Clustering Assignment

There will be some functions that start with the word "grader" ex: grader_actors(), grader_movies(), grader_cost1() etc, you should not change those function definition.

Every Grader function has to return True.

Please check <u>clustering assignment helper functions</u> (<u>https://drive.google.com/file/d/1V29KhKo3YnckMX32treEgdtH5r90DljU/view?usp=sharing</u>) notebook before attempting this assignment.

- Read graph from the given movie actor network.csv (note that the graph is bipartite graph.)
- Using stellergaph and gensim packages, get the dense representation(128dimensional vector) of every node in the graph. [Refer Clustering_Assignment_Reference.ipynb]
- Split the dense representation into actor nodes, movies nodes.(Write you code in def data split())

Task 1: Apply clustering algorithm to group similar actors

- 1. For this task consider only the actor nodes
- 2. Apply any clustering algorithm of your choice

Refer: https://scikit-learn.org/stable/modules/clustering.html (<a href

- 3. Choose the number of clusters for which you have maximum score of Cost1 * Cost2
- 4. Cost1 =

 $\frac{1}{N} \sum_{\text{each cluster i}} \frac{\text{(number of nodes in the largest connected component in the graph with the actor nodes and its movie r}{\text{(total number of nodes in that cluster i)}}$

where N= number of clusters

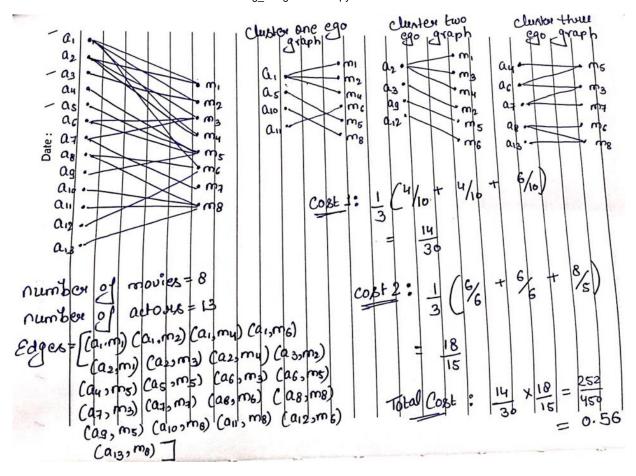
(Write your code in def cost1())

5. Cost2 =

 $\frac{1}{N} \sum_{\text{each cluster i}} \frac{\text{(sum of degress of actor nodes in the graph with the actor nodes and its movie neighbours in cluster i)}}{\text{(number of unique movie nodes in the graph with the actor nodes and its movie neighbours in cluster i)}}$ where N= number of clusters

(Write your code in def cost2())

- 6. Fit the clustering algorithm with the opimal number_of_clusters and get the cluster number for each node
- 7. Convert the d-dimensional dense vectors of nodes into 2-dimensional using dimensionality reduction techniques (preferably TSNE)
- 8. Plot the 2d scatter plot, with the node vectors after step e and give colors to nodes such that same cluster nodes will have same color



Task 2: Apply clustering algorithm to group similar movies

- 1. For this task consider only the movie nodes
- 2. Apply any clustering algorithm of your choice 3. Choose the number of clusters for which you have maximum score of Cost1*Cost2

```
Cost1 = \frac{1}{N} \sum_{\text{each cluster i}} \frac{\text{(number of nodes in the largest connected component in the graph with the movie nodes and its actor r}{\text{(total number of nodes in that cluster i)}}
where N= number of clusters
(Write your code in def cost1())

3. Cost2 = \frac{1}{N} \sum_{\text{each cluster i}} \frac{\text{(sum of degress of movie nodes in the graph with the movie nodes and its actor neighbours in cluster i)}}{\text{(number of unique actor nodes in the graph with the movie nodes and its actor neighbours in cluster i)}}
```

Algorithm for actor nodes

where N= number of clusters (Write your code in def cost2())

```
for number_of_clusters in [3, 5, 10, 30, 50, 100, 200, 500]:
    algo = clustering_algorith(clusters=number_of_clusters)
```

```
Requirement already satisfied: networkx==2.3 in c:\users\disha\anaconda3\lib\si
        te-packages (2.3)
        Requirement already satisfied: decorator>=4.3.0 in c:\users\disha\anaconda3\lib
        \site-packages (from networkx==2.3) (4.4.2)
        import networkx as nx
In [1]:
        from networkx.algorithms import bipartite
        import matplotlib.pyplot as plt
        from sklearn.cluster import KMeans
        import numpy as np
        import warnings
        warnings.filterwarnings("ignore")
        import pandas as pd
        # you need to have tensorflow
        from stellargraph.data import UniformRandomMetaPathWalk
        from stellargraph import StellarGraph
In [2]: data=pd.read_csv('movie_actor_network.csv', index_col=False, names=['movie','actor_network.csv']
In [3]: edges = [tuple(x) for x in data.values.tolist()]
In [4]: B = nx.Graph()
        B.add nodes from(data['movie'].unique(), bipartite=0, label='movie')
        B.add_nodes_from(data['actor'].unique(), bipartite=1, label='actor')
        B.add edges from(edges, label='acted')
In [5]: A = list(nx.connected component subgraphs(B))[0]
```

In [1]: !pip install networkx==2.3

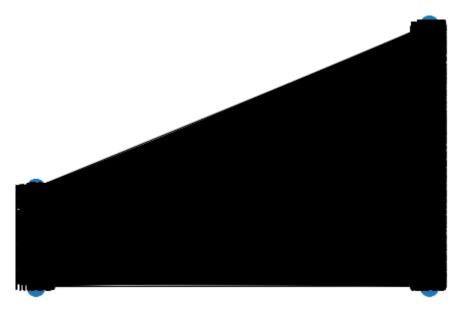
```
In [6]: print("number of nodes", A.number_of_nodes())
print("number of edges", A.number_of_edges())
```

number of nodes 4703 number of edges 9650

```
In [7]: 1, r = nx.bipartite.sets(A)
pos = {}

pos.update((node, (1, index)) for index, node in enumerate(1))
pos.update((node, (2, index)) for index, node in enumerate(r))

nx.draw(A, pos=pos, with_labels=True)
plt.show()
```



```
In [8]: movies = []
    actors = []
    for i in A.nodes():
        if 'm' in i:
            movies.append(i)
        if 'a' in i:
            actors.append(i)
    print('number of movies ', len(movies))
    print('number of actors ', len(actors))
```

number of movies 1292
number of actors 3411

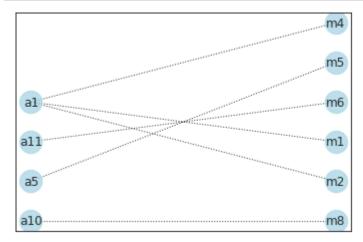
```
In [9]:
          # Create the random walker
          rw = UniformRandomMetaPathWalk(StellarGraph(A))
          # specify the metapath schemas as a list of lists of node types.
          metapaths = [
               ["movie", "actor", "movie"],
               ["actor", "movie", "actor"]
          ]
          walks = rw.run(nodes=list(A.nodes()), # root nodes
                           length=100, # maximum length of a random walk
                                         # number of random walks per root node
                           metapaths=metapaths
          print("Number of random walks: {}".format(len(walks)))
          Number of random walks: 4703
In [10]: from gensim.models import Word2Vec
          model = Word2Vec(walks, size=128, window=5)
In [11]: model.wv.vectors.shape # 128-dimensional vector for each node in the graph
Out[11]: (4703, 128)
In [12]: # Retrieve node embeddings and corresponding subjects
          node ids = model.wv.index2word # list of node IDs
          node embeddings = model.wv.vectors # numpy.ndarray of size number of nodes times
          node_targets = [ A.node[node_id]['label'] for node_id in node_ids]
           print(node ids[:15], end='')
           ['a973', 'a967', 'a964', 'a1731', 'a969', 'a970', 'a1028', 'a1057', 'a965', 'a1003', 'm1094', 'a966', 'm67', 'a988', 'm1111']
           print(node_targets[:15],end='')
           ['actor', 'actor', 'actor', 'actor', 'actor', 'actor', 'actor', 'actor', 'actor', 'movie', 'actor', 'movie', 'actor', 'movie']
```

```
In [13]: import re
                         def data split(node ids,node targets,node embeddings):
                                     '''In this function, we will split the node embeddings into actor embeddings
                                    actor nodes, movie nodes=[],[]
                                    actor embeddings, movie embeddings=[],[]
                                    # split the node_embeddings into actor_embeddings,movie_embeddings based on r
                                    # By using node embedding and node targets, we can extract actor embedding ar
                                    # By using node ids and node targets, we can extract actor nodes and movie no
                                    i = 0
                                    while i < len(node ids):</pre>
                                               if re.search('^a',node_ids[i]):
                                                          actor_nodes.append(node_ids[i])
                                                          actor embeddings.append(node embeddings[i])
                                               else:
                                                          movie_nodes.append(node_ids[i])
                                                         movie embeddings.append(node embeddings[i])
                                               i = i + 1
                                    return actor nodes, movie nodes, actor embeddings, movie embeddings
In [14]: actor nodes, movie nodes, actor embeddings, movie embeddings = data split(node ids, nodes, nodes, movie nodes, mo
                          Grader function - 1
In [15]: def grader actors(data):
                                    assert(len(data)==3411)
                                    return True
                         grader_actors(actor_nodes)
Out[15]: True
                         Grader function - 2
In [16]: def grader movies(data):
                                    assert(len(data)==1292)
                                    return True
                         grader movies(movie nodes)
Out[16]: True
                         Calculating cost1
                         Cost1 =
                                                               (number of nodes in the largest connected component in the graph with the actor nodes and its movie neighb
                           rac{1}{N} \sum_{	ext{each cluster i}}
                                                                                                                                      (total number of nodes in that cluster i)
                          where N= number of clusters
```

```
In [55]:

def cost1(graph,number_of_clusters):
    '''In this function, we will calculate cost1'''
    nodes = graph.nodes
    a = nx.connected_components(graph)
    maximum = max([len(i) for i in a])
    cost1 = (1/number_of_clusters)*((maximum)/graph.number_of_nodes())
    return cost1
```

```
In [56]: import networkx as nx
    from networkx.algorithms import bipartite
    graded_graph= nx.Graph()
    graded_graph.add_nodes_from(['a1','a5','a10','a11'], bipartite=0) # Add the node
    graded_graph.add_nodes_from(['m1','m2','m4','m6','m5','m8'], bipartite=1)
    graded_graph.add_edges_from([('a1','m1'),('a1','m2'),('a1','m4'),('a11','m6'),('a1','a5','a10','a11');r={'m1','m2','m4','m6','m5','m8'}
    pos = {}
    pos.update((node, (1, index)) for index, node in enumerate(1))
    pos.update((node, (2, index)) for index, node in enumerate(r))
    nx.draw_networkx(graded_graph, pos=pos, with_labels=True,node_color='lightblue',a
```



Grader function - 3

```
In [57]: graded_cost1=cost1(graded_graph,3)
    def grader_cost1(data):
        assert(data==((1/3)*(4/10))) # 1/3 is number of clusters
        return True
    grader_cost1(graded_cost1)
```

Out[57]: True

Calculating cost2

```
Cost2 =
```

 $\frac{1}{N} \sum_{\text{each cluster i}} \frac{\text{(sum of degress of actor nodes in the graph with the actor nodes and its movie neighbours in cluster i)}}{\text{(number of unique movie nodes in the graph with the actor nodes and its movie neighbours in cluster i)}}$ where N= number of clusters

```
In [58]: def cost2(graph,number_of_clusters):
    '''In this function, we will calculate cost1'''
    nodes = graph.nodes
    top_nodes = {n for n, d in list(graph.nodes(data=True)) if d["bipartite"] ==
    bottom_nodes = nodes - top_nodes
    degree = 0
    for i in top_nodes:
        degree = degree + graph.degree[i]
    cost2= (1/number_of_clusters) * (degree/len(bottom_nodes))
    return cost2
```

Grader function - 4

```
In [59]: graded_cost2=cost2(graded_graph,3)
    def grader_cost2(data):
        assert(data==((1/3)*(6/6))) # 1/3 is number of clusters
        return True
    grader_cost2(graded_cost2)
```

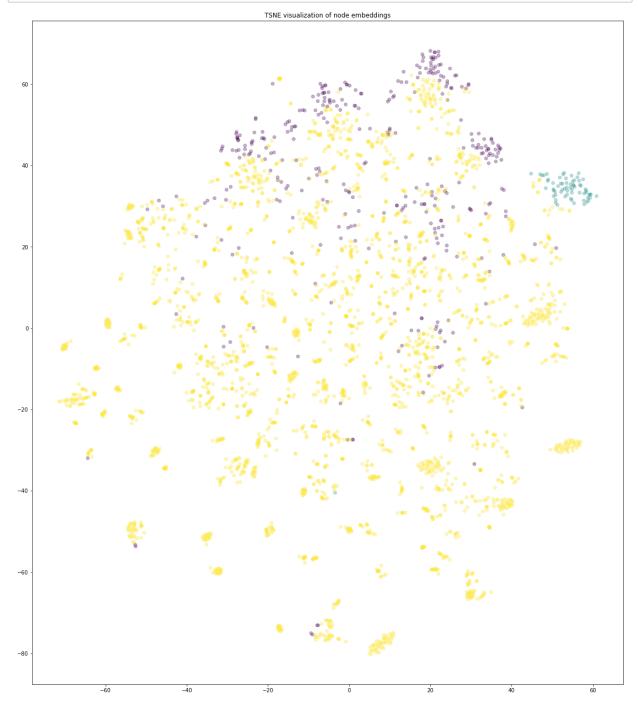
Out[59]: True

Grouping similar actors

```
In [60]: K = [3, 5, 10, 30, 50, 100, 200, 500]
         cost = []
         c = dict()
         for k in [3, 5, 10, 30, 50, 100, 200, 500]:
             kmeans = KMeans(n clusters=k, random state=0).fit(actor embeddings)
             labels = kmeans.labels_
             d = dict()
             for i in range(len(actor_nodes)):
                  d[actor nodes[i]] = labels[i]
             clusters = []
             for i in range(k):
                  e = [k1 for k1, v in d.items() if v == i]
                 clusters.append(e)
             graphs = []
             for i in range(k):
                 g = nx.Graph()
                 for n in clusters[i]:
                      graph = nx.ego graph(B,n)
                      g.add_nodes_from(graph.nodes,bipartite = 1)
                      g.add_edges_from(graph.edges)
                  g.add nodes from(clusters[i],bipartite = 0)
                 graphs.append(g)
             c1, c2 = 0, 0
             for i in range(k):
                 c1 = c1 + (cost1(graphs[i],k))
                 c2 = c2 + (cost2(graphs[i],k))
             cost.append((c1)*(c2))
             c[k] = c1*c2
```

```
In [61]: ind = cost.index(max(cost))
         best_k = K[ind]
In [62]: c
Out[62]: {3: 3.8863795023705694,
          5: 2.981023298207314,
          10: 2.174437913426483,
          30: 1.6117862118008819,
          50: 1.5685894889997078,
          100: 1.58875720918826,
          200: 1.7012620344490466,
          500: 1.8384617856234164}
In [63]: best_k
Out[63]: 3
In [64]: model = KMeans(n_clusters=best_k, random_state=0).fit(actor_embeddings)
         label = model.labels_
In [65]: | from sklearn.manifold import TSNE
         transform = TSNE
         trans = transform(n_components=2)
         node_embeddings_2d = trans.fit_transform(actor_embeddings)
In [66]: label
Out[66]: array([1, 1, 1, ..., 2, 2, 2])
In [ ]:
```

Displaying similar actor clusters



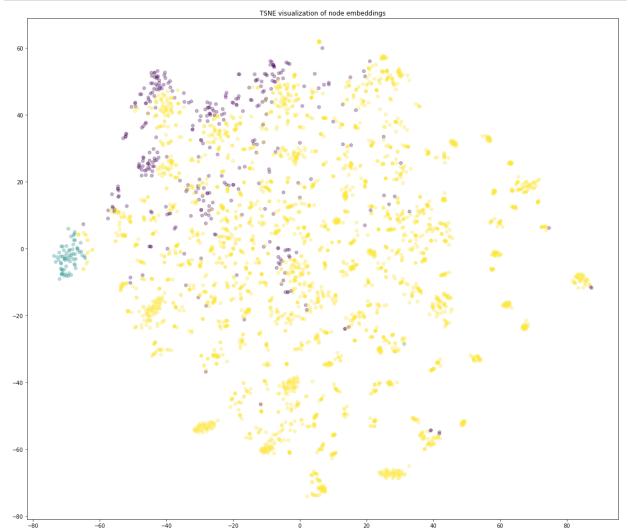
Grouping similar movies

```
In [68]: K = [3, 5, 10, 30, 50, 100, 200, 500]
         cost = []
         c = dict()
         for k in [3, 5, 10, 30, 50, 100, 200, 500]:
             kmeans = KMeans(n clusters=k, random state=0).fit(movie embeddings)
             labels = kmeans.labels_
             d = dict()
             for i in range(len(movie_nodes)):
                  d[movie_nodes[i]] = labels[i]
             clusters = []
             for i in range(k):
                 e = [k1 for k1,v in d.items() if v == i]
                 clusters.append(e)
             graphs = []
             for i in range(k):
                 g = nx.Graph()
                 for n in clusters[i]:
                     graph = nx.ego_graph(B,n)
                      g.add_nodes_from(graph.nodes,bipartite = 1)
                     g.add_edges_from(graph.edges)
                 g.add_nodes_from(clusters[i],bipartite = 0)
                 graphs.append(g)
             c1, c2 = 0, 0
             for i in range(k):
                 c1 = c1 + cost1(graphs[i],k)
                 c2 = c2 + cost2(graphs[i],k)
             cost.append(c1*c2)
             c[k] = c1*c2
```

```
In [69]: ind = cost.index(max(cost))
best_k = K[ind]
```

```
In [70]: best_k
Out[70]: 3
In [71]: c
Out[71]: {3: 2.8352802150560197,
          5: 2.5293719381225657,
          10: 2.7623660667986893,
          30: 2.099404388318737,
          50: 1.8586471995041023,
          100: 1.5901069039311393,
          200: 1.3676762184723799,
          500: 1.2116205928020927}
In [72]: from sklearn.manifold import TSNE
         transform = TSNE
         trans = transform(n_components=2)
         node_embeddings_2d = trans.fit_transform(actor_embeddings)
 In [ ]:
In [ ]:
```

Displaying similar movie clusters



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References

reference notebook that was given

https://networkx.org/documentation/stable/tutorial.html (https://networkx.org/documentation/stable/tutorial.html)

In []: