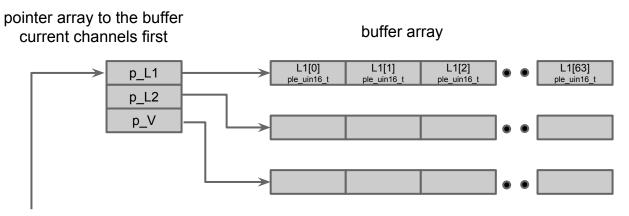
## PLE library (data structure)

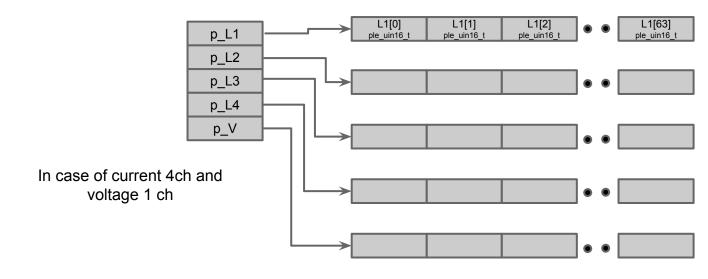
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## **Note** (change list from original one)

- Support variable channels
  - User can specify number of channels for both current and voltage.
- Minimize buffer size in the library
  - Size of work area is changed to for 1 second.
  - User has to pull encoded data right after input data of 1 second.
  - In case of encoding data for 100 seconds, if error has occurred in 90 seconds, user has to quit entire encoding process because there is inconsistency between parameter in PLC header which indicate number of encoded seconds and real length of encoded data.
     In this case, sensor should complete communication to server with error.



PLEPutData(hPle, (const ple\_uint16\_t \*\*)ppusWave);



```
PLC header
    (16bytes)
    PLC data
Current1CH:28bytes
Voltage 1 CH: 4 bytes
```

per 1 second

/\* plc\_uint8\_t ucMinVersion = PLC\_MIN\_VERSION; 1 byte \*/ /\* plc\_uint8\_t\_ucCurrentChannels;

/\* plc\_uint8\_t\_ucVoltageChannels;

/\* Header (16 bytes) ver.4.x \*/

/\* plc\_uint8\_t\_ucBitsPerSample;

/\* plc\_uint8\_t\_pucReserved[2];

/\* plc\_uint8\_t\_ucSamplesPerFrame;

/\* plc\_uint8\_t\_ucFramesPerGroups;

/\* plc\_uint32\_t\_unld = PLC\_CODE;

/\* plc\_uint8\_t ucExSizeL = PLC\_EXT\_SIZE; 1 byte \*/

/\* plc\_uint8\_t ucMajVersion = PLC\_MAJ\_VERSION; 1 byte \*/

/\* plc\_uint8\_t ucExSizeV = PLC\_EXT\_SIZE; 1 byte \*/ /\* plc\_uint8\_t\_ucFundametalFrg; 1 bvte \*/

2 bytes \*/

1 byte \*/

4 bytes \*/

1 byte \*/

1 byte \*/

1 byte \*/

1 byte \*/