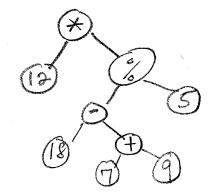
NODE STITCK

RPN 5 % \*

RPN: % \*

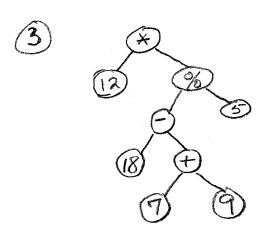
RANGA



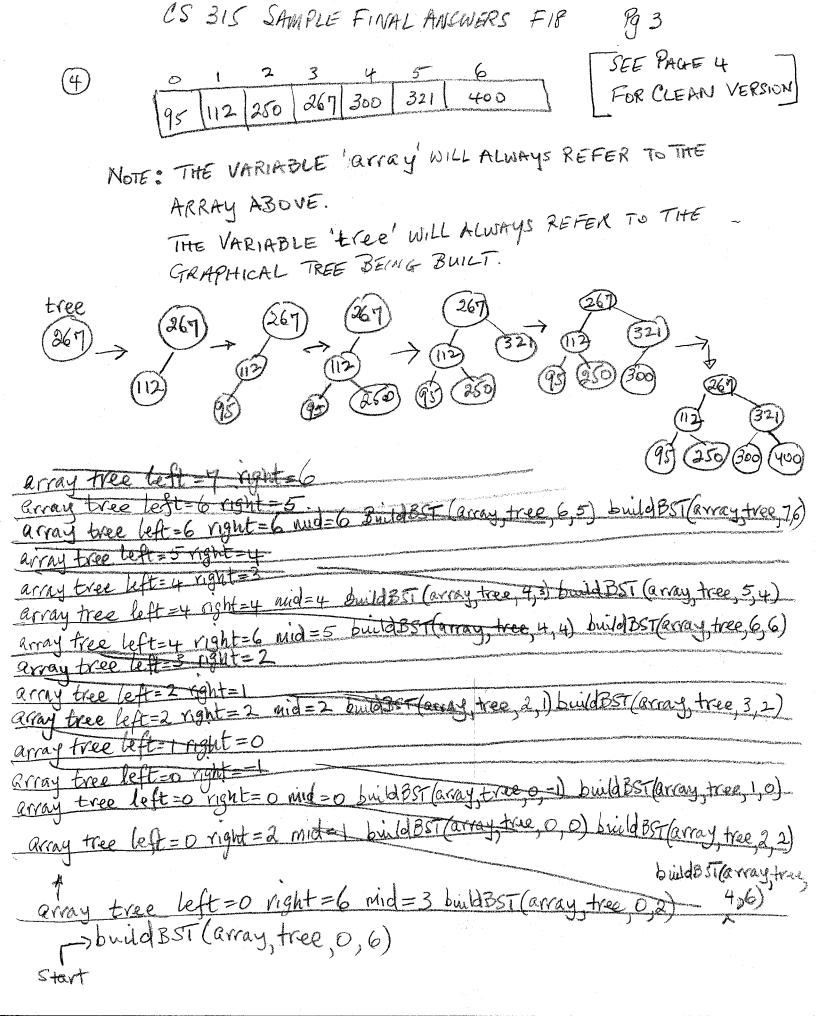
RPWS EMPTY

20 postorder

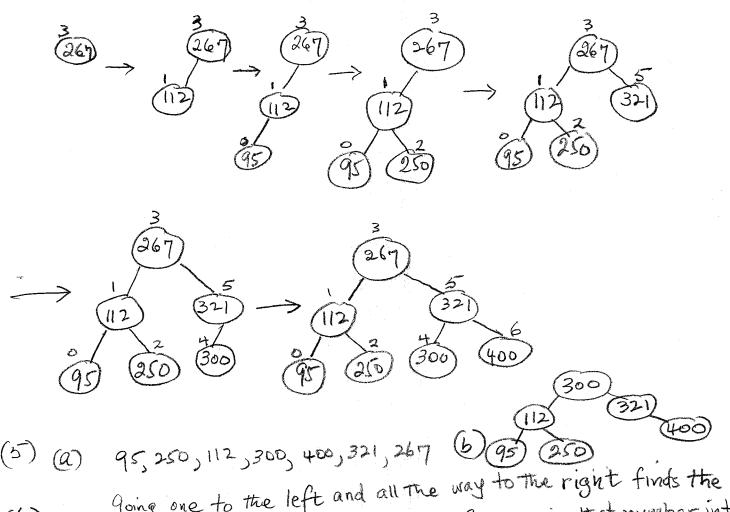
(b) Stack



Using postorder with an operand stack.



THIS SHOWS HOW THE BST IS BUILT ONE NODE AT ATIME. (4) THE NUMBERS ABOVE EACH NODE REPRESENT THE ARRAY INDICES.



going one to the left and all the way to the right finds the biggest value in the left subtree. So swapping that number into (6)the mode to be deleted will still keep every node to the left

Similarly, going one to the right and then all the way Left Smaller will find the smallest value in the right subtree.

So swapping will again preserve the BST.

Example using tree from question (4) Let's remove 267.

(a) go left once and then all the way right finds 250. Replacing 267 with 250 keeps the BST.

(b) go right once and then all the way left finds 300 which also

```
(1) int addNodes OnBST (TreeNode (Integer) root)

{

if (root == null) return 0;

int leftSum = addNodesOnBST (root.left);

int rightSum = addNodesOnBST (root.right);

return leftSum + rightSum + root.data;

}

(8) int countPrimeNodes OnBST (TreeNode (Integer) root)

{

if (root == null) return 0;
```

int count Prime Nodes UnBST (Tree Node (Integer) 800t)

if (root == null) return o;

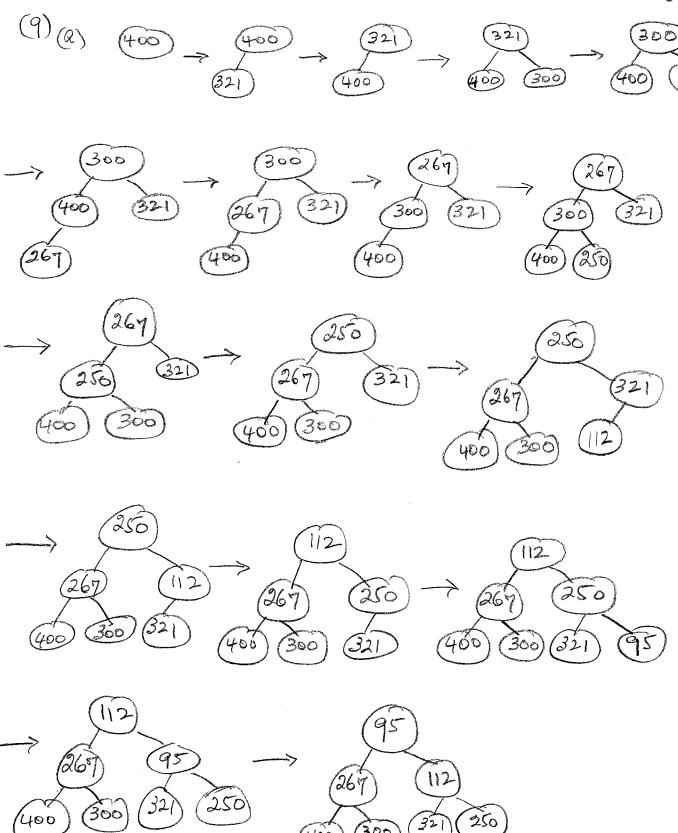
int prime = 0;

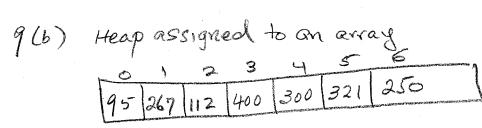
if (is Prime (root.data)) prime = 1;

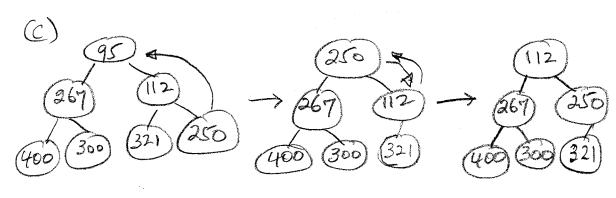
int left Court = count Prime Nodes On BST (root.left);

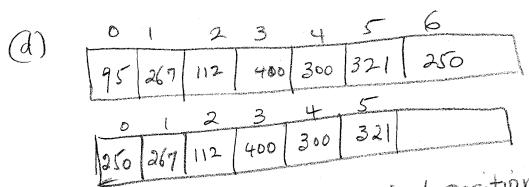
int right Court = count Prime Nodes On BST (root.right),

return left Court + right Count + prime;









Smaller child of index 0 is at position 2 so swap

112/267/250/400/300/321

(10) (a) Vertex List  

$$2 \rightarrow 1,3,7$$
  
 $3 \rightarrow 1,2,4$   
 $4 \rightarrow 3,5$   
 $5 \rightarrow 4,6,7$   
 $6 \rightarrow 1,5,7$   
 $7 \rightarrow 2,5,6$ 

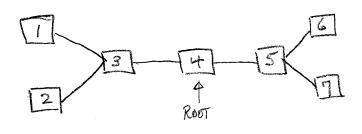
(6)	123 45 6 7
	1011100110
	2 1010000
	3110010100
	5000000000
	6/110/0/11/10
	10110

## (10)(C) BREADTH-FIRST

- (1) QUEUE: 4 VISITED: 4 EDGE LIST:
- (2) QUEUE: 3,5 VISITED: 4,3,5 EDGE LIST: 4→3,4→5
- (3) QUEUE: 5, 1, 2 VISITED: 4, 3, 5, 1, 2 EDGE LIST: 4>3, 4>5, 3>1, 3>2
- (4) QUEUE: 1, 2, 6, 7 VISITED: 4, 3, 5, 1, 2, 6, 7 EDGE LIST: 4->3, 4->5,3->1,3->2,5->6,5->7
- (5) THE NODES CURRENTLY ON THE QUEUE CANNOT BRING IN ANY OTHER NODES BECAUSE ALL HAVE BEEN VISITED SO EVERY OTHER STEP JUST BRINGS THEM OFF THE QUEUE

## RESULT:

QUEUE: EMPTY VISITED: 4,3,5,1,2,6,7



## (10)(d) DEPTH-FIRST

STEPS

(10)(d)

STEPS 8->14

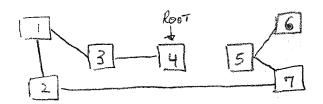
STACK IS POPPED ONE VERTEX AT A TIME AND EACH TIME YOU HAVE TO SEE IF ANY CONNECTED VERTEX HAS NOT BEEN VISITED AS YET.

IF THERE ARE UNVISITED VERTICES, YOU HAVE TO PUSH THEM ON THE STACK AND GO UP AGAIN.

IN THIS CASE, THE STACK WILL BE POPPED COMPLETELY.

RESULT:

VISITED: 4,3,1,2,7,5,6



(11) Vertices' REFERS TO AN ArrayLIST OF WHATEVER TYPE A VERTEX IS.

'adjacency LISTS' IS AN Array LIST OF Array LIST(S) WHERE
EACH OF THE COMPONENT Array LIST(S) CORRESPONDS WITH A
VERTEX STORED 'Vertices'.

EVERY TIME A VERTEX OBJECT IS ADDED TO THE Vertices' LIST A NEW ArrayLIST IS CREATED AND ADDED TO THE 'adjacency Lists' LIST.

Example: vertices  $\rightarrow [A, b, c]$ adjacencyLisTs  $\rightarrow [L], L], L]$ 

ONCE CONNECTED VERTICES START TO BE ADDED THE EMPTY LISTS WILL START TO GET VERTICES.

- (12) (Q) THE TOP OF THE HEAP IS THE FIRST ELEMENT IN ANY REPRESENTATION OF A HEAP SO IT'S A DIRECT ACCESS.
  SO CONSTANT TIME = O(1) or O(K)
  - (b) A SPANNING TREE MUST INCLUDE ALL IN VERTICES AND THERE ARE NO LOOPS SO O(n).
  - (C) THERE ARE N VERTICES TO START FROM AND EACH TREE BUILT IS O(n) SO O(n2).
  - CONSTANT TIME SO O(1) OR O(K).