

Interfere: Studying Intervention Response Prediction in Complex Dynamic Models

D. J. Passey¹, Alice C. Schwarze², Zachary M. Boyd³, and Peter J. Mucha²

¹ University of North Carolina at Chapel Hill, United States ² Dartmouth College, United States ³ Brigham Young University, United States

DOI: [10.xxxxxx/draft](https://doi.org/10.xxxxxx/draft)

Software

- [Review](#)
- [Repository](#)
- [Archive](#)

Editor: [Open Journals](#)

Reviewers:

- [@openjournals](#)

Submitted: 01 January 1970

Published: unpublished

License

Authors of papers retain copyright and release the work under a Creative Commons Attribution 4.0 International License (CC BY 4.0).

Summary

The vision of Interfere is simple: What if we used high-quality scientific models to create causal dynamic benchmark scenarios? Randomized experimental data and intervention response time series are essential for testing methods that attempt to infer dynamic relationships from data, but obtaining such datasets can be expensive and difficult. Mechanistic models are commonly developed to simulate scenarios and predict the response of systems to interventions across economics, neuroscience, ecology, systems biology and other areas (Baker et al., 2018; Banks et al., 2017; Brayton et al., 2014; Izhikevich & Edelman, 2008). Because these models are calibrated to the real world, they have the ability to generate diverse, complex, synthetic intervention responses that are characteristic of the real processes they emulate. Interfere offers the first steps towards this vision by combining (1) a general interface for simulating the effect of interventions on dynamic models, (2) a suite of predictive methods and cross validated hyper parameter optimization tools, and (3) the first known extensible benchmark data set of dynamic intervention response scenarios see Figure 1.

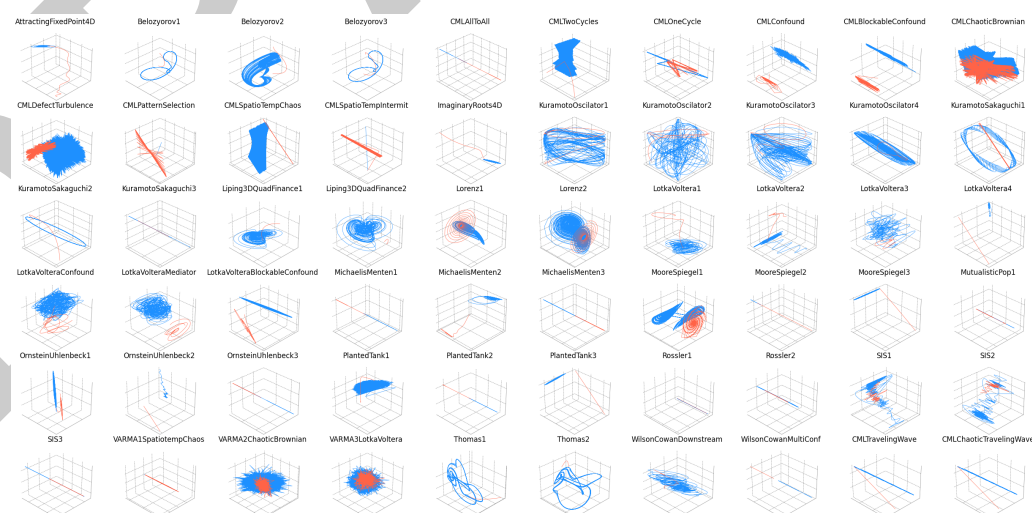
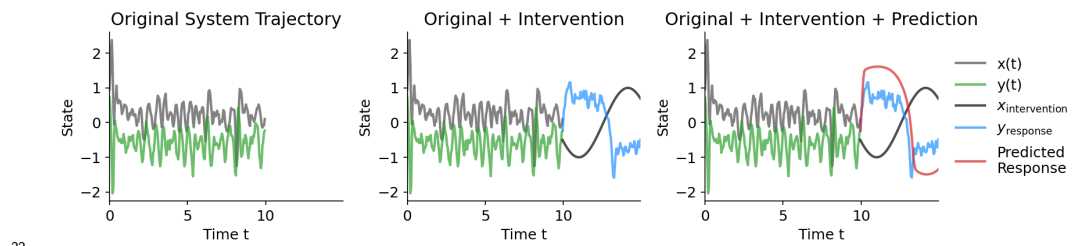


Figure 1: Three-dimensional trajectories of sixty scenarios simulated with the Interfere package. The models simulated here are either differential equations or discrete time difference equations. For each system, the trajectory in blue represents the natural behavior of the system and the red depicts how the system responds to a specified intervention. Many of the models pictured have more than three dimensions (in such cases, only the three dimensions of the trajectory with the highest variance are shown). These sixty scenarios make up the [Interfere Benchmark 1.1.1](#) for intervention response prediction which is available online for download.

21 Statement of Need



23 Over the past twenty years, the scientific community has experienced the emergence of multiple
24 frameworks for identifying causal relationships in observational data (Imbens & Rubin, 2015;
25 Pearl, 2009; Wieczorek & Roth, 2019). The most influential frameworks are probabilistic
26 and, while it is not a necessary condition for identifying causality, historically a static, linear
27 relationship has often been assumed. However, when attempting to anticipate the response of
28 complex dynamic systems in the medium and long term, a linear approximation of the dynamics
29 can be insufficient. Therefore, researchers have increasingly begun to employ non-linear,
30 dynamic techniques for causal discovery and forecasting (e.g. Runge, 2022). Still, there are
31 relatively few techniques that are able to fit causal dynamic nonlinear models to data. Because
32 of this, we see an opportunity to bring together the insights from recent advancements in
33 causal inference with historical work in dynamic modeling and simulation.

34 In order to facilitate this cross pollination, we focus on a key problem — predicting how a
35 complex system responds to a previously unobserved intervention — and designed the Interfere
36 package for benchmarking tools aimed at intervention response prediction. The dynamic models
37 contained in Interfere present challenges for computational methods that can likely only be
38 addressed with the incorporation of mechanistic assumptions alongside probabilistic frameworks
39 for causality. The Interfere package is a toolbox that allows researcher to validate predictive
40 dynamic methods against simulated intervention scenarios. As such, the Interfere package
41 encourages an opportunity for cross pollination between the probabilistic causal inference
42 community and the modeling and simulation community.

43 Primary Contributions

44 The Interfere package provides three primary contributions. (1) Dynamically diverse counter-
45 factuials at scale, (2) cross disciplinary forecast methods, and (3) comprehensive and extensible
46 benchmarking.

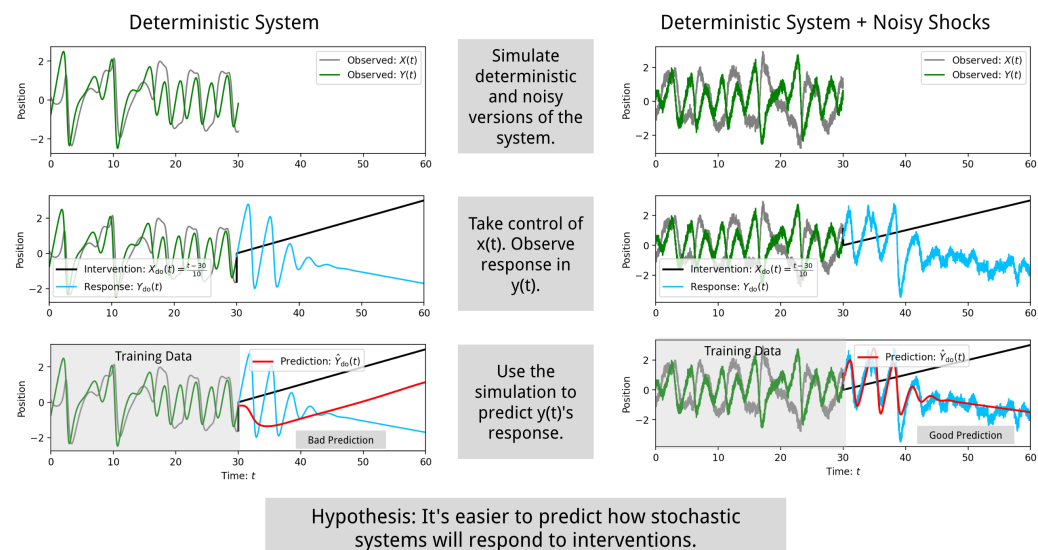


Figure 2: Example experimental setup possible with Interfere: Can stochasticity help reveal associations between variables? Interfere can be used to compare intervention response prediction for deterministic and stochastic versions of the same system.

1. Dynamically Diverse Counterfactuals at Scale

The “dynamics” submodule in the Interfere package contains over fifty dynamic models. It contains a mix of linear, nonlinear, chaotic, continuous time, discrete time, stochastic, and deterministic models. The models come from a variety of disciplines including finance, ecology, biology, neuroscience and public health. Each model inherits the from the Interfere BaseDynamics type and gains the ability to take exogenous control of any observed state and to add measurement noise. Most models also gain the ability to make any observed state stochastic where magnitude of stochasticity can be controlled by a simple scalar parameter or fine tuned with a covariance matrix.

Because of the difficulty of building models of complex systems, predictive methods for complex dynamics are typically benchmarked on less than ten dynamical systems (Brunton et al., 2016; Challu et al., 2023; Pathak et al., 2018; Prasse & Van Mieghem, 2022; Vlachas et al., 2020). As such, Interfere offers a clear improvement over current benchmarking methods for prediction in complex dynamics.

Most importantly, Interfere is built around interventions: the ability to take exogenous control of one or several state variables in a complex system and observe the response. Imbuing a suite of scientific models with general exogenous control is no small feat because models can be complex and are implemented in a variety of ways. Interfere offers the ability to produce complex dynamic intervention response and standard forecasting scenarios at scale. This unique feature enables large scale evaluation of dynamic causal prediction methods—tested against systems with properties of interest to scientists. For example, we can simulate the change in concentration of ammonia based on the nitrogen cycle and an exogenous fertilizing schedule.

2. Cross Disciplinary Forecast Methods

A second contribution of Interfere is the integration of dynamic *forecasting* methodologies from deep learning (LSTM, NHITS), applied mathematics (SINDy, Reservoir Computers) and social science (VAR). The Interfere “ForecastingMethod” class is expressive enough to describe, fit and predict with multivariate dynamic models and apply interventions to the states of the models during prediction. This cross disciplinary mix of techniques has the potential to produce

new insights into the problem of intervention response prediction among others. For example, experiments using this package have revealed that cross validation error does not correlate with well with prediction error when LSTM and NHITS attempt to predict intervention response.

3. Comprehensive and Extensible Benchmarking

The third major contribution of Interfere is the collection of dynamic scenarios organized into the [Interfere Benchmark](#). The Interfere Benchmark is a comprehensive and extensible set of dynamic scenarios that are conveniently available for testing methods that predict the effects of interventions. The benchmark set contains 60 intervention response scenarios for testing, each simulated with different levels of stochastic noise. Each scenario is housed in a JSON file, complete with full metadata annotation, documentation, versioning and commit hashes marking the commit of Interfere that was used to generate the data. The scenarios were reviewed by hand with some systems exposed to exogenous input to ensure that none of the key variables settle into a steady state. Additionally, all interventions were chosen in a manner such that the response of the target variable is a significant departure from its previous behavior.

The Interfere package enables researchers from various backgrounds to systematically study the problem of predicting intervention response on simulated data from a wide range of disciplines. It thereby facilitates future progress towards correctly anticipating how complex systems will respond in new, never before seen scenarios.

Related Software and Mathematical Foundations

Predictive Methods

The Interfere package draws from the Nixtla open source ecosystem for time series forecasting. We implemented intervention support for LSTM and NHITS from the NeuralForecast package, and for ARIMA from the StatsForecast package ([Azul Garza, 2022](#); [Olivares et al., 2022](#)). We followed Nixtla's example for cross validation and hyperparameter optimization approaches. We integrated predictive methods from the PySINDy ([Kaptanoglu et al., 2022](#)) and StatsModels ([Seabold & Perktold, 2010](#)) packages. We also include ResComp, a reservoir computing method for global forecasts from ([Harding et al., 2024](#)). Hyperparameter optimization is designed around the Optuna framework ([Akiba et al., 2019](#)).

While other forecasting methods exist, integrating a method with Interfere requires that the method is capable of (1) multivariate endogenous dynamic forecasting, (2) support for exogenous variables, and (3) support for flexible length forecast windows or recursive predictions. Few forecasting methods meet these criteria, and it is our hope that this package can encourage the development of additional methods.

Dynamic Models

The table below list the dynamic models that are currently implemented in the Interfere package, plus attributions. These dynamic models in were implemented directly from mathematical descriptions except for two, "Hodgkin Huxley Pycustering" and "Stuart Landau Kuramoto" which adapt existing simulations from the PyClustering package ([Novikov, 2019](#)).

Acknowledgements

The work described here was supported by an NSF Graduate Research Fellowship (DJP) and by award W911NF2510049 from the Army Research Office. The content is solely the responsibility of the authors and does not necessarily represent the official views of any agency supporting this research.

References

- Akiba, T., Sano, S., Yanase, T., Ohta, T., & Koyama, M. (2019). Optuna: A next-generation hyperparameter optimization framework. *The 25th ACM SIGKDD International Conference on Knowledge Discovery & Data Mining*, 2623–2631.
- Azul Garza, C. C., Max Mergenthaler Canseco. (2022). *StatsForecast: Lightning fast forecasting with statistical and econometric models*. PyCon Salt Lake City, Utah, US 2022. <https://github.com/Nixtla/statsforecast>
- Baker, R. E., Peña, J.-M., Jayamohan, J., & Jérusalem, A. (2018). Mechanistic models versus machine learning, a fight worth fighting for the biological community? *Biology Letters*, 14(5), 20170660. <https://doi.org/10.1098/rsbl.2017.0660>
- Banks, H. T., Banks, J. E., Bommarco, R., Curtsdotter, A., Jonsson, T., & Laubmeier, A. N. (2017). Parameter estimation for an allometric food web model. *International Journal of Pure and Applied Mathematics*, 114(1). <https://doi.org/10.12732/ijpam.v114i1.12>
- Brayton, F., Laubach, T., & Reifschneider, D. (2014). The FRB/US model: A tool for macroeconomic policy analysis. *FEDS Notes*, 2014-04, 03.
- Brunton, S. L., Proctor, J. L., & Kutz, J. N. (2016). Discovering governing equations from data by sparse identification of nonlinear dynamical systems. *Proceedings of the National Academy of Sciences*, 113(15), 3932–3937. <https://doi.org/10.1073/pnas.1517384113>
- Challu, C., Olivares, K. G., Oreshkin, B. N., Ramirez, F. G., Canseco, M. M., & Dubrawski, A. (2023). NHITS: Neural Hierarchical Interpolation for Time Series Forecasting. *Proceedings of the AAAI Conference on Artificial Intelligence*, 37(6), 6989–6997. <https://doi.org/10.1609/aaai.v37i6.25854>
- Harding, S., Leishman, Q., Lunceford, W., Passey, D. J., Pool, T., & Webb, B. (2024). Global forecasts in reservoir computers. *Chaos: An Interdisciplinary Journal of Nonlinear Science*, 34(2), 023136. <https://doi.org/10.1063/5.0181694>
- Imbens, G. W., & Rubin, D. B. (2015). *Causal Inference for Statistics, Social, and Biomedical Sciences: An Introduction* (1st ed.). Cambridge University Press. <https://doi.org/10.1017/CBO9781139025751>
- Izhikevich, E. M., & Edelman, G. M. (2008). Large-scale model of mammalian thalamocortical systems. *Proceedings of the National Academy of Sciences*, 105(9), 3593–3598. <https://doi.org/10.1073/pnas.0712231105>
- Kaptanoglu, A. A., Silva, B. M. de, Fasel, U., Kaheman, K., Goldschmidt, A. J., Callahan, J., Delahunt, C. B., Nicolaou, Z. G., Champion, K., Loiseau, J.-C., Kutz, J. N., & Brunton, S. L. (2022). PySINDy: A comprehensive python package for robust sparse system identification. *Journal of Open Source Software*, 7(69), 3994. <https://doi.org/10.21105/joss.03994>
- Novikov, A. V. (2019). PyClustering: Data mining library. *Journal of Open Source Software*, 4(36), 1230. <https://doi.org/10.21105/joss.01230>
- Olivares, K. G., Challú, C., Garza, A., Canseco, M. M., & Dubrawski, A. (2022). *NeuralForecast: User friendly state-of-the-art neural forecasting models*. PyCon Salt Lake City, Utah, US 2022. <https://github.com/Nixtla/neuralforecast>
- Pathak, J., Hunt, B., Girvan, M., Lu, Z., & Ott, E. (2018). Model-Free Prediction of Large Spatiotemporally Chaotic Systems from Data: A Reservoir Computing Approach. *Physical Review Letters*, 120(2), 024102. <https://doi.org/10.1103/PhysRevLett.120.024102>
- Pearl, J. (2009). *Causality* (2nd ed.). Cambridge University Press. <https://doi.org/10.1017/CBO9780511803161>
- Prasse, B., & Van Mieghem, P. (2022). Predicting network dynamics without requiring the

- 164 knowledge of the interaction graph. *Proceedings of the National Academy of Sciences*,
165 119(44), e2205517119. <https://doi.org/10.1073/pnas.2205517119>
- 166 Runge, J. (2022). *Discovering contemporaneous and lagged causal relations in autocorrelated*
167 *nonlinear time series datasets*. arXiv. <https://doi.org/10.48550/arXiv.2003.03685>
- 168 Seabold, S., & Perktold, J. (2010). Statsmodels: Econometric and statistical modeling with
169 python. *9th Python in Science Conference*.
- 170 Vlachas, P. R., Pathak, J., Hunt, B. R., Sapsis, T. P., Girvan, M., Ott, E., & Koumoutsakos,
171 P. (2020). Backpropagation algorithms and Reservoir Computing in Recurrent Neural
172 Networks for the forecasting of complex spatiotemporal dynamics. *Neural Networks*, 126,
173 191–217. <https://doi.org/10.1016/j.neunet.2020.02.016>
- 174 Wieczorek, A., & Roth, V. (2019). Information Theoretic Causal Effect Quantification. *Entropy*,
175 21(10), 975. <https://doi.org/10.3390/e21100975>

DRAFT