

# MA345 Differential Equations & Matrix Method

Lecture: 02

Date: 8/28/2018

Professor Berezovski

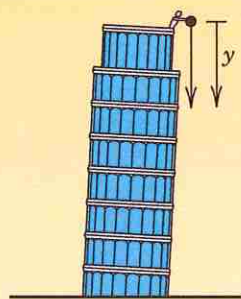
COAS.301.12

$$y'' = 2$$

### **Definition 1.1.1    Differential Equation**

An equation containing the derivatives of one or more dependent variables, with respect to one or more independent variables, is said to be a **differential equation (DE)**.

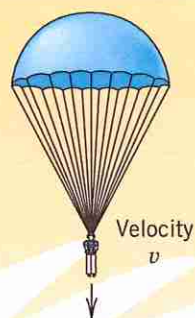
In order to talk about them, we will classify a differential equation by **type, order, and linearity**.



Falling stone

$$y'' = g = \text{const.}$$

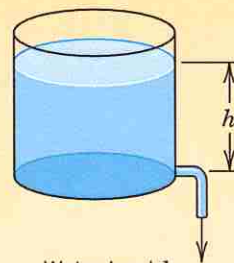
(Sec. 1.1)



Parachutist

$$mv' = mg - bv^2$$

(Sec. 1.2)

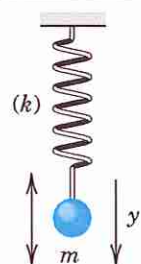


Water level  $h$

Outflowing water

$$h' = -k\sqrt{h}$$

(Sec. 1.3)

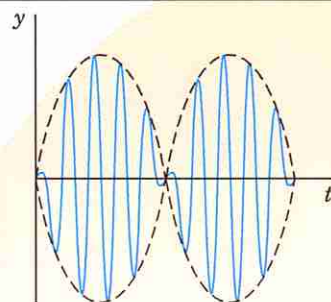


Displacement  $y$

Vibrating mass  
on a spring

$$my'' + ky = 0$$

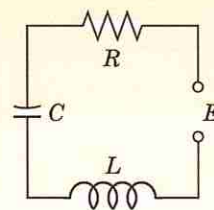
(Secs. 2.4, 2.8)



Beats of a vibrating  
system

$$y'' + \omega_0^2 y = \cos \omega t, \quad \omega_0 \approx \omega$$

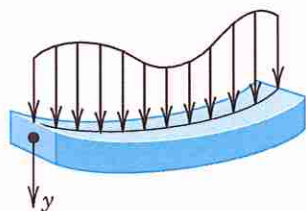
(Sec. 2.8)



Current  $I$  in an  
 $RLC$  circuit

$$LI'' + RI' + \frac{1}{C}I = E'$$

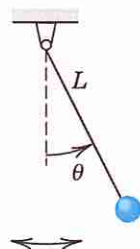
(Sec. 2.9)



Deformation of a beam

$$EIy^{iv} = f(x)$$

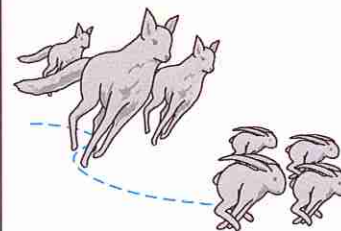
(Sec. 3.3)



Pendulum

$$L\theta'' + g \sin \theta = 0$$

(Sec. 4.5)



Lotka-Volterra  
predator-prey model

$$\begin{aligned} y_1' &= ay_1 - by_1y_2 \\ y_2' &= ky_1y_2 - ly_2 \end{aligned}$$

(Sec. 4.5)

To begin our study of differential equations, we need some common terminology. If an equation involves the derivative of one variable with respect to another, then the former is called a **dependent variable** and the latter an **independent variable**.

$$\frac{d^2x}{dt^2} + a \frac{dx}{dt} + kx = 0$$

$a, k \rightarrow$  constant  
coefficient

$$\underbrace{\frac{dy}{dx}}_{\text{dependent variable}} \underbrace{e^x + \cos x}_{\text{coefficients variable}} \underbrace{\frac{d^2y}{dx^2}}_{\text{dependent variable}} = 0$$

$\rightarrow$  coefficients variable

### Definition 1.1.1 Differential Equation

An equation containing the derivatives of one or more dependent variables, with respect to one or more independent variables, is said to be a **differential equation (DE)**.

In order to talk about them, we will classify a differential equation by **type**, **order**, and **linearity**.

□ **Classification by Type** If a differential equation contains only ordinary derivatives of one or more functions with respect to a *single* independent variable it is said to be an **ordinary differential equation (ODE)**. An equation involving only partial derivatives of one or more functions of two or more independent variables is called a **partial differential equation (PDE)**.

Leibniz notation:  $\frac{dy}{dx}$ ,  $\frac{d^2y}{dx^2}$

prime notation:  $y'$ ,  $y''$

$$y' + 6y = e^{-x}$$

Newton's notation:  $\frac{d^2s}{dt^2} = -32$       $\ddot{s} = -32$

$$\frac{\partial^2 u}{\partial x^2} = u_{xx}$$

$$u_{xx} = u_{tt} - u_t$$

$$u_{xx} + u_{yy} = 0$$



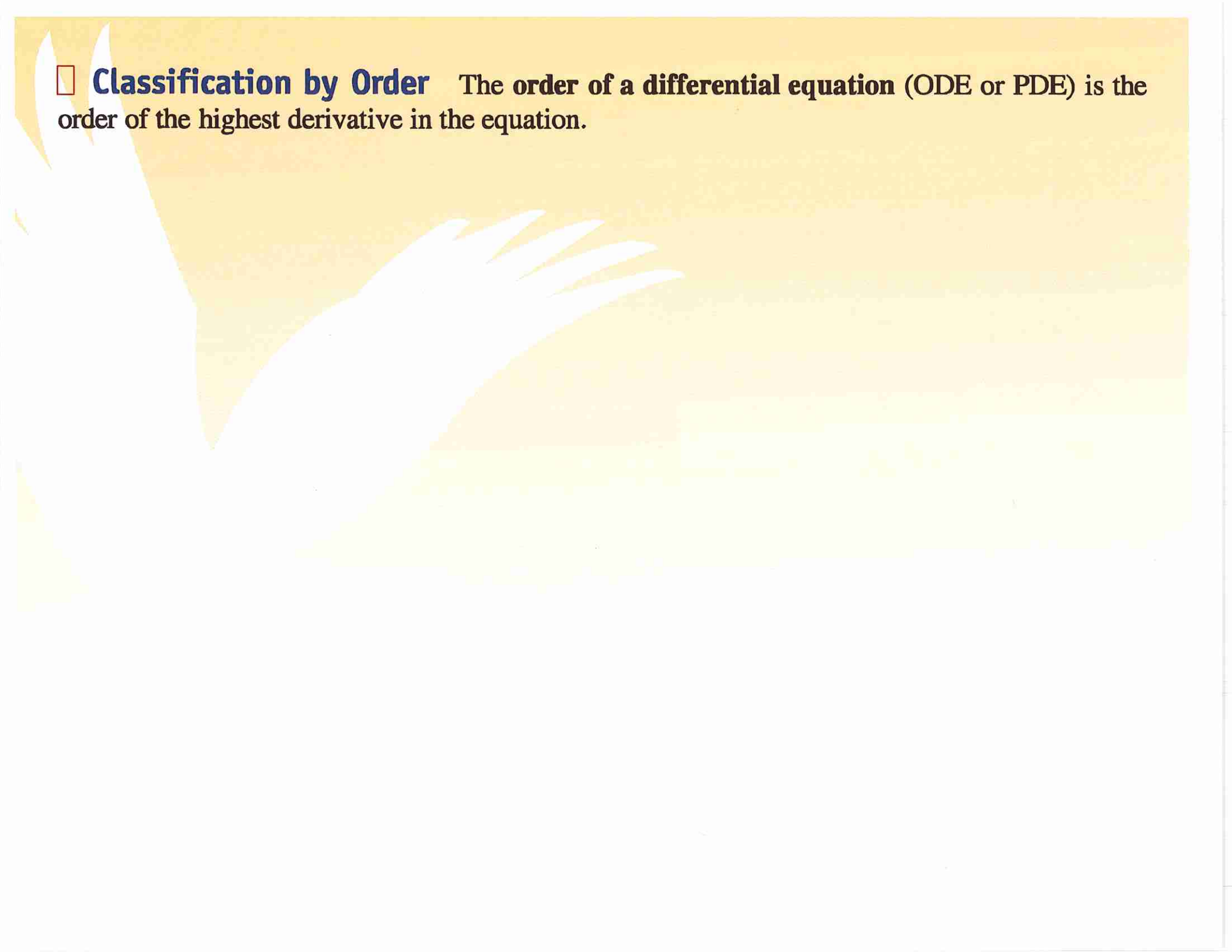
an ODE can contain more  
than one dependent variable

$$\frac{dy}{dx} + 6y = e^{-x}, \quad \frac{d^2y}{dx^2} + \frac{dy}{dx} - 12y = 0, \quad \text{and} \quad \frac{dx}{dt} + \frac{dy}{dt} = 3x + 2y$$

(b) The equations

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0, \quad \frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial t^2} - \frac{\partial u}{\partial t}, \quad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}. \quad (3)$$

are examples of partial differential equations. Notice in the third equation that there are two



□ **Classification by Order** The order of a differential equation (ODE or PDE) is the order of the highest derivative in the equation.

## The differential equations

highest order



$$\frac{d^2y}{dx^2} + 5\left(\frac{dy}{dx}\right)^3 - 4y = e^x,$$

highest order



$$2\frac{\partial^4 u}{\partial x^4} + \frac{\partial^2 u}{\partial t^2} = 0$$

are examples of a **second-order** ordinary differential equation and a **fourth-order** partial differential equation, respectively. ≡

$$M(x,y)dx + N(x,y)dy = 0$$

$$(y-x)dx + 4xydy = 0$$

$$4xy' + y = x$$

$$y' = \frac{dy}{dx}$$

$$(y-x) + 4x \frac{dy}{dx} = 0$$

$$\frac{dy}{dx} = \frac{y-x}{4x}$$



General form:

$$F(x, y, y', \dots, y^{(n)}) = 0$$

### Definition 2.3.1 Linear Equation

A first-order differential equation of the form

$$a_1(x) \left( \frac{dy}{dx} \right) + a_0(x)y = g(x) \quad (1)$$

is said to be a **linear equation** in the dependent variable  $y$ .

When  $g(x) = 0$ , the linear equation (1) is said to be **homogeneous**; otherwise, it is **nonhomogeneous**.

A second-order ODE is called **linear** if it can be written

$$(1) \quad y'' + p(x)y' + q(x)y = r(x)$$

and **nonlinear** if it cannot be written in this form.

The distinctive feature of this equation is that it is *linear in  $y$  and its derivatives*, whereas the functions  $p$ ,  $q$ , and  $r$  on the right may be any given functions of  $x$ . If the equation begins with, say,  $f(x)y''$ , then divide by  $f(x)$  to have the **standard form** (1) with  $y''$  as the first term.

$$y' + 2y = e^x \rightarrow \text{linear first order ODE}$$

$$\underbrace{y''} + (\underbrace{\cos x}) \underbrace{y'} + \underbrace{xy} = 0 \rightarrow \text{linear second order ODE}$$

$$\underbrace{(1-y)}_{\substack{\uparrow \\ \text{non linear}}} \underbrace{y'} + \underbrace{3y} = x^3 \rightarrow \text{nonlinear first order ODE}$$

$$\frac{d^2 y}{dx^2} + \underbrace{\sin y}_{\substack{\downarrow \\ \text{nonlinear function} \\ \text{of } y}} = 0 \rightarrow \text{nonlinear 2nd order ODE}$$