Screenshots:

how can i tokenize a string based on 2 delimiters while also knowing which delimiter each string ended with in C



To tokenize a string based on two delimiters while keeping track of which delimiter was used to end each token in C, you can use a combination of functions and logic. Here's a step-by-step guide to achieve this:

- 1. **Define your delimiters**: Let's say your delimiters are `', '` and `'; '`.
- 2. **Create a function to tokenize and keep track of delimiters**: You'll need a function that processes the string and tracks which delimiter ended each token.

Here's a sample implementation in C:

```
tokens[i] = NULL; // End the array of tokens
endDelim[i] = '\0'; // End the array of delimiters

free(tempStr); // Free the duplicated string
}

int main() {
    const char *str = "token1, token2; token3, token4";
    const char *delims = ",;";
    char *tokens[100]; // Array to store tokens
    char endDelim[100]; // Array to store which delimiter ended each token

    tokenize(str, delims, tokens, endDelim);

// Print tokens and their ending delimiters
for (int i = 0; tokens[i] != NULL; i++) {
    printf("Token: %s, Ended with delimiter: %c\n", tokens[i], endDelim[i]);
    free(tokens[i]); // Free the allocated memory for each token
}

return 0;
}
```

- 1. `strdup`: This duplicates the original string so that you can use `strtok` without modifying the original string.
- 2. `strtok`: This function splits the string into tokens based on delimiters. It modifies the string in place by inserting null characters where delimiters are found.
- 3. Tracking End Delimiters:
 - After extracting a token, you need to determine which delimiter was next in the original string.

- The `endDelim` array is used to store the delimiter that follows each token. The
 condition `(strchr(delims, str[strlen(token) + (token tempStr)]) != NULL)`
 checks if the character at the end of the token is one of the delimiters. If so, it assigns it
 to `endDelim`.
- 4. **Memory Management**: Make sure to `free` any dynamically allocated memory to prevent memory leaks.

This method ensures that you can handle multiple delimiters and keep track of which delimiter ended each token.

put the funciton in the main body directly



Sure, here's how you can include the `tokenize` function directly in the `main` function body:

```
#include <stdio.h>
#include <string.h>
#include <stdlib.h>

int main() {
    const char *str = "token1, token2; token3, token4";
    const char *delims = ",;";
    char *tokens[100]; // Array to store tokens
    char endDelim[100]; // Array to store which delimiter ended each token

    char *tempStr = strdup(str); // Duplicate the string to avoid modifying the ori char *token;
    int i = 0;
```

```
token = strtok(tempStr, delims); // Get the first token
while (token != NULL) {
    tokens[i] = strdup(token); // Save the token
    size_t tokenLen = strlen(token);
    size_t offset = token - tempStr + tokenLen;
    if (str[offset] != '\0' && strchr(delims, str[offset]) != NULL) {
        endDelim[i] = str[offset];
        endDelim[i] = '\0'; // No delimiter at the end of the token
    token = strtok(NULL, delims); // Get the next token
tokens[i] = NULL; // End the array of tokens
endDelim[i] = '\0'; // End the array of delimiters
for (int j = 0; tokens[j] != NULL; j++) {
    printf("Token: %s, Ended with delimiter: %c\n", tokens[j], endDelim[j]);
    free(tokens[j]); // Free the allocated memory for each token
free(tempStr); // Free the duplicated string
```

 String Duplication: The `tempStr` is a duplicate of the original string to be used with `strtok`.

2. Tokenization and Delimiter Tracking:

- `strtok` is used to split the string based on the delimiters.
- After each token is extracted, the code calculates the position of the next character to determine if it's a delimiter and records it in the `endDelim` array.

3. Memory Management:

 After processing, remember to `free` any dynamically allocated memory (both for tokens and the duplicated string).

This code ensures that each token is properly split and you can track which delimiter ended each token.

```
char input[4096];
     // TODO: error message formatting here too
     if (fgets(input, sizeof(input), stdin) == NULL) {
       printf("Failed to input");
       continue;
     // Tokenising
     input[strcspn(input, "\n")] = '\0'; // null-terminate input string
if newline character is present
     /**char *token;
     char *remainingString = input;
     while ((token = strtok_r(remainingString, ";&",
&remainingString))) {
       while (*token == ' ' || *token == '\t') token++;
       for (int i = strlen(token) - 1; i >= 0 && (token[i] == ' ' || token[i]
== '\t'); i--) {
         token[i] = '\0';
       int background_flag = (remainingString &&
(remainingString[0] == '&'));
       printf("%s %d\n", token, background_flag);
     }**/
using this same logic, can you help tokenize for my shell based on &
and; ? commands with an & at the end should have
background_flag 1, those with ; at the end should have background
flag 0. if no delimiter, background flag 0 also
```

®

Certainly! To tokenize the input based on the delimiters `&` and `;`, and determine whether each command should run in the background or foreground, you can use `strtok_r` to handle tokenization and process the delimiters accordingly.

Here's how you can integrate this into your existing code. The code will tokenize the input based on `&` and `;`, and set the `background_flag` based on the presence of these delimiters:

```
#include <stdio.h>
#include <string.h>
#include <stdlib.h>

// Stub functions for the sake of example
int configure() {
    // Simulate configuration process
    return 0; // Indicate success
}

int prompt() {
    // Simulate prompting user
    return 0; // Indicate success
}

int main() {
    // Initial setup
    int config_status = 1; // Set to not done at start
    do {
        config_status = configure();
    } while (config_status != 0);
```

```
config_status = prompt();
if (config_status != 0) continue; // Re-try prompt without taking user inpu
char input[4096];
if (fgets(input, sizeof(input), stdin) == NULL) {
input[strcspn(input, "\n")] = '\0'; // Null-terminate input string if newli
char *token;
char *remainingString = input;
while ((token = strtok_r(remainingString, ";&", &remainingString))) {
   while (*token == ' ' || *token == '\t') token++;
   char *end = token + strlen(token) - 1;
    while (end > token && (*end == ' ' || *end == '\t')) end--;
    *(end + 1) = '\0'; // Null-terminate trimmed string
    int background_flag = 0;
    if (remainingString && remainingString[0] == '&') {
        background_flag = 1;
        remainingString++; // Skip over the '&'
    } else if (remainingString && remainingString[0] == ';') {
        remainingString++; // Skip over the ';'
    // Print the token and it \sqrt{\text{ackground flag}}
    printf("Token: '%s', Background Flag: %d\n", token, background_flag);
```

Command to change cwd into a different one based on input string



To change the current working directory (cwd) in a C program based on an input string, you can use the `chdir` function from the `unistd.h` library. Here's an example demonstrating how to achieve this:

```
#include <stdio.h>
#include <unistd.h>

int main() {
   char newDirectory[256];

   // Prompt user for the new directory
   printf("Enter the path to the new directory: ");
   scanf("%255s", newDirectory);

   // Change the current working directory
   if (chdir(newDirectory) == 0) {
       printf("Successfully changed to directory: %s\n", newDirectory);
   } else {
       perror("chdir failed");
   }

   return 0;
}
```

Explanation

1. Include Necessary Header:



1. Include Necessary Header:

`stdio.h` is included for input/output functions, and `unistd.h` is included for the `chdir` function.

2. Define and Read Input String:

This block of code prompts the user to enter the path to the new directory and reads the input into the `newDirectory` array. The size `255` ensures that the input is safely stored in the array, leaving space for the null terminator.

3. Change the Current Working Directory:

```
if (chdir(newDirectory) == 0) {
    printf("Successfully changed to directory: %s\n", newDirectory);
} else {
    perror("chdir failed");
}
```

The "abdis" function attempts to change the current working directory to the nath specified

The `chdir` function attempts to change the current working directory to the path specified by `newDirectory`. If successful, it returns `0`, and the program prints a success message. If it fails (returns `-1`), `perror` is used to print an error message indicating why the operation failed.

Notes

- Ensure that the path provided is valid and that your program has the necessary permissions
 to change to the specified directory.
- The `chdir` function affects the current working directory of the running process, but this
 change does not persist after the program exits or affect the shell from which the program
 was run.

How can I print file info similar to bash with I flag



To print file information in a manner similar to the `ls -l` command in bash, you can use the `stat` structure and related functions available in the `sys/stat.h` library in C. The `ls -l` command typically shows details like file type, permissions, number of links, owner, group, size, and modification time.

Here's an example program that mimics the `ls -l` command:

```
#include <stdio.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <unistd.h>
#include <pwd.h>
#include <grp.h>
#include <time.h>
```

```
void printFileInfo(const char *filename) {
    char timebuf[80];
    if (stat(filename, &fileStat) < 0) {</pre>
        perror("stat");
    printf((S_ISDIR(fileStat.st_mode)) ? "d" : "-");
    printf((fileStat.st_mode & S_IRUSR) ? "r" : "-");
    printf((fileStat.st_mode & S_IWUSR) ? "w" : "-");
    printf((fileStat.st_mode & S_IXUSR) ? "x" : "-");
    printf((fileStat.st_mode & S_IRGRP) ? "r" : "-");
    printf((fileStat.st_mode & S_IWGRP) ? "w" : "-");
    printf((fileStat.st_mode & S_IXGRP) ? "x" : "-");
    printf((fileStat.st_mode & S_IROTH) ? "r" : "-");
    printf((fileStat.st_mode & S_IWOTH) ? "w" : "-");
    printf((fileStat.st_mode & S_IXOTH) ? "x" : "-");
    printf(" ");
    printf("%ld ", (long)fileStat.st_nlink);
    pw = getpwuid(fileStat.st_uid);
    printf("%s ", pw ? pw->pw_name : "UNKNOWN");
    gr = getgrgid(fileStat.st_gid);
    printf("%s ", gr ? gr->gr_name : \interms KNOWN");
```

```
// File size
printf("%5lld ", (long long)fileStat.st_size);

// Last modification time
strftime(timebuf, sizeof(timebuf), "%b %d %H:%M", localtime(&fileStat.st_mtime)
printf("%s ", timebuf);

// File name
printf("%s\n", filename);
}

int main(int argc, char *argv[]) {
  if (argc != 2) {
    fprintf(stderr, "Usage: %s <filename>\n", argv[0]);
    return 1;
  }

printFileInfo(argv[1]);

return 0;
}
```

1. Include Necessary Headers:

```
#include <stdio.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <unistd.h>
#include <pwd.h>
#include <grp.h>
#include <grp.h>
#include <grp.h>
```

#include <time.n>

These headers provide the necessary functions and structures for file information, user and group information, and time formatting.

2. Get File Status:

```
struct stat fileStat;
if (stat(filename, &fileStat) < 0) {
    perror("stat");
    return;
}</pre>
```

The `stat` function retrieves information about the file specified by `filename`.

3. Print File Type and Permissions:

```
printf((S_ISDIR(fileStat.st_mode)) ? "d" : "-");
printf((fileStat.st_mode & S_IRUSR) ? "r" : "-");
printf((fileStat.st_mode & S_IRUSR) ? "w" : "-");
printf((fileStat.st_mode & S_IXUSR) ? "x" : "-");
printf((fileStat.st_mode & S_IXUSR) ? "x" : "-");
printf((fileStat.st_mode & S_IRGRP) ? "r" : "-");
printf((fileStat.st_mode & S_IXGRP) ? "x" : "-");
printf((fileStat.st_mode & S_IXGRP) ? "x" : "-");
printf((fileStat.st_mode & S_IROTH) ? "r" : "-");
printf((fileStat.st_mode & S_IWOTH) ? "w" : "-");
printf((fileStat.st_mode & S_IXOTH) ? "x" : "-");
```

This series of conditional statements prints the file type and permissions in a format similar to `ls -l`.

4. Print Number of Links, Owner, Group, and 4 Size:

4. Print Number of Links, Owner, Group, and File Size:

```
c
printf("%ld ", (long)fileStat.st_nlink);
struct passwd *pw = getpwuid(fileStat.st_uid);
printf("%s ", pw ? pw->pw_name : "UNKNOWN");
struct group *gr = getgrgid(fileStat.st_gid);
printf("%s ", gr ? gr->gr_name : "UNKNOWN");
printf("%5lld ", (long long)fileStat.st_size);
```

These lines print the number of links, owner name, group name, and file size.

5. Print Last Modification Time:

The `strftime` function formats the modification time in a readable format.

6. Print File Name:

Finally, the filename is printed.

7. Main Function:

```
c
int main(int argc, char *argv[]) {

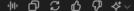
int main(int argc, char *argv[]) {
```

7. Main Function:

```
int main(int argc, char *argv[]) {
   if (argc != 2) {
      fprintf(stderr, "Usage: %s <filename>\n", argv[0]);
      return 1;
   }
   printFileInfo(argv[1]);
   return 0;
}
```

The main function checks for the correct number of arguments and calls `printFileInfo` with the specified filename.

This program provides a detailed output similar to the `ls -l` command in bash, showing file permissions, number of links, owner, group, size, last modification time, and filename.



how can i check if a process i invoked with a fork and execvp has terminated successsfully or failed

To check if a process invoked with `fork` and `execvp` has terminated successfully or failed, you can use the `waitpid` function to wait for the child process to finish and then inspect its exit status. Here is a sample program that demonstrates this:

```
🖒 Copy code
void executeCommand(char *command, char *args[]) {
   pid_t pid = fork();
    if (pid < 0) {</pre>
        perror("fork failed");
        exit(EXIT_FAILURE);
    } else if (pid == 0) {
        if (execvp(command, args) < 0) {</pre>
            perror("execvp failed");
            exit(EXIT_FAILURE);
    } else {
        // Parent process
        int status;
        if (waitpid(pid, &status, 0) < 0) {</pre>
            perror("waitpid failed");
            exit(EXIT_FAILURE);
```

```
exit(EXIT_FAILURE);
}

if (WIFEXITED(status)) {
    int exitStatus = WEXITSTATUS(status);
    if (exitStatus == 0) {
        printf("Child process terminated successfully with status %d\n", ex
    } else {
        printf("Child process terminated with failure status %d\n", exitSta
    }
} else if (WIFSIGNALED(status)) {
    int termSignal = WTERMSIG(status);
    printf("Child process terminated by signal %d\n", termSignal);
} else {
    printf("Child process terminated abnormally\n");
}
}

int main() {
    char *command = "ls";
    char *args[] = (command, "-l", "/nonexistent_directory", NULL);
    executeCommand(command, args);

return 0;
}
```

1. Include Necessary Headers:

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/types.h>
#include <sys/wait.h>
```

These headers provide the necessary functions and structures for process control, error handling, and input/output.

2. Forking and Executing the Command:

```
pid_t pid = fork();
if (pid < 0) {
    perror("fork failed");
    exit(EXIT_FAILURE);
} else if (pid == 0) {
    if (execvp(command, args) < 0) {
        perror("execvp failed");
        exit(EXIT_FAILURE);
    }
}</pre>
```

The `fork` function creates a new child process. In the child process (when `pid == 0`), `execvp` is used to replace the current process image with a new process image specified by `command` and `args`.

3. Waiting for the Child Process to Terminate:

```
c
int status;
if (waitpid(pid, &status, 0) < 0) {
   perror("waitpid failed");
   exit(EXIT_FAILURE);
}</pre>
```

The `waitpid` function waits for the child process to change state. It returns the termination status of the child process in the `status` variable.

4. Checking the Termination Status:

```
if (WIFEXITED(status)) {
   int exitStatus = WEXITSTATUS(status);
   if (exitStatus == 0) {
      printf("Child process terminated successfully with status %d\n", exitStatus);
   } else {
      printf("Child process terminated with failure status %d\n", exitStatus);
   }
} else if (WIFSIGNALED(status)) {
   int termSignal = WTERMSIG(status);
   printf("Child process terminated by signal %d\n", termSignal);
} else {
   printf("Child process terminated abnormally\n");
}
```

- `WIFEXITED(status)` checks if the child process terminated normally. If true,
 `WEXITSTATUS(status)` retrieves the exit status of the child process.
- `WIFSIGNALED(status)` checks if the child process was terminated by a signal. If true,
 `WTERMSIG(status)` retrieves the terminating signal number.

5. Main Function:

```
return 0;
}
```

The main function initializes the command and arguments, then calls `executeCommand` to fork and execute the command.

This program will print whether the child process terminated successfully, terminated with a failure status, or was terminated by a signal.

i want to track the duration processes are running. i looked up clock_monotonic online, how can i use it to track duration of a process



To track the duration a process is running using `clock_monotonic`, you can use the `clock_gettime` function. `clock_monotonic` is a clock that cannot be set and represents monotonic time since some unspecified starting point. This makes it suitable for measuring intervals.

Here's how you can use `clock_gettime` with `clock_MONOTONIC` to track the duration of a child process:

```
#include <stdio.h>
#include <stdib.h>
#include <unistd.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <time.h>

void executeCommand(char *command, ch  args[]) {

struct timespec start, end:
```

```
void executeCommand(char *command, char *args[]) {
    if (clock_gettime(CLOCK_MONOTONIC, &start) == -1) {
        perror("clock_gettime start");
        exit(EXIT_FAILURE);
   pid_t pid = fork();
   if (pid < 0) {
        perror("fork failed");
        exit(EXIT_FAILURE);
    } else if (pid == 0) {
        if (execvp(command, args) < 0) {
            perror("execvp failed");
           exit(EXIT_FAILURE);
        int status;
        if (waitpid(pid, &status, 0) < 0) {
           perror("waitpid failed");
            exit(EXIT_FAILURE);
        if (clock_gettime(CLOCK_MONOTONIC, &end) == -1) {
           perror("clock_gettime end");
            exit(EXIT_FAILURE);
                                      \downarrow
```

```
// Calculate the elapsed time
       double elapsed = (end.tv_sec - start.tv_sec) + (end.tv_nsec - start.tv_nsec
       if (WIFEXITED(status)) {
           int exitStatus = WEXITSTATUS(status);
            if (exitStatus == 0) {
               printf("Child process terminated successfully with status %d\n", ex
               printf("Child process terminated with failure status %d\n", exitSta
       } else if (WIFSIGNALED(status)) {
            int termSignal = WTERMSIG(status);
           printf("Child process terminated by signal %d\n", termSignal);
           printf("Child process terminated abnormally\n");
       printf("Elapsed time: %.6f seconds\n", elapsed);
int main() {
   char *command = "ls";
   char *args[] = {command, "-l", "/nonexistent_directory", NULL};
   executeCommand(command, args);
```

1. Include Necessary Headers:





```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <time.h>
```

These headers provide the necessary functions and structures for process control, error handling, and time measurement.

2. Get the Start Time:

```
c
struct timespec start, end;
if (clock_gettime(CLOCK_MONOTONIC, &start) == -1) {
    perror("clock_gettime start");
    exit(EXIT_FAILURE);
}
```

This uses `clock_gettime` with `CLOCK_MONOTONIC` to get the current time and stores it in the `start` variable.

3. Fork and Execute the Command:

```
pid_t pid = fork();
if (pid < 0) {
    perror("fork failed");
    exit(EXIT_FAILURE);
} else if (pid == 0) {
    if (execvp(command, args) < 0) {
        perror("execvp failed");
        exit(EXIT_FAILURE);
    }
}</pre>
```

```
}
}
```

The `fork` function creates a new child process. In the child process, `execup` is used to replace the current process image with a new process image specified by `command` and `args`.

4. Wait for the Child Process to Terminate:

```
int status;
if (waitpid(pid, &status, 0) < 0) {
    perror("waitpid failed");
    exit(EXIT_FAILURE);
}</pre>
```

The `waitpid` function waits for the child process to change state and returns its termination status in the `status` variable.

5. Get the End Time:

```
if (clock_gettime(CLOCK_MONOTONIC, &end) == -1) {
    perror("clock_gettime end");
    exit(EXIT_FAILURE);
}
```

This uses `clock_gettime` with `CLOCK_MONOTONIC` to get the current time and stores it in the `end` variable.

6. Calculate and Print the Elapsed Time:



6. Calculate and Print the Elapsed Time:

```
c
double elapsed = (end.tv_sec - start.tv_sec) + (end.tv_nsec - start.tv_nsec) /
```

The elapsed time is calculated as the difference between the start and end times in seconds, including nanosecond precision.

7. Print the Child Process Status and Elapsed Time:

```
if (WIFEXITED(status)) {
   int exitStatus = WEXITSTATUS(status);
   if (exitStatus == 0) {
      printf("Child process terminated successfully with status %d\n", exitStatus);
   } else {
      printf("Child process terminated with failure status %d\n", exitStatus);
   }
} else if (WIFSIGNALED(status)) {
   int termSignal = WTERMSIG(status);
   printf("Child process terminated by signal %d\n", termSignal);
} else {
   printf("Child process terminated abnormally\n");
}

printf("Elapsed time: %.6f seconds\n", elapsed);
```

This block prints the status of the child process and the elapsed time.

8. Main Function:

```
c

f) Copy code

int main() {
```

when a process running in the background terminates i want to print the status either exited normally or abnormally using the sigchld how can we reap the child processes and do this



To handle the termination of background processes and print their status using the `SIGCHLD` signal, you can set up a signal handler for `SIGCHLD`. This signal is sent to a parent process whenever one of its child processes terminates. The signal handler can use `waitpid` with the `WNOHANG` option to reap child processes that have terminated without blocking.

Here's an example program that demonstrates this approach:

```
void executeCommand(char *command, char *args[]) {
   pid_t pid = fork();
    if (pid < 0) {</pre>
        perror("fork failed");
        exit(EXIT_FAILURE);
    } else if (pid == 0) {
       // Child process
        if (execvp(command, args) < 0) {</pre>
            perror("execvp failed");
            exit(EXIT_FAILURE);
        printf("Started background process %d\n", pid);
int main() {
    sa.sa_handler = sigchld_handler;
    sigemptyset(&sa.sa_mask);
    sa.sa_flags = SA_RESTART | SA_NOCLDSTOP;
    if (sigaction(SIGCHLD, &sa, NULL) == -1) {
        perror("sigaction failed");
        exit(EXIT_FAILURE);
    // Example commands to run in the background
```

```
char *command1 = "ls";
  char *args1[] = {command1, "-l", NULL};

char *command2 = "sleep";
  char *args2[] = {command2, "5", NULL};

  executeCommand(command1, args1);
  executeCommand(command2, args2);

// Main process doing other work
  while (1) {
    // Simulate doing other work
    printf("Main process doing other work...\n");
    sleep(2);
  }

return 0;
}
```

1. Include Necessary Headers:

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <signal.h>
```

These headers provide the necessary functions and structures for process control, signal handling, and input/output. Ψ

2. SIGCHLD Signal Handler:

```
void sigchld_handler(int signo) {
  int status;
  pid_t pid;

  // Reap all terminated child processes
  while ((pid = waitpid(-1, &status, WNOHANG)) > 0) {
    if (WIFEXITED(status)) {
      int exitStatus = WEXITSTATUS(status);
        printf("Child process %d terminated successfully with status %d\n",
    } else if (WIFSIGNALED(status)) {
      int termSignal = WTERMSIG(status);
        printf("Child process %d terminated by signal %d\n", pid, termSignal
    } else {
        printf("Child process %d terminated abnormally\n", pid);
    }
}
```

The signal handler reaps all terminated child processes using `waitpid` with the `wnohang` option to avoid blocking. It checks the termination status and prints appropriate messages.

3. Executing Commands in the Background:

```
c

void executeCommand(char *command, char *args[]) {
  pid_t pid = fork();

if (pid < 0) {
    perror("fork failed");
    exit(EXIT_FAILURE);
  } else if (pid == 0) {</pre>
```

```
} else if (pid == 0) {
    if (execvp(command, args) < 0) {
        perror("execvp failed");
        exit(EXIT_FAILURE);
    }
} else {
    printf("Started background process %d\n", pid);
}</pre>
```

This function forks a new process to execute the specified command in the background. The parent process does not wait for the child process to terminate but continues executing.

4. Setting Up the SIGCHLD Handler:

```
struct sigaction sa;
sa.sa_handler = sigchld_handler;
sigemptyset(&sa.sa_mask);
sa.sa_flags = SA_RESTART | SA_NOCLDSTOP;
if (sigaction(SIGCHLD, &sa, NULL) == -1) {
    perror("sigaction failed");
    exit(EXIT_FAILURE);
}
```

The `sigaction` function sets up the `sigchld_handler` to handle `SIGCHLD` signals. The `SA_RESTART` flag ensures that interrupted system calls are restarted, and `SA_NOCLDSTOP` prevents the handler from being called when child processes stop.

5. Main Function:

```
int main() {

// Example commands to run in ...e background
```

5. Main Function:

```
int main() {
    // Example commands to run in the background
    char *command1 = "ls";
    char *args1[] = {command1, "-l", NULL};

    char *command2 = "sleep";
    char *args2[] = {command2, "5", NULL};

    executeCommand(command1, args1);
    executeCommand(command2, args2);

    // Main process doing other work
    while (1) {
        printf("Main process doing other work...\n");
        sleep(2);
    }

    return 0;
}
```

The main function sets up the signal handler and executes example commands in the background. It then enters an infinite loop to simulate doing other work, allowing the signal handler to handle terminated child processes.

This program will start background processes, and when they terminate, the `sigchld_handler` will print their status. The main process continues running and simulating other work.





i need to make a function that can check and print status of a process based on pid.

i found this on stack overflow

You can always open and read /proc files in C

/proc/[pid]/stat and /proc/[pid]/status would give the status of the current proces.

The third field in /proc/<pid>/stat contains the process status: R if it's Running, S if it's Sleeping (there's a few others too, like D for Disk Wait and Z for Zombie).

how exactly can we use this to get status of process. also are there similar commands to get the executable path, amount of virtual memory etc



To get the status of a process based on its PID in Linux, you can indeed use the `/proc` filesystem, which provides a wealth of information about processes and other system statistics. Below is a simple example in C that reads the process status from `/proc/[pid]/stat` and `/proc/[pid]/status` files. I'll also show how to get additional details like the executable path and memory usage.

Here's how you can do it:

Example Code in C

```
c Group code

#include <stdio.h>
#include <stdib.h>
#include <string.h>
```

```
void print_process_info(pid_t pid) {
   char path[256];
   FILE *file;
   char status[256];
   char state;
   unsigned long vm_size;
   char exe_path[256];
   snprintf(path, sizeof(path), "/proc/%d/stat", pid);
   file = fopen(path, "r");
   if (file == NULL) {
       perror("fopen");
   if (fscanf(file, "%*d %*s %c", &state) != 1) {
       perror("fscanf");
       fclose(file);
   fclose(file);
   switch (state) {
       case 'R': strcpy(status, "Running"); break;
       case 'S': strcpy(status, "Sleeping"); break;
       case 'D': strcpy(status, "Disk Wait"); break;
       case 'Z': strcpy(status, "Zombie"); break;
       case 'T': strcpy(status, "Stopped"); break;
       default: strcpy(status, "Unknown"); break;
   printf("Status: %s\n", status);
```

```
snprintf(path, sizeof(path), "/proc/%d/status", pid);
    file = fopen(path, "r");
    if (file == NULL) {
        perror("fopen");
    while (fgets(status, sizeof(status), file) != NULL) {
        if (strncmp(status, "VmSize:", 7) == 0) {
            sscanf(status, "VmSize: %lu kB", &vm_size);
            printf("Virtual Memory Size: %lu kB\n", vm_size);
    fclose(file);
    snprintf(path, sizeof(path), "/proc/%d/exe", pid);
    ssize_t len = readlink(path, exe_path, sizeof(exe_path) - 1);
    if (len != -1) {
        exe_path[len] = '\0';
        printf("Executable Path: %s\n", exe_path);
   } else {
        perror("readlink");
int main(int argc, char *argv[]) {
   if (argc != 2) {
        fprintf(stderr, "Usage: %s <pid>\n", argv[0]);
        return EXIT_FAILURE;
                                      \downarrow
   pid_t pid = atoi(argv[1]);
```

```
pid_t pid = atoi(argv[1]);
print_process_info(pid);

return EXIT_SUCCESS;
}
```

- 1. Reading Process Status:
 - Open `/proc/[pid]/stat` and read the third field, which represents the process state.
 - · Translate this state to a human-readable format.

2. Reading Memory Usage:

 Open `/proc/[pid]/status` and look for the `VmSize` field to get the virtual memory size.

3. Getting Executable Path:

• Use `readlink` on `/proc/[pid]/exe` to get the path of the executable.

Additional Notes

- **Error Handling**: Make sure to handle errors properly, especially with file operations and system calls.
- Permissions: Accessing some of these files might require elevated permissions, depending on the user running the code and the PID being queried.
- More Information: You can explore other files in `/proc/[pid]/` to get more details about the
 process, like `/proc/[pid]/cmdline` for the command line arguments, or
 '/proc/[pid]/statm` for more memory details.

Feel free to ask if you need further details or help with something specific!





how can i check if a command is valid before exec on it in C. i read online about something about path env, but im not sure how to implement it



To check if a command is valid before executing it in C, you typically want to verify that the command exists and is executable. One common approach is to use the `access` function, which is part of the POSIX standard. Here's a general outline of how you can do this:

- Check if the Command Exists: Use the `access` function to check if the
 command exists and is executable. The `access` function checks the file
 accessibility of a pathname.
- 2. **Search in PATH Environment Variable**: If the command is a simple name (not a full path), you'll need to search for it in the directories listed in the `PATH` environment variable.

Here's a code example that demonstrates these steps:

#include <stdio.h>
#include <stdib.h>

```
#include <stdlib.h>
int command_exists(const char *cmd) {
    char *path = getenv("PATH");
    if (path == NULL) {
        fprintf(stderr, "Error: PATH environment variable is not set\n");
    // Duplicate PATH variable to tokenize it
    char *path_copy = strdup(path);
    if (path_copy == NULL) {
       perror("strdup");
   char *dir = strtok(path_copy, ":");
   while (dir != NULL) {
        char full_path[1024];
        snprintf(full_path, sizeof(full_path), "%s/%s", dir, cmd);
       // Check if the file exists and is executable
        if (access(full_path, X_OK) == 0) {
            free(path_copy);
       dir = strtok(NULL, ":");
                                     \downarrow
```

```
free(path_copy);
  return 0;
}

int main(int argc, char *argv[]) {
  if (argc < 2) {
    fprintf(stderr, "Usage: %s <command>\n", argv[0]);
    return 1;
  }

  const char *cmd = argv[1];

  if (command_exists(cmd)) {
    printf("Command '%s' is valid and executable\n", cmd);
    // Here you can call exec* functions to execute the command
  } else {
    printf("Command '%s' is not valid or not executable\n", cmd);
  }

  return 0;
}
```

- 'command_exists' Function:
 - Retrieves the `PATH` environment variable.
 - Splits the `PATH` into directories.
 - Constructs the full path for the command by combining each directory with the command name.

2. `main` Function:

- Takes a command as an argument.
- Calls `command_exists` to verify if the command is valid.
- · Prints the result.

This approach ensures that you only attempt to execute commands that exist in one of the directories listed in `PATH` and that you have permission to execute.

