1. Description

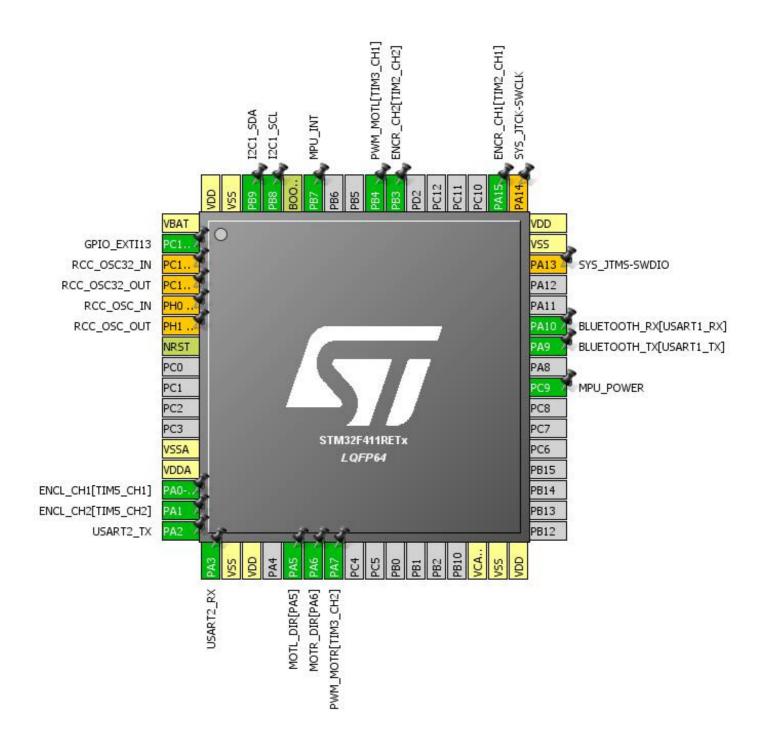
1.1. Project

Project Name	CubeBot
Board Name	NUCLEO-F411RE
Generated with:	STM32CubeMX 4.22.1
Date	10/21/2018

1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F411
MCU name	STM32F411RETx
MCU Package	LQFP64
MCU Pin number	64

2. Pinout Configuration



3. Pins Configuration

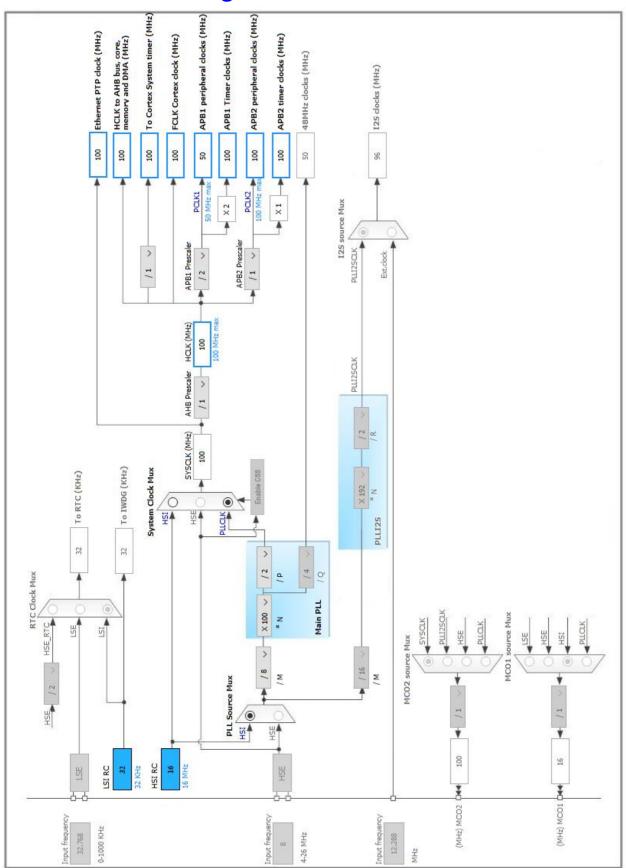
Pin Number	Pin Name	Pin Type	Alternate	Label
LQFP64	(function after	, po	Function(s)	20.00
EQIT 04	reset)		r driction(s)	
1	VBAT	Power		
2	PC13-ANTI_TAMP	I/O	GPIO_EXTI13	
3	PC14-OSC32_IN *	I/O	RCC_OSC32_IN	
4	PC15-OSC32_OUT *	I/O	RCC_OSC32_OUT	
5	PH0 - OSC_IN *	I/O	RCC_OSC_IN	
6	PH1 - OSC_OUT *	I/O	RCC_OSC_OUT	
7	NRST	Reset		
12	VSSA	Power		
13	VDDA	Power		
14	PA0-WKUP	I/O	TIM5_CH1	ENCL_CH1[TIM5_CH1]
15	PA1	I/O	TIM5_CH2	ENCL_CH2[TIM5_CH2]
16	PA2	I/O	USART2_TX	
17	PA3	I/O	USART2_RX	
18	VSS	Power		
19	VDD	Power		
21	PA5 **	I/O	GPIO_Output	MOTL_DIR[PA5]
22	PA6 **	I/O	GPIO_Output	MOTR_DIR[PA6]
23	PA7	I/O	TIM3_CH2	PWM_MOTR[TIM3_CH2]
30	VCAP1	Power		
31	VSS	Power		
32	VDD	Power		
40	PC9 **	I/O	GPIO_Output	MPU_POWER
42	PA9	I/O	USART1_TX	BLUETOOTH_TX[USART1_ TX]
43	PA10	I/O	USART1_RX	BLUETOOTH_RX[USART1 _RX]
46	PA13 *	I/O	SYS_JTMS-SWDIO	
47	VSS	Power		
48	VDD	Power		
49	PA14 *	I/O	SYS_JTCK-SWCLK	
50	PA15	I/O	TIM2_CH1	ENCR_CH1[TIM2_CH1]
55	PB3	I/O	TIM2_CH2	ENCR_CH2[TIM2_CH2]
56	PB4	I/O	TIM3_CH1	PWM_MOTL[TIM3_CH1]
59	PB7 **	I/O	GPIO_Input	MPU_INT
60	BOOT0	Boot		
61	PB8	I/O	I2C1_SCL	

Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
62	PB9	I/O	I2C1_SDA	
63	VSS	Power		
64	VDD	Power		

^{**} The pin is affected with an I/O function

^{*} The pin is affected with a peripheral function but no peripheral mode is activated

4. Clock Tree Configuration



5. IPs and Middleware Configuration

5.1. I2C1

I2C: I2C

5.1.1. Parameter Settings:

Master Features:

I2C Speed Mode Fast Mode *

I2C Clock Speed (Hz) 400000

Fast Mode Duty Cycle Duty cycle Tlow/Thigh = 2

Slave Features:

Clock No Stretch Mode Disabled
Primary Address Length selection 7-bit
Dual Address Acknowledged Disabled
Primary slave address 0
General Call address detection Disabled

5.2. SYS

Timebase Source: SysTick

5.3. TIM1

Clock Source : Internal Clock

5.3.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 79 *
Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 65535 *
Internal Clock Division (CKD) No Division

Repetition Counter (RCR - 8 bits value) 0

Trigger Output (TRGO) Parameters:

Master/Slave Mode Enable (sync between this TIM (Master) and its Slaves

(through TRGO)) *

Trigger Event Selection

Update Event *

5.4. TIM2

Combined Channels: Encoder Mode

5.4.1. Parameter Settings:	
Counter Settings:	
Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value)	4294967295 *
Internal Clock Division (CKD)	No Division
Trigger Output (TRGO) Parameters:	
Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves
Trigger Event Selection	Reset (UG bit from TIMx_EGR)
Encoder:	
Encoder Mode	Encoder Mode TI1 and TI2 *
Parameters for Channel 1	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
Parameters for Channel 2	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

5.5. TIM3

Clock Source : Internal Clock Channel1: PWM Generation CH1 Channel2: PWM Generation CH2

5.5.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 9 *

Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 65535 *
Internal Clock Division (CKD) No Division

Trigger Output (TRGO) Parameters:

Master/Slave Mode Disable (no sync between this TIM (Master) and its Slaves

Trigger Event Selection Reset (UG bit from TIMx_EGR)

PWM Generation Channel 1:

Mode PWM mode 1

Pulse (16 bits value) 0
Fast Mode Disable
CH Polarity High

PWM Generation Channel 2:

Mode PWM mode 1

Pulse (16 bits value) 0
Fast Mode Disable
CH Polarity High

5.6. TIM4

Slave Mode: External Clock Mode 1

Trigger Source: ITR0

5.6.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 0
Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 65535 *

Internal Clock Division (CKD) No Division

Slave Mode Controller ETR mode 1

Trigger Output (TRGO) Parameters:

Master/Slave Mode Disable (no sync between this TIM (Master) and its Slaves

Trigger Event Selection Reset (UG bit from TIMx_EGR)

5.7. TIM5

Combined Channels: Encoder Mode

5.7.1. Parameter Settings:

Counter Settings:	
Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value)	4294967295 *
Internal Clock Division (CKD)	No Division
Trigger Output (TRGO) Parameters:	
Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves
Trigger Event Selection	Reset (UG bit from TIMx_EGR)
Encoder:	
Encoder Mode	Encoder Mode TI1 and TI2 *
Parameters for Channel 1	
Polarity	Rising Edge
C Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
Parameters for Channel 2	
Polarity	Rising Edge
C Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

5.8. USART1

Mode: Asynchronous

5.8.1. Parameter Settings:

Basic Parameters:

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples

5.9. USART2

Mode: Asynchronous

5.9.1. Parameter Settings:

Basic Parameters:

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples

^{*} User modified value

6. System Configuration

6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
I2C1	PB8	I2C1_SCL	Alternate Function Open Drain	Pull-up	Very High	
	PB9	I2C1_SDA	Alternate Function Open Drain	Pull-up	Very High *	
TIM2	PA15	TIM2_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	ENCR_CH1[TIM2_CH1]
	PB3	TIM2_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	ENCR_CH2[TIM2_CH2]
TIM3	PA7	TIM3_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	PWM_MOTR[TIM3_CH2]
	PB4	TIM3_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	PWM_MOTL[TIM3_CH1]
TIM5	PA0-WKUP	TIM5_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	ENCL_CH1[TIM5_CH1]
	PA1	TIM5_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	ENCL_CH2[TIM5_CH2]
USART1	PA9	USART1_TX	Alternate Function Push Pull	Pull-up	Very High *	BLUETOOTH_TX[USART 1_TX]
	PA10	USART1_RX	Alternate Function Push Pull	Pull-up	Very High *	BLUETOOTH_RX[USART 1_RX]
USART2	PA2	USART2_TX	Alternate Function Push Pull	Pull-up	Very High *	
	PA3	USART2_RX	Alternate Function Push Pull	Pull-up	Very High	
Single Mapped	PC14- OSC32_IN	RCC_OSC32_IN	n/a	n/a	n/a	
Signals	PC15- OSC32_OU T	RCC_OSC32_O UT	n/a	n/a	n/a	
	PH0 - OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1 - OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
	PA13	SYS_JTMS- SWDIO	n/a	n/a	n/a	
	PA14	SYS_JTCK- SWCLK	n/a	n/a	n/a	
GPIO	PC13- ANTI_TAMP	GPIO_EXTI13	External Interrupt Mode with Rising edge trigger detection	No pull-up and no pull-down	n/a	
	PA5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTL_DIR[PA5]

IP	Pin	Signal	GPIO mode	GPIO pull/up pull	Max	User Label
				down	Speed	
	PA6	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTR_DIR[PA6]
	PC9	GPIO_Output	Output Push Pull	No pull-up and no pull-down	High *	MPU_POWER
	PB7	GPIO_Input	Input mode	Pull-up *	n/a	MPU_INT

6.2. DMA configuration

nothing configured in DMA service

6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true	0	0
I2C1 event interrupt	true	0	0
USART1 global interrupt	true	0	0
USART2 global interrupt	true	0	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
TIM1 break interrupt and TIM9 global interrupt	unused		
TIM1 update interrupt and TIM10 global interrupt	unused		
TIM1 trigger and commutation interrupts and TIM11 global interrupt	unused		
TIM1 capture compare interrupt		unused	
TIM2 global interrupt	unused		
TIM3 global interrupt	unused		
TIM4 global interrupt	unused		
I2C1 error interrupt	unused		
EXTI line[15:10] interrupts	unused		
TIM5 global interrupt	unused		
FPU global interrupt		unused	

^{*} User modified value

7. Power Consumption Calculator report

7.1. Microcontroller Selection

Series	STM32F4
Line	STM32F411
мси	STM32F411RETx
Datasheet	026289_Rev6

7.2. Parameter Selection

Temperature	25
Vdd	null

8. Software Project

8.1. Project Settings

Name	Value
Project Name	CubeBot
Project Folder	C:\Users\joel\Documents\electronique\STM32_Projects\CubeBot
Toolchain / IDE	TrueSTUDIO
Firmware Package Name and Version	STM32Cube FW_F4 V1.16.0

8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	Yes
Delete previously generated files when not re-generated	No
Set all free pins as analog (to optimize the power	No
consumption)	