

# AstroStatistics and Cosmology Homework

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Exercises 1–3 and 7<sup>1</sup> are in Jupyter notebooks in the folder `astrostat_homework`. They can be most easily accessed through the following links:

1. [https://nbviewer.jupyter.org/github/jacopok/notes/blob/master/ap\\_third\\_semester/astrostat\\_homework/exercises\\_123.ipynb](https://nbviewer.jupyter.org/github/jacopok/notes/blob/master/ap_third_semester/astrostat_homework/exercises_123.ipynb)
2. [https://nbviewer.jupyter.org/github/jacopok/notes/blob/master/ap\\_third\\_semester/astrostat\\_homework/exercise\\_7.ipynb](https://nbviewer.jupyter.org/github/jacopok/notes/blob/master/ap_third_semester/astrostat_homework/exercise_7.ipynb).

## 1 November exercises

### Exercise 4

After being given a probability distribution  $\mathbb{P}(x)$ , we define the *characteristic function*  $\phi$  as its Fourier transform, which can also be expressed as the expectation value of  $\exp(-i\vec{k} \cdot \vec{x})$ :

$$\phi(\vec{k}) = \int d^n x \exp(-i\vec{k} \cdot \vec{x}) \mathbb{P}(x) = \mathbb{E} \left[ \exp(-i\vec{k} \cdot \vec{x}) \right]. \quad (1.1)$$

**Claim 1.1.** *A multivariate normal distribution*

$$\mathcal{N}(\vec{x}|\vec{\mu}, C) = \frac{1}{(2\pi)^{n/2} \sqrt{\det C}} \exp\left(-\frac{1}{2} \vec{y}^\top C^{-1} \vec{y}\right) \Big|_{\vec{y}=\vec{x}-\vec{\mu}}, \quad (1.2)$$

has a characteristic function equal to

$$\phi(\vec{k}) = \exp\left(-i\vec{\mu} \cdot \vec{k} - \frac{1}{2} \vec{k}^\top C \vec{k}\right). \quad (1.3)$$

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<sup>1</sup> It is not finished yet.

*Proof: completing the square.* The integral we need to compute is given, absorbing the normalization into a factor  $N$ , by

$$\phi(\vec{k}) = N \int d^n x \exp\left(-i\vec{k} \cdot \vec{x} - \frac{1}{2}\vec{y}^\top C^{-1}\vec{y}\right) \Big|_{\vec{y}=\vec{x}-\vec{\mu}}. \quad (1.4)$$

The only integrals we really know how to do are Gaussian ones, so we want to rewrite the argument of the exponential so that it is a quadratic form. The manipulation goes as follows, considering the opposite of the argument the exponential in order to have less minus signs and defining the symmetric matrix  $V = C^{-1}$ :

$$i\vec{k} \cdot \vec{x} + \frac{1}{2}\vec{y}^\top V\vec{y} = i\vec{k} \cdot \vec{x} + \frac{1}{2}\vec{x}^\top V\vec{x} - \vec{x}^\top V\vec{\mu} + \frac{1}{2}\vec{\mu}^\top V\vec{\mu} \quad (1.5)$$

$$= \frac{1}{2}\vec{x}^\top V\vec{x} + \vec{x}^\top (i\vec{k} - V\vec{\mu}) + \frac{1}{2}\vec{\mu}^\top V\vec{\mu} \quad (1.6)$$

$$= \underbrace{\frac{1}{2}(\vec{x} + V^{-1}(i\vec{k} - V\vec{\mu}))^\top V(\vec{x} + V^{-1}(i\vec{k} - V\vec{\mu}))}_{\textcircled{1}} + \underbrace{-\frac{1}{2}(i\vec{k} - V\vec{\mu})^\top V^{-1}(i\vec{k} - V\vec{\mu}) + \frac{1}{2}\vec{\mu}^\top V\vec{\mu}}_{\textcircled{2}}, \quad (1.7)$$

which we can now integrate, since it is now a quadratic form in terms of a shifted variable,  $\vec{x} + \vec{p}$ , where the constant (with respect to  $\vec{x}$ ) vector  $\vec{p}$  is given by  $V^{-1}(i\vec{k} - V\vec{\mu})$ .<sup>2</sup>

Now, shifting the integral from one in  $d^n x$  to one in  $d^n(x + p)$  does not change the measure, since the Jacobian of a shift is the identity. Then, we have

$$\phi(\vec{k}) = N \int d^n(x + p) \exp(-\textcircled{1} - \textcircled{2}) \quad (1.12)$$

$$= N \sqrt{\frac{(2\pi)^n}{\det V}} \exp(-\textcircled{2}) \quad (1.13)$$

$$= \underbrace{\frac{1}{\sqrt{\det V \det C}}}_{=1} \exp(-\textcircled{2}), \quad (1.14)$$

since the determinant of the inverse is the inverse of the determinant.

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<sup>2</sup> In the last step we applied the matrix square completion formula: for a symmetric matrix  $A$  and vectors  $\vec{x}$ ,  $\vec{b}$  we have

$$\frac{1}{2}(\vec{x} + A^{-1}\vec{b})^\top A(\vec{x} + A^{-1}\vec{b}) - \frac{1}{2}\vec{b}^\top A^{-1}\vec{b} = \quad (1.8)$$

$$= \frac{1}{2}[\vec{x}^\top A\vec{x} + \vec{x}^\top A A^{-1}\vec{b} + (A^{-1}\vec{b})^\top A\vec{x} + (A^{-1}\vec{b})^\top A A^{-1}\vec{b} - \vec{b}^\top A^{-1}\vec{b}] \quad (1.9)$$

$$= \frac{1}{2}[\vec{x}^\top A\vec{x} + \vec{x}^\top \vec{b} + \vec{b}^\top (A^{-1})^\top A\vec{x} + \vec{b}^\top (A^{-1})^\top \vec{b} - \vec{b}^\top A^{-1}\vec{b}] \quad (1.10)$$

$$= \frac{1}{2}\vec{x}^\top A\vec{x} + \vec{b}^\top \vec{x}, \quad (1.11)$$

which we used with  $\vec{b} = i\vec{k} - V\vec{\mu}$ .

Now, we only need to simplify ②:

$$\textcircled{2} = -\frac{1}{2} \left[ -\vec{k}^\top V^{-1} \vec{k} - 2i\vec{\mu}^\top V V^{-1} \vec{k} + \vec{\mu}^\top V V^{-1} V \vec{\mu} \right] + \frac{1}{2} \vec{\mu}^\top V \vec{\mu} \quad (1.15)$$

$$= \frac{1}{2} \vec{k}^\top C \vec{k} + i\vec{\mu}^\top \vec{k}, \quad (1.16)$$

inserting which into the exponent yields the desired result.  $\square$

*Proof: by diagonalization.* We now follow a different approach: the covariance matrix  $C$  is symmetric, so we will always be able to find an orthogonal matrix  $O$  (satisfying  $O^\top = O^{-1}$ ) such that  $C = O^\top D O$ , where  $D$  is diagonal. We will then also have  $V = C^{-1} = O^\top D^{-1} O$ . Let us denote the eigenvalues of  $D$  as  $\lambda_i$ , and the eigenvalues of  $D^{-1}$  as  $d_i = \lambda_i^{-1}$ .

Defining  $\vec{z} = O\vec{x}$ ,  $\vec{m} = O\vec{\mu}$ ,  $\vec{u} = O\vec{k}$  the negative of the argument of the integral becomes:

$$i\vec{k} \cdot \vec{x} + \frac{1}{2} (\vec{x} - \vec{\mu})^\top C^{-1} (\vec{x} - \vec{\mu}) = i\vec{u} \cdot \vec{z} + \frac{1}{2} (\vec{z} - \vec{m})^\top D^{-1} (\vec{z} - \vec{m}) \quad (1.17)$$

$$= i\vec{u} \cdot \vec{z} + \frac{1}{2} \sum_i d_i (z_i - m_i)^2 \quad (1.18)$$

$$= \sum_i \left[ iu_i z_i + \frac{d_i}{2} (z_i^2 + m_i^2 - 2m_i z_i) \right] \quad (1.19)$$

$$= \sum_i \left[ z_i^2 \frac{d_i}{2} + z_i (iu_i - m_i d_i) + \frac{d_i}{2} m_i^2 \right]. \quad (1.20)$$

With this, and since by  $\det O = 1$  we have  $d^n z = d^n x$ , we can decompose our Gaussian integral into a product of Gaussian integrals:

$$\phi(\vec{k}) = N \int d^n x \exp \left( -i\vec{k} \cdot \vec{x} - \frac{1}{2} (\vec{x} - \vec{\mu})^\top C^{-1} (\vec{x} - \vec{\mu}) \right) \quad (1.21)$$

$$= N \int d^n z \exp \left( -\sum_i \left[ z_i^2 \frac{d_i}{2} + z_i (iu_i - m_i d_i) + \frac{d_i}{2} m_i^2 \right] \right) \quad (1.22)$$

$$= N \prod_i \int dz_i \exp \left( -z_i^2 \frac{d_i}{2} - z_i (iu_i - m_i d_i) - \frac{d_i}{2} m_i^2 \right) \quad (1.23)$$

$$= N \prod_i \sqrt{\frac{2\pi}{d_i}} \exp \left( \frac{(iu_i - m_i d_i)^2}{2d_i} - \frac{d_i m_i^2}{2} \right) \quad (1.24)$$

$$= \frac{1}{\sqrt{\det C \det V}} \prod_i \exp \left( \frac{-u_i^2 + m_i^2 d_i^2 - 2iu_i m_i d_i}{2d_i} - \frac{d_i m_i^2}{2} \right) \quad (1.25)$$

$$= \exp \left( \sum_i \left[ -\frac{u_i^2}{2d_i} - iu_i m_i \right] \right) \quad (1.26)$$

$$= \exp \left( -\frac{1}{2} \vec{u}^\top C \vec{u} - i\vec{u} \cdot \vec{m} \right) \quad (1.27)$$

$$= \exp \left( -\frac{1}{2} \vec{k}^\top C \vec{k} - i\vec{k} \cdot \vec{\mu} \right), \quad (1.28)$$

where we have used the expression for the single-variable Gaussian integral:

$$\int dz \exp(-az^2 + bz + c) = \sqrt{\frac{\pi}{a}} \exp\left(\frac{b^2}{4a} + c\right), \quad (1.29)$$

which comes from the one-variable completion of the square:

$$-az^2 + bz + c = -a\left(z - \frac{b}{2a}\right)^2 + \frac{b^2}{4a} + c. \quad (1.30)$$

Also, we used the fact that orthogonal transformation do not change fully-contracted objects, such as scalar products or bilinear forms.  $\square$

### Exercise 5

We can calculate the moments of a distribution through its characteristic function:

$$\mathbb{E}\left[x_\alpha^{n_\alpha} \dots x_\beta^{n_\beta}\right] = \frac{\partial^{n_\alpha \dots n_\beta} \phi(\vec{k})}{\partial(-ik_\alpha)^{n_\alpha} \dots \partial(-ik_\beta)^{n_\beta}} \Big|_{\vec{k}=0}. \quad (1.31)$$

In the multivariate Gaussian case we can then calculate the mean (component by component) as

$$\mathbb{E}(x_\alpha) = \frac{\partial \phi(\vec{k})}{\partial(-ik_\alpha)} \Big|_{\vec{k}=0} \quad (1.32)$$

$$= \frac{\partial}{\partial(-ik_\alpha)} \Big|_{\vec{k}=0} \exp\left(-\frac{1}{2} \vec{k}^\top C \vec{k} - i \vec{k} \cdot \vec{\mu}\right) \quad (1.33)$$

$$= \left[-i \sum_{\beta} k_\beta C_{\beta\alpha} + \mu_\alpha\right] \exp\left(-\frac{1}{2} \vec{k}^\top C \vec{k} - i \vec{k} \cdot \vec{\mu}\right) \Big|_{\vec{k}=0} \quad (1.34)$$

$$= \mu_\alpha, \quad (1.35)$$

where we used the fact that the differentiation of a symmetric bilinear form is as follows:

$$\frac{\partial}{\partial k_\alpha} \left( \sum_{\beta\gamma} k_\beta k_\gamma C_{\beta\gamma} \right) = 2 \sum_{\beta\gamma} \delta_{\beta\alpha} k_\gamma C_{\beta\gamma} = 2 \sum_{\gamma} k_\gamma C_{\alpha\gamma}. \quad (1.36)$$

The covariance matrix can be computed by linearity as

$$\tilde{C}_{\alpha\beta} = \mathbb{E}\left[(x_\alpha - \mathbb{E}(x_\alpha))(x_\beta - \mathbb{E}(x_\beta))\right] = \mathbb{E}[x_\alpha x_\beta] - \mu_\alpha \mu_\beta, \quad (1.37)$$

the first term of which reads as follows:

$$\mathbb{E}[x_\alpha x_\beta] = \frac{\partial^2 \phi(\vec{k})}{\partial(-ik_\beta) \partial(-ik_\alpha)} \Big|_{\vec{k}=0} \quad (1.38)$$

$$= \frac{\partial}{\partial(-ik_\beta)} \Big|_{\vec{k}=0} \left[ -i \sum_{\beta} k_\beta C_{\beta\alpha} + \mu_\alpha \right] \exp \left( -\frac{1}{2} \vec{k}^\top C \vec{k} - i \vec{k} \cdot \vec{\mu} \right) \quad (1.39)$$

$$= C_{\alpha\beta} + \mu_\alpha \mu_\beta, \quad (1.40)$$

therefore, as expected,  $\tilde{C}_{\alpha\beta}$  is indeed  $C_{\alpha\beta}$ .

## Exercise 6

**Claim 1.2.** *The characteristic function of a multivariate Gaussian is, up to normalization, a multivariate Gaussian.*

*Proof.* The characteristic function is the exponential of (minus)

$$\frac{1}{2} \vec{k}^\top C \vec{k} + i \vec{k} \cdot \vec{\mu} = \frac{1}{2} \left( \vec{k} + i C^{-1} \vec{\mu} \right)^\top C \left( \vec{k} + i C^{-1} \vec{\mu} \right) + \frac{1}{2} \vec{\mu}^\top C^{-1} \vec{\mu}, \quad (1.41)$$

which means that the characteristic function is in the form

$$\phi(\vec{k}) = \text{const} \times \exp \left( -\frac{1}{2} (\vec{k} - \vec{m})^\top C (\vec{k} - \vec{m}) \right), \quad (1.42)$$

a multivariate normal with mean  $\vec{m} = -i C^{-1} \vec{\mu}$  and covariance matrix  $C^{-1}$ , the inverse of the covariance matrix of the corresponding MVN.  $\square$

## Exercise 8

For clarity, we denote with Greek indices those ranging from 1 to  $N$ , the size of the vector of data; and with Latin indices those ranging from 1 to  $M$ , the number of templates.

We are assuming that the data have a Gaussian distribution with a covariance matrix  $C$ , and we are modelling their mean  $\mu_\alpha$  as a sum of templates  $t_{i\alpha}$  with coefficients  $A_i$ :

$$\mu_\alpha = t_{i\alpha} A_i, \quad (1.43)$$

where the Einstein summation convention has been used. Therefore, the likelihood is proportional to

$$\mathcal{L}(d_\alpha | A_i) \propto \exp \left( -\frac{1}{2} (d_\alpha - A_i t_{i\alpha}) C_{\alpha\beta}^{-1} (d_\beta - A_j t_{j\beta}) \right). \quad (1.44)$$

The normalization only depends on the covariance matrix  $C_{\alpha\beta}$ , which we assume is fixed. Therefore, maximizing the likelihood<sup>3</sup> is equivalent to minimizing the  $\chi^2$ , which reads

$$\chi^2 = (d_\alpha - A_i t_{i\alpha}) C_{\alpha\beta}^{-1} (d_\beta - A_j t_{j\beta}). \quad (1.45)$$

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<sup>3</sup> Which is equivalent to maximizing the posterior if we are using a flat prior.

We want to maximize this as the amplitudes vary: therefore, we set the derivative with respect to  $A_k$  to zero,

$$\frac{\partial \chi^2}{\partial A_k} = -2t_{k\alpha} C_{\alpha\beta}^{-1} (d_\beta - A_j t_{j\beta}) = 0, \quad (1.46)$$

which means that

$$t_{k\alpha} C_{\alpha\beta}^{-1} d_\beta = (t_{k\alpha} C_{\alpha\beta}^{-1} t_{j\beta}) A_j, \quad (1.47)$$

a linear system of  $M$  equations (indexed by  $k$ ) in the  $M$  variables  $A_j$ . If we denote the evaluations of bilinear forms in the data ( $N$ -dimensional) space with brackets, as  $a_\alpha C_{\alpha\beta} b_\beta \stackrel{\text{def}}{=} (a|C|b)$ , this reads

$$(t|C^{-1}|d)_k = (t|C^{-1}|t)_{kj} A_j \quad (1.48)$$

$$\left[ (t|C^{-1}|t)^{-1} \right]_{mk} (t|C^{-1}|d)_k = \underbrace{\left[ (t|C^{-1}|t)^{-1} \right]_{mk} (t|C^{-1}|t)_{kj}}_{=\delta_{mj}} A_j = A_m \quad (1.49)$$

$$A_m = \left[ (t|C^{-1}|t)^{-1} \right]_{mk} (t|C^{-1}|d)_k, \quad (1.50)$$

where the inverse of  $(t|C^{-1}|t)$  is to be computed in the  $M$ -dimensional vector space.

## Exercise 9

Our model for the mean value is in the form  $\mu(\Theta, A) = A\bar{x}(\Theta)$ , where  $\bar{x}$  is a generic function of  $\Theta$ , while  $A$  is our scale parameter.<sup>4</sup> Our likelihood then reads

$$\mathcal{L}(x|\Theta, A) = \underbrace{\frac{1}{(2\pi)^{N/2} \sqrt{\det C}}}_{B_1} \exp\left(-\frac{1}{2}(x - A\bar{x}(\Theta))^\top C^{-1}(x - A\bar{x}(\Theta))\right). \quad (1.51)$$

If the priors for both  $A$  and  $\Theta$  are flat, this corresponds to the joint posterior  $P(\Theta, A|x)$ . We want to marginalize over  $A$ , which amounts to integrating over it: dropping the dependence on  $\Theta$  of  $\bar{x}$  and defining  $V = C^{-1}$  we find

$$P(\Theta|x) = B_1 \int \exp\left(-\frac{1}{2}(x - A\bar{x})^\top V(x - A\bar{x})\right) dA \quad (1.52)$$

$$= B_1 \int \exp\left(-\frac{1}{2}\left(x^\top Vx - 2A\bar{x}^\top Vx + A^2\bar{x}^\top V\bar{x}\right)\right) dA. \quad (1.53)$$

Used the symmetry of  $V$ .

Applying the formula for the single-variable Gaussian integral (1.29) (the bilinear forms are all evaluated to yield scalars, we are only integrating over the scalar  $A$ !) we then get

$$P(\Theta|x) = \underbrace{B_1 \exp\left(-\frac{1}{2}x^\top Vx\right)}_{B_2} \exp\left(\frac{(\bar{x}^\top Vx)^2}{4(\bar{x}^\top V\bar{x})}\right) \sqrt{\frac{\pi}{\bar{x}^\top V\bar{x}}} \quad (1.54)$$

<sup>4</sup> This is not specified in the problem, but it seems natural to think that  $|\bar{x}(\Theta)|$  is a constant for varying  $\Theta$ .

$$= B_2 \sqrt{\frac{\pi}{\bar{x}^\top V \bar{x}}} \exp\left(\frac{\bar{x}^\top \Omega \bar{x}}{4\bar{x}^\top V \bar{x}}\right), \quad (1.55)$$

where we defined the bilinear form  $\Omega = V x x^\top V^\top$ .<sup>5</sup>

Let us consider a simple example of this as a sanity check: suppose that  $x$  is two-dimensional, and  $\bar{x}(\Theta) = (\cos \Theta, \sin \Theta)^\top$ ; further, suppose that  $V$  is diagonal, so that

$$V = \begin{bmatrix} \sigma_x^{-2} & 0 \\ 0 & \sigma_y^{-2} \end{bmatrix}. \quad (1.56)$$

Also, suppose that the observed data parameter is

$$x = A_x \begin{bmatrix} \cos \varphi \\ \sin \varphi \end{bmatrix}. \quad (1.57)$$

Then, the multiplicative constant in front of the marginalized posterior reads

$$B_2 = B_1 \exp\left(-\frac{1}{2} A_x^2 \left(\frac{\cos^2 \varphi}{\sigma_x^2} + \frac{\sin^2 \varphi}{\sigma_y^2}\right)\right); \quad (1.58)$$

while the bilinear form  $\Omega$  is

$$\Omega = A_x^2 \begin{bmatrix} \sigma_x^{-2} & 0 \\ 0 & \sigma_y^{-2} \end{bmatrix} \begin{bmatrix} \cos^2 \varphi & \cos \varphi \sin \varphi \\ \cos \varphi \sin \varphi & \sin^2 \varphi \end{bmatrix} \begin{bmatrix} \sigma_x^{-2} & 0 \\ 0 & \sigma_y^{-2} \end{bmatrix} \quad (1.59)$$

$$= A_x^2 \begin{bmatrix} \cos^2 \varphi / \sigma_x^4 & \cos \varphi \sin \varphi / \sigma_x^2 \sigma_y^2 \\ \cos \varphi \sin \varphi / \sigma_x^2 \sigma_y^2 & \sin^2 \varphi / \sigma_y^4 \end{bmatrix}. \quad (1.60)$$

Then, when we evaluate the marginalized posterior we will find something in the form

$$P(\Theta|x) = B_1 \sqrt{\pi} \left(\frac{\cos^2 \Theta}{\sigma_x^2} + \frac{\sin^2 \Theta}{\sigma_y^2}\right)^{-1/2} \exp\left(A_x^2 F(\Theta, \varphi)\right), \quad (1.61)$$

where  $F(\Theta, \varphi)$  is some function whose specific form does not really matter; the point is that the amplitude of the observed data vector,  $A_x$ , appears only as a multiplicative prefactor: its exact value will be taken care of by the evidence, and it cannot affect the shape of the distribution. Therefore, we see that by marginalizing over  $A$  we have “forgotten” any scaling information about  $x$ .

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<sup>5</sup> With explicit indices,  $\Omega_{im} = V_{ij} x_j x_k V_{km}$ .