

Interfere: Studying Intervention Response Prediction in Complex Dynamic Models

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Summary

The Interfere package focuses on *intervention response prediction*—forecasting how complex, dynamic systems respond to novel interventions. When developing predictive methods capable of solving this problem, ideal benchmarking data comes from controlled, longitudinal experiments. Such experiments are often infeasible due to confounding, cost, and ethical constraints.

Synthetic benchmarks, which are often used in response to this problem [cite], typically rely on models with static linear relationships and overly independent noise profiles that lack the complex interdependent feedback we find in the real world.

As a solution, we propose a middle ground: Scientists in many disciplines, such as economics, ecology, systems biology and others, employ mechanistic dynamic models as a part of their research and application toolkit (Baker et al., 2018; Banks et al., 2017; Brayton et al., 2014; Izhikevich & Edelman, 2008). Many of these models are accompanied by a body of evidence demonstrating that they do indeed capture important characteristics of the real world problems they emulate. Instead of using simple synthetic data for benchmarking, we propose using data generated by detailed scientific models as a ground truth against which we can benchmark methods that predict intervention response.

The logic is this: Methods that accurately predict intervention responses of scientific models should generalize to real-world processes insofar as these models capture them.

Interfere offers the first steps towards this vision by combining (1) a general interface for simulating the effect of interventions on dynamic models, (2) a suite of predictive methods and cross validated hyper parameter optimization tools, and (3) the first known [extensible benchmark data set](#) of dynamic intervention response scenarios see Figure 1.

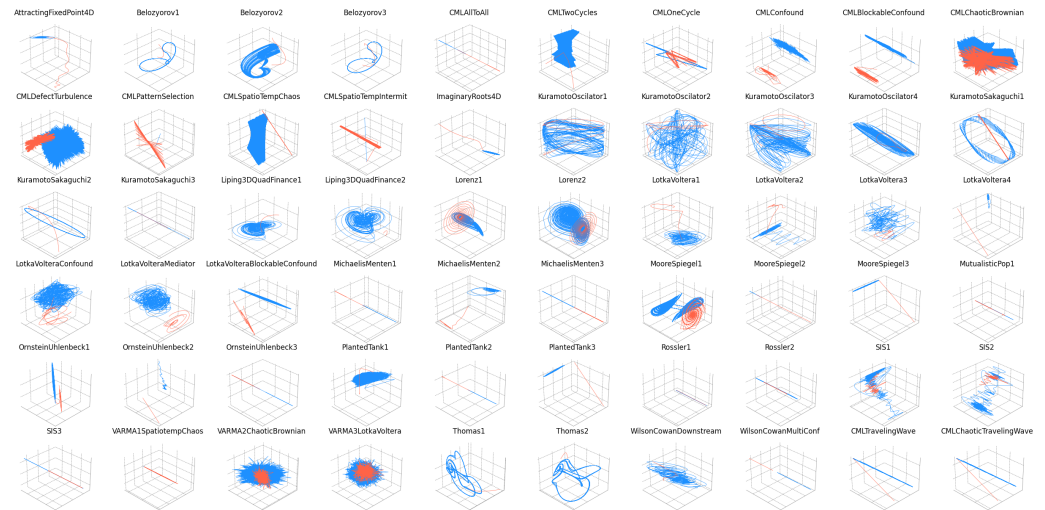


Figure 1: Three-dimensional trajectories of sixty scenarios simulated with the Interfere package. Simulated models are either differential equations or discrete time difference equations. Trajectories in blue represent the natural behavior of the system, while red depicts response to a specified intervention. For models with more than three dimensions, only the three dimensions with highest variance are shown. These sixty scenarios, making up the [Interfere Benchmark 1.1.1](#) for intervention response prediction, are available for download.

29 Statement of Need

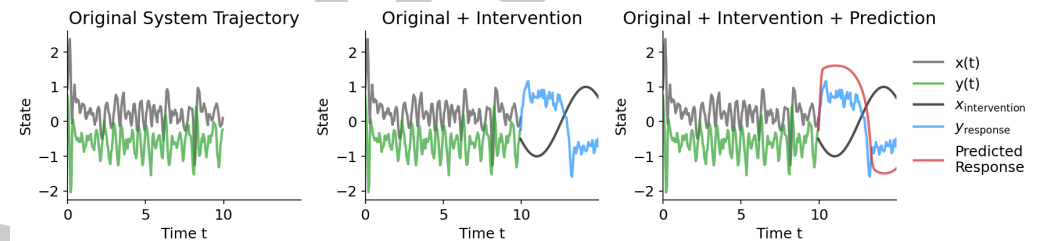


Figure 2: Original System Trajectory (Left): The natural, uninterrupted evolution of the quadratic Belozyorov system ([Belozyorov, 2015](#)) simulated using the Interfere package with a small amount of stochastic noise. **System Trajectory After Intervention (Center):** The effect that taking exogenous control of $x(t)$ by via $do(x(t) = \sin(t))$ beginning at time $t = 10$ has on y . The intervention (black) and response (blue), depict a clear departure from the natural behavior of the system (green and gray). **Intervention Response Prediction (Right):** Example of forecasting the response of the Belozyorov system to the sinusoidal intervention. The ground truth response, $y(t)$ for $t > 10$ is plotted in blue. Here, an equation discovery algorithm, SINDy, ([Brunton et al., 2016](#)) is fit to the data that occurs prior to the intervention and makes an attempt to predict the intervention response (red curve).

30 Over the past twenty years, multiple frameworks have emerged for identifying causal relationships
31 in observational data ([Imbens & Rubin, 2015](#); [Pearl, 2009](#); [Wieczorek & Roth, 2019](#)). The most
32 influential frameworks are probabilistic and, while it is not a necessary condition for identifying
33 causality, a static, linear relationship has often been assumed. However, when attempting to
34 anticipate the response of complex dynamic systems in the medium and long term, a linear
35 approximation of the dynamics can be insufficient. Therefore, non-linear, dynamic techniques
36 have been employed for causal discovery and forecasting (e.g. [Runge, 2022](#)). Nevertheless,
37 there are relatively few techniques that are able to fit causal dynamic nonlinear models to data.
38 Leveraging recent advancements in causal inference and historical work in dynamic modeling

and simulation, we focus on a key problem — predicting how a complex system responds to a previously unobserved intervention — and designed the Interfere package for benchmarking tools aimed at this intervention response prediction. The dynamic models contained in Interfere present challenges for this prediction that likely require incorporating mechanistic assumptions alongside probabilistic frameworks for causality. Interfere allows researchers to validate predictive dynamic methods against simulated intervention scenarios, encouraging cross-pollination between probabilistic causal inference and modeling/simulation perspectives.

Primary Contributions

Interfere provides three primary contributions: (1) dynamically diverse counterfactuals, (2) cross-disciplinary forecast methods, and (3) comprehensive and extensible benchmarking.

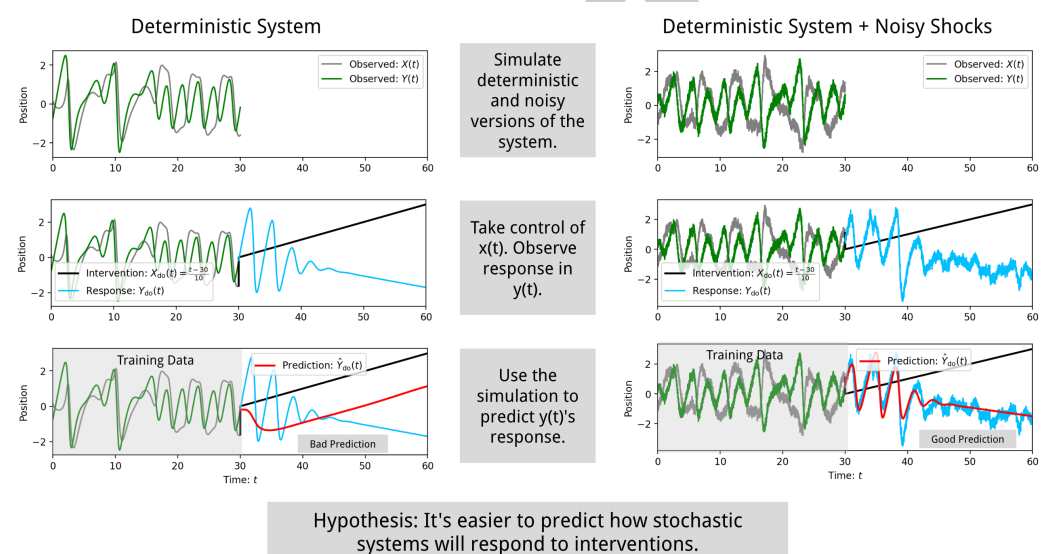


Figure 3: Example experimental setup possible with Interfere: Can stochasticity help reveal associations between variables? Interfere can be used to compare intervention response prediction for deterministic and stochastic versions of the same system.

1. Dynamically Diverse Counterfactuals at Scale

Whereas most predictive methods for complex dynamics are typically benchmarked on fewer than ten systems (Brunton et al., 2016; Challu et al., 2023; Pathak et al., 2018; Prasse & Van Mieghem, 2022; Vlachas et al., 2020), Interfere's "dynamics" submodule contains over fifty dynamic models, with a mix of linear, nonlinear, chaotic, continuous-time, discrete-time, stochastic, and deterministic models, from a variety of disciplines including finance, ecology, biology, neuroscience and public health. Most importantly, Interfere is built for studying interventions: each model inherits the Interfere BaseDynamics type, with possible exogenous control of any observed state, added measurement noise, and, for most models, stochasticity controlled by a scalar parameter or fine tuned with a covariance matrix. Interfere thus offers a user-friendly framework to produce complex dynamic intervention response and standard forecasting scenarios at scale.

2. Cross Disciplinary Forecast Methods

Interfere integrates dynamic *forecasting* methodologies from deep learning (LSTM, NHITS), applied mathematics (SINDy, Reservoir Computers) and social science (VAR). The Interfere

64 “ForecastingMethod” class is expressive enough to describe, fit and predict with multivariate
65 dynamic models and apply interventions to the states of the models during prediction.

66 3. Comprehensive and Extensible Benchmarking

67 Interfere organizes a variety of dynamic scenarios into the [Interfere Benchmark](#), a comprehensive
68 and extensible set containing 60 intervention response scenarios for testing, each simulated
69 with different levels of stochastic noise. Each scenario is housed in a JSON file, with metadata
70 annotation, documentation, versioning and commit hashes marking the commit of Interfere
71 that was used to generate the data. The scenarios were reviewed by hand with some systems
72 exposed to exogenous input to ensure that none of the key variables settle into a steady state.
73 Additionally, all interventions were chosen so that the target variable response significantly
74 departs from its prior behavior. We aim for this benchmark to facilitate future progress towards
75 correctly anticipating how complex systems will respond to never before seen scenarios.

76 Related Software and Mathematical Foundations

77 Predictive Methods

78 Interfere draws from the Nixtla open source ecosystem for time series forecasting. We
79 implemented intervention support for LSTM and NHITS from the NeuralForecast package,
80 and for ARIMA from the StatsForecast package ([Azul Garza, 2022](#); [Olivares et al., 2022](#)). We
81 followed Nixtla’s example for cross validation and hyperparameter optimization approaches. We
82 integrated predictive methods from the PySINDy ([Kaptanoglu et al., 2022](#)) and StatsModels
83 ([Seabold & Perktold, 2010](#)) packages. We also include ResComp, a reservoir computing
84 method for global forecasts from ([Harding et al., 2024](#)). Hyperparameter optimization is
85 designed around the Optuna framework ([Akiba et al., 2019](#)).

86 While other forecasting methods exist, integrating a method with Interfere requires that
87 the method is capable of (1) multivariate endogenous dynamic forecasting, (2) support for
88 exogenous variables, and (3) support for flexible length forecast windows or recursive predictions.
89 Few forecasting methods meet these criteria, and it is our hope that this package will encourage
90 development of additional methods.

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