

Live probes for free

Jean-Baptiste Döderlein^a, Tijs van der Storm^b, and Riemer van Rozen^b

a ENS Rennes, Bruz, France

b CWI, Amsterdam, The Netherlands

Abstract *Context* In his presentation "Inventing on Principles", Bret Victor demonstrates a live code editor: by specifying input values for a function, we can observe in real time the values taken by the variables during execution, as the code is written. This information is often obtained using a language designed for live programming or by instrumentation of a specific runtime. *Inquiry ... Approach* In this paper we propose to exploit the capabilities of debuggers to obtain the data needed to design a live code editor. *Knowledge ... Grounding ... Importance ...*

ACM CCS 2012

- **General and reference** → *Computing standards, RFCs and guidelines*;
- **Applied computing** → **Publishing**;

Keywords programming journal, paper formatting, submission preparation

The Art, Science, and Engineering of Programming

Perspective The Art of Programming

Area of Submission Social Coding, General-purpose programming



© Jean-Baptiste Döderlein, Tijs van der Storm, and Riemer van Rozen
This work is licensed under a "CC BY 4.0" license.
Submitted to *The Art, Science, and Engineering of Programming*.

1 Introduction

2 Problem Overview

3 Using the Debugger ?

3.1 Stack Recording

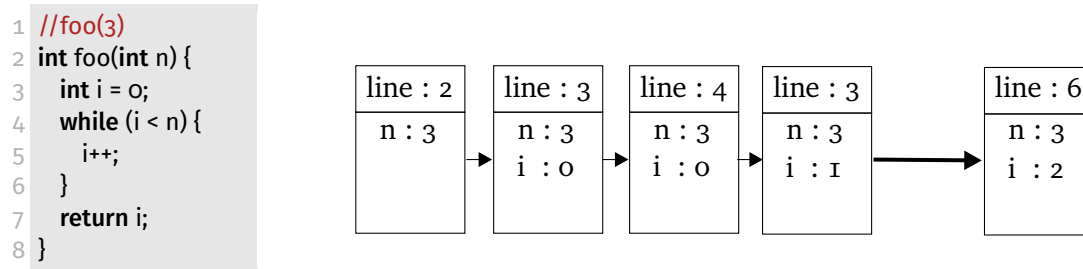


Figure 1 Stack Recording Example

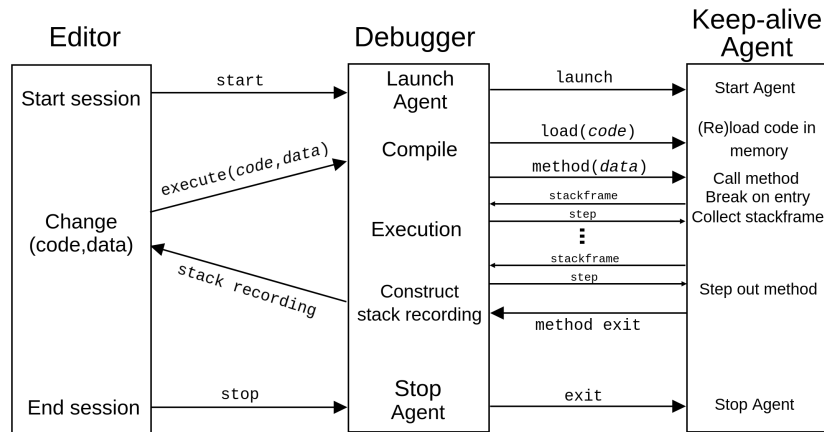
In order to generate the data needed to probe a variable, we need to be able to retrieve the state of the variable during execution. This information is contained in the stackframe at the time of execution. However, we need to add spatial and temporal information to this: we need to associate each stackframe state with the location in the code at which it was retrieved, and we also need to know the order in which these stackframes were retrieved.

In this paper, we introduce a structure for representing this data: a *stack recording*. A stack record represents the different states of the stack frame during the execution of a method. The stack record is presented as a chain of recorded stack frames, to which information has been added about the source code's location and height in the stack. This representation allows us to maintain a link between the spatial location (the reference to the source code) and the temporal location (the order of these stackframes) of the execution. This representation has several advantages: it is easy to construct from debugger information, and it applies to most programming languages. Figure 1 shows an example of a stack recording.

3.2 Keep Alive Agent

A live environment must be able to react to two different events: a change in the code or a change in the test/input data. If the code changes, we need to re-execute the code, and in the case of a compiled language, we need to compile the new code first. If the data changes, we need to be able to re-execute the programme with the new data. In addition, it is necessary to keep compilation and execution times low enough to maintain an interactive experience with the user.

To meet these constraints, we propose to use the debugger on an intermediate program, a *keep-alive agent*. This program keeps the debugger alive between executions



■ **Figure 2** Keep Alive Agent

and code changes to reduce initialisation times. The general operation of a keep-alive agent is shown in Figure 2 :

- At the start of the session, the debugger is started on the agent. Once initialised, the agent is paused.
- The target code is loaded into the agent and a breakpoint is set at the input of the target method.
- Execution of the target method triggers the breakpoint at the input of the method, and execution continues step by step to build the *stack recording*.

4 Live Probes in Java with JDI

We developed a Java backend using JDI, a debugging interface for Java, to implement the concepts discussed in the previous section. The keep-alive agent includes a method for loading classes into the JVM.

When executing the target method, the arguments are created in the client JVM and then passed to the debugger JVM using the `mirrorOf` and `newInstance` methods from the reflection API. The target method is invoked using `invokeMethod`. To handle events from the JDI when breakpoints are set, a dedicated thread is used to prevent deadlocks.

If modifications are needed in the code of the target method, we employ the `redefineClasses` method. This method allows changing the content of a class loaded in the JVM using an array of byte codes. However, it has a limitation: it only works if the class signature remains unchanged. If the class structure is modified, restarting the debugger is necessary.

5 Generalizing Live Probes with Debugger Adapter Protocol

The Debug Adapter Protocol (DAP), developed by Microsoft, is a standard method of communicating with a programming language debugger. It is compatible with various editors, including VS Code, and provides a unified interface for all programming languages.

By exploiting this protocol, we have created a new language parametric backend, which we have implemented for the C, Python and Java programming languages. These languages are chosen to cover both compiled and interpreted languages. This backend offers an interface common to all three languages, which includes methods for starting and initialising the debugging server, loading and reloading code in the debugger, and executing a method while performing stack recording.

These methods allow us to carry out stack recording independently of the chosen language and facilitate the future implementation of live programming interfaces.

The implementation for each language includes a keep-alive agent and code to communicate with the debugger and keep-alive agent to provide the interface functionality. These methods depend on both the implementation of the debugging server and the keep-alive agent. The debug server initialisation parameters are specific to each language.

The way in which the code is loaded also depends on the language. For interpreted languages such as Python, the code can be interpreted at runtime and then loaded into the debugger's memory. For Java, we have extended the ClassLoader to add and modify classpaths and classes at runtime in the keep-alive agent. For C, the code is loaded into shared libraries that can be added and reloaded during execution.

Method execution for Java and Python is different to that used in C. For Java and Python, calling methods directly from the debugger does not trigger breakpoints for these languages. To remedy this, execution must be initiated from the agent and not by a debugger command. To do this, the Python and Java agents have fields for referencing a method and its arguments; when this information is entered, the agent starts execution. For C, as is the case in the backend using JDI, the method call is made from the debugger console.

6 Evaluation

6.1 Demo : A Small C Live Programming Environment

6.2 Performance

In the context of a live programming environment, it is essential to have short response times after user interactions. We therefore measured the performance of our approach in response to various questions:

- What is the average performance during a live programming session?
- What is the compilation time as a function of programme size ?

```

1 //binary_search({1,2,3,4,5,6},6,9)
2 int binary_search(int arr[], int length, int target) {
3     int left = 0;
4     int right = length - 1;
5     while (left <= right) {
6
7         int mid = (left + right) / 2;
8         if (arr[mid] == target) {
9             return mid;
10        } else if (arr[mid] < target) {
11            left = mid + 1;
12        } else {
13            right = mid - 1;
14        }
15    }
16    return -1;
17 }

```

```

1
2 arr=int *{...}; length=6; target=9; -> return_value=-1
3 left= 0
4 right= 5
5 left = 0 | 3 | 5 | 6
6 right = 5 | 5 | 5 | 5
7 mid= 2 | 4 | 5
8
9
10
11 left= 3 | 5 | 6
12
13
14
15
16
17

```

■ **Figure 3** Demo of the live programming environment for C.

- How long does it take to load the code into the debugger, depending on the size of the programme?
- How long does it need to run the program, depending on the number of steps to make the stack recording ?

6.2.1 What is the average performance during a live programming session?

To measure the performance of our approach in the general context of a live programming session, we measured 4 points :

- Agent initialisation time, which occurs once at the start of the session.
- The compilation time, if there is a compilation stage.
- The time taken to load the code into the debugger.
- Program execution time.

Language	One time	Each Iteration		
	Initialization	Compile	Load Code	Execute
C	1.24	0.067	0.0098	0.193
Java	5.92	0.57	0.015	1.28
Python	0.639	0	0.144	3.26

■ **Table 1** Average time in seconds for each step of the live programming session.

6.2.2 What is the compilation time as a function of programme size ?

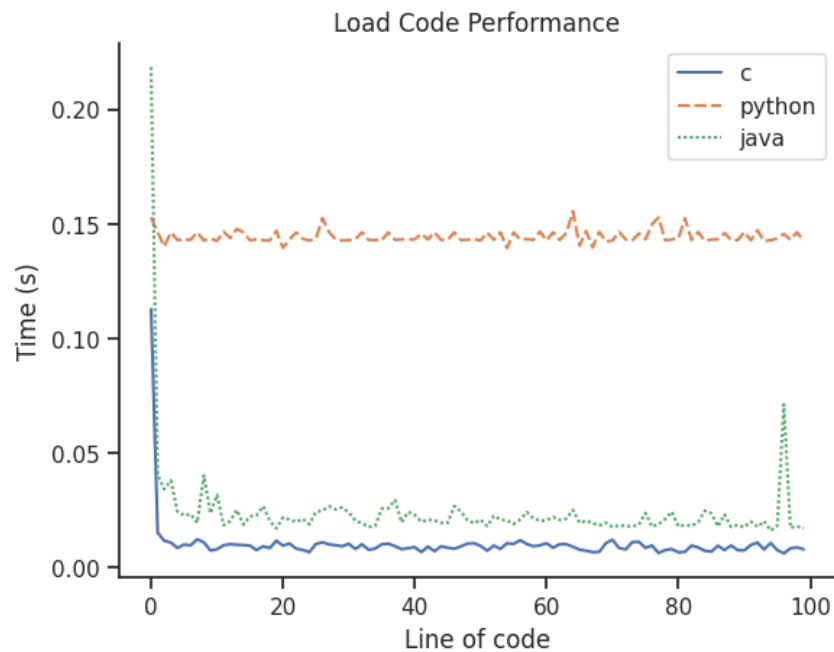
6.2.3 How long does it take to load the code into the debugger, depending on the size of the programme?

6.2.4 How long does it need to run the program, depending on the number of steps to make the stack recording ?

7 Related Work

Example-Based Live Programming for Everyone[3] : Use GraalVM/Truffle to get live information from the code of multiple languages.

Live probes for free



■ **Figure 4** Load code time in seconds depending on the size of the program.

Example Centric Programming[1] : Use BeanShell(custom JVM) to get live information. Prototype for Java in Eclipse.

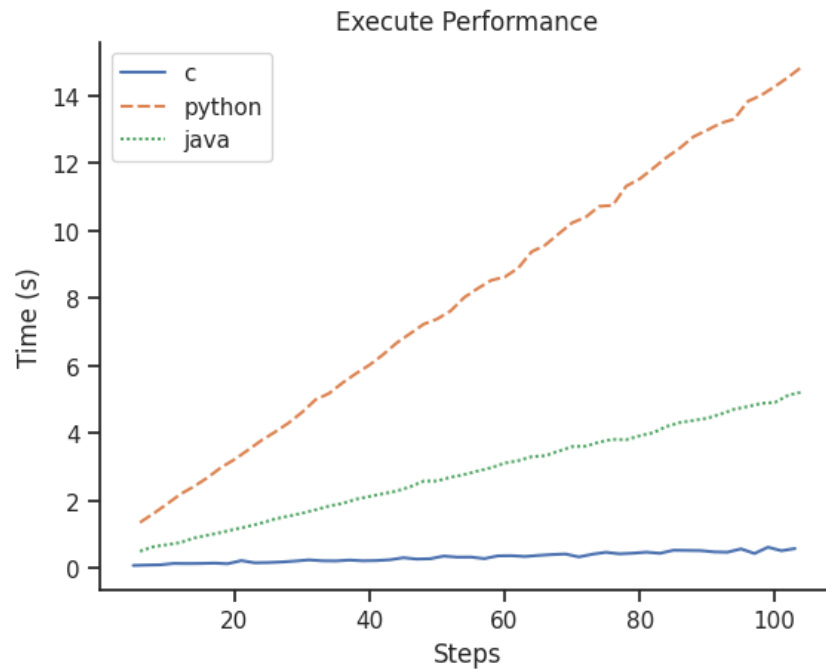
Usable Live Programming[2] : New language for live programming(Ying Yang) with incremental compilation. Live programming environment for this language. Use source location to relate execution and code(=> almost like stack recording that link stackframe and code location)

Scalable Omniscient Debugging[4] : Omniscient debugging with a lot of data. Use a lot of memory to store all the data. In this paper they record almost everything, we only record the stackframe.

8 Conclusion

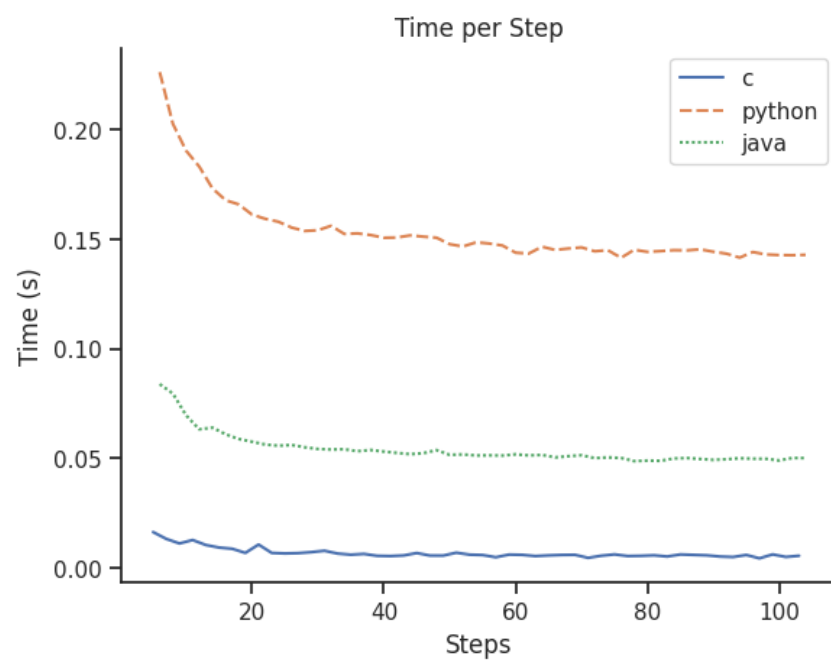
References

- [1] Jonathan Edwards. "Example Centric Programming". In: *SIGPLAN Not.* 39.12 (Dec. 2004), pages 84–91. ISSN: 0362-1340. DOI: 10.1145/1052883.1052894. URL: <https://doi.org/10.1145/1052883.1052894>.
- [2] Sean McDirmid. "Usable Live Programming". In: *Proceedings of the 2013 ACM International Symposium on New Ideas, New Paradigms, and Reflections on Programming & Software*. Onward! 2013. Indianapolis, Indiana, USA: Association for Computing Machinery, 2013, pages 53–62. ISBN: 9781450324724. DOI: 10.1145/2509578.2509585. URL: <https://doi.org/10.1145/2509578.2509585>.



■ **Figure 5** Execution time in seconds depending on the number of steps.

- [3] Fabio Niephaus, Patrick Rein, Jakob Edding, Jonas Hering, Bastian König, Kolya Opahle, Nico Scordialo, and Robert Hirschfeld. “Example-Based Live Programming for Everyone: Building Language-Agnostic Tools for Live Programming with LSP and GraalVM”. In: *Proceedings of the 2020 ACM SIGPLAN International Symposium on New Ideas, New Paradigms, and Reflections on Programming and Software*. Onward! 2020. Virtual, USA: Association for Computing Machinery, 2020, pages 1–17. ISBN: 9781450381789. DOI: 10.1145/3426428.3426919. URL: <https://doi.org/10.1145/3426428.3426919>.
- [4] Guillaume Pothier, Éric Tanter, and José Piquier. “Scalable Omniscient Debugging”. In: *SIGPLAN Not.* 42.10 (Oct. 2007), pages 535–552. ISSN: 0362-1340. DOI: 10.1145/1297105.1297067. URL: <https://doi.org/10.1145/1297105.1297067>.



■ **Figure 6** Execution time in seconds per step.