

## Daniel Johan

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### EDUCATION

**University of Notre Dame** | Notre Dame, IN  
*Bachelor of Science* | Computer Science and Engineering

August 2022 - May 2026  
GPA: 3.92 | *Dean's List* | *Tau Beta Pi*

### SKILLS

**Languages:** Python, C, C++, Java, Go, HTML, CSS, JavaScript, bash, MATLAB

**Technical:** GitHub, REST API, Flask, PyTorch, Tensorflow, openCV, Jupyter, Machine Learning, Linux, Statistics, Linear Algebra

### RELATED COURSEWORK

Data Science, Computer Vision, Game Development, Computer Graphics, Natural Language Processing, Introduction to AI, Operating Systems Principles, Data Structures, Algorithms, Computer Architecture

### INTERNSHIPS/EXPERIENCE

**KPMG** | Dallas, TX

June 2025 – August 2025

*Enterprise Architecture Intern*

- Prototyped AI agents integrating **LeanIX APIs** with **OpenAI**, automating analysis of **100+** enterprise architecture components and reducing manual reporting time by **40%**.
- Presented AI-enhanced insights to executives, highlighting opportunities for **20%** cost savings across enterprise processes.

**University of Notre Dame & Lockheed Martin** | Notre Dame, IN

September 2024 – Present

*Machine Learning Engineer Intern*

- Developed **autonomous multi-agent simulations** that increased search-and-rescue mission success rate by **75%** and reduced simulated response time
- Optimized **ML** pipelines with **LangChain** and **RAG**, decreasing data processing time by **60%** while integrating **OpenAI API** for structured decision outputs.

**Yaskawa** | Kitakyushu, Japan

May 2024 – June 2024

*Researcher*

- **Collaborated with Japanese university students** to develop and refine a calibration algorithm for a robotic arm in microchip production, reducing positioning errors to **<100 microns** and increasing simulated throughput by **15%**.

**Kubota** | Tokyo, Japan

July 2024 - August 2024

*Researcher*

- Designed a **PID-controlled** autonomous tractor system in **C**, enabling simulated tractor trajectory corrections with less than 5° deviation on uneven terrain and improving simulated efficiency by 20% compared to baseline.

### PROJECTS AND ACTIVITIES

**Mini Golf Game** | University of Notre Dame

- Developing a **3D mini golf game** in **Godot** with **Blender** models; implemented physics-based ball interactions and **ray-traced** lighting to enhance visual fidelity and gameplay immersion for a playable prototype.

**SteamPunk Discord Bot**

- Built a **full-stack Discord bot** with **Python** backend and **Go** frontend for a server of **600+ users**, optimizing **REST API** calls and pipelines to provide low-latency, real-time game and player data notifications.
- Integrated API caching and rate-limiting to support over **10,000** requests/day without performance degradation.

**Object Tracking Robot**

- Designed a robot using a U-Net Neural Network for real-time object tracking with **92% accuracy**, processing **60 frames/sec** via **multithreading** for continuous tracking of multiple objects.
- Conducted training on a **3,000+** image dataset, improving robustness to lighting changes and occlusions.

**Notre Dame Robotic Football**

August 2023 - Present

- Managing code for **20+** robots, integrating **computer vision** with arUco markers, improving throwing accuracy and movement precision, and reducing error in dynamic simulations.

**CS for Good**

August 2022 - May 2024

- Engineered a **Django/Python** backend with a scalable database, enabling real-time progress tracking for **100+** students and reducing latency by **30%**.