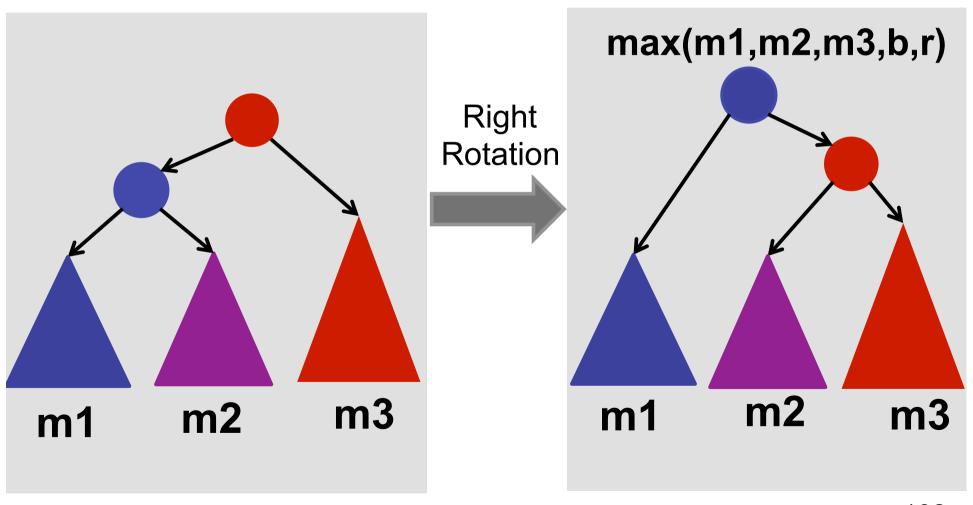
Insertion: left-rotate, right-rotate

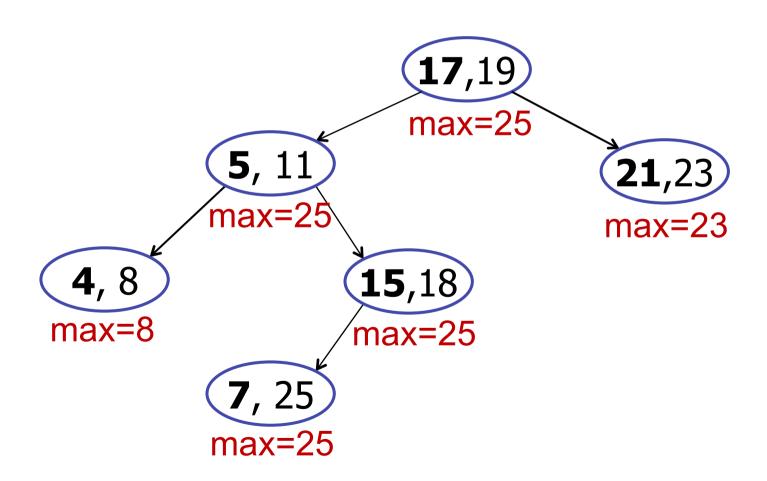


#### Maintain MAX during rotations:



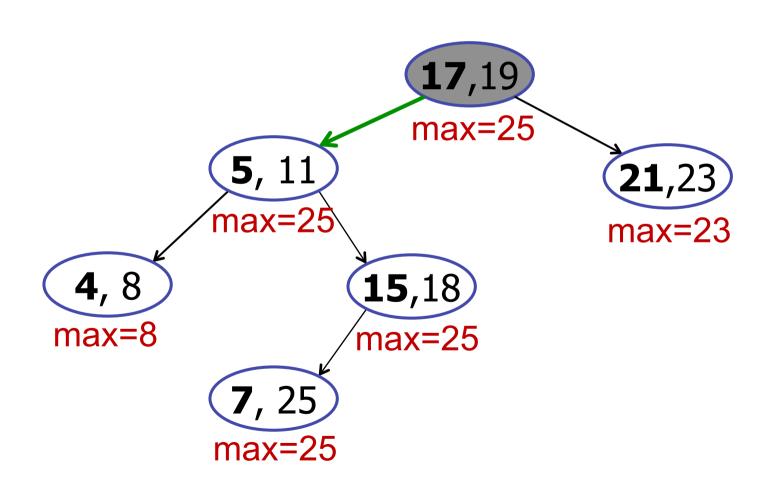
#### Maintain MAX during rotations:

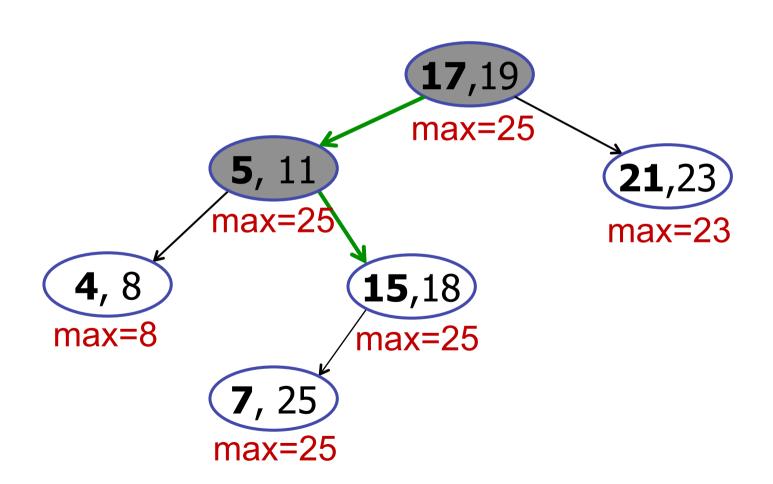


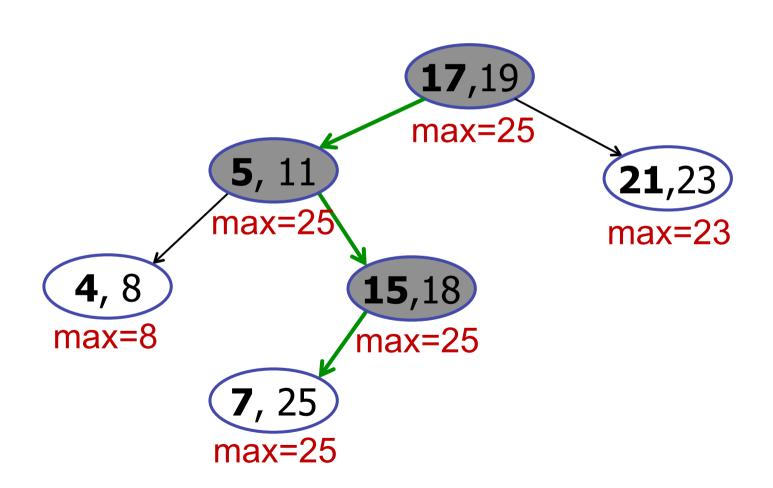


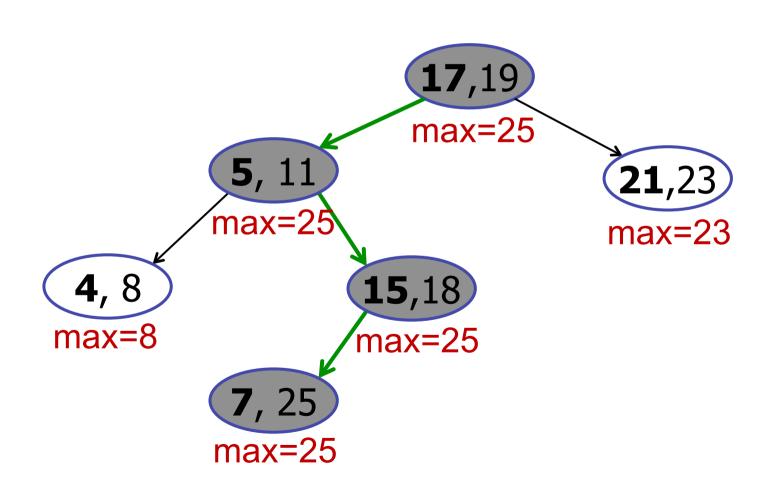
# **Dynamic Order Statistics**

```
interval-search(x): find interval containing x
interval-search(x)
    c = root;
    while (c != null and x is not in c.interval) do
          if (c.left == null) then
                 c = c.right;
          else if (x > c.left.max) then
                c = c.right;
          else c = c.left;
    return c.interval;
```





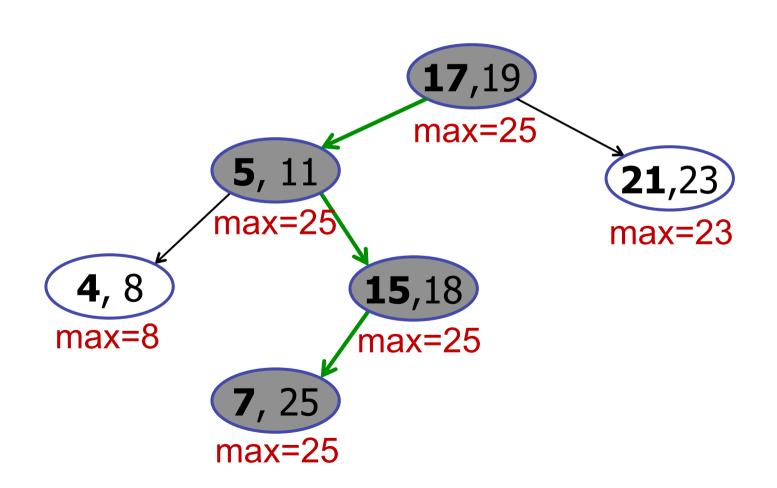




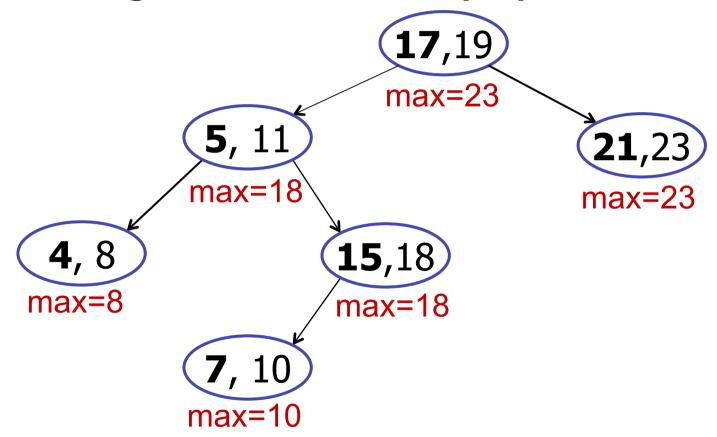
## **Dynamic Order Statistics**

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          else if (x > c.left.max) then
                c = c.right;
          else c = c.left;
    return c.interval;
```

Will any search find (21, 23)?

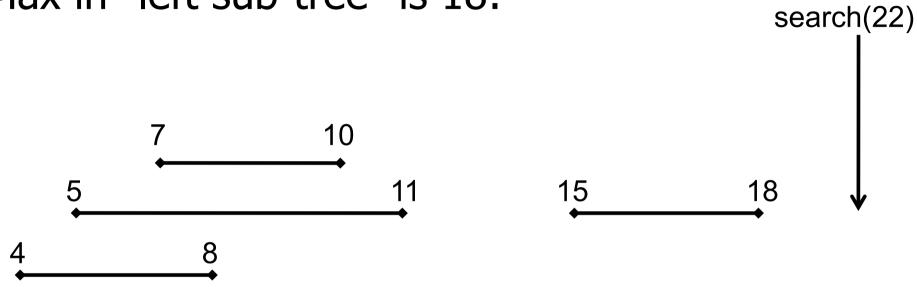


Searching: interval-search(22)



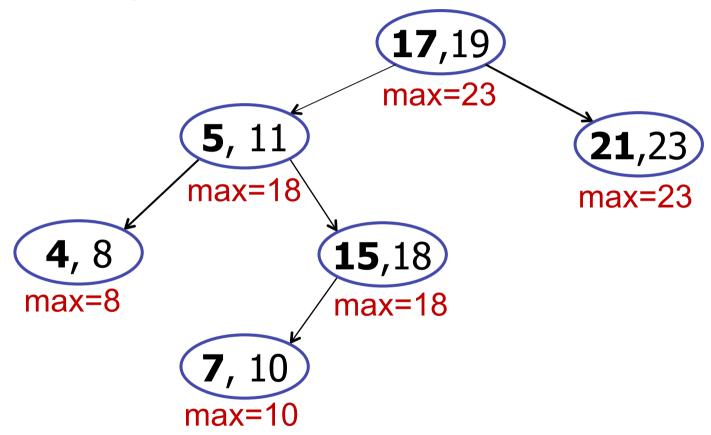
Claim: if search goes right, then no overlap in left subtree.

Max in "left sub-tree" is 18:



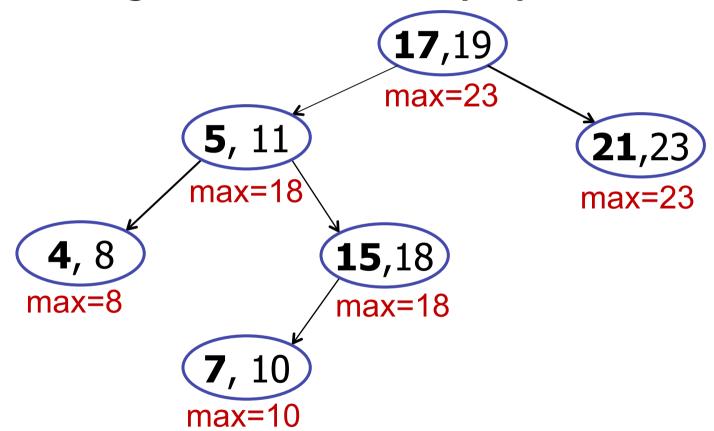
Safe to go right: 22 is not in the left sub-tree.

Searching: interval-search(13)



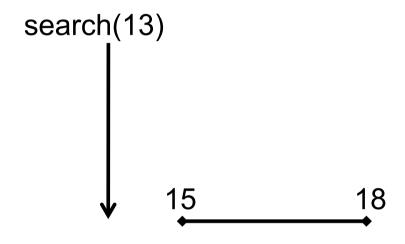
**Claim:** if search goes left and there is no overlap in the left subtree...

Searching: *interval-search(13)* 



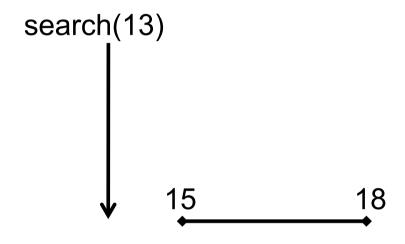
Claim: if search goes left, then safe to go left.

Max in "left sub-tree" is 18:



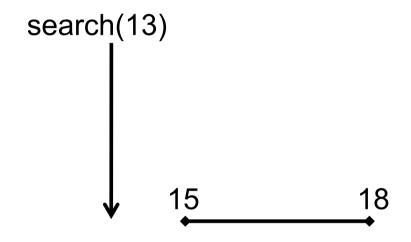
Go left: search(13) < 18

Max in "left sub-tree" is 18:



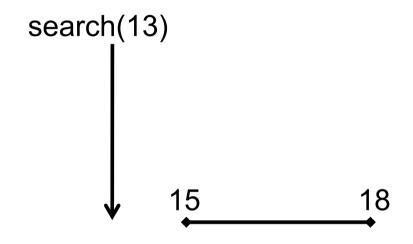
Go left: search(13) < 15 < 18

Max in "left sub-tree" is 18:



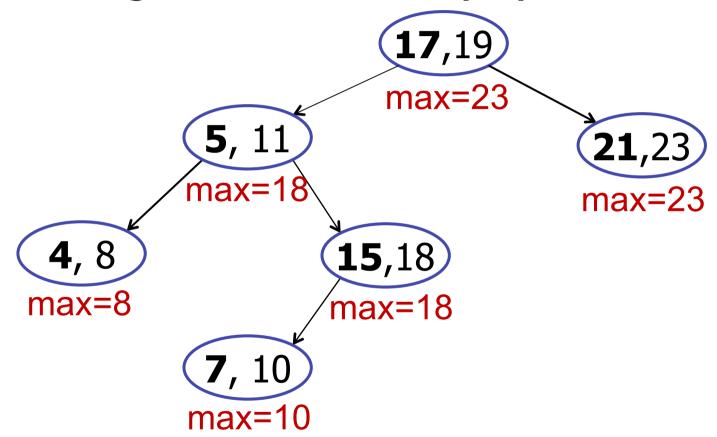
Go left: search(13) < 15 < 18 Tree sorted by left endpoint.

Max in "left sub-tree" is 18:



Go left: search(13) < 15 < 18
Tree sorted by left endpoint.
search(13) < every interval in right subtree

Searching: interval-search(13)



**Claim:** if search goes left and no overlap, then search < every interval in right sub-tree.

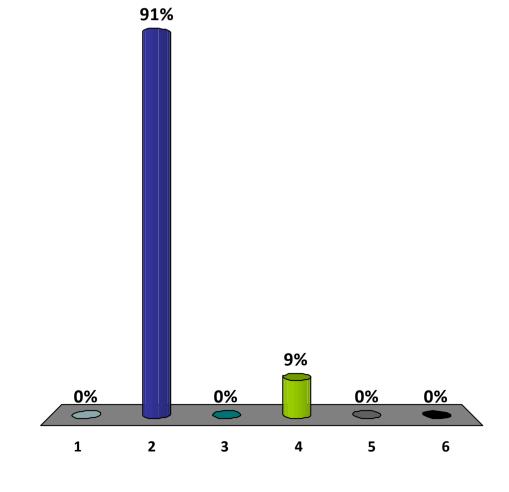
If search goes right, then no overlap in left subtree.

If search goes left, and if there is no overlap in left subtree, then there is no overlap in right subtree either.

Conclusion: search finds an overlapping interval.

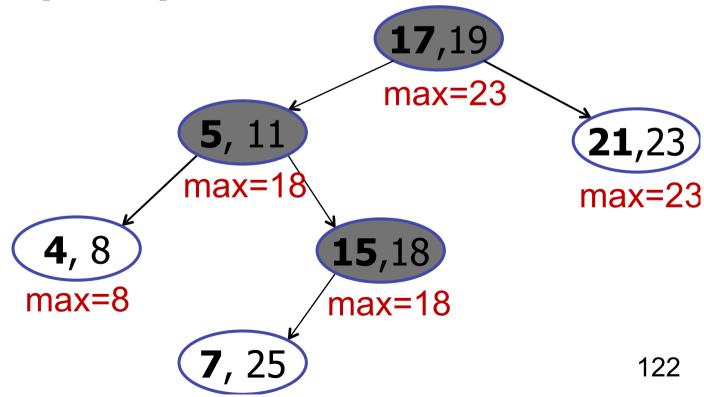
#### The running time of interval-search is:

- 1. O(1)
- 2. O(log n)
- 3. O(n)
- 4. O(n log n)
- 5.  $O(n^2)$
- 6. Can't say.



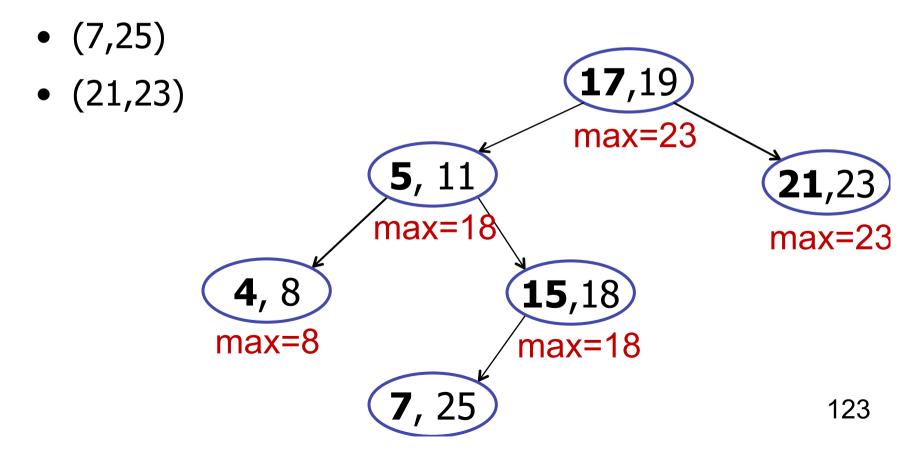
#### **Extensions**

- What if you want to search for two intervals that overlap?
- Eg: search(14,16)



#### **Extensions**

- Cost for listing all intervals that overlap with point?
- E.g.: search(22) returns:



#### **Extensions**

- Cost for listing all intervals that overlap with point?
- All-Overlaps Algorithm:

**Repeat** until no more intervals:

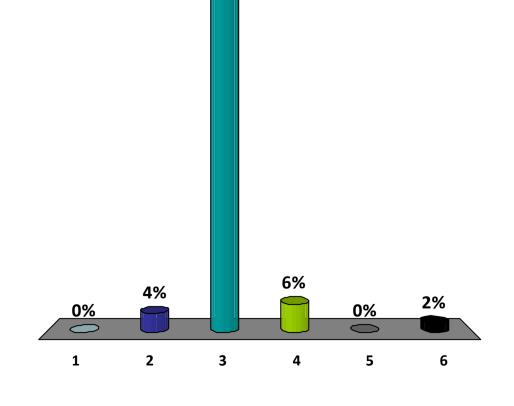
- -Search for interval.
- -Add to list.
- Delete interval.

**Repeat** for all intervals on list:

-Add interval back to tree.

# The running time of All-Overlaps, if there are k overlapping intervals?

- 1. O(1)
- 2. O(k)
- 3. O(k log n)
- 4. O(k + log n)
- 5. O(kn)
- 6. O(kn log n)



87%

#### **Extensions**

- Cost for listing all intervals that overlap point?
- All-Overlaps Algorithm: O(k log n)

**Repeat** until no more intervals:

- -Search for interval.
- -Add to list.
- Delete interval.

**Repeat** for all intervals on list:

- -Add interval back to tree.
- Best known solution: O(k + log n)

## Today

Three examples of augmenting BSTs

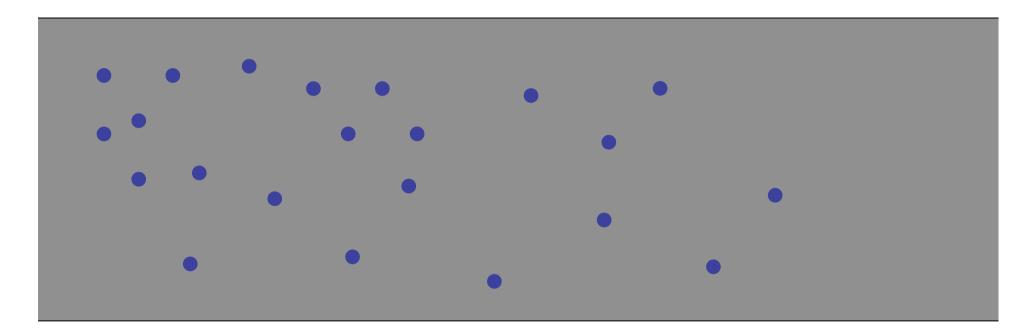
1. Order Statistics

2. Intervals

3. Orthogonal Range Searching

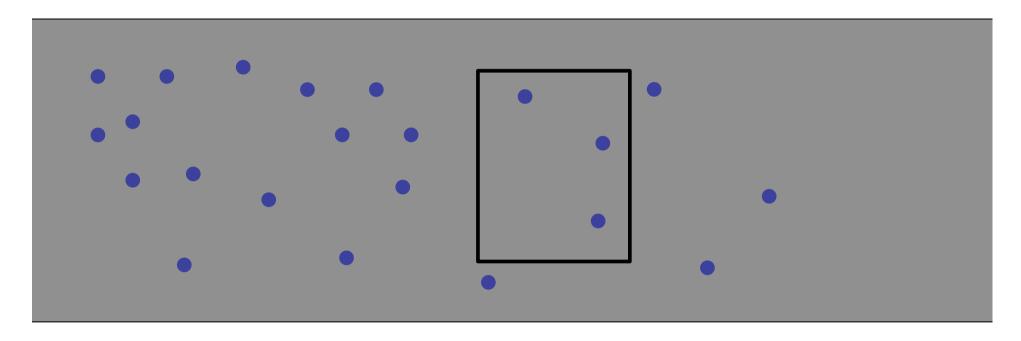
## Orthogonal Range Searching

Input: *n* points in a 2d plane



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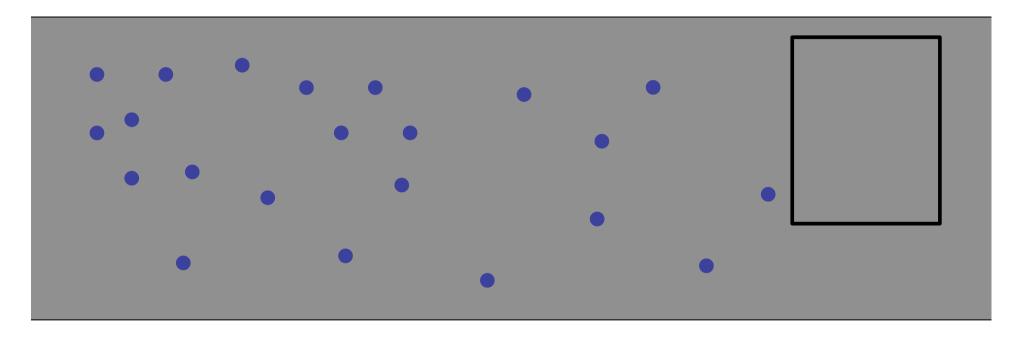


#### Query: Box

- Contains at least one point?
- How many?

## Orthogonal Range Searching

Input: *n* points in a 2d plane

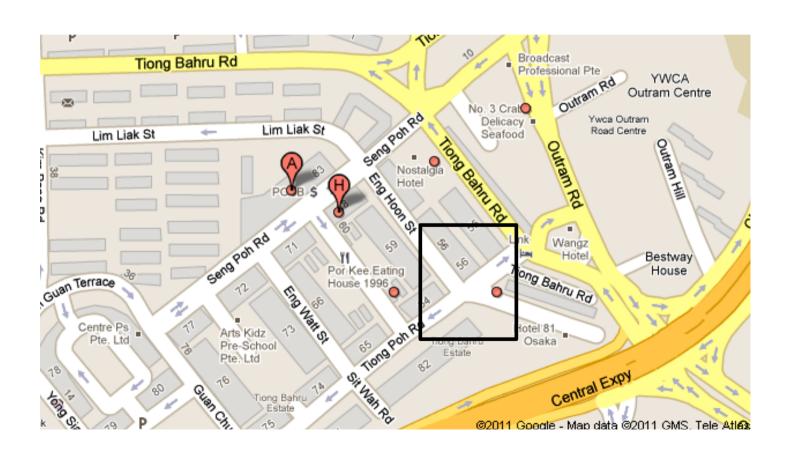


#### Query: Box

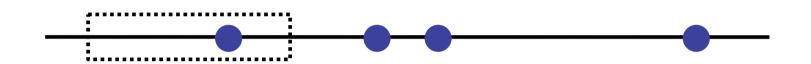
- Contains at least one point?
- How many?

## Practical Example

Are there any good restaurants within one block of me?



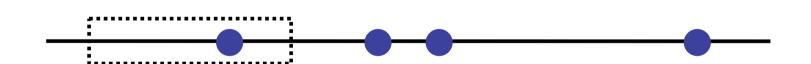
## One Dimension



## One Dimension

#### Range Queries

- Important in databases
- "Find me everyone between ages 22 and 27."

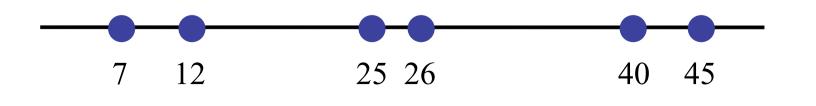


### One Dimension

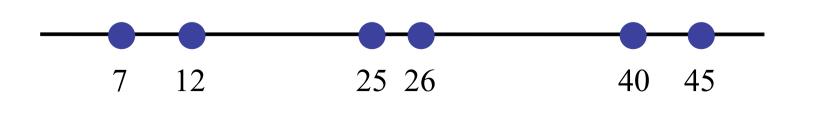
#### Strategy:

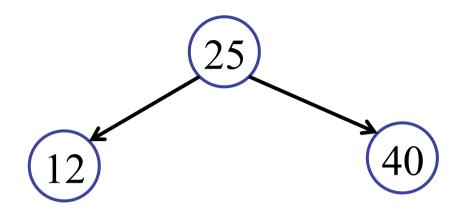
1. Use a binary search tree.

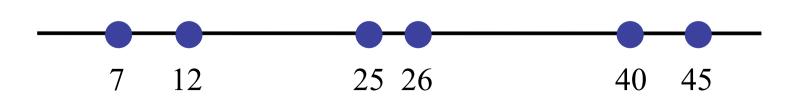
- 2. Store all points in the <u>leaves</u> of the tree. (Internal nodes store only copies.)
- 3. Each internal node *v* stores the MAX of any leaf in the left sub-tree.

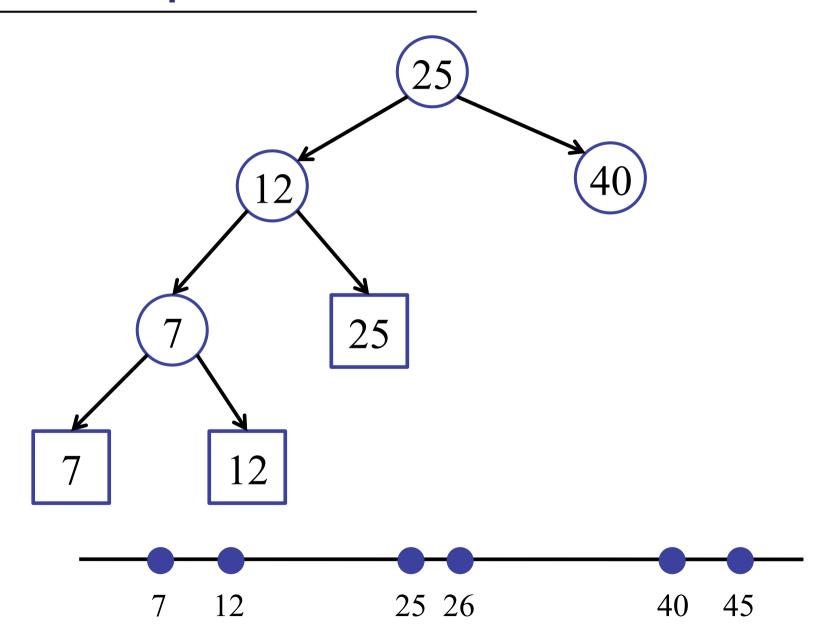




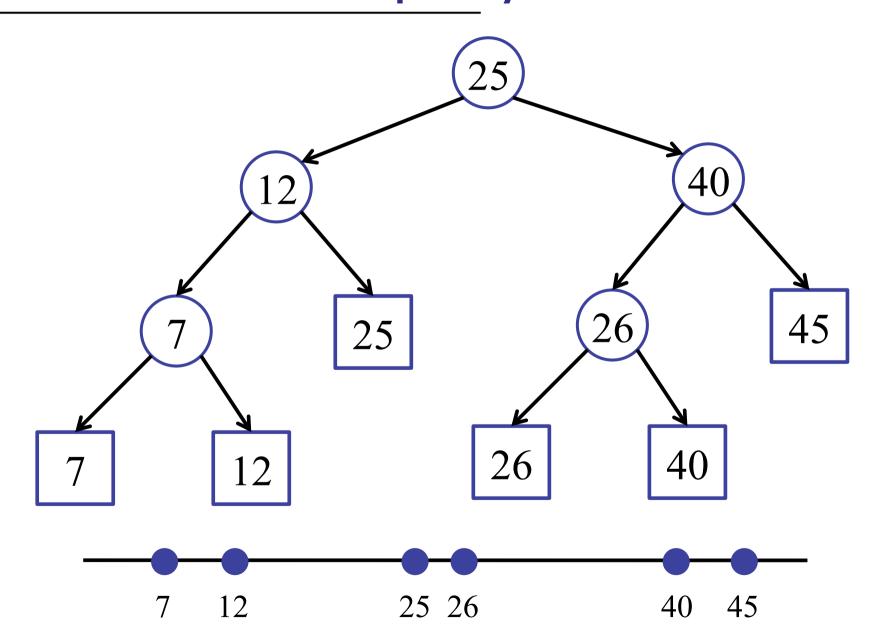




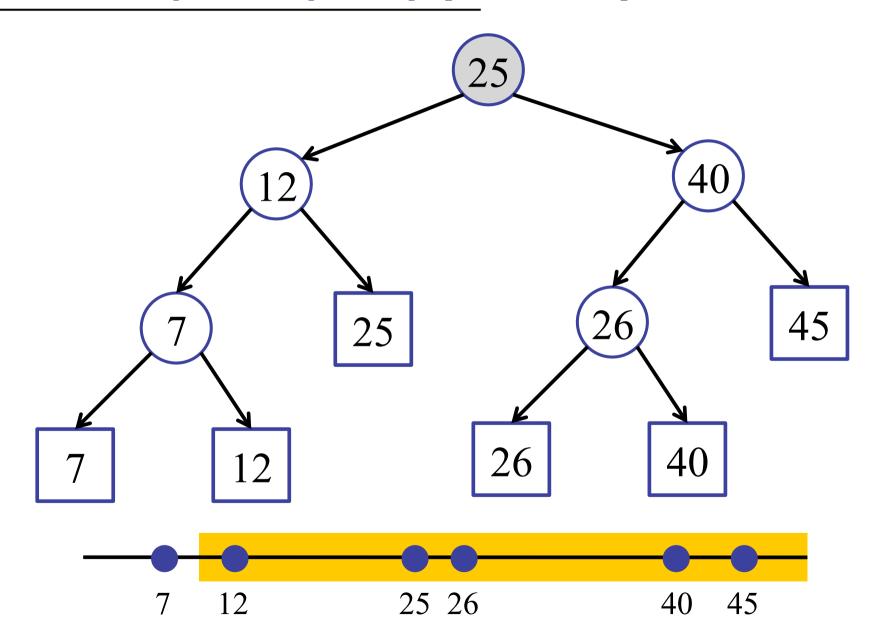




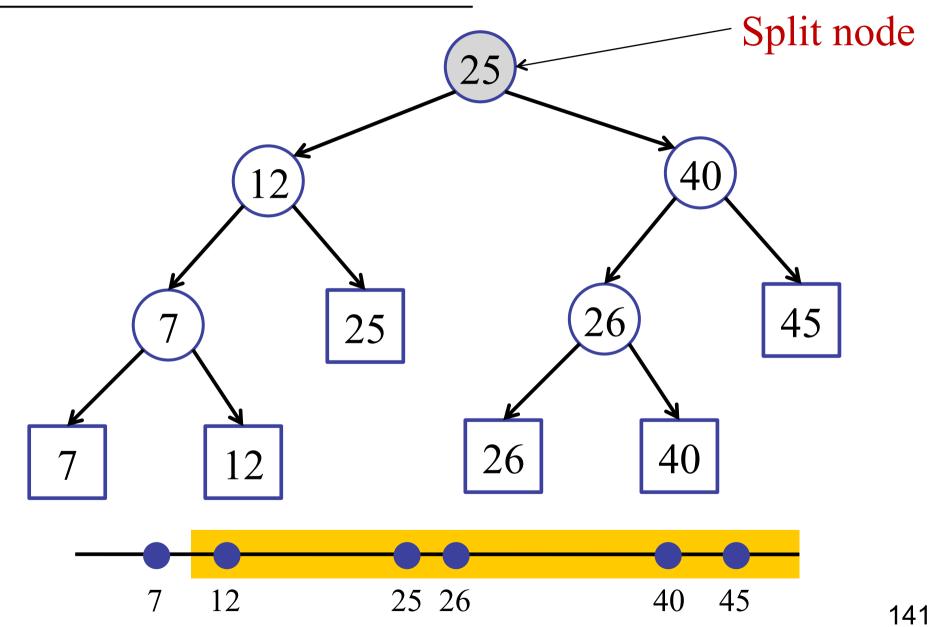
## Note: BST Property



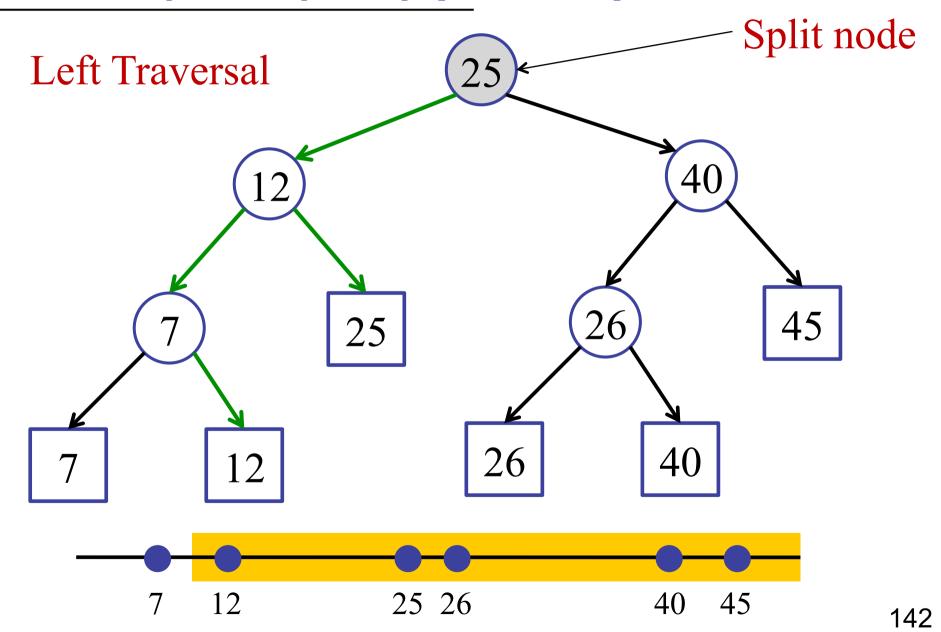
## Example: query(10, 50)

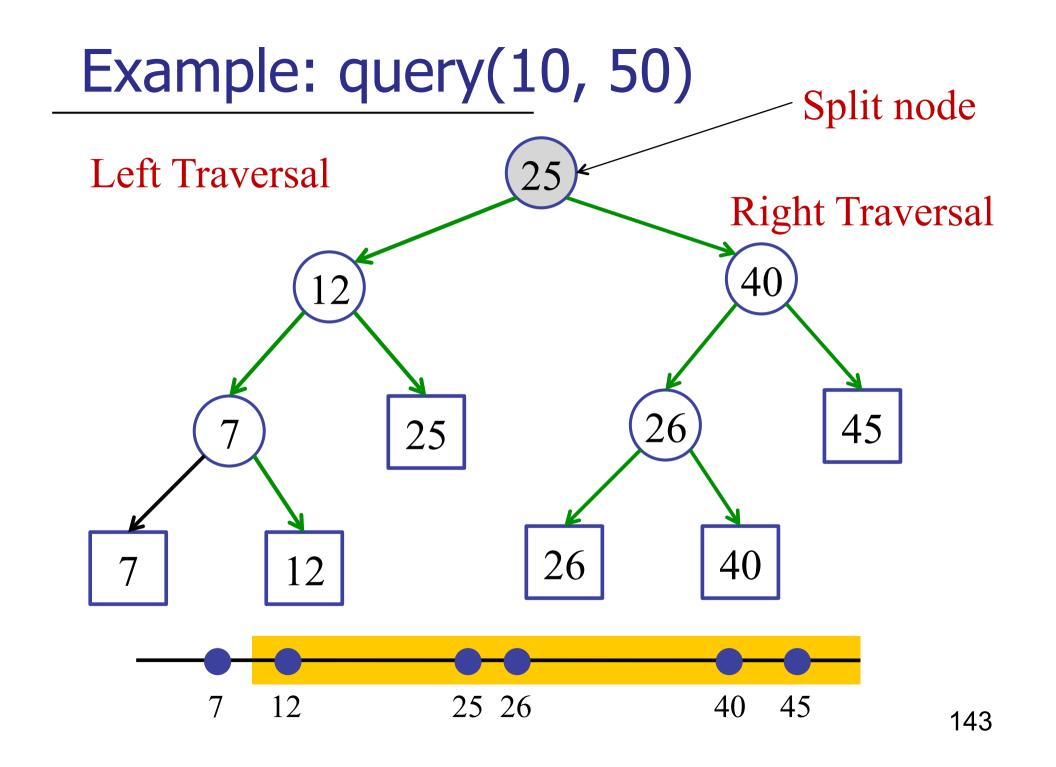


## Example: query(10, 50)

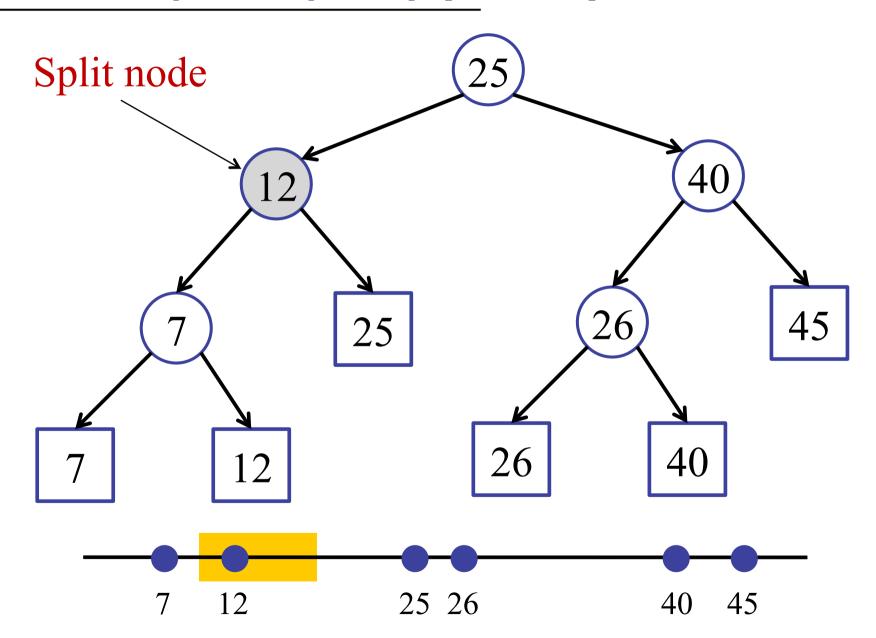


## Example: query(10, 50)

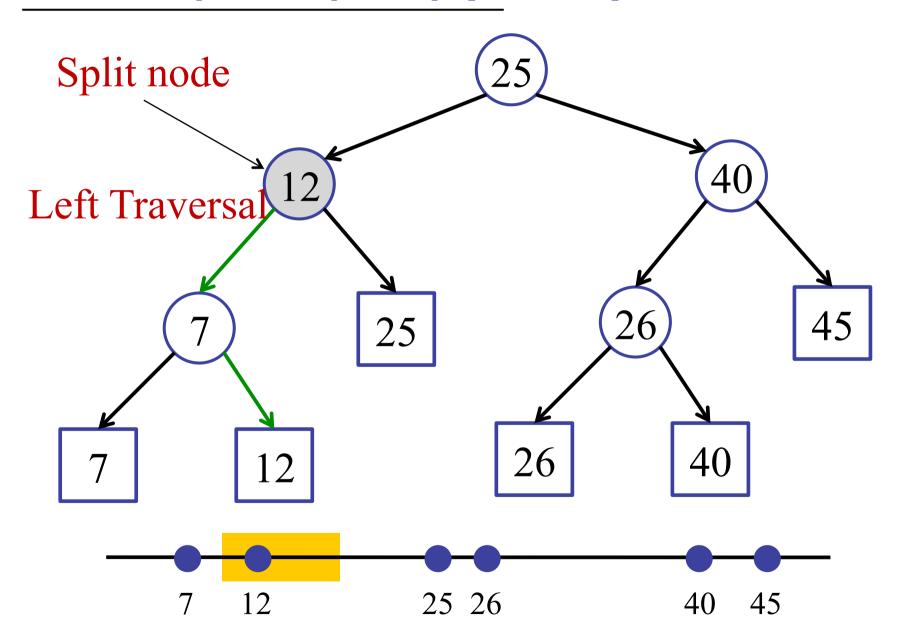




## Example: query(8, 20)



# Example: query(8, 20)

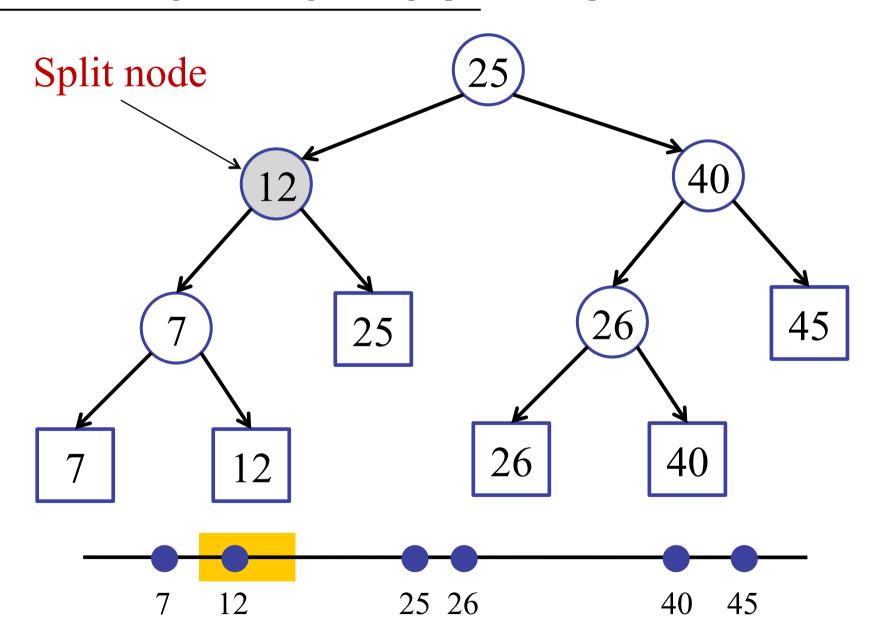


#### Algorithm:

- Find "split" node.
- Do left traversal.
- Do right traversal.

```
FindSplit(low, high)
     v = root;
     done = false;
     while !done {
            if (high <= v.key) then v=v.left;
            else if (low > v.key) then v=v.right;
            else (done = true);
     return v;
```

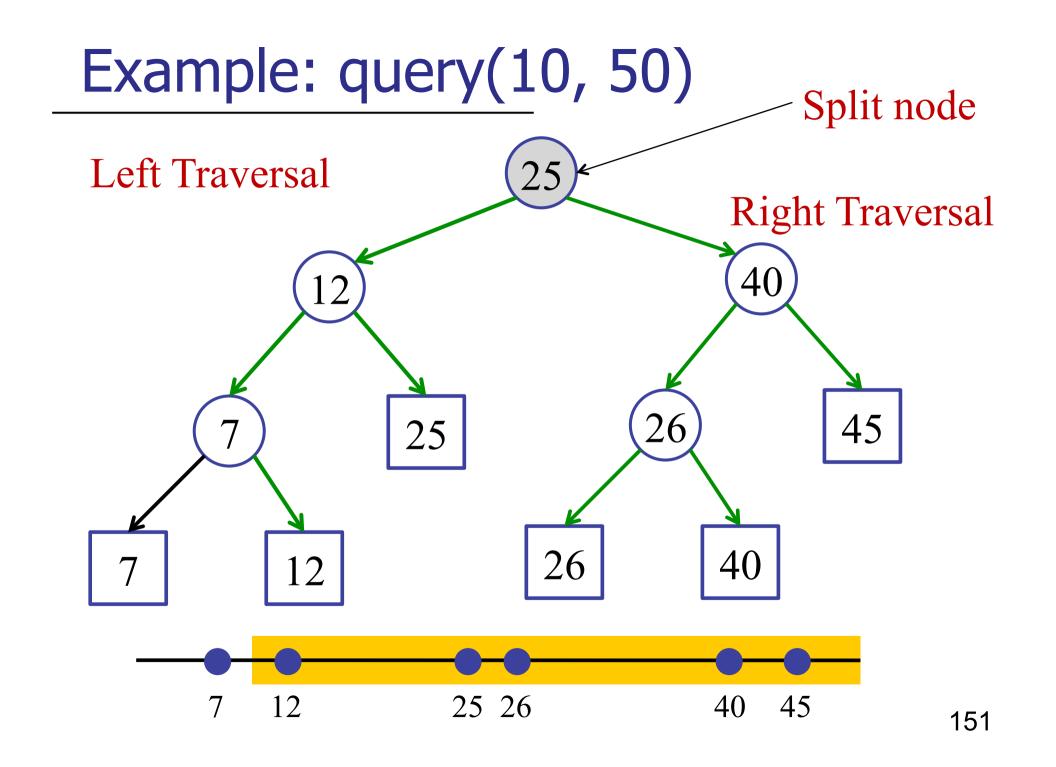
# Example: query(8, 20)



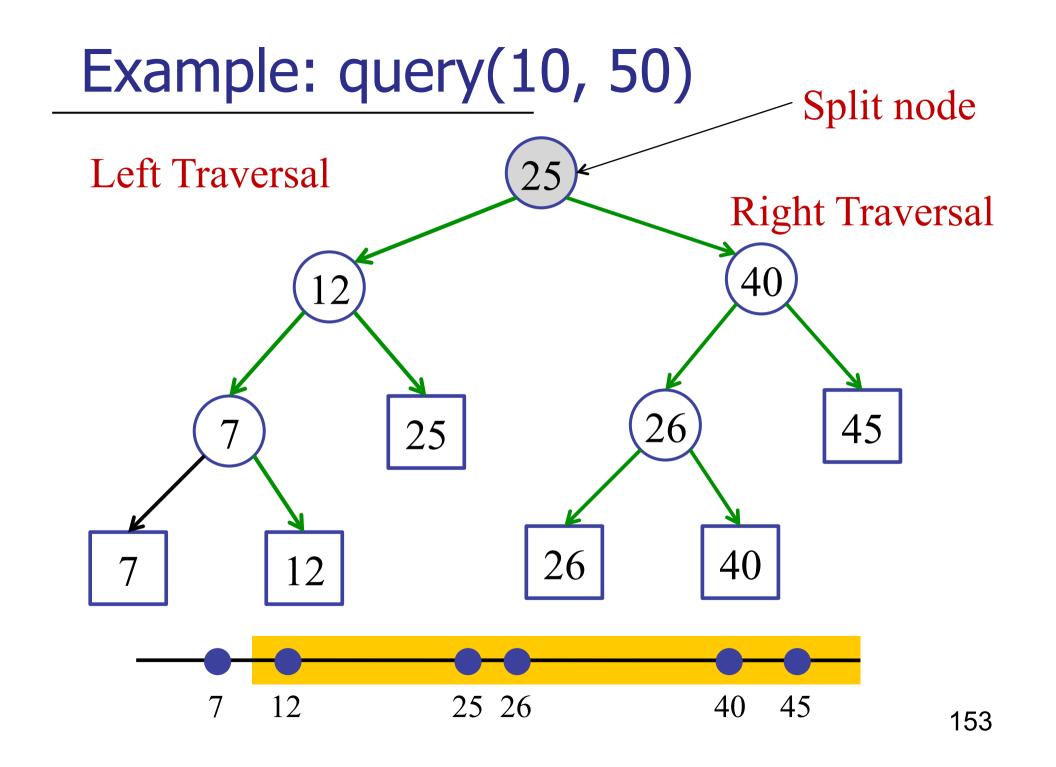
#### Algorithm:

- v = FindSplit(low, high);
- LeftTraversal(v, low, high);
- RightTraversal(v, low, high);

```
LeftTraversal(v, low, high)
     if (low <= v.key) {
           all-leaf-traversal(v.right);
           LeftTraversal(v.left, low, high);
     else {
           LeftTraversal(v.right, low, high);
```



```
RightTraversal(v, low, high)
     if (v.key <= high) {
           all-leaf-traverasal(v.left);
           RightTraversal(v.right, low, high);
     else {
           RightTraversal(v.left, low, high);
```



#### Query time:

- Finding split node: O(log n)
- Left Traversal:

At every step, we either:

- 1. Output all right sub-tree and recurse left.
- 2. Recurse right.
- Right Traversal:

At every step, we either:

- 1. Output all left sub-tree and recurse right.
- 2. Recurse left.

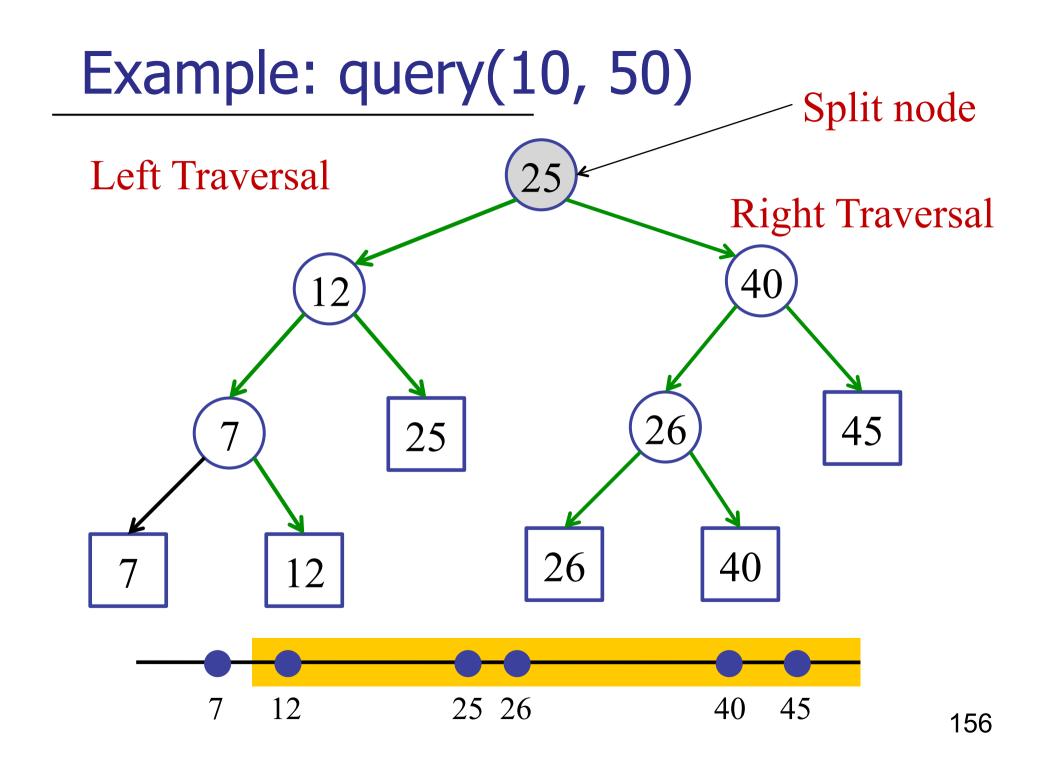
#### – Left Traversal:

At every step, we either:

- 1. Output all right sub-tree and recurse left.
- 2. Recurse right.

#### – Counting:

- 1. Recurse at most O(log n) times.
- 2. How expensive is "output all sub-tree"?



#### – Left Traversal:

At every step, we either:

- 1. Output all right sub-tree and recurse left.
- 2. Recurse right.

#### – Counting:

- 1. Recurse at most O(log n) times.
- 2. "Output all sub-tree" costs O(k).

Query time complexity:

$$O(k + \log n)$$

where k is the number of points output.

Preprocessing (buildtree) time complexity:

 $O(n \log n)$ 

Total space complexity:

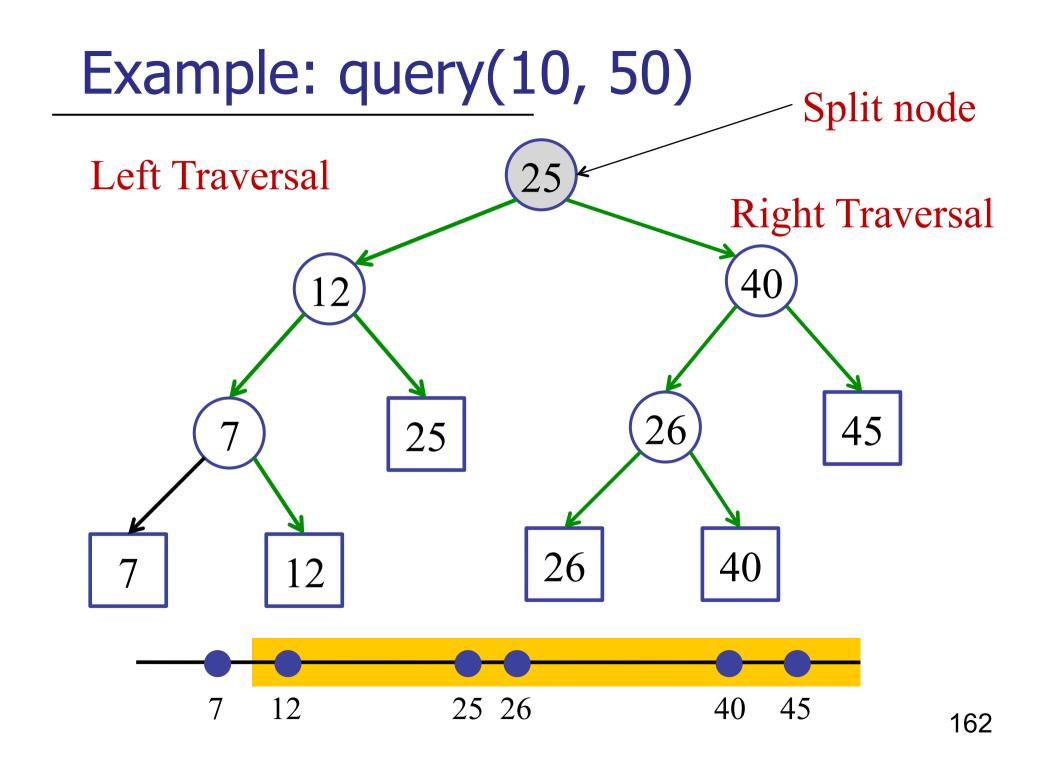
O(n)

What if you just want to know *how many* points are in the range?

What if you just want to know *how many* points are in the range?

- Augment the tree!
- Keep a count of the number of nodes in each sub-tree.
- Instead of walking entire sub-tree, just remember the count.

```
LeftTraversal(v, low, high)
     if (low <= v.key) {
           all-leaf-traversal(v.right);
           total += v.right.count;
           LeftTraversal(v.left, low, high);
     else {
           LeftTraversal(v.right, low, high);
```

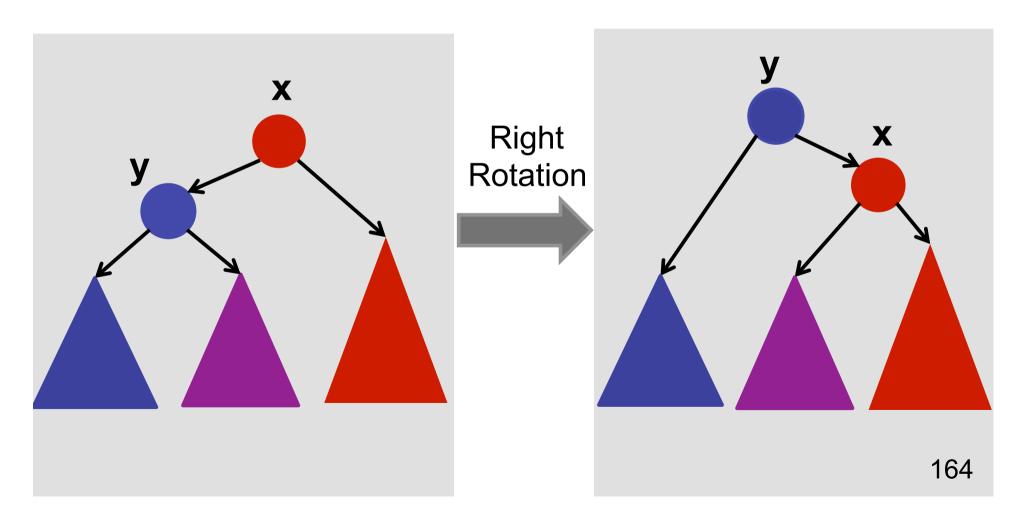


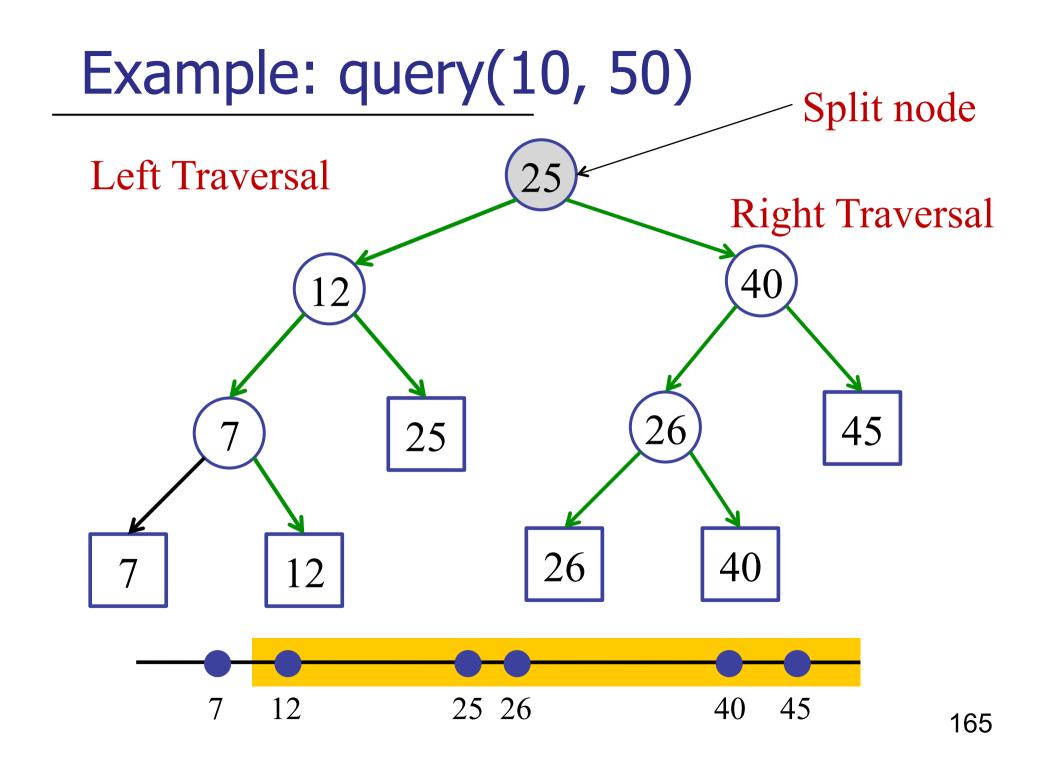
# 1D Range Tree

Done??

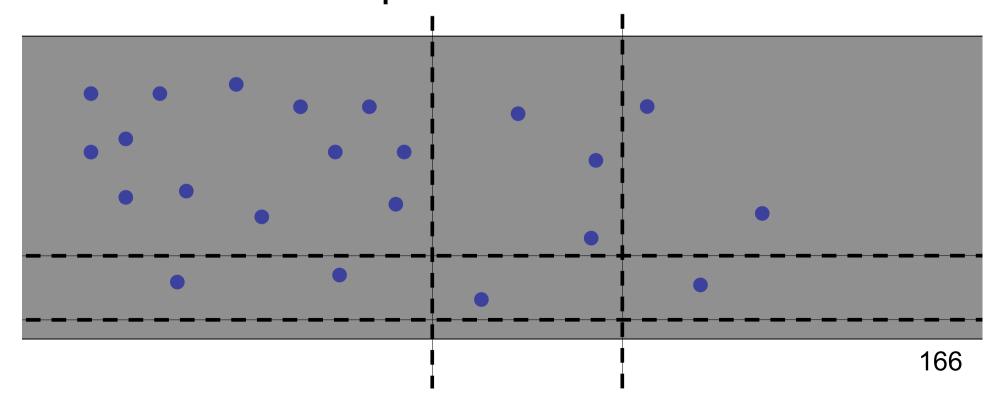
What about dynamic updates?

– Need to verify rotations!



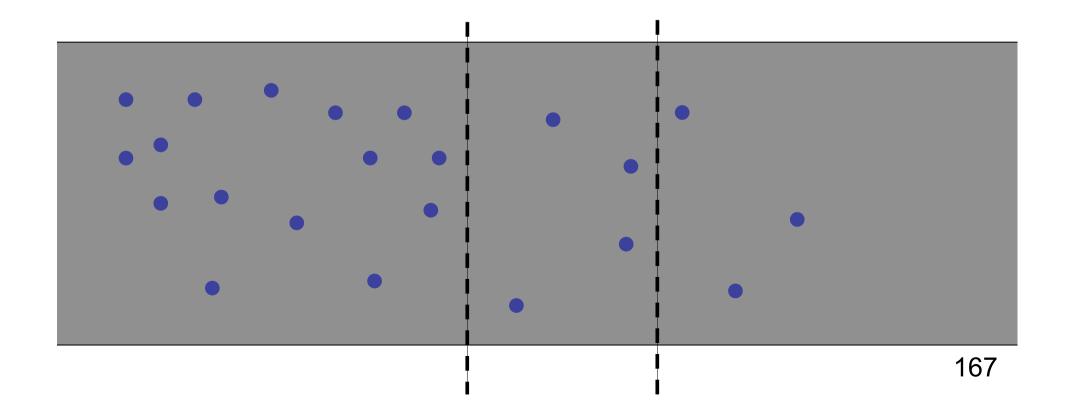


Ex: search for all points between dashed lines.

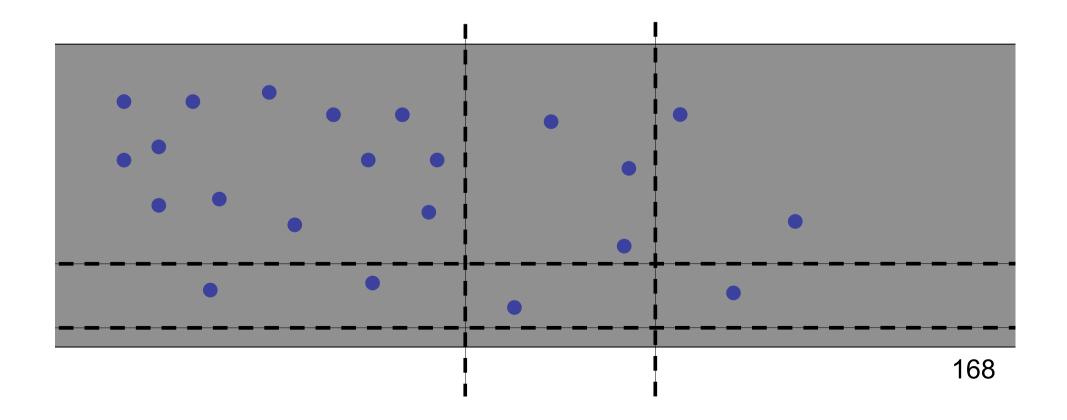


#### Step 1:

Create a range-tree on the x-coords.



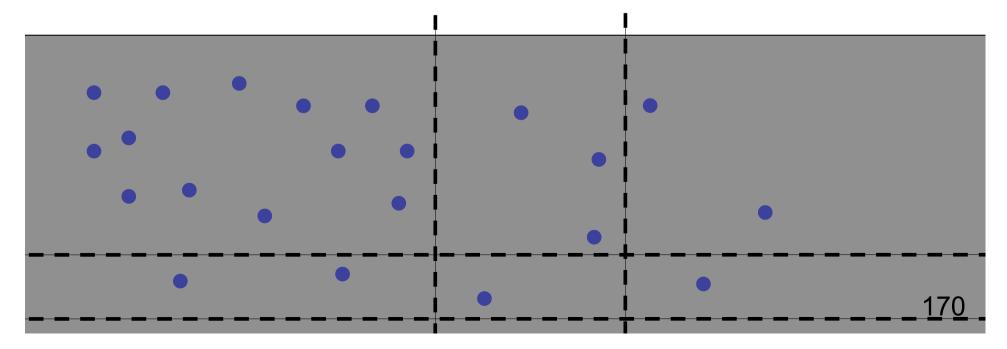
**Problem**: can't enumerate entire sub-trees, since there may be too many nodes that don't satisfy the y-restriction.



```
LeftTraversal(v, low, high)
  if (v.key >= low) {
        all-leaf-traversal(v.right);
        LeftTraversal(v.left, low, high);
  else {
        LeftTraversal(v.right, low, high);
```

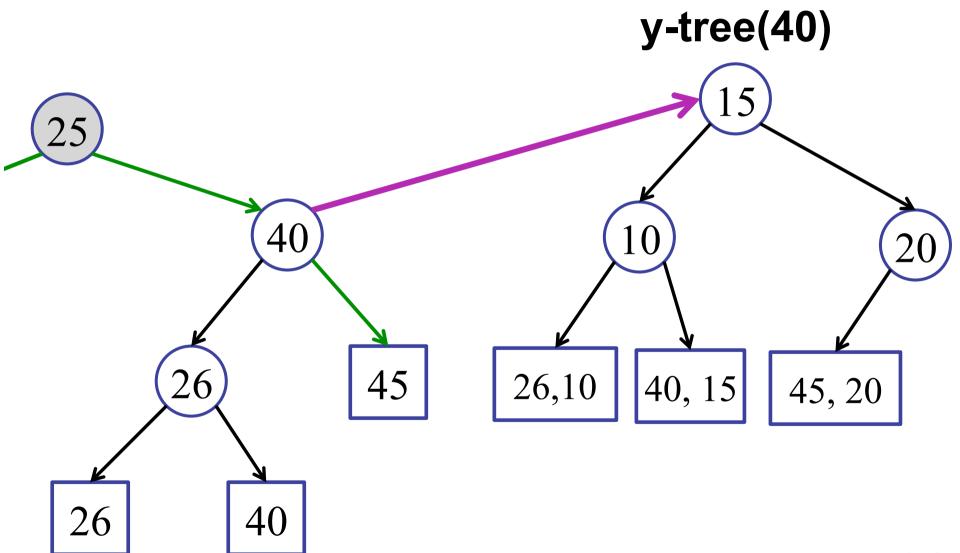
#### **Solution**: Augment!

- Each node in the x-tree has a set of points in its sub-tree.
- Store a y-tree at each x-node containing all the points in the sub-tree.



```
LeftTraversal(v, low, high)
  if (v.key.x >= low.x) {
        ytree.search(low.y, highy);
        LeftTraversal(v.left, low, high);
  else {
        LeftTraversal(v.right, low, high);
```

# Example:



Query time:  $O(log^2n + k)$ 

- O(log n) to find split node.
- O(log n) recurse steps
- O(log n) y-tree-searches of cost O(log n)
- O(k) enumerating output

#### Space complexity: O(n log n)

- Each point appears in at most one y-tree per level.
- There are at O(log n) levels.
- The rest of the x-tree takes O(n) space.

Building the tree: O(n log n)

- Tricky...
- − Left as a puzzle... ☺

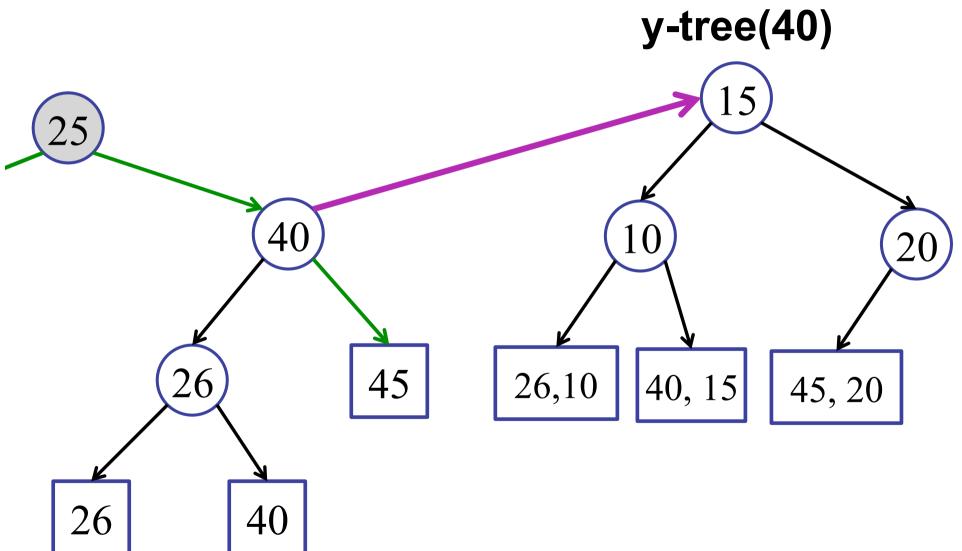
NB Challenge of the Day

#### **Dynamic Trees**

#### What about inserting/deleting nodes?

- Hard!
- How do you do rotations?
- Every rotation you may have to entirely rebuild the y-trees for the rotated nodes.
- Cost of rotate: O(n) !!!!

# Example:



#### d-dimensional

# What if you want high-dimensional range queries?

- Query cost: O(log<sup>d</sup>n + k)
- buildTree cost: O(n log<sup>d-1</sup>n)
- Space: O(n log<sup>d-1</sup>n)

#### Idea:

- Store d–1 dimensional range-tree in each node of a 1D range-tree.
- Construct the d–1-dimeionsal range-tree recursively.

#### **Curse of Dimensionality**

# What if you want high-dimensional range queries?

- Query cost: O(logdn + k)
- buildTree cost: O(n log<sup>d-1</sup>n)
- Space: O(n log<sup>d-1</sup>n)

#### Idea:

- Store d–1 dimensional range-tree in each node of a 1D range-tree.
- Construct the d–1-dimeionsal range-tree recursively.

# Real World (aside)

#### kd-Trees

- Alternate levels in the tree:
  - vertical
  - horizontal
  - vertical
  - horizontal
- Each level divides the points in the plane in half.

# Real World (aside)

#### kd-Trees

- Alternate levels in the tree
- Each level divides the points in the plane in half.
- Query cost:  $O(\sqrt{n})$  worst-case
  - Sometimes works better in practice for many queries.
  - Easier to update dynamically.
  - Good for other types of queries: e.g., nearestneighbor

# Today

Three examples of augmenting BSTs

1. Order Statistics

2. Intervals

3. Orthogonal Range Searching