Introduction to Machine Learning - CS725
Instructor: Prof. Ganesh Ramakrishnan
Lecture 6 - Bayesian Inference for (Multivariate)
Gaussian and Bayesian Linear Regression

Recap: Bayesian Inference for Bernoulli

Let $\mathcal{D} \mid H$ follow a distribution Ber(p) (p is probability of heads) and p follow a distribution $Beta(p; \alpha, \beta) \sim \frac{p^{(\alpha-1)}(1-p)^{(\beta-1)}}{B(\alpha,\beta)}$,

The Maximum Likelihood Estimațe:

$$\hat{p} = \underset{p}{\operatorname{argmax}} {^{n}C_{h}p^{h}(1-p)^{n-h}} = \frac{h}{n}$$

The Posterior Distribution:

$$Pr(p \mid \mathcal{D}) = Beta(p; \alpha + h, \beta + n - h)$$

The Maximum a-Posterior (MAP) Estimate: The mode of the posterior distribution

$$\tilde{p} = \underset{H}{\operatorname{argmax}} \Pr(H \mid \mathcal{D}) = \underset{p}{\operatorname{argmax}} \Pr(p \mid \mathcal{D})$$

= argmax
$$Beta(p; \alpha + h, \beta + n - h) = \frac{\alpha + h - 1}{\alpha + \beta + \beta + \beta}$$

Recap: Conjugate Prior for (univariate) Gaussian

- Let $\Pr(X) \sim \mathcal{N}(\mu, \sigma^2)$ and let the data $\mathcal{D} = x_1...x_m$
- $\mu_{MLE} = \frac{1}{m} \sum x_i$ and $\sigma_{MLE}^2 = \frac{1}{m} \sum (x_i \mu_{MLE})^2$
- Suppose you are told that the conjugate prior for the (univariate) normally distributed random variable X in the case that σ^2 is not a random variable is $\Pr(\mu) = \mathcal{N}(\mu_0, \sigma_0^2)$. Then the **posterior** is?
- Answer: $\Pr(\mu|x_1...x_m) = \mathcal{N}(\mu_m, \sigma_m^2)$ such that $\mu_m =$ and $\frac{1}{\sigma_m^2} = \dots \qquad \therefore \quad \mathcal{U}_{\text{MLE}} \quad \mathcal{U}_{\text{Inter}}, \quad \mathcal{U}_{\text{m}} = \partial_t \mathcal{U}_{\text{MLE}} + \partial_z \mathcal{U}_{\text{o}} \qquad \text{is always a Gaussian}$ • Helpful tip: Product of Gaussians is always a Gaussian



$$\Pr(\mu) = \frac{1}{\sqrt{2\pi\sigma_0^2}} \exp\left(\frac{-(\mu - \mu_0)^2}{2\sigma_0^2}\right)$$

$$\Pr(x_i|\mu;\sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-(x_i - \mu)^2}{2\sigma^2}\right) \text{ if } \Pr(\mathbf{x}_i|\mathbf{M}_i \sigma^2)$$

$$\Pr(\mathcal{D}|\mu) = \left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^m \exp\left(\frac{-1}{2\sigma^2}\sum_{i=1}^m (x_i - \mu)^2\right) \text{ i.d.} \text{$$

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Our reference equality:

$$exp\left(\frac{-1}{2\sigma^2}\sum_{i=1}^m(x_i-\mu)^2-\frac{(\mu-\mu_0)^2}{2\sigma_0^2}\right)=exp\left(\frac{-1}{2\sigma_m^2}(\mu-\mu_m)^2\right),$$

Matching coefficients of μ^2 , we get

$$\left(\frac{5}{2} - \frac{1}{2\sigma^2}\right) - \frac{1}{2\sigma_0^2} = \frac{-1}{2\sigma_m^2} \int_{0}^{\infty} \frac{m}{\sigma^2} + \frac{1}{\sigma_0^2} = \frac{1}{\sigma_m^2}$$
An $m \rightarrow 0$, $\sigma_m^2 \propto \frac{1}{m}$

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Matching coefficients of μ^2 , we get

$$\frac{-\mu^2}{2\sigma_m^2} = \frac{-\mu^2}{2} \left(\frac{m}{\sigma^2} + \frac{1}{\sigma_0^2} \right) \Rightarrow$$

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$$\mu$$
, we get
$$\frac{-1}{2\sigma^2} \left(\frac{5}{2\sigma^2} - 21 \right) - \left(\frac{-24\sigma}{2\sigma^2} \right) = \frac{-(-24m)}{2\sigma^2}$$

Our reference equality:

$$exp\left(\frac{-1}{2\sigma^2}\sum_{i=1}^m(x_i-\mu)^2-\frac{(\mu-\mu_0)^2}{2\sigma_0^2}\right)=exp\left(\frac{-1}{2\sigma_m^2}(\mu-\mu_m)^2\right),$$

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Matching coefficients of μ , we get

$$\frac{2\mu\mu_m}{2\sigma_m^2} = \mu \left(\frac{2\sum_{i=1}^m x_i}{2\sigma^2} + \frac{2\mu_0}{2\sigma_0^2} \right) \Rightarrow$$



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Matching coefficients of μ , we get

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$$\mu_m = \sigma_m^2 \left(\frac{m\hat{\mu}_{ML}}{\sigma^2} + \frac{\mu_0}{\sigma_0^2} \right) \Rightarrow$$



Our reference equality:

$$\exp\left(\frac{-1}{2\sigma^2}\sum_{i=1}^m(x_i-\mu)^2-\frac{(\mu-\mu_0)^2}{2\sigma_0^2}\right)=\exp\left(\frac{-1}{2\sigma_m^2}(\mu-\mu_m)^2\right),$$
 Matching coefficients of μ^2 , we get
$$\frac{-\mu^2}{2\sigma_m^2}=\frac{-\mu^2}{2}(\frac{m}{\sigma^2}+\frac{1}{\sigma_0^2})\Rightarrow\frac{1}{\sigma_m^2}=\frac{1}{\sigma_0^2}+\frac{m}{\sigma^2}$$

$$\theta_i=\frac{m6\sigma^2}{m6\sigma^2}+\frac{m}{\sigma^2}$$
 Matching coefficients of μ , we get
$$\frac{2\mu\mu_m}{2\sigma_m^2}=\mu\left(\frac{2\sum_{i=1}^mx_i}{2\sigma^2}+\frac{2\mu_0}{2\sigma_0^2}\right)\Rightarrow\mu_m=\sigma_m^2\left(\frac{\sum_{i=1}^mx_i}{\sigma^2}+\frac{\mu_0}{\sigma_0^2}\right)$$
 or
$$\mu_m=\sigma_m^2\left(\frac{m\hat{\mu}_{ML}}{\sigma^2}+\frac{\mu_0}{\sigma_0^2}\right)\Rightarrow\mu_m=\left(\frac{\sigma^2}{m\sigma_0^2+\sigma^2}\mu_0\right)+\left(\frac{m\sigma_0^2}{m\sigma_0^2+\sigma^2}\hat{\mu}_{ML}\right)$$

Summary: Conjugate Prior for (univariate) Gaussian

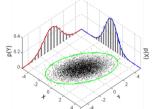
- Let $\Pr(X) \sim \mathcal{N}(\mu, \sigma^2)$ and let the data $\mathcal{D} = x_1...x_m$
- $\mu_{MLE} = \frac{1}{m} \sum_{i=1}^{m} x_i$ and $\sigma_{MLE}^2 = \frac{1}{m} \sum_{i=1}^{m} (x_i \mu_{MLE})^2$
- Suppose σ^2 is not a random variable and $\Pr(\mu) = \mathcal{N}(\mu_0, \sigma_0^2)$. • $\Pr(\mu|x_1...x_m) = \mathcal{N}(\mu_m, \sigma_m^2)$ such that
- $\mu_m = \left(\frac{\sigma^2}{m\sigma_0^2 + \sigma^2}\mu_0\right) + \left(\frac{m\sigma_0^2}{m\sigma_0^2 + \sigma^2}\hat{\mu}_{ML}\right)$ and $\left(\frac{1}{\sigma_m^2}\right) = \frac{1}{\sigma_0^2} + \frac{m}{\sigma^2}$ where $1/\sigma_0^2$ can be attributed to uncertainty in μ

and m/σ^2 can be attributed to noise in observation



Multivariate Normal Distribution and MLE estimate

• The multivariate Gaussian (Normal) Distribution is: $\mathcal{N}(\mathbf{x}; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}}|\Sigma|^{\frac{1}{2}}} e^{-\frac{1}{2}(\mathbf{x}-\mu)^T \Sigma^{-1}(\mathbf{x}-\mu)} \text{ when } \Sigma \in \Re^{n \times n} \text{ is positive-definite and } \mu \in \Re^n$



xi's are neither assumed to be independent nor have identical distribution

and
$$\mu \in \mathbb{R}^n$$

$$\chi = \left[\chi_1 - \dots \chi_n \right]$$

$$\text{het} \quad \chi_1 - \chi_n \wedge \mathcal{N}(\cdot)$$

$$\text{individually}$$

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$$\text{subsets of } \left[\chi_1 - \chi_n \right] \sim \mathcal{N}(\cdot)$$

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Multivariate Normal Distribution and MLE estimate

Can be ignored for the

• The multivariate Gaussian (Normal) tribution is: $\mathcal{N}(\mathbf{x};\mu,\Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}}|\Sigma|^{\frac{1}{2}}} e^{-\frac{1}{2}(\mathbf{x}-\mu)^T \Sigma^{-1}(\mathbf{x}-\mu)} \text{ when } \Sigma \in \Re^{n\times n} \text{ is positive-definite and } \mu \in \Re^n$ $\mu_{MLE} = \frac{1}{m} \sum_{i=1}^{m} \mathbf{x}_{i} \sim \frac{1}{m} \sum_{i=1}^{m} \phi(\mathbf{x}_{i}) \text{ and } \frac{\text{dostract}}{\text{represent}}$ $\sum_{MLE} \sim \frac{1}{m} \sum_{i=1}^{m} (\phi(\mathbf{x}_i) - \mu_{MLE}) (\phi(\mathbf{x}_i) - \mu_{MLE})^T$ $\sum_{MLE} \sim \frac{1}{m} \sum_{i=1}^{m} (\phi(\mathbf{x}_i) - \mu_{MLE}) (\phi(\mathbf{x}_i) - \mu_{MLE})^T$ $\sum_{MLE} \sim \frac{1}{m} \sum_{i=1}^{m} (\phi(\mathbf{x}_i) - \mu_{MLE}) (\phi(\mathbf{x}_i) - \mu_{MLE})^T$ $\sum_{MLE} \sim \frac{1}{m} \sum_{i=1}^{m} (\phi(\mathbf{x}_i) - \mu_{MLE}) (\phi(\mathbf{x}_i) - \mu_{MLE})^T$ $\sum_{MLE} \sim \frac{1}{m} \sum_{i=1}^{m} (\phi(\mathbf{x}_i) - \mu_{MLE}) (\phi(\mathbf{x}_i) - \mu_{MLE})^T$ $\sum_{MLE} \sim \frac{1}{m} \sum_{i=1}^{m} (\phi(\mathbf{x}_i) - \mu_{MLE}) (\phi(\mathbf{x}_i) - \mu_{MLE})^T$ $\sum_{MLE} \sim \frac{1}{m} \sum_{i=1}^{m} (\phi(\mathbf{x}_i) - \mu_{MLE}) (\phi(\mathbf{x}_i) - \mu_{MLE})^T$

Summary for MAP estimation with Normal Distribution

Sumulative: With
$$\mu \sim \mathcal{N}(\mu_0, \sigma^2_0)$$
 and $\mathbf{x} \sim \mathcal{N}(\mu, \sigma^2)$, $p(\mathbf{x}|D) \sim \mathcal{N}(\mu_m, \sigma_m^2)$ and $\mathbf{x} \sim \mathcal{N}(\mu, \sigma^2)$, $p(\mathbf{x}|D) \sim \mathcal{N}(\mu_m, \sigma_m^2)$ and $\mathbf{x} \sim \mathcal{N}(\mu, \sigma^2)$ and $\mathbf{x} \sim \mathcal{N}($

Summary for MAP estimation with Normal Distribution

• Univariate: With $\mu \sim \mathcal{N}(\mu_0, \sigma^2_0)$ and $x \sim \mathcal{N}(\mu, \sigma^2), p(x|D) \sim \mathcal{N}(\mu_m, \sigma_m^2)$

$$\frac{1}{\sigma_m^2} = \frac{m}{\sigma^2} + \frac{1}{\sigma_0^2}$$
$$\frac{\mu_m}{\sigma_m^2} = \frac{m}{\sigma^2} \hat{\mu}_{mle} + \frac{\mu_0}{\sigma_0^2}$$

• Multivariate: By **extrapolation** (Bayesian setting for fixed Σ) $\mathbf{x} \sim \mathcal{N}(\mu, \Sigma), \ \mu \sim \mathcal{N}(\mu_0, \Sigma_0) \ \& \ p(\mathbf{x}|D) \sim \mathcal{N}(\mu_m, \Sigma_m)$

$$egin{align} \Sigma_m^{-1} &= m \Sigma^{-1} + \Sigma_0^{-1} \ \Sigma_m^{-1} \mu_m &= m \Sigma^{-1} \hat{\mu}_{mle} + \Sigma_0^{-1} \mu_{0} \ \end{pmatrix}$$



Different Estimators

	Point?	p(x D)
MLE 🗸	$\hat{ heta}_{MLE} = \operatorname{argmax}_{ heta} LL(D heta)$	$p(x \theta_{MLE})$
Bayes Estimator	$\hat{ heta}_B = extstyle E_{p(heta D)} E[heta]$	$p(x \theta_B)$
MAP 🗸	$ig \hat{ heta}_{ extit{MAP}} = \operatorname{argmax}_{ heta} extit{p}(heta D)$	$p(x \theta_{MAP})$
Pure Bayesian		$p(\theta D) = \frac{p(D \theta)p(\theta)}{\int_{m} p(D \theta)p(\theta)d\theta}$
	Opnor - D - Opost	$egin{aligned} ho(D heta) = \prod_{i=1}^{r} ho(x_i heta) \end{aligned}$
Pi	(x D) = query pt x	$p(x D) = \int_{\theta} p(x \theta)p(\theta D)$

Back to Linear Regression: Why Bayesian?

- The Bayesian interpretation of probabilistic estimation is a logical extension that enables reasoning with uncertainty but in the light of some background belief
- Bayesian linear regression: A Bayesian alternative to Maximum Likelihood least squares regression to address overfitting
- Continue with Normally distributed errors
- Model the w using a prior distribution and use the posterior over w as the result
- Intuitive Prior: Components of **w** should not become too large!



Back to Linear Regression: Prior Distribution for w

$$y = \mathbf{w}^T \phi(\mathbf{x}) + \varepsilon$$

 $\varepsilon \sim \mathcal{N}(0, \sigma^2)$

- Maximum (log)-likelihood estimate is $\hat{\mathbf{w}}_{MLE} = (\Phi^T \Phi)^{-1} \Phi^T y$
- We can use a Prior distribution on w to avoid over-fitting

$$W_i \sim N(O_i \frac{1}{\lambda}) \circ R N(O_i \sigma^2)$$
 $997. W_i \in [-\frac{3}{1\lambda}, +\frac{3}{1\lambda}] \quad HW: \quad \text{on} \quad W \in N(O_i \neq I)$

Back to Linear Regression: Prior Distribution for w

$$y = \mathbf{w}^{T} \phi(\mathbf{x}) + \varepsilon$$
 $\varepsilon \sim \mathcal{N}(0, \sigma^{2})$

- Maximum (log)-likelihood estimate is $\hat{\mathbf{w}}_{MLE} = (\Phi^T \Phi)^{-1} \Phi^T y$
- We can use a Prior distribution on \mathbf{w} to avoid over-fitting $w_i \sim \mathcal{N}(0, \frac{1}{\lambda})$

(that is, each component w_i is approximately bounded within $\pm \frac{3}{\sqrt{\lambda}}$ by the $3-\sigma$ rule). λ is also called the precision of the Gaussian

• Q: Bayesian Estimation?

