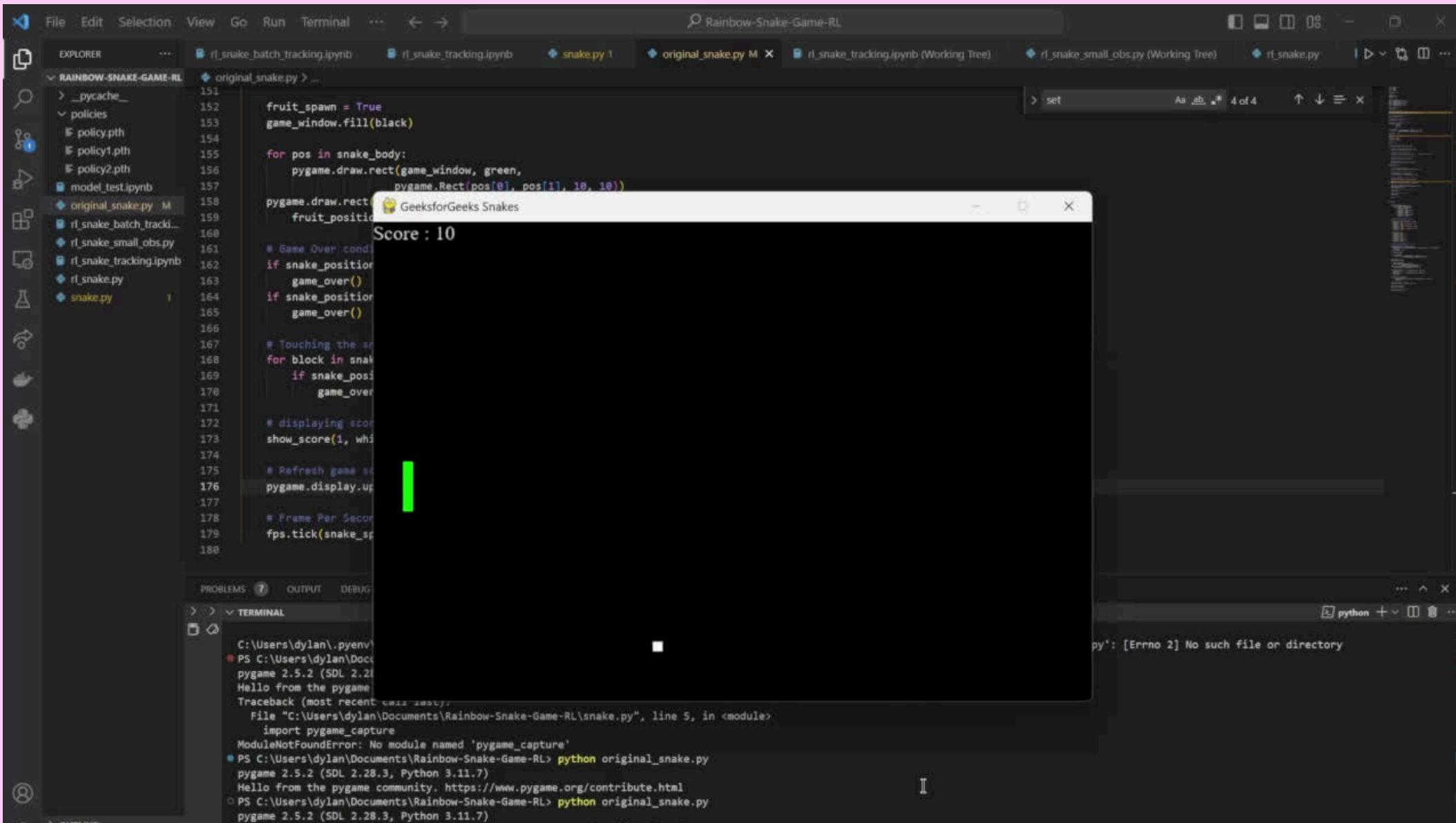


REINFORCEMENT LEARNING RAINBOW SNAKE

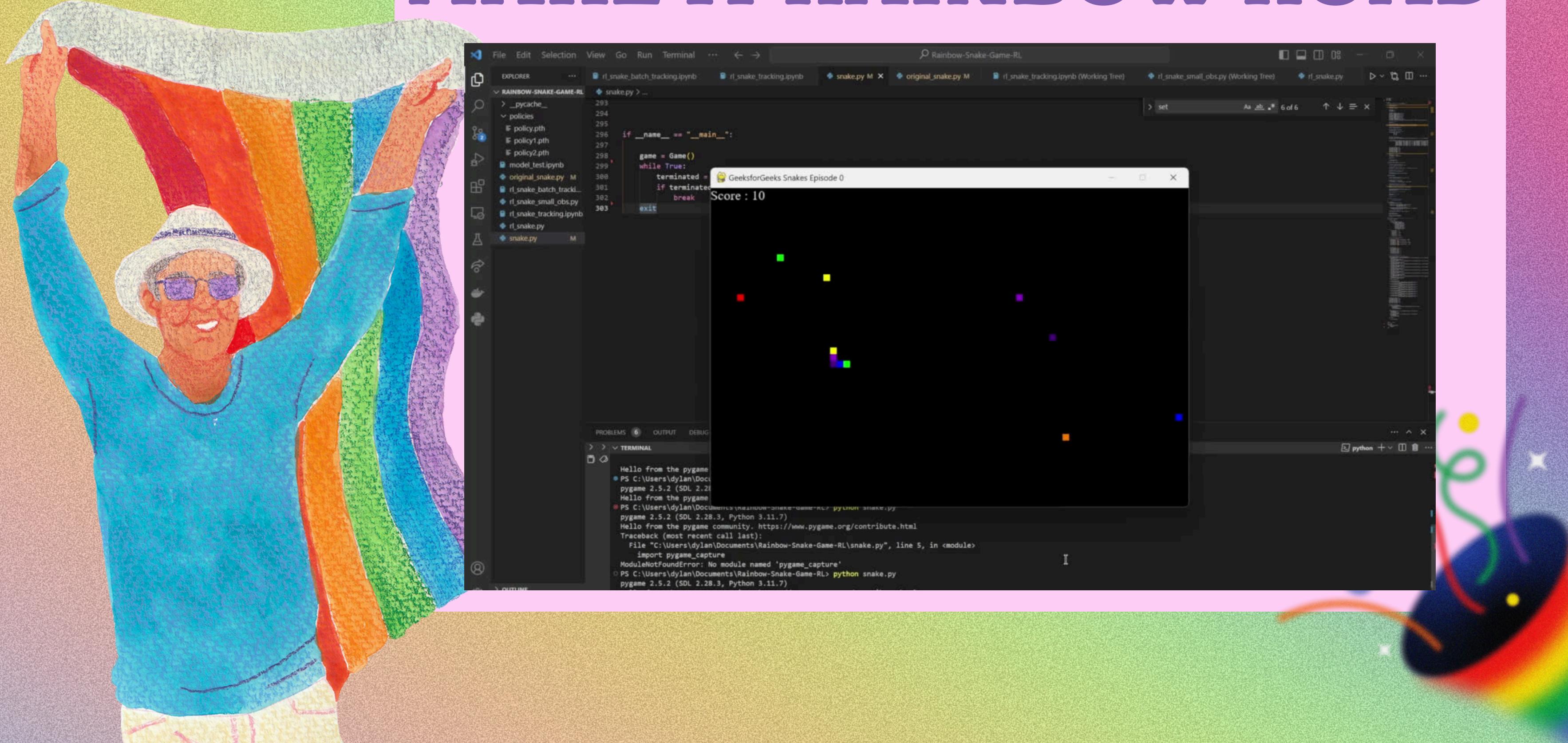
Created by: Dyla Louie

THE GAME:



<https://www.geeksforgeeks.org/snake-game-in-python-using-pygame-module/>

MAKE IT RAINBOW ROAD



MODEL ARCHITECTURE

Double DQN

```
class DQN(nn.Module):
    def __init__(self, n_observations, n_actions):
        super(DQN, self).__init__()
        self.fc1 = nn.Linear(n_observations, 128)
        self.fc2 = nn.Linear(128, 128)
        self.fc3 = nn.Linear(128, 128)
        self.fc4 = nn.Linear(128, n_actions)

    def forward(self, x):
        x = F.relu(self.fc1(x))
        x = F.relu(self.fc2(x))
        x = F.relu(self.fc3(x))
        x = self.fc4(x)
        return x
```

```
# hyperparameters
batch_size = None
gamma = 0.99
epsilon = 0.90
epsilon_start = 0.90
epsilon_end = 0.05
epsilon_decay = 50
tau = 0.005
lr = 1e-3
batch_size = 128

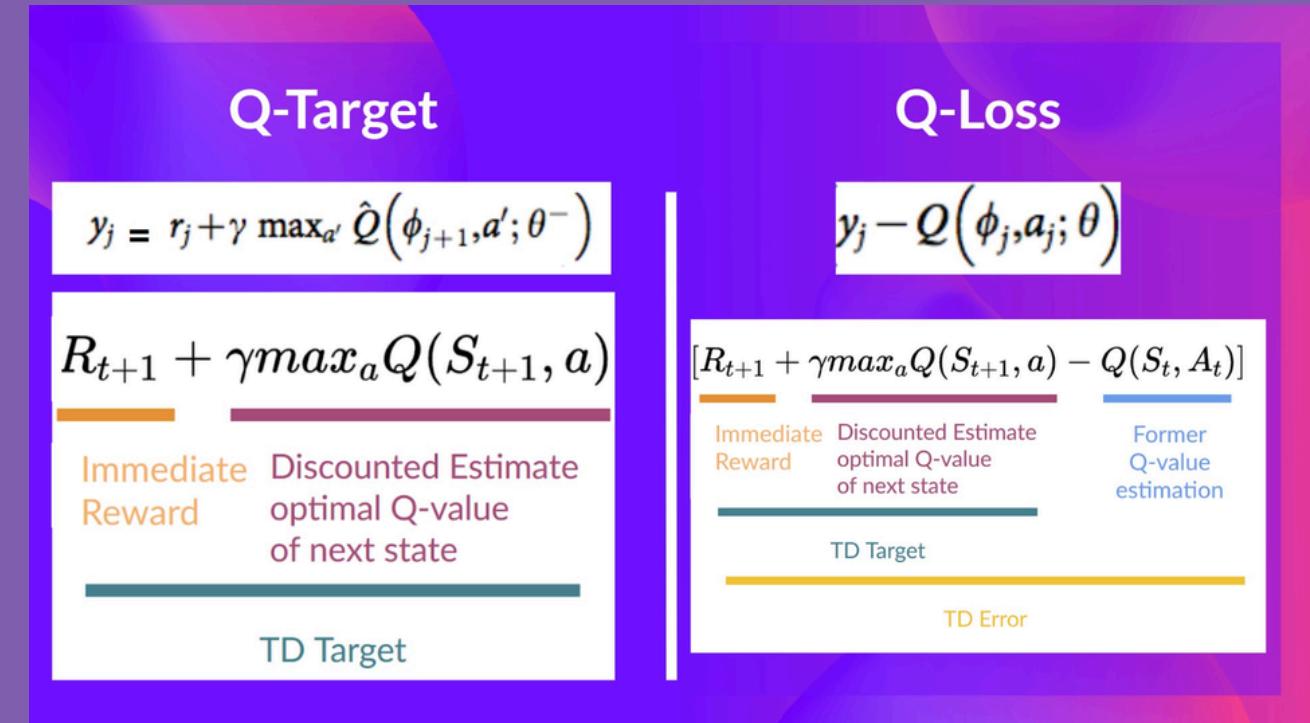
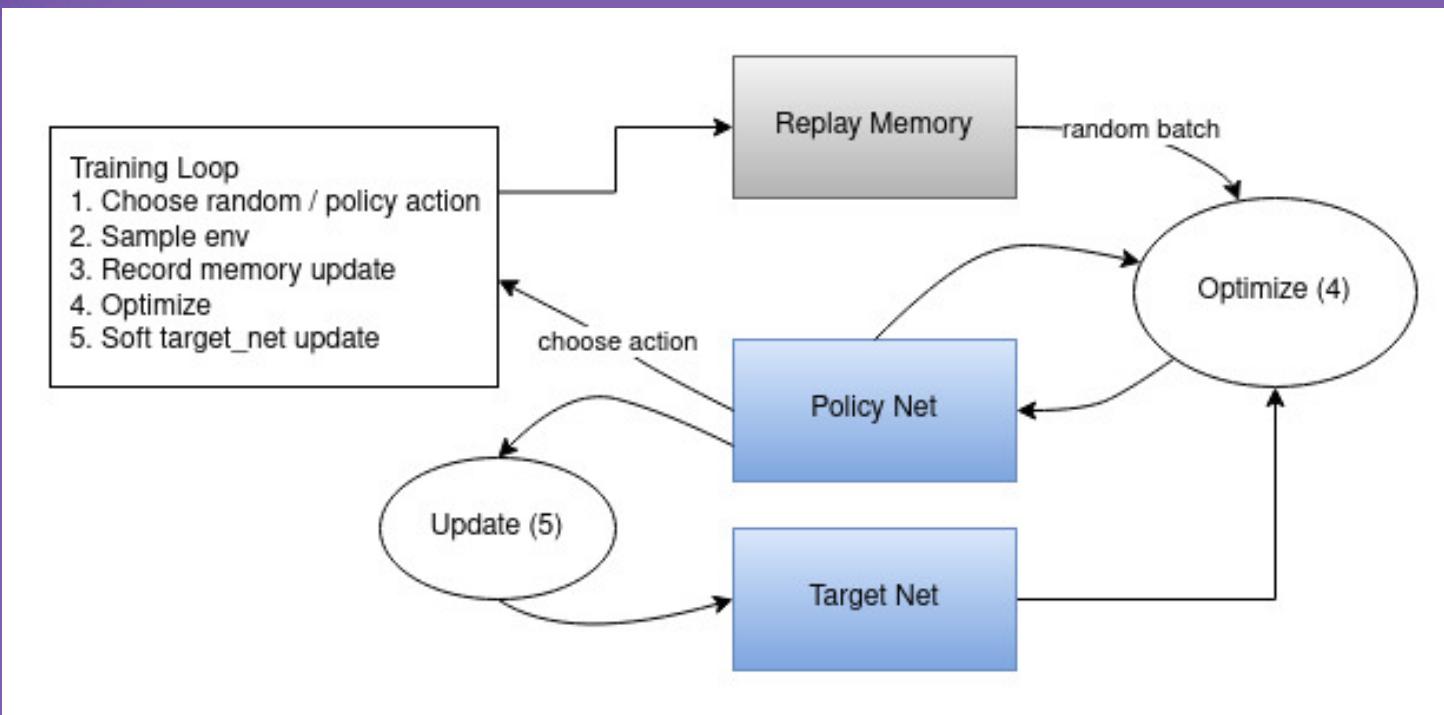
# action space and observation space size
x_window_size = 720
y_window_size = 480
x_axis_size = int(x_window_size / 10)
y_axis_size = int(y_window_size / 10)
n_actions = 4 # up down left right
n_observations = 28 # length of obs vectpr

# initialize neural networks
policy_net = DQN(n_observations, n_actions) #.to(device)
target_net = DQN(n_observations, n_actions) #.to(device)

# set target net to have the same weights as policy net
target_net.load_state_dict(policy_net.state_dict())

# set optimizer
optimizer = optim.AdamW(policy_net.parameters(), lr=lr, amsgrad=True)
```

MODEL ARCHITECTURE



STRUGGLES

- Designing Reward
- Snake not Learning T-T

CREDITS

- https://pytorch.org/tutorials/intermediate/reinforcement_q_learning.html
- <https://www.geeksforgeeks.org/snake-game-in-python-using-pygame-module/>
- <https://huggingface.co/learn/deep-rl-course/unit0/introduction>

PROUD