

plumeAnalyser

May 31, 2019

```
In [1]: from bentPlumeAnalyser import *
        from fumarolePlumeModel import *
        from scipy.io.matlab import loadmat

        import pandas
        import numpy as np
        import matplotlib.pyplot as plt
        import matplotlib as mpl
        import os, sys
        import json

        # Set numpy options, notably for the printing of floating point numbers
        np.set_printoptions(precision=6)

        # Set matplotlib options
        mpl.rcParams['figure.dpi'] = 300

In [2]: exptNo    = 3
        plotResults = True

        # Read analysed experimental data from file
        fname      = './data/ExpPlumes_for_Dai/GCTA_plumeData.xlsx'
        exptData = pandas.read_excel(fname, sheet_name='exp%02d' % exptNo)

        # Display the first 5 lines of the data frame
        exptData.head()
```

	axisLocn_x	axisLocn_y	distAlongAxis	plumeAngle	plumeWidth
0	-0.082073	0.122375	0.147349	1.510677	0.277366
1	0.079714	1.257440	1.293886	1.449785	0.319537
2	0.024641	2.499398	2.537064	1.176742	0.650992
3	1.443832	4.561191	5.040081	0.783431	1.048499
4	2.855947	5.234923	6.604684	0.565428	1.329422

```
Out[2]:
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In [3]: ## DEFINE THE DISTANCE ALONG THE AXIS, THE ANGLE AND THE WIDTH OF THE PLUME
        # sexp = exptData.distAlongAxis
        # thexp = exptData.plumeAngle
        # bexp = exptData.plumeWidth
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path = './data/ExpPlumes_for_Dai/exp%02d/' % exptNo
with open(path + 'exp%02d_initGuess.json' % exptNo) as f:
    data = json.load(f)
p = np.array(data['data'])

data = np.flipud(loadmat(path + 'gsplume.mat')['gsplume'])
xexp = loadmat(path + 'xcenter.mat')['xcenter'][0]
zexp = loadmat(path + 'zcenter.mat')['zcenter'][0]
0x, 0z = (xexp[0], zexp[0])
xexp = (xexp - 0x) / scaleFactor
zexp = (0z - zexp) / scaleFactor

pPixels = p.copy() * scaleFactor
pPixels[:,0] += 0x
pPixels[:,1] -= 0z
pPixels[:,1] *= -1

# Calculate angle, width and distance along plume and errors
thexp, sig_thexp = plumeAngle(p[:,0], p[:,1], errors=[1/scaleFactor]*2)
_, bexp, sig_p, sig_bexp = trueLocationWidth(pPixels, data, errors=[1/scaleFactor])
sexp = distAlongPath(p[:,0], p[:,1])
bexp /= scaleFactor
sig_bexp /= scaleFactor
bexp[0] = 0.55 / 2
thexp[0] = np.pi / 2

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In [4]: V0, p = loadICsParameters(pathname, exptNo, alpha=0.05, beta=0.5, m=2)
p

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Out[4]: (0.05, 0.5, 0.313390044481266, 2, 4.8)

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In [5]: # Load initial conditions for a given experiment, run the model for those conditions
# and then compare model and experimental data
V0, p = loadICsParameters(pathname, exptNo)

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# Initialise an integrator object
r = ode(derivs).set_integrator('lsoda', nsteps=1e6)
r.set_initial_value(V0, 0.)
r.set_f_params(p)
V = [V0] # State vector
s = [0.] # Axial distance

# Set integration domain and step size
t1 = 30.
dt = .1

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# Integrate, whilst successful, until the domain size is reached
while r.successful() and r.t < t1:
    r.integrate(r.t + dt)
    V.append(r.y)
    s.append(r.t)
s = np.array(s)
V = np.array(V)

In [6]: # Calculate the model predictions
# Extract the plume parameters from the state vector
Q      = V[:,0]
M      = V[:,1]
F      = V[:,2]
theta  = V[:,3]

# Calculate more intuitive plume parameters (width, speed and specific gravity)
b      = Q / np.sqrt(M)
u      = M / Q
gp     = F / Q

xmod, zmod = [0.], [0.]
ds_ = np.diff(s)
for (ds, th) in zip(ds_, theta):
    xmod.append(xmod[-1] + ds * np.cos(th))
    zmod.append(zmod[-1] + ds * np.sin(th))

In [7]: # Directly compare the plume width and angle for experiment and model
# First, the model data has to be interpolated onto the same grid as the experimental data
from scipy.interpolate import interp1d
# Plume width
f = interp1d(s, b)
bmod = f(sexp)
# Plume angle
f = interp1d(s, theta)
thmod = f(sexp)

In [8]: # Calculate an "objective function" which measures the misfit between data and model
# Initially, only use width and angle
Vexp = np.array([bexp, thexp]).T
Vmod = np.array([bmod, thmod]).T
sigV = np.array([sig_bexp, sig_thexp]).T

# The residual between experimental and model data
res = (Vexp - Vmod) / sigV
objFn = objectiveFn(Vexp.ravel(), Vmod.ravel(), np.diagflat(sigV.ravel())**2, p)

In [9]: res

```

```
Out[9]: array([[ -3.532460e+01,  0.000000e+00],
               [-1.201401e+02, -1.249190e+00],
               [-3.656068e+02,  2.738030e+00],
               [-2.794884e+02,  9.362794e+00],
               [-4.192654e+02,  9.905390e+00],
               [-6.470368e+02,  2.901345e+00],
               [-5.948145e+02, -9.002785e-01],
               [-6.486114e+02,  5.924460e+00],
               [-7.211442e+02,  2.334827e+00],
               [-7.825163e+02,  1.110875e+00],
               [-7.291918e+02,  1.427530e+00],
               [-6.633525e+02, -1.087277e+00],
               [-4.723200e+02, -2.372019e+00],
               [-3.632287e+02, -6.876940e-01],
               [-3.798735e+02, -3.013567e+00],
               [-3.282476e+02, -1.781407e+00],
               [-3.087669e+02, -4.467491e+00],
               [-3.229840e+02, -1.798174e+01]])
```

```
In [11]: fig, ax = plt.subplots(1, 2, figsize=(8,4))
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# On an image of the experimental plume, show the plume trajectories for
# 1) GCTA, 2) our initial guess, 3) the model solution
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data, xexp, zexp, extent = loadExptData(exptNo)
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if data.mean() < .5:
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    data = 1. - data
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ax[0].imshow(data, extent=extent, cmap=plt.cm.gray)
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```
ax[0].invert_yaxis()
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ax[0].set_xlabel(r'$x$/[cm]')
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```
ax[0].set_ylabel(r'$z$/[cm]')
```

```
# 1) GCTA
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ax[0].plot(xexp, zexp, 'r-', label='GCTA', lw=2)
```

```
# 2) our initial guess
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ax[0].plot(exptData.axisLocn_x, exptData.axisLocn_y, 'r--', label='Init. guess', lw=2)
```

```
# 3) the model solution
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```
ax[0].plot(xmod, zmod, 'g--', label='model', lw=1)
```

```
ax[0].set_xlim((extent[:2]))
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```
ax[0].legend(loc=2)
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```
ax[1].plot(res[:,0], sexp, '-', label=r'$\mathrm{b_{exp}} - \mathrm{b_{mod}}/\sigma_{\mathrm{b}}$')
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```
ax[1].plot(res[:,1], sexp, '-', label=r'$\mathrm{\theta_{exp}} - \mathrm{\theta_{mod}}$')
```

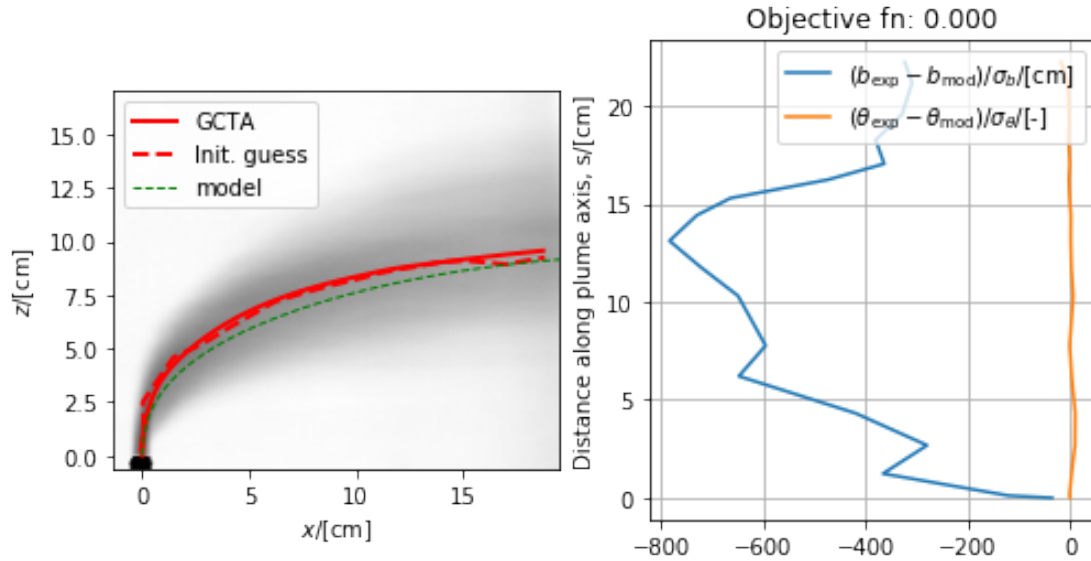
```
ax[1].legend(loc=1, fancybox=True, framealpha=.8)
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```
ax[1].grid()
```

```
ax[1].set_ylabel('Distance along plume axis, s/[cm]')
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```
ax[1].set_title('Objective fn: %.3f' % objFn)
```

```
plt.savefig('plumeAnalyser.png', dpi=300)
```



(Left) Image of experimental plume with calculated and estimated trajectories. (Right) Difference between experimental (guessed) and model solutions as a function of the distance along the plume axis.

1 To do:

- Make a grid of possible initial conditions and run the model for each case
- Compare these solutions against the experimental data, computing an objective function for each case
- Identify which cases produce minima in the objective function

```
In [10]: # Uncomment the following line to transform this notebook into a latex file
!jupyter nbconvert --to latex plumeAnalyser.ipynb
```

```
[NbConvertApp] Converting notebook plumeAnalyser.ipynb to latex
[NbConvertApp] Support files will be in plumeAnalyser_files/
[NbConvertApp] Making directory plumeAnalyser_files
[NbConvertApp] Writing 36000 bytes to plumeAnalyser.tex
```

```
In [11]: # Now run pdflatex plumeAnalyser from the command line
```