**Post Study Interview and Debriefing Information**

After the participant finished the study, the experimenter asked four open ended questions to the participant:

1. What do you think about your experience interacting with the robot in general?
2. Did you notice anything unusual during your interaction with the robot?
3. What did you think when the robot made that error?
4. For each of the error situations that the robot performed but was not mentioned by the participants when they answered question 2, the researcher asked if the participants realised that the robot had made those errors.

After the short interview, the experimenter told the participant that all the errors that he/she experienced during the study were intentionally introduced by the experimenter. The experimenter then further told the participant that the real purpose of the study is to gather dataset of human reaction to various error situations that the robot created during HRI. The experimenter explained briefly the categorisation of error situations which is adopted in the study: Social Norm Violations (SNV), Execution Errors (EE), and Planning Errors (PE). The experimenter concluded the debriefing by telling the participant that the dataset collected in the study will be utilised to train a machine learning algorithm to detect error situations in HRI automatically.