Neural Networks for Supervised Learning

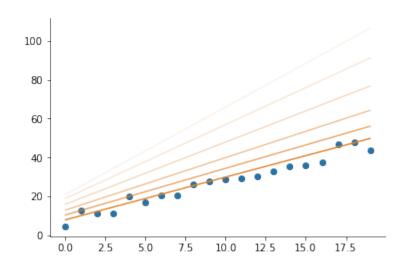
Supervised Learning task

The task is essentially to learn the association between the training examples \boldsymbol{X} and the labels \boldsymbol{y} .

$$X \rightarrow y$$

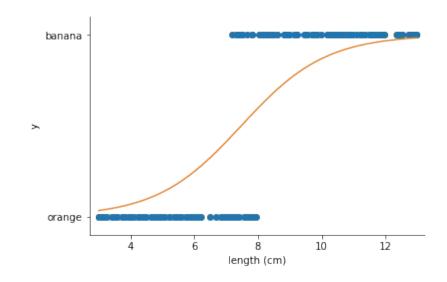
Linear Regression

- 1. Random initialization *W*, *b*.
- 2. Generate line $\hat{y} = Wx + b$.
- 3. Calculate total cost *J*.
- 4. Compute gradients $\frac{dJ}{dW}$ and $\frac{dJ}{db}$.
- 5. Update W and b.
- 6. Repeat steps 2 5 until cost stops dropping.



Logistic Regression

- Linear classifier
- Use of activation function (sigmoid) to output "probability"
- Loss function, again, checks distance from predicted probability to actual value
- Other than that training occurs same as in linear regression



Case study 1: linear classifier

Let's now see how well a logistic regression classifier works on two different datasets:

One that is linearly separable

One that is not

Logistic Regression to Neural Networks

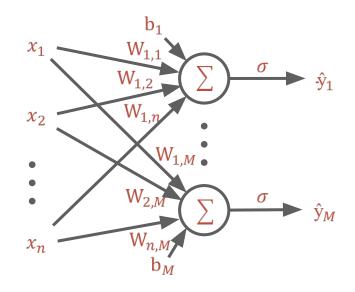
Simple logistic regression function:

$$\hat{y} = \sigma(Wx + b)$$

 Or in the case of multiple input features or output classes:

$$\hat{\mathbf{Y}}_i = f\left(\sum_{j=1}^M (w_{i,j}x_i + b_i)\right)$$

• We can imagine the above case as multiple simple regressors:

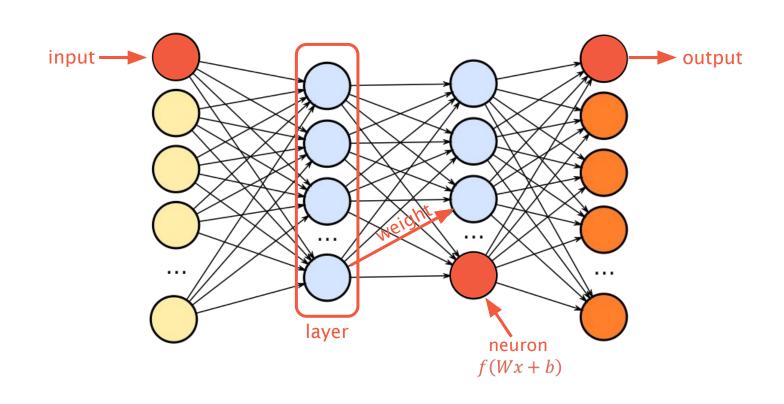


This is essentially a neural network.

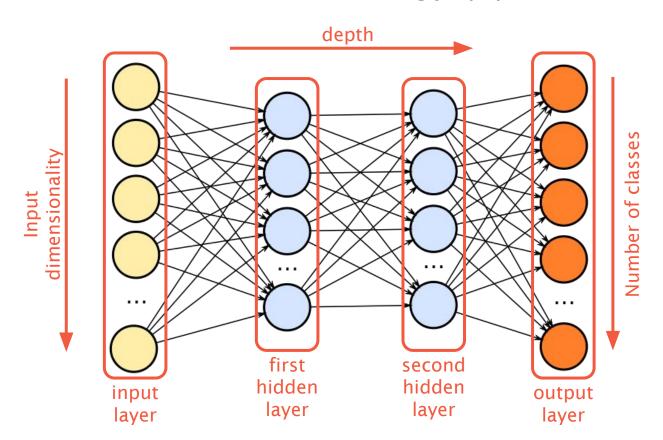
Neural Networks – terminology (1)

- Each logistic regression unit $(\hat{y} = \sigma(WX + b))$ is called a **neuron**.
- The matrices W and b are called weights and biases.
- Neurons sharing the same inputs X are called a layer.
- Using this definition, logistic regression is essentially a neural network with one layer.
- By adding a second layer, we give the network the capacity of modelling non-linear problems.
- The layer whose neurons constitute the network's output is called the **output layer**.
- The layers whose outputs are fed into another layer are referred to as hidden layers.

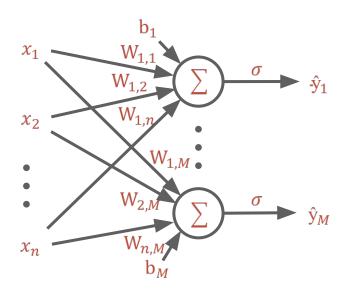
Neural Networks – terminology (2)



Neural Networks – terminology (3)



Inside each layer...



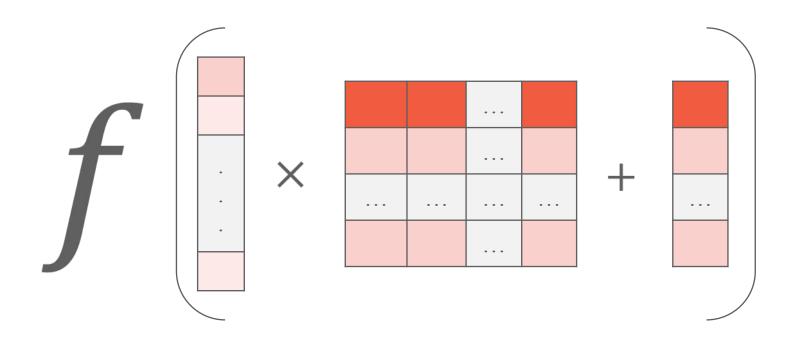
In matrix format

$$\hat{y} = f(XW + b)$$

If we have n input features and M neurons:

- Weight matrix has $M \times n$ values.
- Bias matrix has $M \times 1$ values.

Inside each layer...



$$\hat{y} = f(xW + b)$$

Activation functions

What exactly is f in $\hat{y} = f(xW + b)$?

f is a non-linear function called an activation function

The most popular functions are:

• sigmoid (what is used in logistic regression):

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

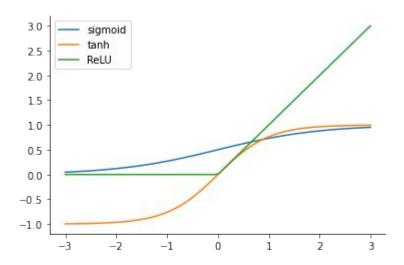
tanh

$$\tanh(z) = \frac{e^{2z} - 1}{e^{2z} + 1}$$

ReLU

$$ReLU(z) = max(0, z)$$

Activation functions

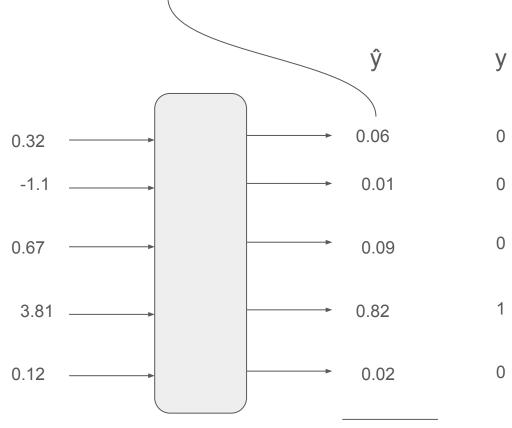


Output

- Regression (single value):
 - One output neuron
 - No activation function for the final layer
 - The output will be a single real number
- Classification:
 - Binary:
 - One output neuron
 - Sigmoid or softmax activation
 - The output will be a real number in [0, 1] (probability of belonging to class 1)
 - Multiclass:
 - Output neurons as many as classes
 - Softmax activation
 - The output will be a vector with one real number per class. All numbers are in [0, 1] and must sum to 1.

Softmax activation

$$\sigma(ec{z})_i = rac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$



1.00

Case study 2: MLP

Let's now see how well a Neural Network with one hidden layer (also referred to as a Multi-Layer Perceptron) performs on the same two datasets:

- <u>Linearly separable dataset</u>
- Not linearly separable dataset

Training: cost function

- The cost function is essentially a distance metric showing *how close* our predictions are to the labels.
- Cost functions always compare continuous values (even for classification)
- Regression:
 - Most commonly Mean Squared Error

$$J(y,\hat{y}) = \sum (y - \hat{y})^2$$

- Classification:
 - Most commonly cross-entropy

$$J(y,\hat{y}) = -\sum y \log \hat{y}$$

Softmax activation

	ŷ	У
	0.06	0
	0.01	0
Σy logŷ =	0.09	0
0 * log 0.06 + 0 * log 0.01 + + 1 * log 0.82	0.82	1
=	0.02	0

Training: backpropagation

- The cost function shows us how good or bad our model is doing.
- We need a way of knowing how much each parameter of the network contributed to the total loss:

$$\frac{\partial J}{\partial w} \ \forall \ w \in \theta$$

- **Backpropagation**: an algorithm that computes the partial derivatives of each parameter in the network efficiently
- · It does this by starting from the output layer and moving backwards.
- The vector containing all partial derivatives is called the **gradient** and it is key to training the network:

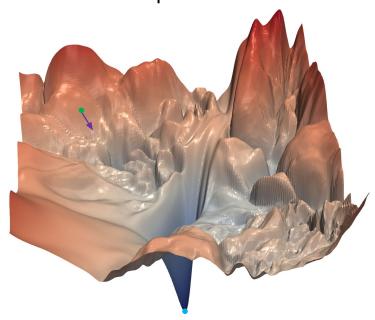
$$\nabla J = \left[\frac{\partial J}{\partial w_1}, \frac{\partial J}{\partial w_2}, \dots \right]$$

Training: optimization

- Besides the contribution of each parameter to the total error, the gradient shows us the **direction** we need to move each parameter to **decrease** the error.
- The optimizer is in charge of updating the parameters.
- Different optimizers have different strategies in updating their parameters.
- Ideally we'd want an optimizer that besides being good (i.e. reducing the loss), also converges fast.

Training: intuition and challenges

- Remember the loss landscape of linear regression?
- Here things are a bit more complicated...
- Consider this 2D representation of a Neural Network loss landscape:
- We start at one random point (random weight initialization) and want to reach the global minimum.
- The gradient shows us the slope of the surface at our current position.
- Problem: we can get stuck in local minima, ridges and plateaus!
- Even worse, the loss depicts performance on the training set, which does not always correlate with performance on the test set.



Case study 3: Even harder problems...

Let's now see how well a Neural Network with one hidden layer (also referred to as a Multi-Layer Perceptron) performs on the same two datasets:

- <u>Circles</u>
- Spiral