

Hidden Markov Models: lecture 10

Links and extensions

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HMM definition

- ▶ A Hidden Markov Model (HMM) is a Markov chain in which the sequence of states C_1, \dots, C_T is not observed but hidden
- ▶ Instead of observing the sequence of states, we observe the emissions X_1, \dots, X_T
- ▶ A HMM is defined by two quantities:
 - ▶ The transition matrix Γ of elements γ_{ij} where i and j are states:

$$\gamma_{ij} = p(C_t = j | C_{t-1} = i)$$

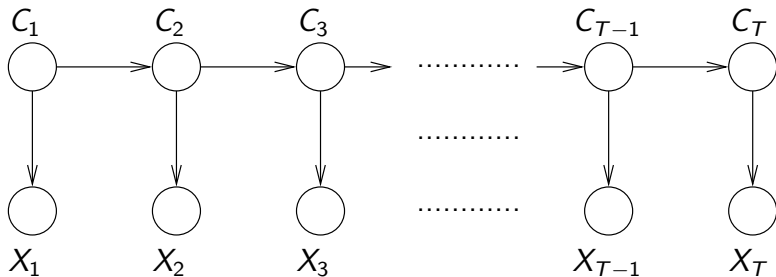
- ▶ The emission probabilities $p_i(x)$ where i is a state and x is an emission:

$$p_i(x) = p(X_t = x | C_t = i)$$

- ▶ The unconditional distribution at t is denoted $\mathbf{u}(t)$ and the initial distribution is $\mathbf{u}(1)$

$$\mathbf{u}(t) = (p(C_t = 1), p(C_t = 2), \dots, p(C_t = m))$$

Dependency graph of a hidden Markov model

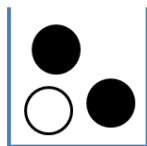


$$p(\mathbf{X}^{(T)}, \mathbf{C}^{(T)}) = p(C_1) \prod_{k=2}^T p(C_k | C_{k-1}) \prod_{k=1}^T p(X_k | C_k)$$

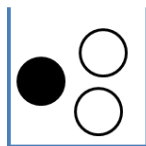
$$p(\mathbf{x}^{(T)}, \mathbf{c}^{(T)}) = u_{c_1}(1) \prod_{k=2}^T \gamma_{c_{k-1}c_k} \prod_{k=1}^T p_{c_k}(x_k)$$

Definitions of HMMs as generalization of models

- ▶ HMM is an extension of an independent mixture model (cf lecture 1, earthquake example)
- ▶ HMM is an extension of Markov chain models (cf lecture 2, weather example)
- ▶ When the data is categorical (multinomial-HMM) the HMM is a generalization of the urn problem with replacement, in which the choice of urn is ruled by a Markov chain



Urn A



Urn B

Regular grammars

- ▶ Transformational grammars are important objects in computer science
- ▶ Grammars are defined by:
 - ▶ A set of terminal symbols, usually denoted with lower case: a, b, c, \dots
 - ▶ A set of non-terminal symbols, usually denoted with upper case: A, B, C, \dots
 - ▶ Production rules of the form $\alpha \rightarrow \beta$ where α and β are strings of (terminal or non-terminal) symbols
- ▶ The most fundamental type is the regular grammar, in which the only allowed rules are of the form $X \rightarrow a$ or $X \rightarrow aY$

Examples

- ▶ Let S denote the start and ϵ denote the end
- ▶ A regular grammar allowing any string of as and bs :

$$S \rightarrow aS, S \rightarrow bS, S \rightarrow \epsilon$$

- ▶ This is also written:

$$S \rightarrow aS|bS|\epsilon$$

- ▶ A regular grammar for strings of as and bs with an odd number of as :

$$S \rightarrow aT|bS, \quad T \rightarrow aS|bT|\epsilon$$

- ▶ The grammar of palindroms however is not regular:

$$S \rightarrow aSa|bSb|\epsilon$$

Link between HMMs and grammars

- ▶ In a stochastic grammar, each rule is given a probability such that the probabilities of the production rules from any non-terminal symbol add up to one
- ▶ HMMs are equivalent to stochastic regular grammars
- ▶ More general classes of grammars also exist
- ▶ An important class is the stochastic context-free grammar (SCFG), which allows any rule of the form $X \rightarrow \beta$ (but not something like $aXb \rightarrow a\beta b$ which would be context dependent)
- ▶ The palindrom grammar in the previous slide is an example of context-free grammar
- ▶ SCFGs have their own dynamic programming algorithms (inside, outside and CYK equivalent to forward, backward and Viterbi, respectively) which are less computationally efficient but still usable
- ▶ More general grammars are very hard to work with

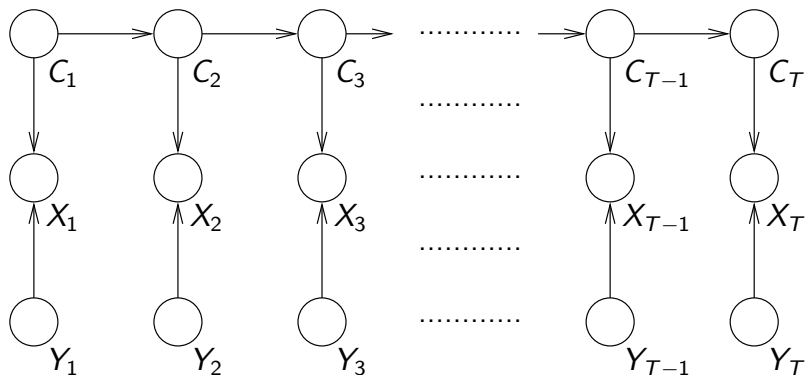
HMMs with various univariate state-dependent distributions

- ▶ Many forms of the emission distribution can be used and all the results and algorithms we have described remain applicable
- ▶ We have seen several types of HMMs depending on the form of the emission probabilities:
 - ▶ Poisson-HMM (lecture 1, earthquake example)
 - ▶ Bernoulli-HMM (lecture 2, rain example)
 - ▶ Multinomial-HMM (lecture 3, casino example)
- ▶ If the data are real numbers, we could use for example a Normal-HMM
- ▶ If the data are proportions, we could use for example a Beta-HMM

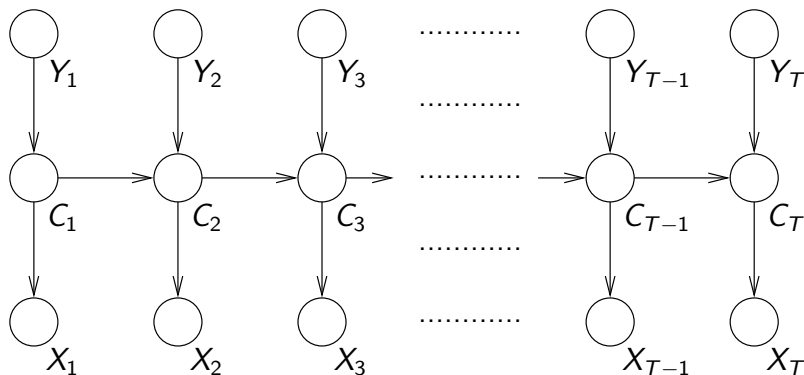
HMMs for multivariate data

- ▶ HMMs can also be used if the data is multivariate with q variables
- ▶ Need to have longitudinal conditional independence, ie the vectors observed at each time point are mutually independent given the hidden states
- ▶ Are the individual variables also mutually independent at each time point given the state?
- ▶ If not, need to specify a multivariate distribution for each state, for example a multivariate Normal distribution with location vector of length q and covariance matrix of dimension $q \times q$
- ▶ If yes, then we have contemporaneous conditional independence, and can specify q separate univariate distributions, for example q separate Normal distributions

Covariates in the state-dependent distribution

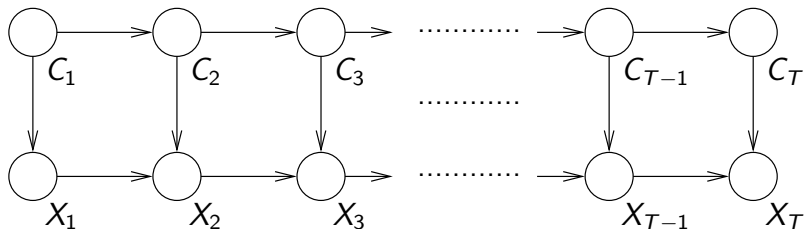


Covariates in the transition probabilities



- This structure is called a non-homogenous HMM

Markov-switching model



- ▶ Markov-switching AR(1) model
- ▶ Can likewise have AR(2), AR(3),...

State space models

- ▶ Instead of considering a discrete number of states, it may be useful to have a continuous-valued state space
- ▶ For example, in the earthquake dataset, we could have:

$$C_t = \phi C_{t-1} + \sigma \nu_t \text{ and } X_t \sim \text{Poisson}(\beta \exp(C_t))$$

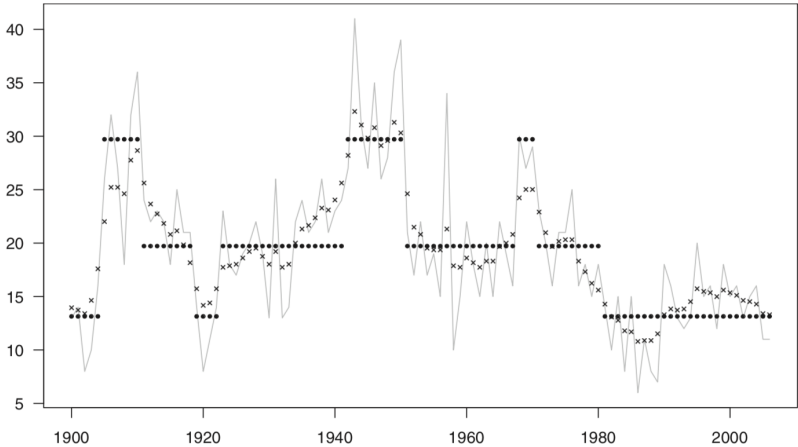
with $0 < \phi < 1$ and $\beta > 0$ and $\sigma > 0$ and $\nu_t \sim \text{Normal}(0, 1)$

- ▶ The dependencies are the same as in a HMM
- ▶ But the state process $\{C_t\}$ determines the rate of occurrence of major earthquakes
- ▶ $\{C_t\}$ is an autoregressive process of order 1, with values fluctuating around zero
- ▶ This is a state-space model (SSM) with continuous-valued state process
- ▶ A HMM is the special case of a SSM when the state space is discrete
- ▶ What can we do if the state space is continuous as above?

State space models

- ▶ Linear Gaussian SSMs can be fitted using the Kalman filter
- ▶ Otherwise (as in the model above) need to use complex approximate method such as extended Kalman filter or particle filter (aka sequential Monte-Carlo, SMC)
- ▶ Alternatively, can use a fine (eg $m = 50$ to $m = 200$) discretization of the state space to make the HMM methodology applicable to the SSM
- ▶ Can vary the number of states m and range of values to make sure the approximation is stable
- ▶ For example, compare HMM with 3 states with SSM from previous slide with discretization $m = 200$
- ▶ This technique works well for one-dimensional state spaces but is problematic for high-dimensional state spaces

Earthquake example



Higher order of HMM

- ▶ For example, a second-order HMM has transition probabilities:

$$\gamma(i, j, k) = p(C_t = k | C_{t-1} = j, C_{t-2} = i)$$

- ▶ This implies a stationary bivariate distribution:

$$u(j, k) = p(C_{t-1} = j, C_t = k)$$

- ▶ A second-order HMM with m states can be defined as a first-order HMM with m^2 states and only m^3 possible transitions (because a state (i, j) can only transit to a state (j, k))
- ▶ The time to compute the likelihood is therefore $O(Tm^3)$
- ▶ The number of free parameters in the transition matrix is $m^2(m - 1)$

Hidden semi-Markov models

- ▶ Considering higher orders of HMM is computationally demanding
- ▶ Hidden semi-Markov models (HSMMs) are an alternative way of relaxing the Markov assumption
- ▶ The number of steps where the model stays in a state is called the dwell time
- ▶ For a HMM, the dwell times are geometrically distributed
- ▶ A HSMM allows us to use different dwell times distributions
- ▶ A HSMM with m states consists of:
 - ▶ A transition matrix $\mathbf{\Omega}$ with zeros on the diagonal (so that staying in the same state is not allowed)
 - ▶ A dwell time distribution $d_i(r)$ for each state i
 - ▶ An emission distribution $p_i(x)$ for each state i
- ▶ Note that if all $d_i(r)$ are Geometric, the HSMM is a HMM

HSMM exactly represented as a HMM

- ▶ There are forward and backward recursions for HSMM but they are much more complex and computationally demanding than for HMM
- ▶ However, it is often possible to rewrite a HSMM as a HMM
- ▶ This can be done exactly if all dwelling distribution are either geometric or of finite support
- ▶ For example, consider a two-state Poisson-HSMM with $\lambda_1 = 5$ and $\lambda_2 = 10$ and $d_1(1) = 1/4$, $d_1(2) = 3/8$, $d_1(3) = 1/4$, $d_1(4) = 1/8$ and $d_2(r) = 0.1 \times 0.9^{r-1}$ for $r = 1, 2, 3, \dots$
- ▶ This is equivalent to a 5-states HMM with $\lambda_1 = \lambda_2 = \lambda_3 = \lambda_4 = 5$, $\lambda_5 = 10$ and:

$$\mathbf{\Gamma} = \begin{pmatrix} 0 & 3/4 & 0 & 0 & 1/4 \\ 0 & 0 & 1/2 & 0 & 1/2 \\ 0 & 0 & 0 & 1/3 & 2/3 \\ 0 & 0 & 0 & 0 & 1 \\ 1/10 & 0 & 0 & 0 & 9/10 \end{pmatrix}$$

HSMM approximately represented as a HMM

- ▶ If one of the dwelling time distribution is not geometric and with infinite support (for example a Poisson distribution shifted up by one) then there is no exact equivalent HMM
- ▶ But we can build an approximately equivalent HMM
- ▶ Each state i with a non-geometric infinite support is decomposed into m_i consecutive states, such that the cumulative distribution function associated with $d_i(r)$ is the same up to m_i
- ▶ The m_i -th state uses a geometric distribution which is approximate but a good approximation when m_i is large

Conclusions

- ▶ Hidden Markov Models can be formulated as:
 - ▶ An extension of an independent mixture model
 - ▶ An extension of Markov chain models
 - ▶ A type of urn problem with replacement
 - ▶ A stochastic regular grammar
- ▶ HMMs can accomodate multivariate data
- ▶ Covarites can be included within both emission or transition processes
- ▶ Hidden Markov Models can be extended into:
 - ▶ A state space model (SSM) by considering a continuous state space
 - ▶ A higher-order HMM
 - ▶ A hidden-semi Markov Model (HSMM)
- ▶ These extensions are harder to work with, but can often be approximated by HMMs with high number of states
- ▶ The powerful dynamic programming algorithms available for HMMs is what makes them so popular