Tabelle 1: Ground Truth - Variable Exclusions

Component	Variable 1	Variable 2	Reason
Rotary Indexing Table	TableInPosition	NOT(TableRotating)	The table cannot be in position and rotating at the same time.
	TableAutomatic	TableManual	The rotary indexing table cannot be in both automatic and manual mode simultaneously.
Station 1	LinearBack1	LinearFront1	The linear unit cannot be in both the rear and front positions simultaneously.
	HandlingUp1	HandlingDown1	The gripper cannot be in both the upper and lower positions simultaneously.
	ClampOpen1	ClampClosed1	The gripper clamp cannot be both open and closed at the same time.
	PartInSingulation1	PartEntered1	Test-part cannot be in both upper singulation and transfer area.
	PreSingulationUp1	PreSingulationDown1	Singulation cannot be in both upper and lower positions simultaneously.
	SingulationDown1	SingulationUp1	Singulation cannot be in both lower and upper position simultaneously.
Station 2	PressingUp2	PressingDown2	The piston cannot be in both the upper and lower positions simultaneously.
Station 3	ClampingUp3	ClampingDown3	Clamping cannot be in both the upper and lower

			positions
			simultaneously.
	PlungerUp3	PlungerDown3	The plunger cannot
	i tangarapa	T tunger bown o	be in both the
			upper and lower
			positions
			simultaneously.
	TriggerBack3	TriggerFront3	The trigger cannot
	Magorbaoko	11188011101110	be in both the rear
			and front positions
			simultaneously.
Station 5	TriggerBack5	TriggerFront5	The trigger cannot
otation o	1118801240110	8891911.0	be in both the rear
			and front positions
			simultaneously.
	ClampingUp5	ClampingDown5	Clamping cannot
		3.0	be in both the
			upper and lower
			positions
			simultaneously.
	PlungerUp5	PlungerDown5	The plunger cannot
			be in both the
			upper and lower
			positions
			simultaneously.
	ContactingBack5	ContactingFront5	Contacting cannot
			be in both the rear
			and front positions
			simultaneously.
Station 6	StampBack6	StampFront6	The stamp cannot
	·	·	be in both the rear
			and front positions
			simultaneously.
Station 7	LinearBack7	LinearFront7	The linear unit
			cannot be in both
			the rear and front
			positions
			simultaneously.
	HandlingUp7	HandlingDown7	The gripper cannot
			be in both the
			upper and lower
			positions
			simultaneously.
	ClampOpen7	ClampClosed7	The gripper clamp
			cannot be both
			open and closed at
			the same time.

LinearInPos7	LinearBack7;	The linear unit
	LinearFront7;	cannot be in both a
		bod position and
		front/rear positions
		simultaneously.
LinearUnitForward7	LinearUnitBack7	The linear unit
		cannot be driven
		forward and
		backward
		simultaneously.