Building Prior Knowledge

Our

Signals

Estimation Format

Algorithms

$$egin{bmatrix} x(t_1) & y(t_1) & z(t_1) & t_1 \ x(t_2) & y(t_2) & z(t_2) & t_2 \ x(t_3) & y(t_3) & z(t_3) & t_3 \ x(t_4) & y(t_4) & z(t_4) & t_4 \ & \cdots & \cdots & \cdots \end{bmatrix}$$