

AbcRanger

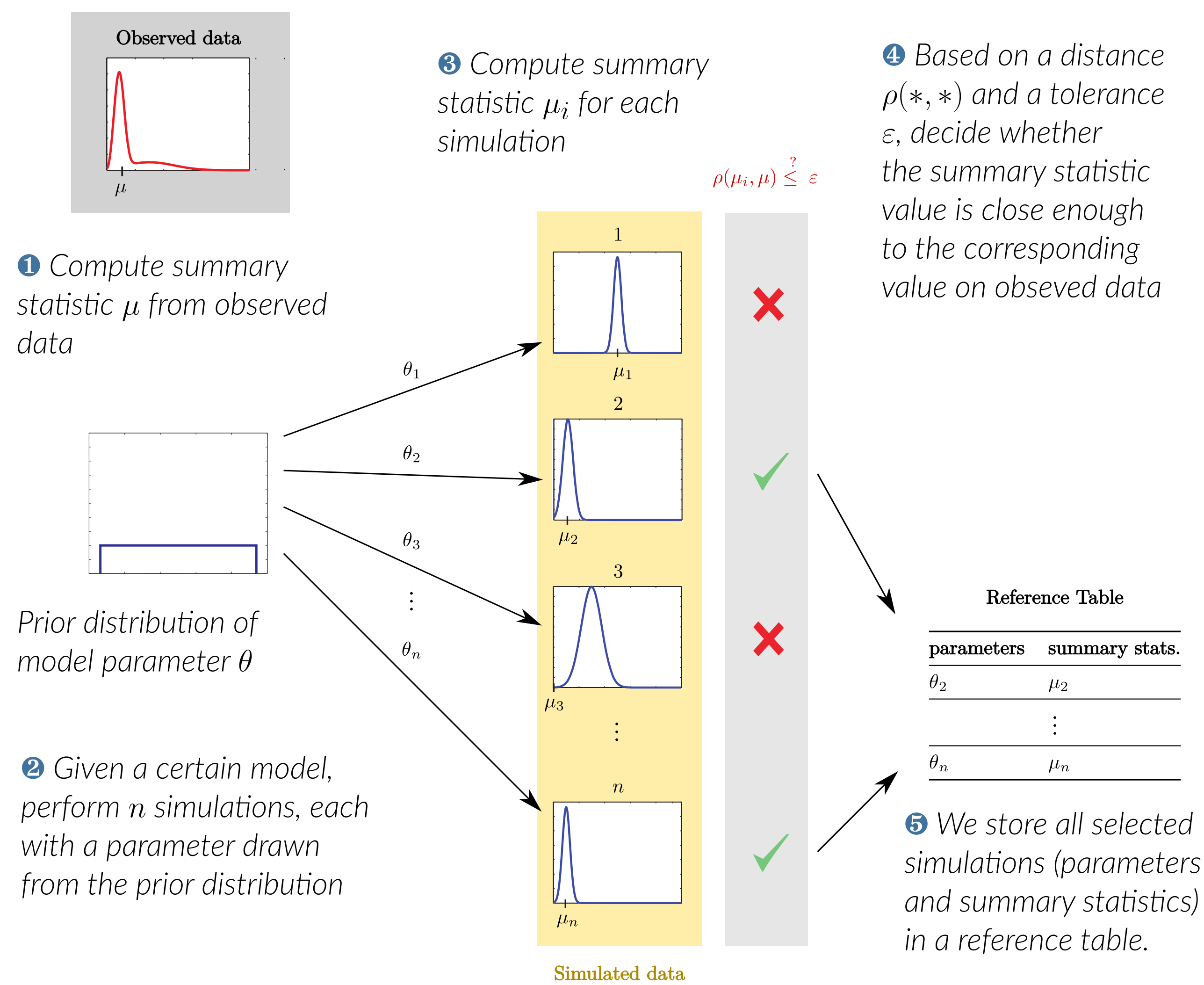
A fast and scalable random forest library for ABC model choice and parameter estimation

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First building block : ABC simulations



Given an observed data, the basic idea of ABC, *Approximate Bayesian Computations* [1], is to approximate the likelihood of a parametrized model with selected simulations, by comparing the observed data and simulated ones via computed *summary statistics*. The table of summary statistics for simulated data is called *the reference table*.

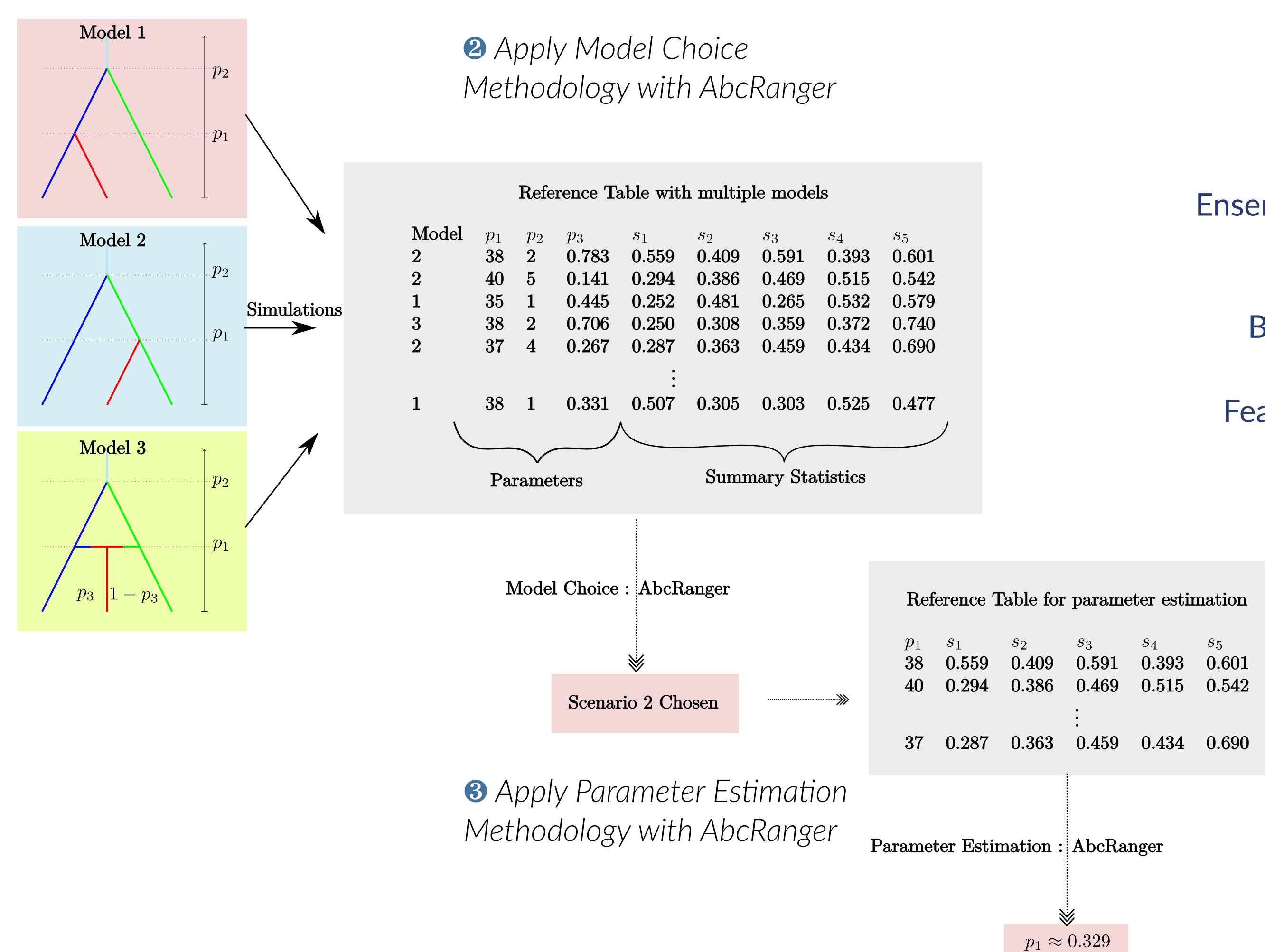
ABC posterior methodologies

Model choice: Simulate data for several models and choose the best model to fit our data

Parameter estimation: Simulate data for one model and infer one or several parameters for this model given the observed data

A sensible workflow is to first choose a model and then infer its parameters.

1 Compute simulations with several models, and the reference table with model-indexed lines using a simulator (DIYAC, PyABC etc.)



Challenges of ABC

in the context of population genetics recent advances

Number of simulated data : could be > 100 000

Number of summary statistics : could range from several hundred to tens of thousands (scenario with several populations and combinatory "explosion") : how to select the *meaningful* ones?

Classical Methods for ABC (*k*-nn and local methods) doesn't cope very well with this situation.

Our solution

[2] and [3] proposed a novel approach, relying on *Random Forests* to provide both model choice and parameter estimation methodologies

Second building block : Random Forests

CART

Random Forests are based on a CART, *Classification and Regression Trees*, algorithm [4].

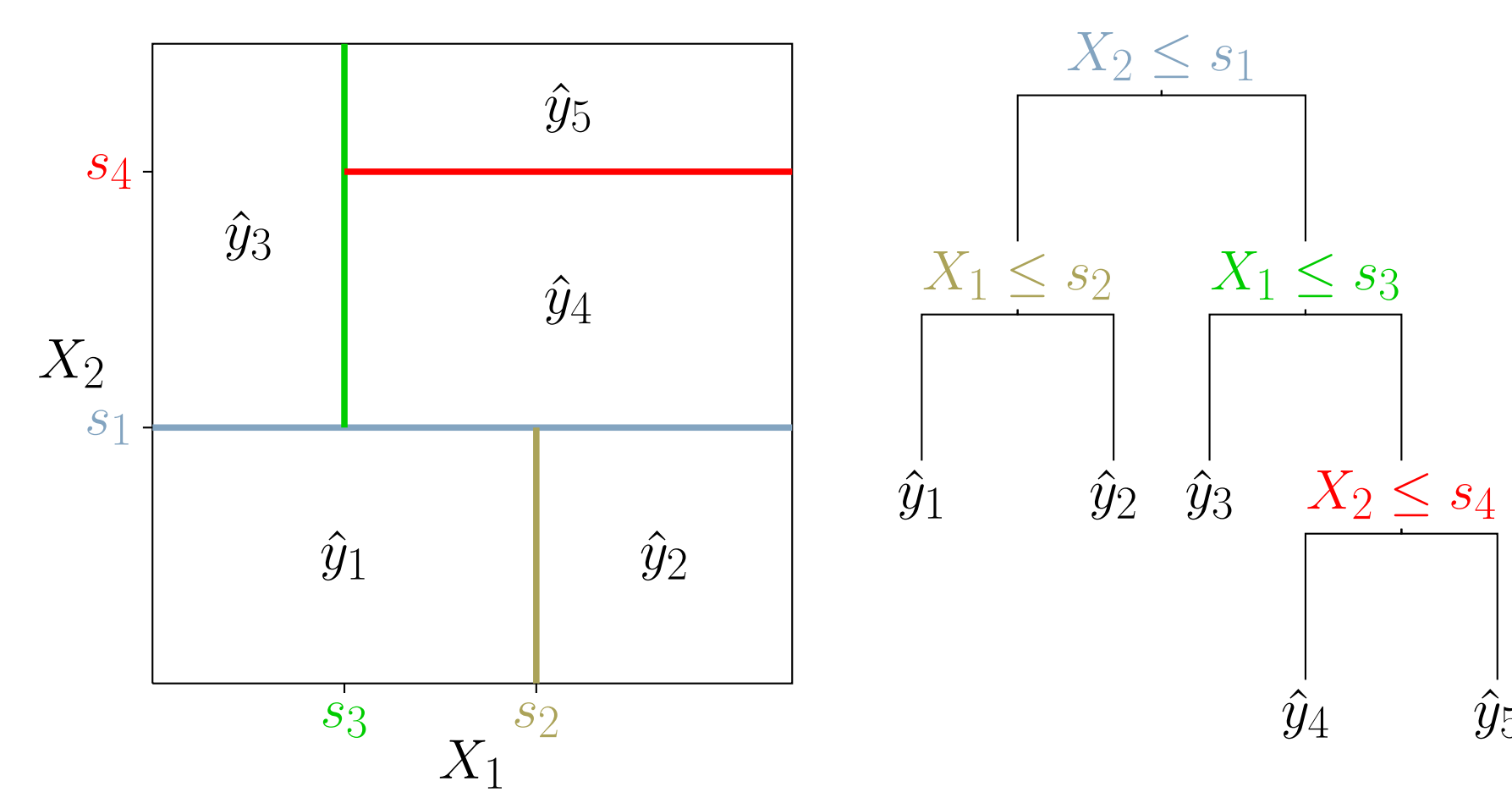


Figure 3. An example of CART and the associated partition of the two dimensional predictor space. Each splitting condition takes the form $X_j \leq s$ and the prediction at a leaf is denoted \hat{y}_i .

A CART is a *machine learning algorithm* whose principle is to partition the predictor space into disjoint subspaces, in an iterative manner, and each one is assigned a prediction value which will be used for test data falling in this subspace.

Once the partitioning is done, we have a binary tree structure which could predict outcomes from an input data, either classes or continuous values.

Random Forests

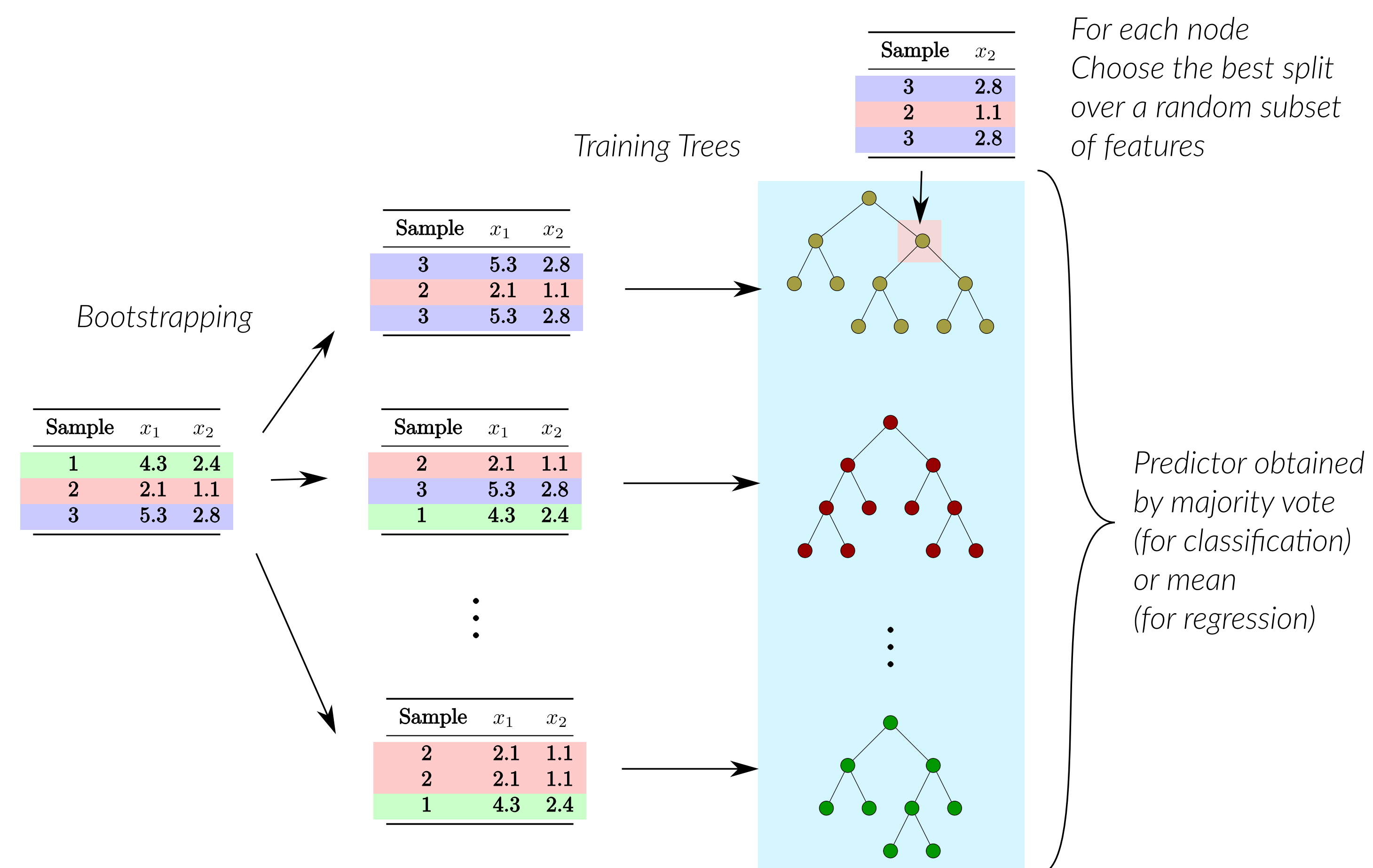


Figure 4. Random Forest

Random Forests [5] are a three pronged extension of CART:

- Ensemble method** Training a set of CART (not just one), and getting the majority vote (resp. mean) for classification (resp. regression)
- Bootstrapping** Training data is random sampled (with replacement) for *each* tree
- Feature bagging** At each node of a growing tree, find the best split on a random subset of the features

Advantages in an ABC setting :

- robust to noise
- (almost) free variable importance
- free (out-of-bag) cross-validation procedure
- easy parallelization
- good scaling properties on number of samples and on number of features (summary statistics)
- classifier and regressor

Computational challenges with ABC/Random Forests

With 100 000 lines and more than 10 000 summary statistics, each tree could reach over 1 gigabyte of memory size. Typically we need 500 or 1000 trees for good prediction performance, so, even with state of the art RF packages like [6], memory constraints are preventing completion of the training.

A new implementation of Random Forest for ABC

Since ABC procedures only use trained Random Forests on a known set of observations, we have altered the random forest training computation by using only a subset of in-memory trees at a time and accumulating the required outcomes (predictions and statistics). Memory footprint is vastly improved and there is no performance cost.

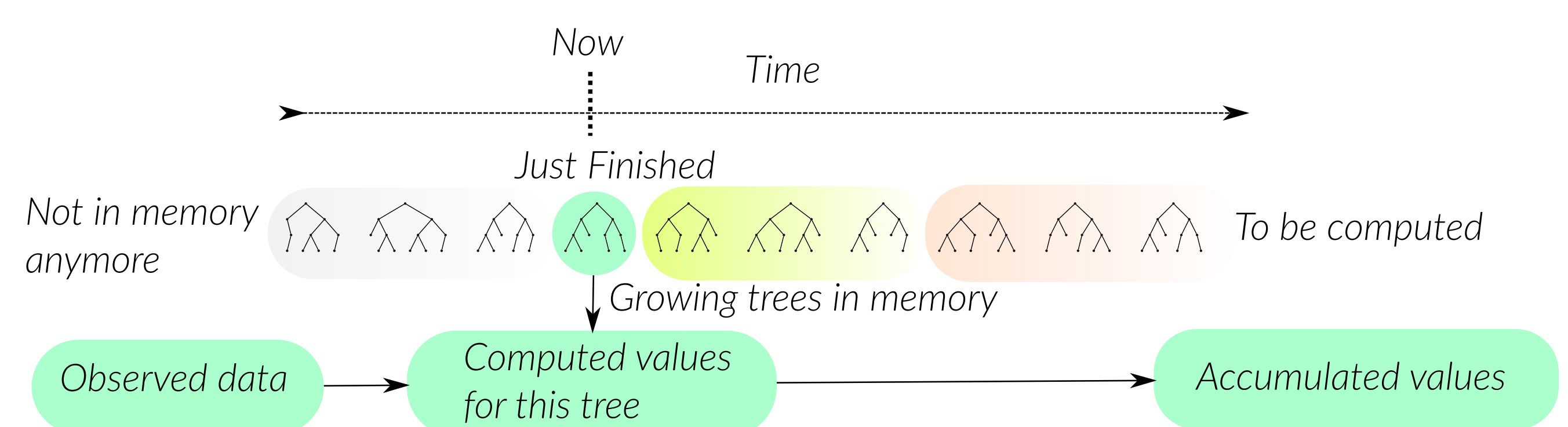


Figure 5. Window of growing trees

Ongoing project *LeafLitter* intends to pursue that line even further: for a growing tree, only encountered leaves are stored. Thus, the memory footprint of trees becomes negligible, and could be parallelized at full scale.

References

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