Finite-Dimensional Vector Space

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Given a list of vectors $v_1, v_2, ..., v_n \in V(F)$, and a list of scalars $c_1, c_2, ..., c_n (i = 1, 2, ..., n) \in F$

$$c_1 v_1 + c_2 v_2 + \ldots + c_n v_n$$

is then called linear combination of $\{v_1, v_2, ..., v_n\}$. All linear combinations of a certain list of vectors form a set called spanning set, notation by $\operatorname{span}\{v_1, v_2, ..., v_n\}$.

Span is the smallest containing subspace

Theorem 1. The span of a list of vectors is the smallest subspace containing all the vectors of the list

Proof. For a list of vectors $v_1, v_2, ..., v_n \in V$

Let $a_i = 0$ for i = 1, 2, ..., n, $a_1v_1 + a_2v_2 + ... + a_nv_n = 0 \in \text{span}(v_1, v_2, ..., v_n)$ $\{b_i\}$ for i = 1, 2, ..., n is another list of scalars than $\{a_i\}$, $a_i \neq 0$ here

 $(b_1v_1 + \ldots + b_nv_n) + (a_1v_1 + a_2v_2 + \ldots + a_nv_n) = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n \in \operatorname{span}\{v_1, v_2, \ldots, v_n\} = (a_1 + b_1)v_1 + \ldots + (a_n + b_n)v_n +$

 λ is a scalar in F

$$\lambda(a_1v_1 + ... + a_nv_n) = \lambda a_1v_1 + ... + \lambda a_nv_n \in \text{span}\{v_1, v_2, ..., v_n\}$$

Thus span $\{v_1, v_2, ..., v_n\}$ is a subspace of V, and since any subspace containing all vectors of $\{v_i\}$ must contain their span (from the definition of vector space), any subspace other than the span is "larger" (containing more vectors) than the span.

If a list of vectors form a span which is equal to V, in other words, span $\{v_1, v_2, ..., v_n\} = V$, we say $v_1, v_2, ..., v_n$ span V. If a vector space can be spanned by a finite set of vectors within itself, it is a *finite dimensional vector space*, otherwise, an *infinite vector space*. (Not really defined yet here)

Polynomial P(F)

A function $P: F \to F$ is said to be a *polynomial* with coeffecients if there are $a_0, a_1, a_2, ..., a_m \in F$ s.t.

$$p(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_m x^m$$
 for $x \in F$

P(F) is the set of all polynomials with coefficients in F, it is a subspace of F^F . Every polynomial can be uniquely determined by its coefficients.

A polynomial is said to have a degree of m if there are coefficients $a_m \neq 0$, $a_i(i > m) = 0$ s.t.

$$p(x) = a_0 + a_1 x + \dots + a_m x^m + (a_i x^{m+1} + \dots)$$

Zero polynomial is defined to have a degree $-\infty$

 $P_m(F)$ is defined as the set containing all polynomials of which degree is no more than m.

What if a vector in a span can be uniquely represented, i.e. only one list of scalars makes it a linear combination of a certain list of vectors. Here we define *linear independence*.

Suppose a list of vectors $v_1, v_2, ..., v_n$ in V_F , if the only choice to make $a_1v_1 + a_2v_2 + ... + a_nv_n$ is $a_1 = a_2 = ... = a_n = 0$, then $v_1, v_2, v_3, ..., v_n$ are linear independent.

The definition is just a unique of representatin of zero. Suppose there is a nonzero vector $v \in \text{span}\{v_1, v_2, ..., v_n\}$, and that it cannot be uniquely represented, that is

there exist $\{a_i\}$ $\{b_i\}$ s.t.

$$v = a_1 v_1 + a_2 v_2 + \dots + a_n v_n \tag{1}$$

$$v = b_1 v_1 + b_2 v_2 + \dots + b_n v_n \tag{2}$$

$$(1) - (2)$$
: $(a_1 - b_1)v_1 + ... + (a_n - b_n)v_n = 0$

(1) – (2): $(a_1 - b_1)v_1 + ... + (a_n - b_n)v_n = 0$ Since $\{v_i\}$ is linearly independent, $a_i - b_i = 0$ $(i = 1, 2, ..., n) \rightarrow a_i = b_i$, thus v must be uniquely represented by $\{v_i\}$.

Conversely, if all vectors can be uniquely represented, choose 0, all coefficients must be zero, implying linear independence (the definition of linear independence). Thus, for a list of vectors, linear independence is equivalent to unique representation. And linear independence is so defined that we can coefficients other than all zeros s.t. $a_1v_1 + + a_nv_n = 0$.