Study Goals: "I want to estimate"

	Presence/ Absence	Abundance	Density	Survival	Survival and Movement
Unmarked Individuals	Occupancy	Double Observer	Distance Sampling		
	Distribution	Removal (Depletion)			
		N-mixture	*N*-mixture known area	Generalized (open) *N*-mixture	
Marked Individuals		Closed Mark-Recapture	Spatial Capture Recapture	Known-fate	Multi-State MR
				Cormack-Jolly-Seber (CJS)	Robust design MR
				Recovery	Open or Robust SCR
				Open SCR	