

## Centrality and Specialization

I read through the changes you made and they seem great.

Dallas does use  $A_{ij}$  is an edge from  $v_i$  to  $v_j$  so I'll need to change my proofs.

I looked at the section on dynamic networks and it looks like you were using the  $A_{ij}$  is an edge from  $v_j$  to  $v_i$ , specifically after definition 4.2 in the equation:

$$F_i(\mathbf{x}) = \sum_{j=1}^n A_{ij} f_{ij}(x_j), \quad \text{for } i \in N = \{1, 2, \dots, n\} \quad (1)$$

To me, it looks like you are using  $A_{ij}$  to weight the effect  $x_j$  has on  $x_i$ . Thus it seems to represent the edge weight from  $v_j$  to  $v_i$ .

This is important because I'm concerned that I need to define eigenvectors for the transpose of the adjacency matrix. When we define the adjacency matrix  $A$  the way Dallas did, the dynamics should technically be  $F(\mathbf{x}) = A^T \mathbf{x}$  (for example), then the eigenvectors that really matter are the eigenvectors of  $A^T$  and my results should be about those. (Hope that made sense...)

Also, I think that we do get a little more than just centrality for free, so why don't we go ahead and include a lambda in the eigenvector transfer matrix to make it more general. Maybe  $T_\lambda(\beta, Z)$ . I'll think more carefully about this as well as the result for weighted graphs as I rewrite my proof.

I've put together a plan for using the updated definitions to prove my results in the appendix. Let me know what you think.

## Theorem

**(Eigenvectors of Specialized Graphs)** Let  $G = (V, E, \omega)$  be a graph and  $B \subseteq V$  a base.

(i) If  $(\lambda, \mathbf{x})$  is an eigenpair of the graph  $G$  and  $\lambda \notin \sigma(G|_B)$  then there is an eigenpair  $(\lambda, \mathbf{y})$  of  $\mathcal{S}_B(G)$  such that  $\mathbf{x}_B = \mathbf{y}_B$ .

Furthermore, suppose  $G$  is strongly connected with positive edge weights and let  $\mathbf{u}$  be a leading eigenvector of  $G$ . Also, let  $Z$  be a strongly connected component of  $\beta \in \mathcal{B}_S(G)$ . Then there is a leading eigenvector  $\mathbf{v}$  of  $\mathcal{S}_B(G)$  such that the following hold.

(ii) For all  $Z_i \in \mathcal{C}(Z)$  the eigenvector restriction

$$\mathbf{v}_{Z_i} = T(\beta, Z) \mathbf{v}_B.$$

Hence, if  $Z_i, Z_j \in \mathcal{C}(Z)$  have the same incoming branch then  $\mathbf{v}_{Z_i} = \mathbf{v}_{Z_j}$ .

(iii) For  $Z_i \in \mathcal{C}(Z)$  let  $\cup_{k=1}^\ell \{Z_k\}$  be the copies of  $Z$  that have the same outgoing

branch as  $Z_i$ . Then

$$\mathbf{u}_Z = \sum_{k=1}^{\ell} \mathbf{v}_{Z_k} = \sum_{k=1}^{\ell} T(\beta, Z) \mathbf{v}_B.$$

*Proof.* (ii) with the new definition this will be really easy

(iii) I'll need the lemma below. I've reworked it to fit with the new definitions  $\square$

### Definition

Let  $S_i, S_j$  be strongly connected components of a graph  $G$ . Let  $S$  be the set of vertices containing in  $S_i$  and  $S_j$ . We let

$$B_{in}(S_i, S_j) = \{In(\beta, S_j) \mid \beta \in \mathcal{B}_{S_i}(G)\}$$

### Lemma

Assume  $G = (V, E, \omega)$  is not strongly connected and let  $\lambda \notin \sigma(G)$ . If  $S_1, S_2, \dots, S_k$  are the strongly connected components of  $G$ , then there exists an adjacency matrix  $A$  for  $G$  such that

$$(\rho I - A)^{-1} = \begin{bmatrix} X_{11} & X_{12} & \cdots & X_{1k} \\ & X_{22} & \cdots & X_{2k} \\ & & \ddots & \vdots \\ X_{kk} & & & \end{bmatrix}$$

Where

$$X_{ij} = \sum_{\beta \in B_{in}(S_j, S_i)} T(\beta, S_i) (\rho I - S_j)^{-1}$$

if  $i < j$  and

$$X_{ij} = (\rho I - S_j)^{-1}$$

if  $i = j$