

Lecture 3 - DC

→ noise immunity

Scalability: DC allows ideal regenerⁿ of bits - hence if you can communicate over a link reliably, you are done

① → Infⁿ bits are tx'd without interpretation, the same link can be used for multiple kinds of msgs.

② → Multiple links can be present b/w SRC encoder & dec. with proper error recovery mechanisms - such as retransmission



① & ② have enabled internet

AM:- link perforⁿ depends on message prop., successive links incur noise accumulⁿ & this limits the no. of links that can be cascaded.

Why AM still persists? - RF front end is still analog.

- legacy systems - AM/FM are still in use.

- Modulator in a DC system:-

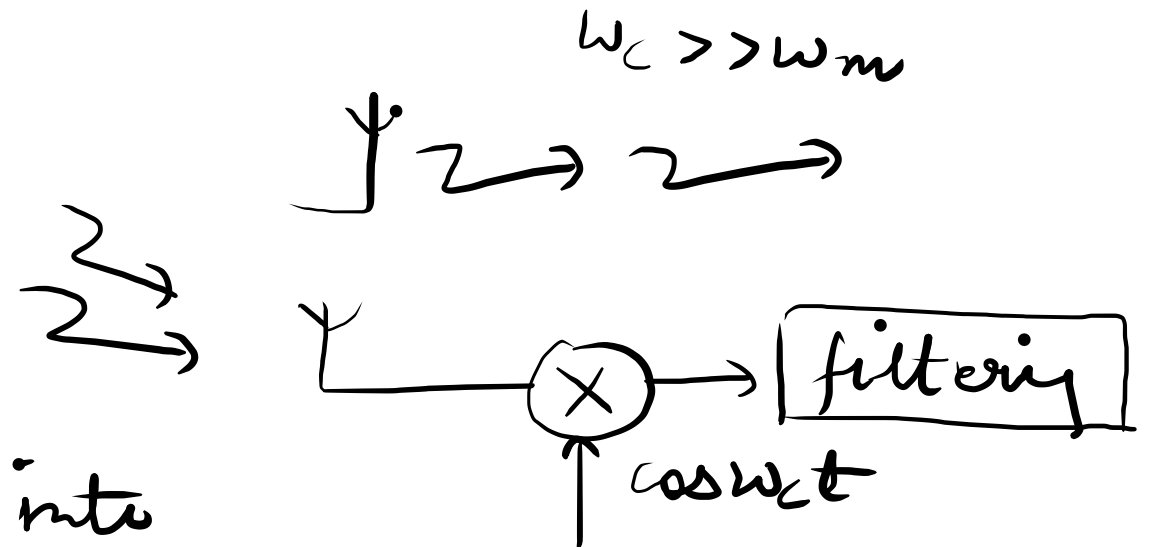
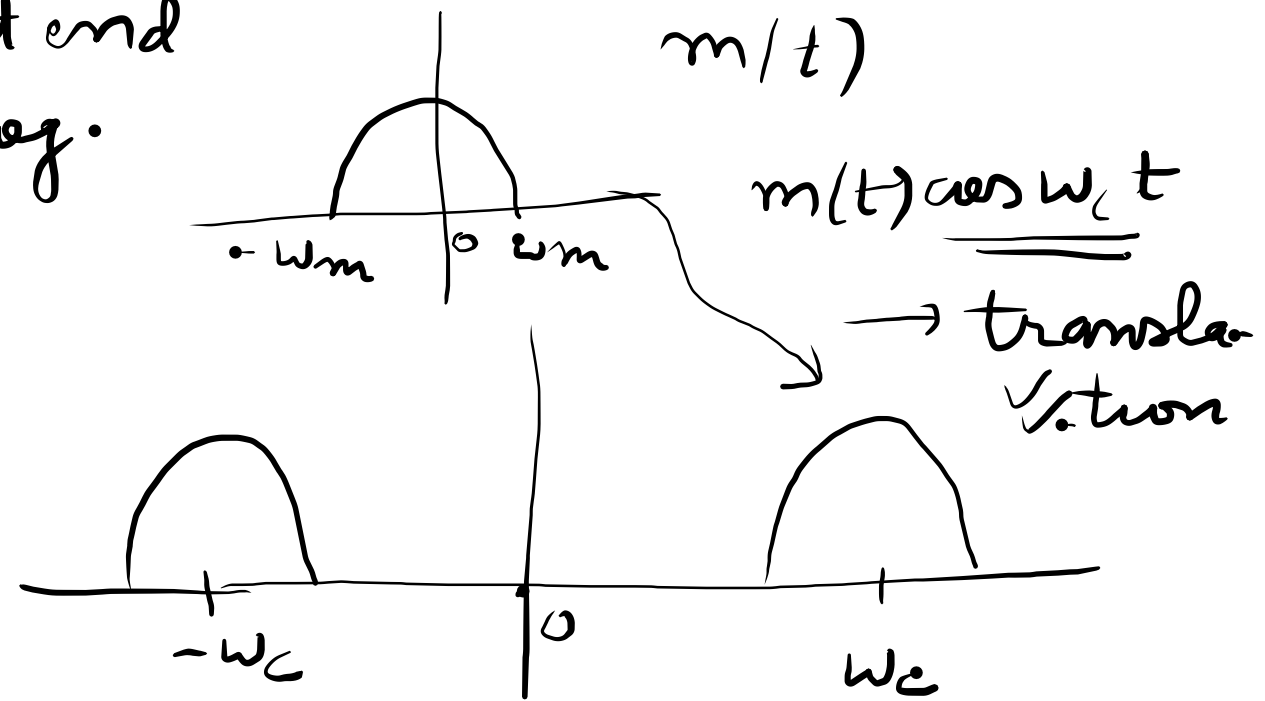
coded bits after channel encoder

→ Tx'd signals

req:- Tx sig. to fit within a given freq. band & adhere to 'stringent power constraint' & 'manage interference'.

bit $0 \rightarrow s(t) \rightarrow s(t)$ must fit into

$1 \rightarrow -s(t)$ spectral constraint. no interf. to other users i.e. band sepⁿ.



successive bits should not interfere with each other.

→ LTI? $f(ax + by) = af(x) + bf(y)$

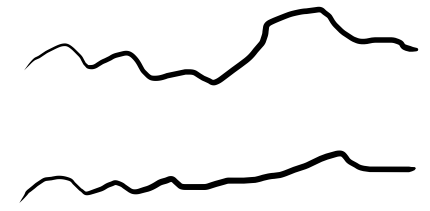
TI $x(t) \rightarrow y(t)$

$\leadsto x(t-t_0) \rightarrow y(t-t_0)$

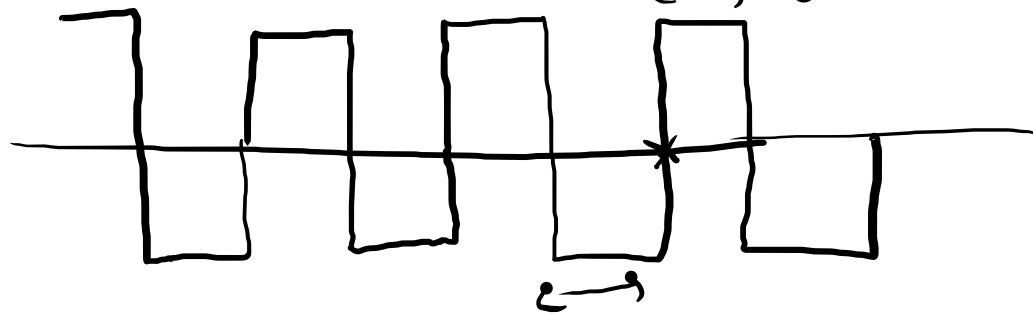
$x(t) \rightarrow \boxed{} \rightarrow y(t)$
 $ \searrow h(t)$

channel:- primarily is LTI but yes
 others models are also
 studied.

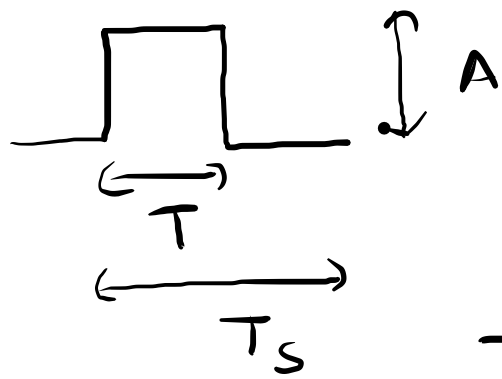
5/8 \swarrow
 6/8 \nearrow 9 \rightarrow 6



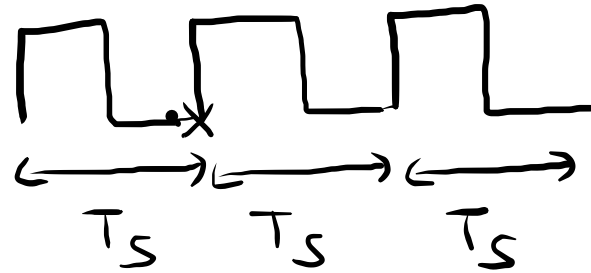
Pulse Modulation (PM) - some parameter of 'periodic' pulse
 train is varied in accordance with the msg.
 sig.



→ amplitude - PAM
 → duration - PWM
 → position - PPM.



$$T < T_s$$



Two types of PM

APM - analog

DPM

Digital

APM - infoⁿ is Txd in analog form but at discrete times

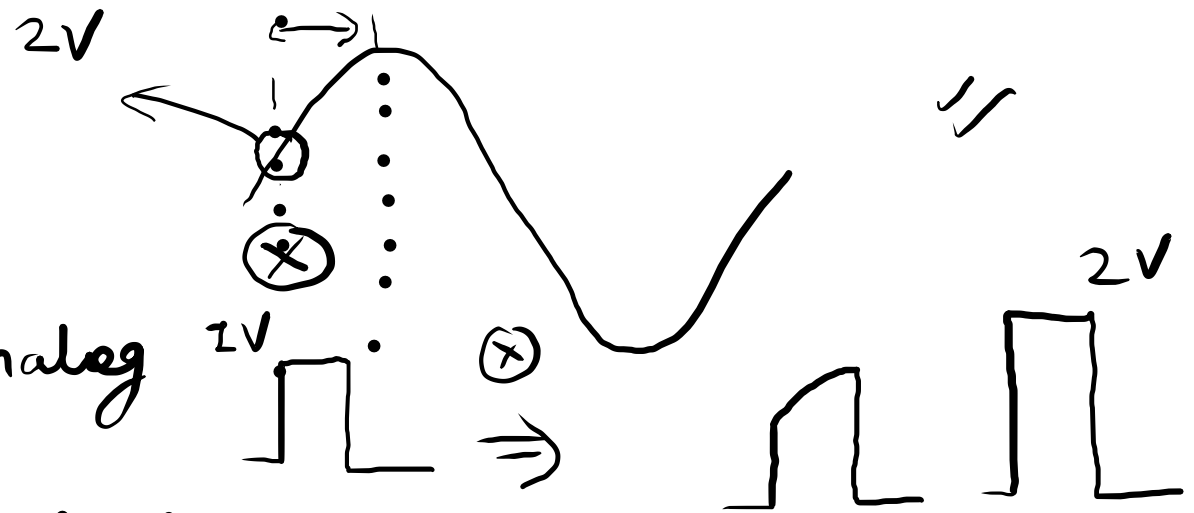
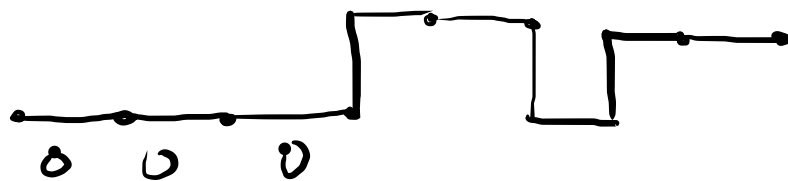
DPM - Message sig. is discrete in time & amplitude both, hence can be txd as seq. of coded pulses.

CW (continuous wave) modulation - some parameter of sinusoidal carrier wave is varied acc. to msg. signal.

{1, 2, 3, 4}

00, 01, 10, 11

! 2, 3, 4



$\{1, 2, 3, 4\}$

1 1 2 2 3 4 1 2 3

↓
↓
0

For DC, the base req. is use of coded pulses for Tx of analog unif^r bearing signals.

Sampling process:- heart of DSP & DC

Analog sig \rightarrow seq. of samples that are 'usually'
spaced uniformly in time.