

Advanced astrophysics notes

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1 Introduction

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1.1 Topics

They are selected topics in stellar physics.

1. Stellar pulsations and Astroseismology (dr. Michele Trabucchi);
2. stellar winds (dr. Paola Marigo);
3. final fates of massive & very massive stars (dr. Paola Marigo).

Basics in Stellar Physics: “astrophysics II” inside the bachelor’s degree in astronomy (second semester). It can be taken as an optional course.

Material:

1. *Introduction to stellar winds* by Lamers, Cassinelli.
2. *Stellar Atmospheres: Theory and observations* (lecture notes from 1996).

and more on Paola Marigo’s site.

1.1.1 Stellar Winds

Moving flows of materials ejected by stars. 20 to 2×10^3 km/s.

See *Bubble Nebula* in Cassiopea, there is a $45M_{\odot}$ star ejecting stellar wind at 1700 km/s.

Diagram: luminosity vs effective temperature. We see the *main sequence*. We can also plot the *mass loss rate*, $\dot{M} > 0$ in solar masses/year. An other important parameter is v_{∞} .

Diagram: mass loss (or gain) rate vs age of star.

Stellar winds affect stellar evolution, the dynamics of the interstellar medium, the chemical evolution of galaxies.

Momentum is approximately injected with $\dot{M}v$, kinetic energy with $1/2\dot{M}v^2$. Within 1×10^8 yr around half of the infalling matter is reemitted.

1.1.2 Contents

We will start with the basic theory of stellar winds, and then: *coronal*, *line-driven* and *dust-driven* winds.

1.2 Final fates of massive & very massive stars

Masses over $10M_{\odot}$.

1.3 Stellar oscillations

...see slides.

Material: slides on moodle or Marigo's page.

1. *Pulsating stars* by Catelan & Smith (introductory);
2. *Theory of stellar pulsation* by Cox (harder).

Written exam, partial exam on stellar pulsation.

2 Variability in Astronomy

First observations of variable stars: ~ 1600 , omicron-Ceti. It changes in magnitude by 6 orders of magnitude.

Others are found from the 1600 onwards, but since the XX century the reason is unknown. Is it *rotation*, *eclipses*?

For some it sure are eclipses, but the Cepheids are different. See δ -Cephei, asymmetric continuous curve. What if stars *pulsate*?

The *light curve* is the luminosity curve over time.

We can also look at the *phased* light curve. Of course we need the period: the phase is

$$\varphi = \frac{(t - t_0) \bmod \Pi}{\Pi} \quad (1)$$

where Π is the period. $E(t) = \lfloor (t - t_0)/\Pi \rfloor$ is the epoch.

We can then measure the period, but if the light curve is multiperiodic we can subtract the model from the curve to see if there are additional periods: this is *prewhitening*.

We can also look at the luminosity in Fourier space.

Of course there are issues with observational gaps (day-night, full moon): aliases; accuracy, duration of observations. . .

Also, the period can change in time.

Things have improved a great deal with large-scale surveys and space suveys.

2.1 Classification

By variability type: regular, semi-regular or irregular.

By intrinsic variability: extrinsic, external to the star: eclipses, transits, microlensing, rotation; intrinsic: rotation, eclipses (self-occultation), eruptive and explosive variables, oscillations, secular variations (?).

Whether rotation is to be considered intrinsic or extrinsic is a matter of taste.

Oscillations can be classified by several criteria.

The geometry can be radial (classical pulsators) or non-radial.

The restoring force can be the pressure gradient or the gravitational force (bouyancy, not gravitational waves).

The excitation mechanisms can be different.

The evolutionary phase and mass of the star can also be different.

3 Summary of stellar structure & evolution

Eulerian: properties of a gas are fields, the position is the position of an observer. To differentiate position with respect to time is meaningless: position is an independent variable. $f = f(r^i, t)$.

Lagrangian: we follow an element of fluid: $dr^i/dt = v^i$. We can identify univocally these fluid elements.

When treating stellar structure & evolution, we look at mass layers dm . $f = f(m, t)$. Do note that m is the mass of the whole full sphere under a certain layer, not the mass of the shell.

In the lagrangian case, we use the convective derivative $d/dt = \partial_t + v^i \partial_i$ where v^i is the velocity defined before.

3.1 Equations of stellar structure

We write these in the spherically symmetric case.

The continuity equation is:

$$\frac{\partial r}{\partial m} = \frac{1}{4\pi r^2 \rho}. \quad (2)$$

Momentum conservation is given by:

$$\frac{\partial P}{\partial m} = -\frac{Gm}{4\pi r^4}, \quad (3)$$

where

Energy conservation is given by:

$$\frac{dL}{dm} = \varepsilon - \varepsilon_\nu - \varepsilon_g, \quad (4)$$

where L is the luminosity, ε is the rate of nuclear energy generation per unit mass, while ε_ν is the rate of energy loss due to neutrino emission per unit mass, and ε_g is the work done by the gas per unit mass & time.

The energy transfer equation is:

$$\frac{\partial T}{\partial m} = -\frac{GmT}{4\pi r^4 P} \nabla, \quad (5)$$

where $\nabla = \partial \log T / \partial \log P$ is the temperature gradient, which has contributions from radiation, conduction, convection...

With the diffusion approximation, we can write the gradient as

$$\nabla = \nabla_{\text{rad}} = \frac{3}{16\pi acG} \frac{\kappa_R LP}{mT^4}, \quad (6)$$

where a is a constant depending on the Stefan-Boltzmann constant and the speed of light.

where κ_R is the Rosseland mean opacity, given by

$$\frac{1}{\kappa_R} = \frac{\int_0^\infty \frac{dB_\nu}{dT} \frac{1}{\kappa_\nu} d\nu}{\int_0^\infty \frac{dB_\nu}{dT} d\nu} \quad (7)$$

Substituting in the result in (6) we get:

$$L = -\frac{64\pi^2 ac}{3} r^4 \frac{T^3}{\kappa} \frac{\partial T}{\partial m} \quad (8)$$

where κ is a generalized opacity, the harmonic mean of the Rosseland opacity κ_R and the convective opacity $\kappa_c = 4acT^3 / (3\rho\lambda_c)$.

Where λ_c is...?

If we need to deal with convection, this defies any simple modeling. There are instability criteria: where is it relevant? This is given by Ledoux's criterion,

$$\nabla_{\text{rad}} > \nabla_{\text{ad}} - \frac{\chi_\mu}{\chi_T} \nabla_\mu, \quad (9)$$

where:

$$\nabla_\mu = \frac{d \log \mu}{d \log P} \quad (10a)$$

$$\nabla_{\text{ad}} = \left(\frac{\partial \log T}{\partial \log P} \right)_{\text{ad}} \quad (10b)$$

$$\chi_\mu = \left(\frac{\partial \log P}{\partial \log \mu} \right)_{\rho, T} \quad (10c)$$

$$\chi_T = \left(\frac{\partial \log P}{\partial \log T} \right)_{\rho, \mu} \quad (10d)$$

which are thermodynamic parameters.

how are these called? What do they mean?

In the convective core, $\nabla \approx \nabla_{\text{ad}}$, but outside of it we need something else.
Mixed-length theory model convection with "bubbles":

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Figure 22.8 in some PDF: run of adiabatic, radiation gradients vs $\log T$.

We compute ∇_{ad} and ∇_{rad} and see whether the region is convective or radiative.

We can move from the Eulerian and Lagrangian formalisms using the continuity equation. In the Eulerian formalism:

$$m(r) = \int_0^r 4\pi r'^2 \rho(r') dr' . \quad (11)$$

We need several *constitutive equations* for the parameters ρ , c_P (heat capacity of stellar matter), the opacity κ , the nuclear transformation rate r_{ij} and the rate of generation of nuclear energy ϵ . These can all be considered as functions of P , T , μ .

We define:

$$\mu^{-1} = \sum_i (1 + v_i) \frac{X_i}{A_i} \quad (12)$$

(CHECK)

The variables X , Y and Z represent the abundances of H, He and metals, and satisfy $X + Y + Z = 1$.

We may need to know the metal mixture inside Z , but often we can approximate it as the Sun's distribution.

$$\frac{\partial X_i}{\partial t} = \frac{m_i}{\rho} \sum_j (r_{ji} - r_{ij}) \quad (13)$$

3.2 Classification of stars

Low mass stars have between 0.8 and 2 solar masses. Intermediate mass stars have masses between 2 and $8 M_{\odot}$. Massive stars have masses of over $8 M_{\odot}$. (Add characteristics of these).

3.2.1 Low-mass star evolution

See slides for figures. What are Hayashi lines?

3.2.2 Intermediate-mass star evolution

Idem

4 Stellar oscillations

Today we will look at typical time-scales, the period-mean density relation, the energy equation and perturbation theory w/ linearization.

No derivations of the equations in the exam.

4.1 Time-scales

The *free fall* time scale is:

$$\tau_{\text{dyn}} \sim \left(\frac{R}{g} \right)^{1/2} = \left(\frac{R^3}{GM} \right)^{1/2}, \quad (14)$$

this is associated with pulsation. It is calculated using the travel time of a mass in free fall across the stellar radius accelerated by constant acceleration equal to surface acceleration.

We note that $\tau_{\text{dyn}} \propto \bar{\rho}^{-1/2}$. For the Sun it is about 25 min.

The *thermal* time scale is the relaxation time of deviations from thermal equilibrium:

$$\tau_{\text{th}} \sim E_{\text{th}}/L. \quad (15)$$

It is calculated as the time required for a star to irradiate all its energy.

Proof. Roughly, $3 \int_V P \, dV = -\Omega$ with $\Omega = - \int_M \dots$ □

Typically, $\tau_{\text{th}} \sim GM^2/(LR) \sim 10^7 \dots$ It is much larger than the dynamic time scale.

The *nuclear* time scale is even longer.

This allows us to say that oscillations will not be heavily affected by thermal conduction, and even less by nuclear processes: the pulsations will be almost *adiabatic*.

The best candidate for these oscillations are *sound waves*: is the adiabatic speed of sound roughly right?

The speed of sound is:

$$v_s^2 = \Gamma_1 \frac{P}{\rho} \quad (16)$$

If the gas follows the perfect equation of state

$$\frac{P}{\rho} = \frac{k_B T}{m_H \mu}, \quad (17)$$

we get

$$v_s^2 = \frac{\Gamma_1 k_B T}{m_H \mu}. \quad (18)$$

Typical values are $\mu \sim (2X + 3Y/4 + Z/2)^{-2} \sim 0.6$, $\Gamma_1 = 5/3$, and $T_{\text{He}} \sim 4.5 \times 10^4 \text{ K}$.

So we get $v_s \sim 32.2 \text{ km/s}$.

The timescale is $\Pi \sim 2R/v_s \sim 22 \text{ d}$, while $\Pi_{\text{obs}} = 5.336 \text{ d}$, in terms of orders of magnitude it works.

We can use the equation for the sound speed in the virial theorem, and get:

$$\Omega = -3 \frac{\int_M v_s^2 / \Gamma_1 \, dm}{\int_M dm} M = -3 \left\langle \frac{v_s^2}{\Gamma_1} \right\rangle M \quad (19)$$

If Γ_1 and v_s are independent, we can compute their averages separately.

This allows us to write Π wrt the moment of inertia, $I = \int_r r^2 \, dm(r)$:

$$\Pi \sim \left(\frac{I_{\text{osc}}}{-\Omega} \right)^{1/2} \quad (20)$$

This is further evidence that we are dealing with a dynamical phenomenon.

Of course the speed of sound changes throughout the interior of the star. We compute the period as the travel time of sound waves throughout the diameter:

$$\Pi = 2 \int_0^R dt(r) = 2 \int_0^R \frac{dr}{\sqrt{\Gamma_1(r)P(r)/\rho(r)}}, \quad (21)$$

since $dt = dr / v_s$.

We also rewrite the differential equation for P substituting $m = \rho r$. Doing this we get

$$\Pi \bar{\rho}^{1/2} = \sqrt{\frac{3\pi}{2\Gamma_1 G}} \quad (22)$$

Which confirms Ritter's relation $\Pi \propto \bar{\rho}^{-1/2}$.

This works for acoustic modes, but if we consider non-radial g-modes it stops working, such as variables of type ZZ Ceti.

4.2 The energy equations

Just an overview for now: we will consider the star as a thermodynamic engine.

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Reference books can be found in the Moodle: they are ordered by difficulty, Catelan to Aerts to Salaris.

The exam for this part of the course: it might be around the end of october.

The subscripts on last lecture *were* inverted after all.

The *mirror principle*: when the core contracts or expands, the envelope does the opposite.

The shell must remain at around the same temperature to maintain equilibrium: contracting the core would increase the temperature, therefore the envelope expands. This heuristic argument is actually derived from simulations.

The relevant time scale for oscillations is the free-fall, dynamical time scale.

We come back to the energy equation

$$\frac{\partial L}{\partial m} = \varepsilon - \varepsilon_\nu - \varepsilon_g \quad (23)$$

we incorporate $\varepsilon - \varepsilon_\nu = \varepsilon_{\text{eff}}$ and call $\varepsilon_g = \frac{dQ}{dt} = \varepsilon_{\text{eff}} - \frac{\partial L}{\partial m}$.

This makes the meaning of this transfer equation clearer. Using the first and second laws of thermodynamics, and recalling some thermodynamical values $c_V =$

$\left(\frac{\partial Q}{\partial t}\right)_V, \chi_T, \chi_\rho, \Gamma_{1,2,3}$. These are all *exponents* in some power law. We use log values since our variables change by orders of magnitude.

The final result we get from manipulations is:

$$\frac{dQ}{dt} = \frac{P}{\rho(\Gamma_3 - 1)} \left(\frac{\partial \log P}{\partial t} - \Gamma_1 \frac{\partial \log \rho}{\partial t} \right) \quad (24a)$$

$$\frac{\partial \log P}{\partial t} = \Gamma_1 \frac{\partial \log \rho}{\partial t} + \frac{\rho}{P} (\Gamma_3 - 1) \left(\varepsilon_{\text{eff}} - \frac{\partial L}{\partial m} \right) \quad (24b)$$

$$\frac{dQ}{dt} = c_V T \left(\frac{\partial \log T}{\partial t} - (\Gamma_3 - 1) \frac{\partial \log \rho}{\partial t} \right) \quad (24c)$$

$$\frac{\partial \log T}{\partial t} = (\Gamma_3 - 1) \frac{\partial \log \rho}{\partial t} + \frac{1}{c_V T} \left(\varepsilon_{\text{eff}} - \frac{\partial L}{\partial m} \right) \quad (24d)$$

The second and fourth of these equations substitute our equation of energy conservation.

Say we have a solution for these equations, we look at linear perturbations of them. This makes sense: the main solution is basically static on the pulsation time-scales.

The perturbed model is $f = f(m)$, the unperturbed one is $f_0(m)$. The Lagrangian perturbation is $\delta f(m, t) = f(m, t) - f_0(m, t)$.

Let us consider specific cases for r : the radial displacement is $\delta r(m, t)$. The position of the layer at time t is $r = r_0 + \delta r$.

We can write:

$$r = r_0 \left(1 + \frac{\delta r}{r_0} \right) = r_0 (1 + \zeta). \quad (25)$$

In general the fractional perturbation $\delta f / f_0$ is assumed to be $\ll 1$. So, $\delta f / f_0 \sim \delta_f / f$. We will insert expressions which are functions of perturbations of all our variables, and thus get linear differential equations.

Let us try the continuity equation: $r = r_0(1 + \zeta)$ and $\rho = \rho_0(1 + \delta\rho/\rho_0)$.

$$\frac{\partial}{\partial m} (r_0(1 + \zeta)) = \frac{1}{4\pi r_0^2} (1 + \zeta)^{-2} \left(1 + \frac{\delta\rho}{\rho_0} \right)^{-1} \quad (26)$$

and we use $(1 + x)^n \approx 1 + nx$:

$$4\pi\rho_0^2 \left(\frac{\partial r_0}{\partial m} (1 + \zeta) + r_0 \frac{\partial \zeta}{\partial m} \right) = (1 - 2\zeta) - \frac{\delta\rho}{\rho_0} \quad (27)$$

We can collapse the equation into:

$$\frac{\delta\rho}{\rho_0} = -3\zeta - 4\pi r_0^3 \rho_0 \frac{\partial \zeta}{\partial m} \quad (28)$$

or, the density perturbation is proportional with a negative constant to the radial perturbation, plus a term proportional to $\partial\zeta/\partial m$. If there is a positive gradient of radial perturbation, the corresponding layer expands.

Let us also perturb the momentum conservation equation, assuming hydrostatic equilibrium $\partial^2 r_0/\partial t^2$.

We have a purely geometric term $-16\pi r_0^2 \zeta \partial P_0/\partial m = 4\zeta Gm/r_0^2$: when a layer moves outwards it expands. There is a restoring force toward equilibrium.

Let us also consider the $\log P$ form of the energy conservation equation. We also perturb the adiabatic exponents and the dQ/dt term.

After difficult manipulations we get back an equation which relates the changes in density and pressure to the change in energy: we manipulate until we get something which is similar to the original equation.

In general for a Lagrangian perturbation $\delta(f^n) = n f_0^{n-1} \delta f$. We have rules for the perturbation of product which work just like logarithmic derivatives. δ commutes with partial derivatives.

In the radiative case with the diffusion approximation we can perturb the luminosity: $L \propto r^4 T^4 \kappa_R^{-1} \frac{\partial \log T}{\partial m}$.

$$\frac{\delta L}{L_0} = 4\zeta + 4\frac{\delta T}{T_0} - \frac{\delta \kappa_R}{\kappa_{R,0}} + \frac{\frac{\partial}{\partial m} \frac{\delta T}{T}}{\frac{\partial \log T}{\partial m}} \quad (29)$$

In the end, we have a set of four linear PDE equations (written as a 5-equation system).

These describe implicitly how the properties of the star change over time.

Pulsation usually affects mostly the outer layers of a star.

Moving on to

5 Adiabatic oscillations

Exploiting the adiabatic approximation we will get the LAWE: Linear Adiabatic Wave Equation: a single equation which summarizes the 4.

This can be solved explicitly.

We suppose that each layer does not lose nor gain heat: $\delta(\varepsilon_{\text{eff}} - \partial L/\partial m) = 0$.

Is this approximation justified? The term multiplying $\delta(\varepsilon_{\text{eff}} - \partial L/\partial m)$ in the perturbed energy equation is $\rho/P(\Gamma_3 - 1) = \chi_T/(c_V T)$. Usually $\chi_T \sim 1$, $\Gamma_1 \sim 1$.

This term, $\chi_T/(c_V T)\delta(\varepsilon_{\text{eff}} - \partial L/\partial m)$, is of the order $1/\tau_{\text{th}}$, the thermal time scale of this layer, while the term before, $\Gamma_1 \partial/\partial t (\delta\rho/\rho)$, is of the order $1/\tau_{\text{dyn}}$, the dynamical time scale.

Therefore, we neglect the second part. This only works for the star as a whole, not for single layers. There are stellar layers which are *strongly* non-adiabatic (driving

layers). We will need some non-adiabatic theory to explain how pulsations *start*.
 [Insert derivation of the LAWE, which can be found in the slides].

$$r \frac{\partial^2 \zeta}{\partial t^2} = 4\pi r^2 \zeta \frac{\partial}{\partial m} ((3\Gamma_1 - 4)P) + \frac{1}{r} \frac{\partial}{\partial m} \left(16\pi^2 \Gamma_1 P \rho r^6 \frac{\partial \zeta}{\partial m} \right) \quad (30)$$

We decompose: $\zeta(m, t) = \eta(m) e^{i\sigma t}$ with a constant σ : putting this into the LAWE we simplify the exponentials and get the space dependent form of the LAWE. It is a Storm-Liouville equation.

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Last lecture we started talking about linearization & perturbation theory.

We will have analytic solutions for the adiabatic case, with the additional hypotheses of either $\Gamma_1 = 4/3$ or $\Gamma_1 > 4/3$ and homogeneity.

The justification of the adiabatic approx might be asked at the exam.

After plugging our ansatz in the LAWE we should take the real part.

What are the boundary conditions we should set?

1. $\delta r = 0$ at $r = 0$;
2. $\partial \eta / \partial r = 0$ at $r = 0$, which allows us to fix many divergences at the center;
3. $(4 + R^3 \sigma^2 / (GM)) \eta + \delta P / P = 0$ at $r = R$;
4. $\eta = \delta r / r = 1$ at $r = R$.

What is the $\frac{\partial^2 \eta}{\partial r^2}$ stuff about?

We use the Eulerian form of the LAWE to figure out the surface boundary conditions. We assume that all perturbation are in phase, and write them all as proportional to $\exp(i\sigma t)$. The pressure scale height is defined as:

$$H_P = - \left(\frac{\partial \log P}{\partial r} \right)^{-1} \quad (31)$$

and represents “how far we should move in the star for the pressure to change e -fold”. By inserting this in the equation we see that $H_P \rightarrow 0$ when $r \rightarrow R$: the pressure changes very quickly in the photosphere of the star. Therefore, the term multiplying it must also go to zero.

The last condition comes from the fact that we want our study to give us *periods*, not *amplitudes*: we cannot find those out, so we normalize. The LAWE is 1-homogeneous!

The LAWE can be written compactly with a linear operator \mathcal{L} :

$$\mathcal{L}(\eta) = \sigma^2 \eta, \quad (32)$$

therefore the eigenvalue is the square of the pulsation. There are infinitely many solutions to the LAWE, only (finitely many?) fulfill the boundary condition. The eigenvalues are real [\mathcal{L} is Hermitian], have a wavefunction associated: $\eta_m(r)$ corresponding to σ_m^2 .

If $\sigma^2 > 0$ we have an oscillating solution, if $\sigma^2 < 0$ we have an exponential collapse or explosion since the solution is proportional to $\exp(i\sigma t)$.

We label solutions by *radial order* $m \in \mathbb{N}$: $m = 0$ has the lowest frequency, and then we have overtones. We choose the labels so that $\sigma_{m_1} < \sigma_{m_2} \iff m_1 < m_2$.

The radial order m is also the number of nodes.

The eigenfunctions are orthogonal wrt the scalar product

$$\langle \eta_m | \eta_n \rangle = \int_0^R \eta_m \eta_n \rho r^4 dr \quad (33)$$

Possibly there is a 4π missing in order for this to be consistent with the following?

The functions ζ_m are orthogonal wrt the same product. The system is linear: we can write a general solution as a superposition.

We can define the moment of inertia:

$$J_m = \int_0^M |\zeta_m|^2 r^2 dm \quad (34)$$

and the following holds:

$$\sigma_m^2 = \frac{1}{J_m} \int_0^M \zeta_m^* \mathcal{L} \zeta_m r^2 dm \quad (35)$$

5.1 Simplifications

5.1.1 Period-mean density relation

If $\eta = \text{const}$, and ρ and Γ_1 are also constant, we immediately get:

$$\sigma^2 = (3\Gamma_1 - 4) \frac{GM}{r^3} \quad (36)$$

and by inserting the mean density formula we get the period-mean density relation: this is consistent with our previous assumptions.

5.1.2 Polytropic model

It is a gas sphere with the following constitutive equation:

$$P = K_n \rho^{1+1/n} = K_n \rho^{\frac{n+1}{n}} \quad (37)$$

with varying *polytropic* index n . It models spheres with different mass distributions: $n = 0$ is constant density, $n = 5$ is infinite central density, $n = 3$ is the Eddington standard model, which is reasonable for the Sun and stars on the main sequence.

With these assumptions we can explicitly solve for the wavefunctions, and make predictions of the fractional modulus of the oscillations at a certain radius wrt the modulus at the surface (which can be found only experimentally).

The overtones die out toward the center even faster than the fundamental: these oscillations are very much a *surface phenomenon*.

Beyond the η s we can also plot the pressure perturbations: these will not be normalized.

5.1.3 A concrete example

This is done looking at an RR Lyrae variable. We integrate the stellar structure equations numerically. We can see that $\sigma_m - \sigma_{m-1} \approx \text{const}$ when m gets large.

The wavefunctions die out faster than the polytropic model when $r \rightarrow 0$.

There are “bumps” in the pressure plot: these are the partial ionization regions of H and He.

These appear because we start from a solution of the stellar structure equations, where all the properties of stellar matter were used, to start off with the LAWE.

6 Non-adiabatic oscillations

How can we tell, theoretically, how stable and how wide the various modes are? We expect to see the stable modes, and not to see the unstable ones.

Let us start from the Lagrangian momentum conservation:

$$\frac{\partial^2 r}{\partial t^2} = -4\pi r^2 \frac{\partial P}{\partial m} - \frac{Gm}{r} \quad (38)$$

and apply to it the identity: $1/2 \frac{\partial}{\partial t} v^2 = \frac{\partial r}{\partial t} \frac{\partial^2 r}{\partial t^2}$, by multiplying everything by $\partial r / \partial t$.

We then integrate everything with respect to m and apply some manipulations [see slides].

$$\frac{\partial}{\partial t} \int_M \frac{v^2}{2} dm = -\frac{d\Omega}{dt} + \int_M P \frac{\partial}{\partial t} \frac{1}{\rho} dm \quad (39)$$

We integrate a pulsation period, which cancels out the gravitational potential term which is conservative.

$$\left\langle \frac{dW}{dt} \right\rangle_{\Pi} = \frac{1}{\Pi} \int_{\Pi} \int_M P \frac{\partial}{\partial t} \left(\frac{1}{\rho} \right) dm dt \quad (40)$$

Some layers will provide energy to the oscillation motion (*drive* it), some others will *damp* it. These are characterized by the sign of the RHS of this equation.

If it is positive, we have instability; if it is negative the pulsations will tend to die out, giving stability.

The average time scale of change of the perturbations is

$$\kappa \stackrel{\text{def}}{=} \frac{1}{\tau} = -\frac{1}{2} \frac{\left\langle dW/dt \right\rangle_{\Pi}}{\left\langle \delta\psi \right\rangle_{\Pi}} \quad (41)$$

The term $\left\langle dW/dt \right\rangle_{\Pi}$ can also be interpreted as the net heat gain fed into mechanical work during a pulsation cycle.

In the adiabatic case, we had $\frac{\partial}{\partial t} \left(\frac{\delta P}{P} - \Gamma_1 \frac{\delta \rho}{\rho} \right) = 0$: the perturbations were in phase.

Now we add a term to the time derivatives: the pressure and density perturbations will stop being in phase. The sign of the heat variation term gives us the difference between *driving* heat transfer and *damping* heat transfer.

In a PV diagram, we can see that these correspond to right and left oriented loops (as opposed to the loops with zero total signed area we had in the adiabatic case).

The star is effectively a thermal engine converting heat into work; this will result in an increased overall entropy of the star, and a smoothing of its temperature gradient, however:

1. the timescales on which this process occurs are much larger than the timescales on which oscillating motions are created and destroyed;
2. then energies of the oscillations are much smaller than the global thermal energy of the star.

therefore this process is typically not relevant.

Mon Oct 14 2019

Summary of past lectures: we discussed:

1. the different time scales of stellar evolution, and their impact on the adiabatic approximation;
2. easy approximations for stellar pulsation;
3. acoustic approximations;
4. Ritter's relation;
5. linearized structure equations: the adiabatic approximation (arguments for it!), deriving the LAWE;
6. examples of solutions to the LAWE and stability conditions;
7. the LNAWE: today;

We consider the LNAWE: inside of $\zeta(r, t) = \eta(r)e^{i\sigma t}$ we insert $\sigma = \omega + i\kappa$: this means we also consider *damped* exponential solutions and *diverging* exponential solutions.

The time scales for these parameters are $\omega \sim \omega_{\text{ad}}$, while $\kappa \sim 1/\theta_{\text{th}}$: therefore $\omega \gg |\kappa|$.

Using this result, we can make some useful *quasi-adiabatic* approximations: in the LNAWE we identify the LAWE operator \mathcal{L} , and replace its application to the wavefunction with the corresponding eigenvalue.

We only look at the first order terms in κ . We define the *work integral* C , and then we derive

$$\kappa = -\frac{C}{2\omega^2 J}. \quad (42)$$

We make some considerations on the expression of C , integrate by parts, getting:

$$C = \int_M \left(\frac{\delta T}{T} \right) \delta \left(\epsilon_{\text{eff}} - \frac{\partial L}{\partial m} \right) dm, \quad (43)$$

which allows us to study the mechanisms which create perturbations.

The energy of the vibrations comes from the internal thermal energy of the star, which ultimately comes from thermonuclear reactions.

The two terms in C come respectively from energy generation and transfer.

The ϵ -mechanism is about energy generation, which is assumed to be due to nuclear reactions, without considering neutrino processes: this can happen if the magnitude of the temperature and density perturbations are large enough.

The κ - γ -mechanism: we look at regions where the luminosity gradient and temperature gradient are discordant. This means that the considered stellar layer is absorbing or emitting; this is usually assumed to be happening through free-free interactions (bremsstrahlung and inverse bremsstrahlung).

Tue Oct 15 2019

Today we look at the κ - γ -mechanism.

This deals with the term

$$\int_M \frac{\delta T}{T} \frac{\partial \delta L}{\partial m} dm, \quad (44)$$

which keeps account of the regions in which the two terms multiplied in the integrand are discordant.

The mean Rosseland opacity is approximated by a law in the form:

$$\kappa_R \simeq \bar{\kappa}_R \rho^n T^{-s}, \quad (45)$$

with $n \approx 1$, $s \approx 7/2$ in the case of free-free absorption (inverse & direct bremsstrahlung) in a non-degenerate, totally ionized gas.

This allows us to relate the perturbations in ρ to those in T . However, in this law δT is positive iff $\delta \rho$ is positive: *damping layers*.

Driving layers, however, are present in certain regions: where there is ionization, it provides an additional channel for energy stocking: it is like a *dam* for energy.

The ionization energy is released through mechanical work.

We look at the linearized equations of continuity and radiative transfer for an expression for the gradient of δL : in the outer regions of the star we have $\partial L / \partial m \approx 0$. In these regions $\kappa_R \propto \rho^n T^{-s}$ with negative s .

There is an opacity bump at $5 < \log(T) < 6.5$, which was found in the eighties by Simon. Do note that these are temperatures reached when looking a bit inside the star, not at the surface (although close to it).

There are very luminous *strange modes*, very dim convectively driven modes.

Convective driving is called the δ -mechanism.

There also are *stochastically driven* oscillations: they are intrinsically stable.

The pulsation region has boundaries: for the κ -mechanism:

- if the star is too hot, the regions of partial ionization get too close to the surface;
- if the star is too cold, they are too far in: in the outer region the pulsation is damped.

What is the optimal region? We will only look at the fundamental mode. We define

$$\phi(m) \equiv \frac{1}{L(\Pi/2\pi)} \int_m^M c_V T dm, \quad (46)$$

which represents the thermal balance of a single oscillation.

We are in the helium ionization region: there are no nuclear reactions, so we set energy generation to zero.

$$\frac{\delta T}{T} = (\Gamma_3 - 1) \frac{\delta \rho}{\rho} - i \left(\frac{\partial \phi}{\partial x} \right)^{-1} \frac{\partial}{\partial x} \left(\frac{\delta L}{L} \right), \quad (47)$$

where δT is actually complex, since the perturbations are out of phase.

On the surface, the imaginary term is negligible. In the interior, it is relevant.

The pulsation region is the one in which the ionization region can build up an energy excess.

6.1 RR Lyrae

Now for some star zoology: RR Lyrae. It is a stage, which lasts no more than 10^8 yr.

They are classified by a, b, or c according to the shape of the light curve, its amplitude, its period:

1. RRa: sharp rise, large amplitude: the fundamental;
2. RRb: similar to RRa with smaller amplitude, longer period: the fundamental;
3. RRc: more symmetric light curve, short periods, low amplitudes: they pulsate in the first overtone.

We have also RRd: bimodal, RRe: second overtone.

[Argument for the different amplitudes at different wavelengths: to understand]

[Qualitative part of the lecture.]

Mon Oct 21 2019

We were talking about RR Lyrae variables, classifying them. In a Bailey diagram we plot variables as points with the coordinates amplitude and period.

We can tell whether a star is a RR Lyr variable, and then we can use it as a standard candle.

We have nonlinear models which accurately predict the light curves. There are HUMPs, BUMPs, JUMPs and LUMPs in the light curves: they tell us about the propagation of shock waves in the star.

We also have the Blazhko Effect: when it is not present, the light curve is the same at every cycle; when it is present the light curve changes, it is modulated every cycle. This is a poorly understood effect, it might have something to do with magnetic fields.

In a given Globular Cluster, we look at the distribution of RR Lyr with respect to period: we can see two distinct clusters, corresponding to the fundamental and first harmonic. We can characterize them with respect to the Oosterhoff group (the one of the fundamental): if it is big with respect to the first harmonic it is a type I, if it is comparable it is a type II.

6.2 Classical Cepheids

They are younger than RR Lyr. They are very important if the *cosmic distance ladder*.

We have a very important Period-Luminosity relation: this can be used to measure distances.

Period is not affected by reddening.

The fundamental relation is

$$L = 4\pi R^2 \sigma T_{\text{eff}}^4, \quad (48)$$

which can be converted into a relation involving the bolometric magnitude. In the end, using the mass luminosity relation of main sequence stars, we have:

$$\log(\Pi) = -0.24M_{\text{bol}} - 3\log(T_{\text{eff}}) + \log(Q) + \text{const}. \quad (49)$$

The derivation of this might be asked at the exam.

7 Non-radial oscillations and astroseismiology

This is just an introduction, a full course might be given at the PhD level.

We use the same assumptions as before, except we lose the spherical symmetry.

We have several families of solutions:

1. *p*-modes, mostly radial, pressure;
2. *g*-modes, mostly horizontal, buoyancy;
3. *f*-modes; without nodes.

We can derive equations for this case similarly to the LAWE.

[Equations]

We get two different velocities of propagation: $L_\ell = \ell(\ell + 1)(v_s/r)^2$ is the Lamb frequency, while $N^2 = -g \left(d \ln \rho / dr - 1/\Gamma_1 d \ln P / dr \right)$ is the Brunt-Väisälä frequency.

We can approximate the differential equations locally as a single differential equation, which is a harmonic oscillator for the perturbation, with wavenumber

$$k_r^2 = -\frac{1}{v_s^2 \sigma^2} \left(L_\ell^2 - \sigma^2 \right) \left(\sigma^2 - N^2 \right). \quad (50)$$

This is negative iff σ^2 is either smaller or larger than both N^2 and L_ℓ^2 ; these are respectively *g* and *p*-modes. If σ^2 is between them, we get a real exponential as a solution. This is called the *evanescent regime*.

p -modes are characterized by a *turning point*: below a certain radius, the mode is in the evanescent regime. For g -modes we have the opposite behaviour: they only exist in the core, and are evanescent for large radii.

We can plot N and L_ℓ as a function of radius.

Mixed modes arise when the evanescent region is thin, therefore the mode can tunnel through.

The frequencies are degenerate in m , but the degeneracy is split when the star is rotating.

In the slide for “asymptotic behaviour”, the y axis is frequency.

We analyze the power spectra of stars.

Tue Oct 22 2019

For the physics undergraduate students: “Fundamental Astronomy” by Karttunen, Kröger, Öja, Poutanen, Donner.

7.1 Red variable stars

They include the ζ Hydrae, SR and Mira stars. These are low temperature stars.

They are evolved stars, and most all of the evolved stars are at least somewhat variable.

Miras, SRVs and OSARGs have very long periods, on the order of a year.

We need good estimates for the radius: because of the period-mean density relation, the fundamental at a certain radius can correspond to the first overtone at a larger radius.

We have different period-luminosity relations corresponding to which overtone we see. Using Weisenheit indices, which compensate for self-reddening, these relations are even more evident.

We can simulate galaxies, and observe the same patterns.

The linear models are not appropriate for the fundamental. Today, we do 3D models.

8 Summary

- $\tau_{\text{dyn}} \propto 1/\sqrt{\bar{\rho}}$;
- the inequality between the timescales;
- variability is due to mechanical, acoustic phenomena!
- derivation of the period-mean density relation;

- the balance of heat absorption;
- meaning of perturbation theory;
- the final result: the perturbed structure equations;
- the adiabatic approximation: justification, cases in which it does not hold: driving layers, stability;
- ideas of how the LAWE is solved (not boundary conditions): the Sturm-Liouville problem;
- the meaning of the solutions of the LAWE: nodes, the shape of the eigenfunctions, orthogonality;
- stability conditions: inequalities which tell us whether a star pulsates or not, driving and damping layers, phase lag;
- NOT the derivation of the LNAWE, but qualitative characterization of its solutions; the expression of the coefficient κ ;
- the ϵ and κ - γ mechanisms: orders of magnitude;
- the opacity bump mechanism;
- the difference between self-excited and stochastically driven oscillation;
- the classical instability strip: not important to know the derivation;
- RR Lyrae, typical parameters;
- Cepheids: derivation of the mass-luminosity relation;
- NOT nonradial oscillations and astroseismiology;
- NOT red variables.

Mon Oct 28 2019

9 Stellar Winds

With Paola Marigo, now.

One should be able to follow this part even without a strong background in stellar astrophysics.

Bubble Nebula in Cassiopeia: a $45 M_{\odot}$ star is ejecting mass at 1.7×10^6 m/s.

Some important quantities: we introduce

1. \dot{M} is the mass loss rate:

$$\dot{M} = -\frac{dM}{dt} > 0; \quad (51)$$

2. v_∞ is the terminal wind velocity, in the limit of radial infinity.

The gas initially escapes from the star at low (subsonic, 1 km/s) velocity; then it is accelerated. It is accelerated, and in the far field when no more forces are acting on it it approaches v_∞ . We describe it with a *velocity law*: $v(r)$, and physically since the force is always radially outward we have

$$\frac{dv}{dr} > 0 \quad (52)$$

for any r . A typical law is something like:

$$v(r) = v_0 + (v_\infty - v_0) \left(1 - \frac{R_*}{r}\right)^\beta, \quad (53)$$

where $\beta \approx 0.8$, and R_* is the radius of the photosphere (where, from infinity, we have an opacity of $\tau = 1$).

In an H-R diagram we can plot the mass loss rate.

The relation $\dot{M}(M)$ seems to be something like a power law: what is it?

We have Massive, Cool Luminous and Solar-type stars.

The momentum input can come either from a force, like radiation pressure; or from heating.

We have:

1. coronal winds: driven by gas pressure;
2. line driven winds: driven by radiation pressure on highly ionized atoms, O and B stars;
3. dust driven winds: due to radiation pressure on dust grains, solid particles, which are very opaque.

Are ionized atoms more opaque to radiation?

We will not consider winds driven by pulsation, sound waves and Alfvén waves (magnetic winds).

We will assume:

1. spherical symmetry;
2. stationarity;

3. no magnetic fields.

The equation of continuity with the hypothesis of stationarity is given by $\dot{M} = 4\pi r^2 \rho(r) v(r) \equiv \text{const.}$

If we differentiate \dot{M} with respect to t we get 0 on the LHS, and on the RHS:

$$0 = 2\rho v + rv \frac{d\rho}{dr} + r\rho \frac{dv}{dr}, \quad (54)$$

where we simplified the 4π . If we divide by $\rho v r$ we get:

$$\frac{2}{r} + \frac{1}{\rho} \frac{d\rho}{dr} + \frac{1}{v} \frac{dv}{dr} = 0, \quad (55)$$

and then this gives us

$$2\log(r)' + \log(v)' + \log(\rho)' = 0, \quad (56)$$

where the prime denotes derivatives with respect to r . The gradients of the velocity and density are related.

The force per unit volume is given by

$$F = \rho \frac{dv}{dt}, \quad (57)$$

and if we divide by ρ we get the force per unit mass:

$$f = \frac{F}{\rho} = \frac{dv}{dt}. \quad (58)$$

Under stationarity ($\partial_t = 0$), we have:

$$\frac{dv}{dt} = v(r) \frac{dv}{dr}. \quad (59)$$

The conservation of momentum gives us the Euler equation:

$$v \frac{dv}{dt} = -\frac{1}{\rho} \frac{dP}{dr} - \frac{GM}{r^2} + f(r), \quad (60)$$

where $f(r)$ is a generic unspecified external force, which we assume to be *outward* (no dissipative effects!).

The projection of $\nabla_\mu T^{\mu\nu} = 0$ along the flow of the fluid u^ν , which is a timelike Killing vector field, gives us the conservation of the energy: the 1st law of thermodynamics.

$$\frac{dQ}{dt} = \frac{du}{dt} + P \frac{d\rho^{-1}}{dt}, \quad (61)$$

where Q is the specific heat, u is the specific internal energy.

The internal energy, for an ideal gas, scales linearly with the temperature:

$$u = \frac{3}{2} \frac{k_B T}{\mu m_u} = \frac{3}{2} \frac{RT}{\mu}, \quad (62)$$

where μ is the mean molecular weight, while m_u is the atomic unit of mass: $R = k_B/m_u$.

We will also assume that the gas pressure follows the ideal gas law:

$$P = \frac{k_B T \rho}{\mu m_u} = \frac{RT \rho}{\mu}. \quad (63)$$

All time derivatives can be written as $\frac{d}{dt} = v \frac{d}{dr}$.

We define

$$q(r) = \frac{dQ}{dr}, \quad (64)$$

the heat input or loss per unit mass per unit distance in the wind. Inserting in the previous equation, we get:

$$q = \frac{3}{2} \frac{R}{\mu} \frac{dT}{dr} + P \frac{d\rho^{-1}}{dr}. \quad (65)$$

These can be incorporated in the global energy equation:

$$\frac{d}{dr} \left(\frac{v^2}{2} + \frac{5}{2} \frac{RT}{\mu} - \frac{GM}{r} \right) = f(r) + q(r), \quad (66)$$

where the expression inside the brackets is the total internal energy. The terms are called A, B, C. This clarifies the claim from before: we can change the internal energy by applying a force.

Was the claim from before not the reverse?

Equation (66) can be written in integral form, by integrating from a generic radius r_0 , we could choose the photospheric radius.

Near the photosphere $|C| \gg A + B$, so $e(r_0) \approx GM/r_0 < 0$.

At large radii $B, C \rightarrow 0$: $e(r_\infty) \approx v_\infty^2/2$.

If we integrate from r_0 at the photosphere to infinity then we get:

$$\frac{v_\infty^2}{2} = -\frac{GM}{r_0} + \int_{r_0}^{\infty} f(r) + q(r) dr, \quad (67)$$

so the sum of the two integrals must be large enough for the gas to escape the gravitational well.

Can't this be made stronger by simply swapping the equality with a less than sign, and integrating not only from r_0 but from any radius?

Now we will treat isothermal winds. These calculations were first done by Parker.

The assumption of constant temperature already gives us $T(r) \equiv T$, and then we do not need the energy equation: there must be an energy input.

So we do not consider the energy equation because energy *is not conserved*?

This is a good model for low \dot{M} , which does not affect the total mass of the star. Tomorrow we will discuss full solutions in this case.

Now, let us talk about the corona. It is very hot: it goes to 10^6 degrees, but with very low density. We see this experimentally by seeing highly ionized elements like $\text{Fe}^{+5 \div 13}$.

Why is this the case? We *do not know*. Magnetism?

Tue Oct 29 2019

Recall the equations from last time: continuity, momentum and energy conservation in the isothermal case:

$$\dot{M} = 4\pi r^2 \rho v \quad (68a)$$

$$v \frac{dv}{dr} = -\frac{1}{\rho} \frac{dP}{dr} - \frac{GM}{r^2} \quad (68b)$$

$$T(r) \equiv T. \quad (68c)$$

The term $\rho^{-1} dP/dr$ is equal to

$$\frac{RT}{\mu} \frac{1}{\rho} \frac{d\rho}{dr}, \quad (69)$$

so we manipulate the equation into

$$v \frac{dv}{dr} = -\frac{1}{\rho} \frac{RT}{\mu} \frac{d\rho}{dr} - \frac{GM}{r^2}, \quad (70)$$

but we know by the continuity equation that

$$-\frac{1}{\rho} \frac{d\rho}{dr} = \frac{1}{v} \frac{dv}{dr} + \frac{2}{r}, \quad (71)$$

which we can substitute into the equation: we get

$$v \frac{dv}{dr} = -\frac{RT}{\mu} \left(\frac{1}{v} \frac{dv}{dr} + \frac{2}{r} \right) - \frac{GM}{r^2}. \quad (72)$$

The isothermal speed of sound is given by

$$a^2 = \frac{\partial P}{\partial \rho} = \frac{\partial}{\partial \rho} \left(\frac{R\rho T}{\mu} \right) = \frac{RT}{\mu}, \quad (73)$$

so

$$v \frac{dv}{dr} = -a^2 \left(\frac{1}{v} \frac{dv}{dr} + \frac{2}{r} \right) - \frac{GM}{r^2}. \quad (74)$$

Now we put all the terms which are proportional to the velocity gradient on the LHS:

$$\frac{dv}{dr} \left(v - \frac{a^2}{v} \right) = \frac{2a^2}{r} - \frac{GM}{r^2}, \quad (75)$$

which is just

$$\frac{1}{v} \frac{dv}{dr} (v^2 - a^2) = \frac{2a^2}{r} - \frac{GM}{r^2}, \quad (76)$$

so the Jacobian of the differential equation is zero is singular in $v = a$: if $v = a$ we must have $2a^2r = GM$, which fixes the radius to the Parker radius: $r_p = GM/2a^2$. Close to the star, the speed is subsonic and the numerator is negative in

$$\frac{1}{v} \frac{dv}{dr} = \frac{N}{D}, \quad (77)$$

which is consistent with our assumption $dv/dr > 0$, which we make since we are considering winds, as opposed to accretion.

Far from the star the numerator is positive, so the speed must still be supersonic.

The critical velocity *must* be attained at the Parker radius in order to have a physically meaningful solution.

The velocity gradient at the critical point can be found by de l'Hôpital's rule to be

$$\left. \frac{dv}{dr} \right|_{r_p} = \pm \frac{a^3}{GM}. \quad (78)$$

So, the only physical solution is transsonic.

Claim 9.1 (Exercise). *The speed of sound at the critical point equals half of the escape velocity at that radius.*

The boundary condition is the velocity at some r_0 .

There are other solutions, but if we trace a cross in the r, v plane centered on the critical point and speed of sound we see that all solutions meet it perpendicular to it.

Accretion solutions are also found in this diagram: what is plotted is the *absolute value* of the velocity. They have always-negative absolute velocity gradient.

Always-supersonic solutions and always-subsonic ones are also found, but they do not obey the monotonicity of the velocity.

The choice we make for $v_0 = v(r_0)$ is key, and nontrivial.

If we have the density, velocity and radius of the lower boundary we have fixed the accretion rate: $\dot{M} = 4\pi r_0^2 \rho_0 v_0$. We can fix these by fixing the constant temperature T and the velocity v_0 at the critical radius r_0 and assuming our solution is transsonic.

What is stated in the slides seems different. What are we fixing?

We can solve the momentum equation analytically: we get

$$\frac{v}{v_0} \exp\left(\frac{-v^2}{2a^2}\right) = \left(\frac{r_0}{r}\right)^2 \exp\left(\frac{GM}{a^2} \left(\frac{1}{r_0} - \frac{1}{r}\right)\right). \quad (79)$$

At large distances, we get $v \rightarrow 2a \ln(r/r_0)$.

Now we look at the structure of the wind in the subcritical region.

In the corresponding slide: the dashed line in the density profile is the density we'd expect in a hydrostatic atmosphere, while the solid one is the solution.

The hydrostatic density structure is given by

$$\frac{1}{\rho} \frac{dP}{dr} + \frac{GM}{r^2} = 0, \quad (80a)$$

manipulating this we get

$$\frac{r^2}{\rho} \frac{d\rho}{dr} = -\frac{GM}{a^2}, \quad (81)$$

So the density profile follows a decreasing exponential law:

$$\frac{\rho(r)}{\rho_0} = \exp\left(\frac{-(r - r_0)}{H_0} \frac{r_0}{r}\right), \quad (82)$$

where H_0 is the scale height, $H_0 = RT/(\mu g_0)$ with $g_0 = GM/r_0^2$. The length scale at which this decreases is defined by H_0 .

The density profile in the subsonic region is very well approximated by this hydrostatic profile.

The mass loss rate is our main prediction: we have $\dot{M} = 4\pi r_0^2 \rho_0 v_0 = 4\pi r_c^2 \rho_c a$.

Then, we can use the density profile equation:

$$\dot{M} = 4\pi r_c^2 a \rho_0 \exp\left(\frac{-(r_c - r_0)}{H_0} \frac{r_0}{r}\right). \quad (83)$$

If we consider this numerically, we find that the exponential is the dominant part. The mass loss rate is lower when the critical point moves outward. We can specify it by fixing

1. the temperature at the corona, T_C ;
2. the radius at the bottom of the corona, r_0 ;
3. the stellar mass M ;
4. the density at the bottom of the corona ρ_0 .

In the slides there are numerical estimates. As H_0 increases, the density profile is less steep: the density remains high at larger radii.

Mon Nov 04 2019

No lectures tomorrow, instead on Wednesday at 14.30.

Last time we found that the only physical solution to the stellar wind is the transsonic solution.