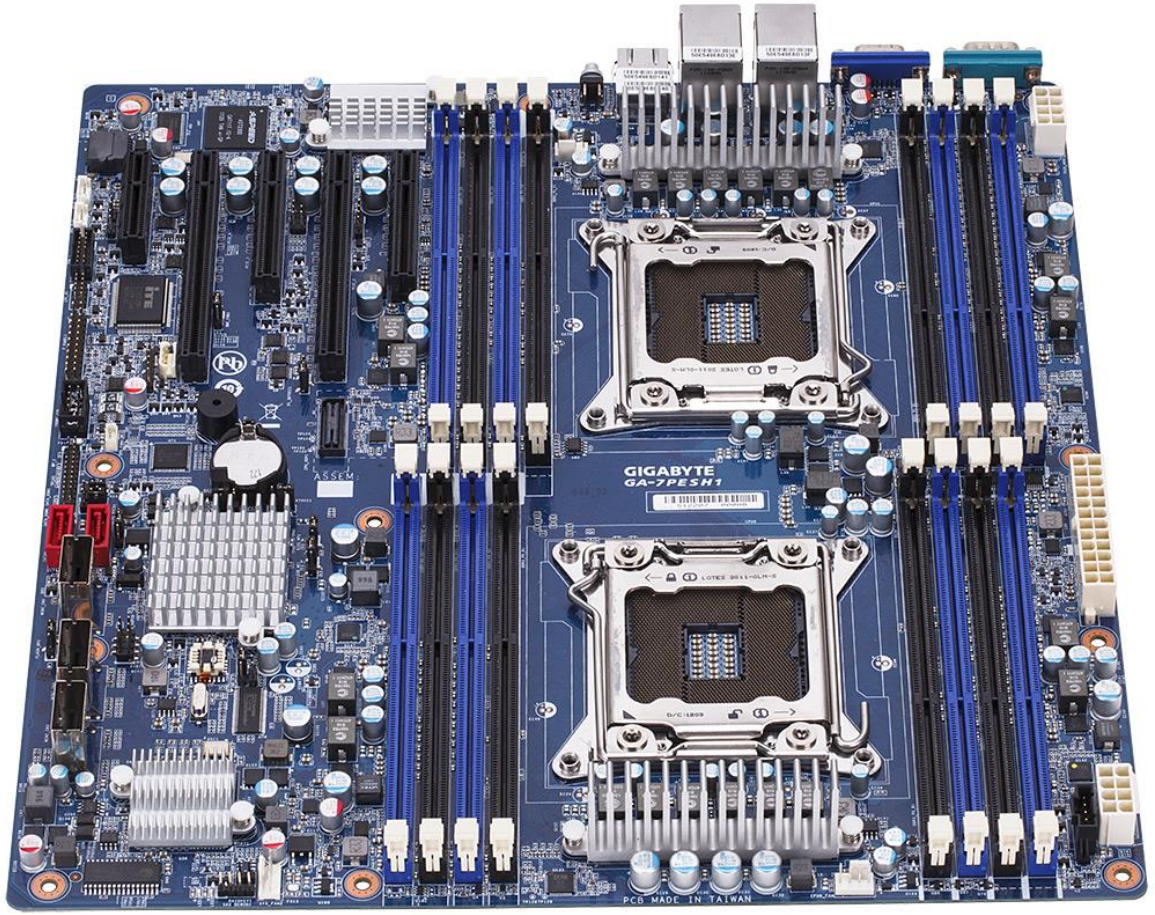
# HYPERTHREADING

DAVID PERRONE AND RUSSELL ROYALITY

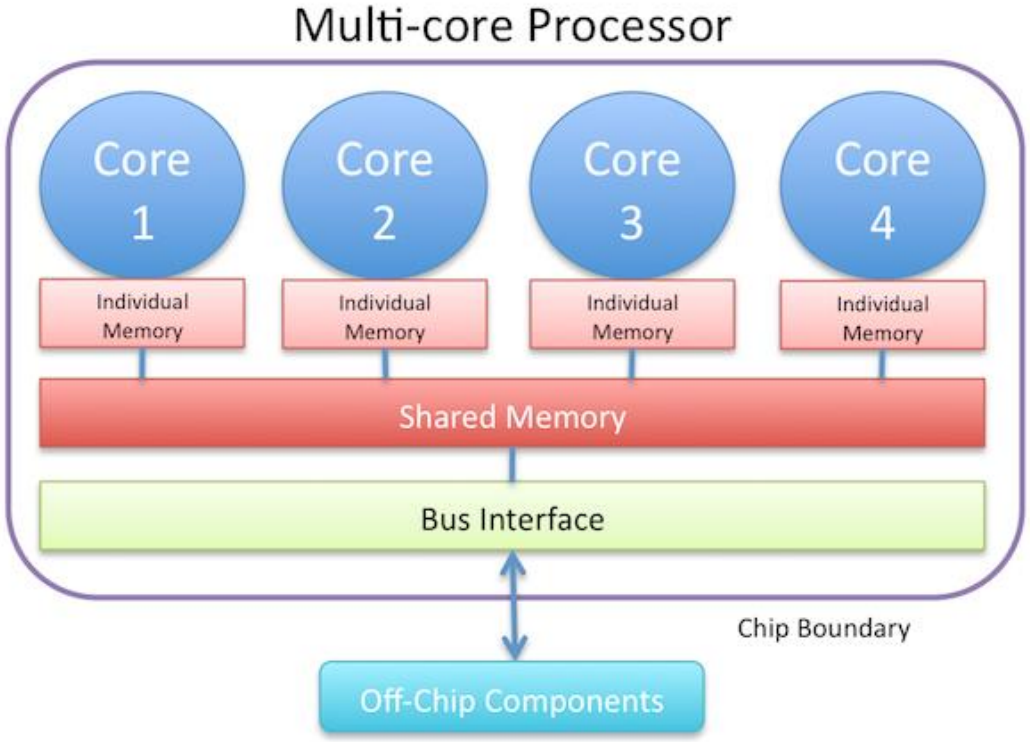
# CPU

- Receives instructions from software and hardware
- More CPUs = more processing power
  - Expensive, requires space

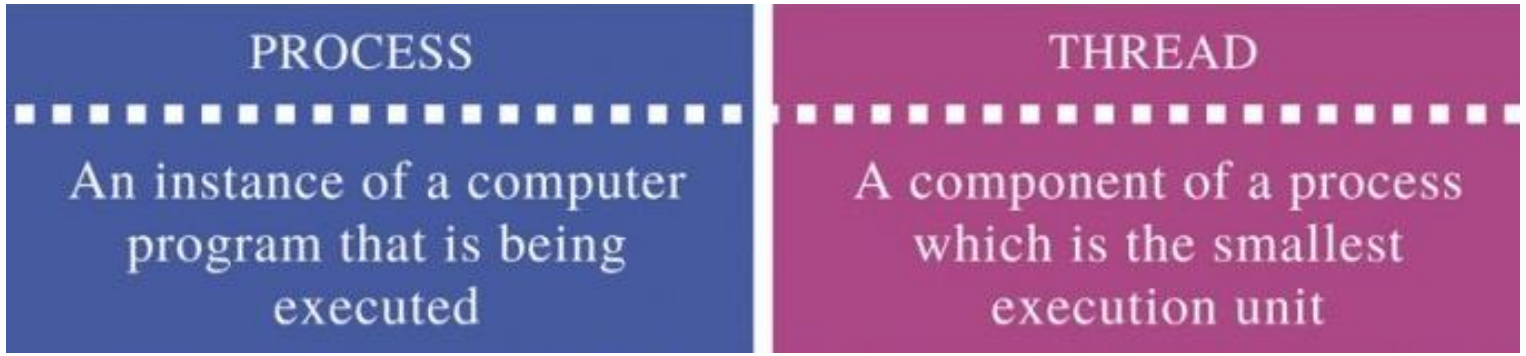


# CORE

- Hardware Component
- Execution unit inside the CPU that receives and executes instructions.
- Contains an ALU, control unit, and registers
- One CPU can contain multiple cores
    - Each core can run its own process

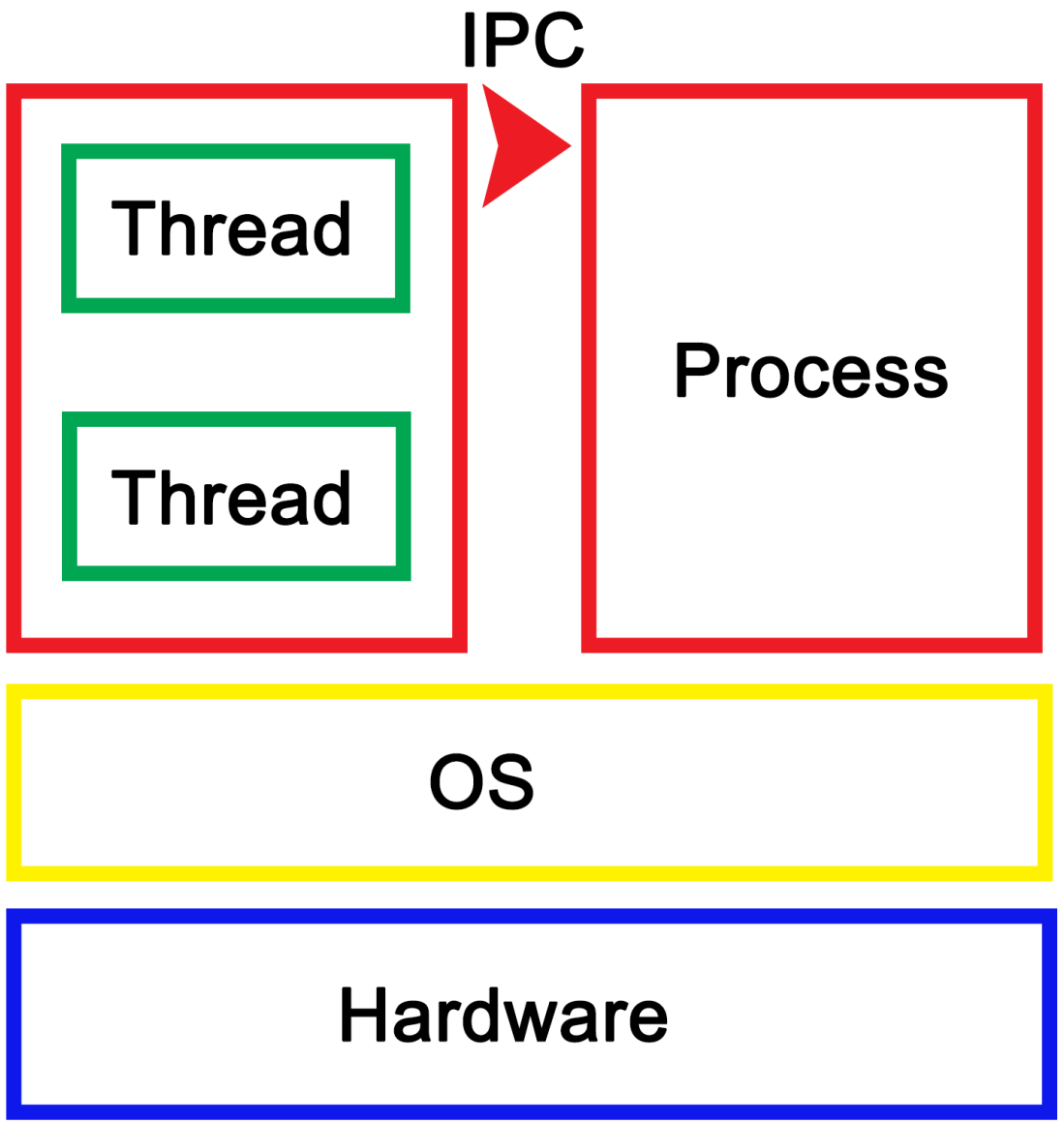


# PROCESS VS THREAD

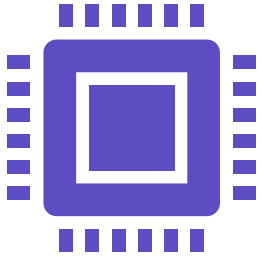



- A process includes one or more threads
- A thread includes:
  - Program counter (Instruction Pointer)
  - Register state
  - A stack

# PROCESS VS THREAD

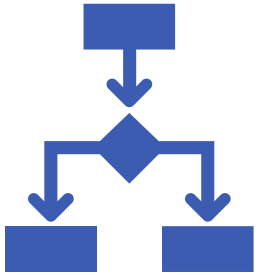


# DEFINING MULTITHREADING



## Multiprocessing

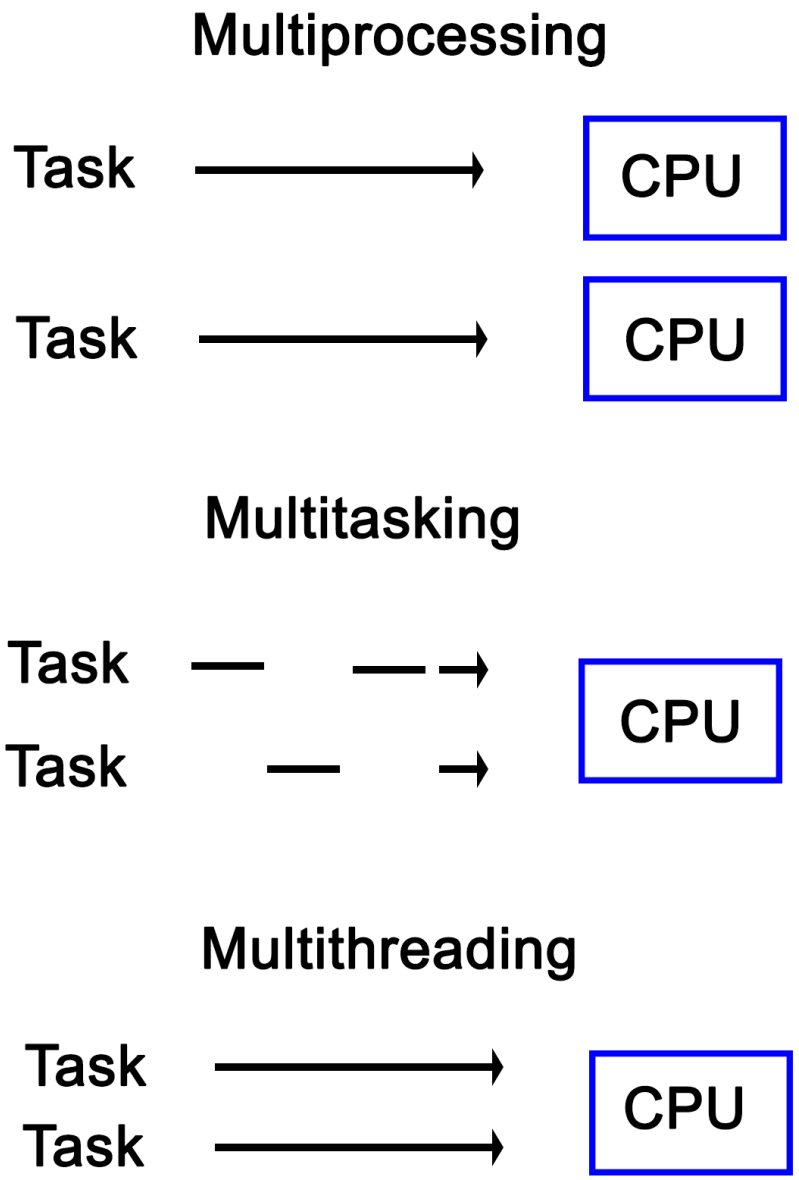
One task per processor with multiple, physical processors



## Multithreading

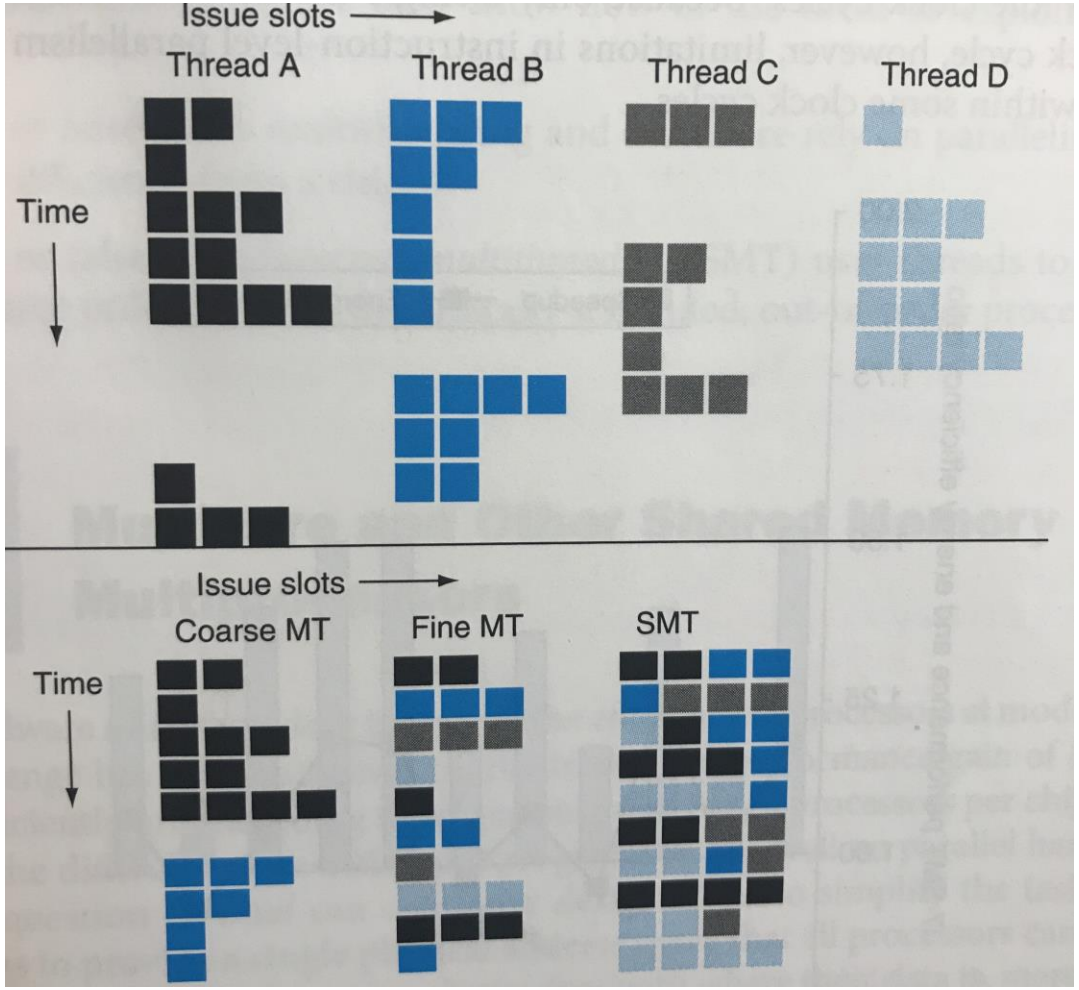
Multiple tasks on a singular processor, using multiple threads

# DEFINING MULTITHREADING



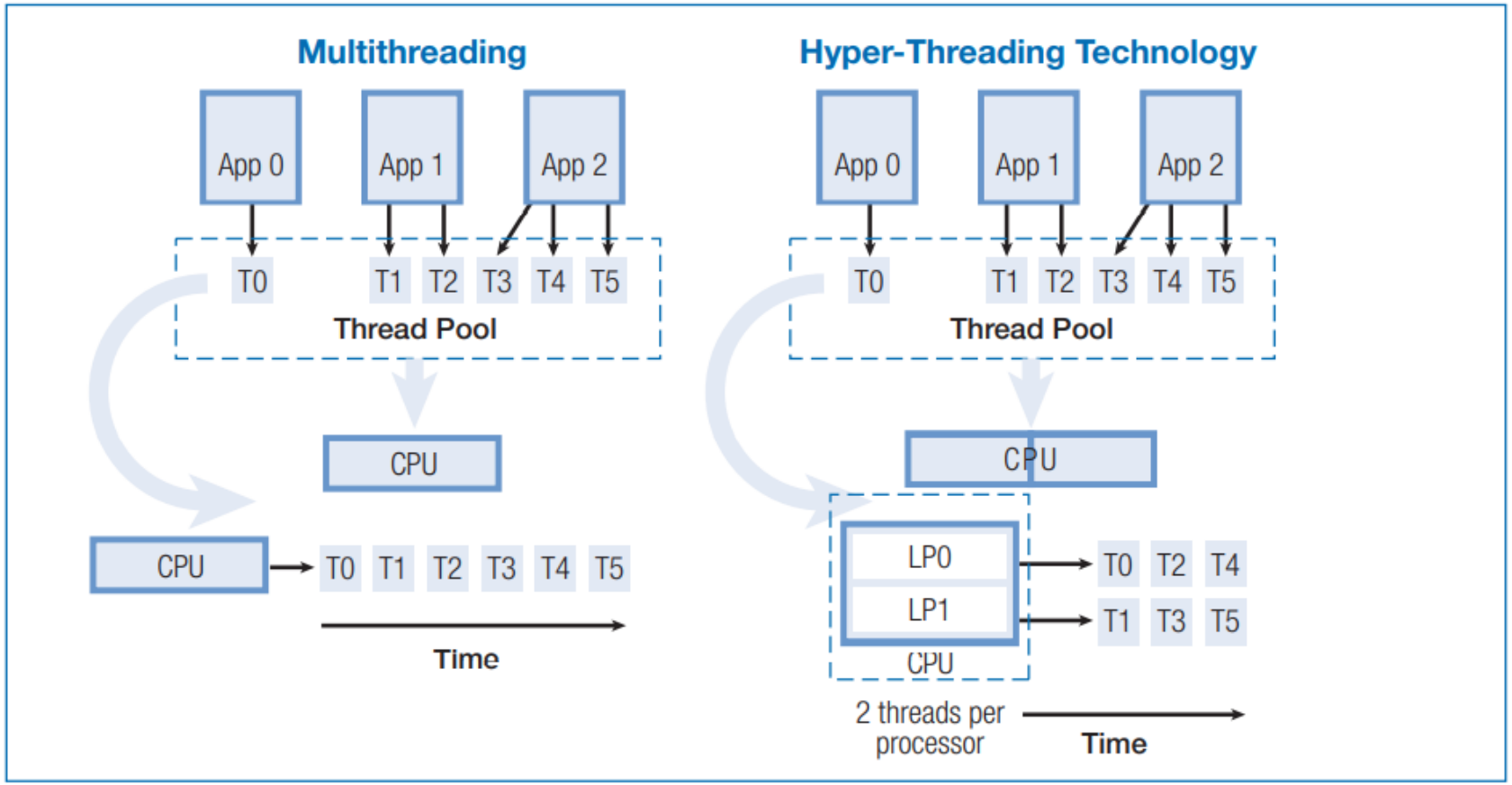
# MULTITHREADING

- Three different types
  - Fine-grained, course-grained, simultaneous
- Course-grained
  - Switch threads only on stall (cache miss)
- Fine-grained
  - Switch threads every clock cycle
- Simultaneous
  - Uses Idle threads to execute instructions



# LOGICAL PROCESSORS

- Instructions are dispatched for execution by processor core
- Processor core executes the two threads concurrently, using out-of-order instruction



# HYPERTHREADING

Uses dynamically scheduled pipelined processor

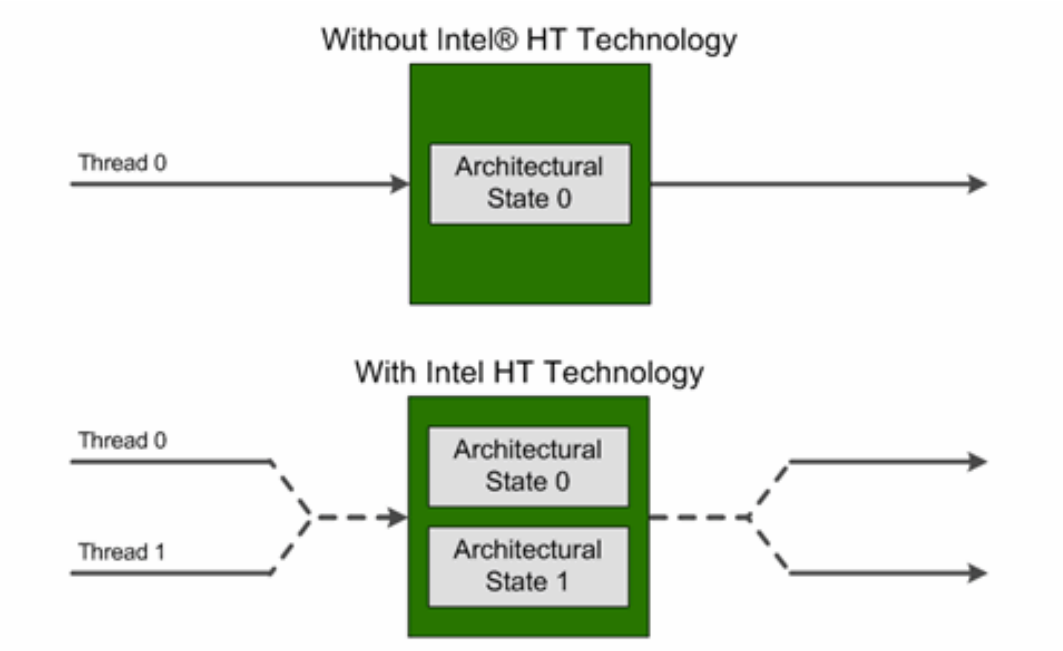
Out-of-order execution avoids hazards and stalls

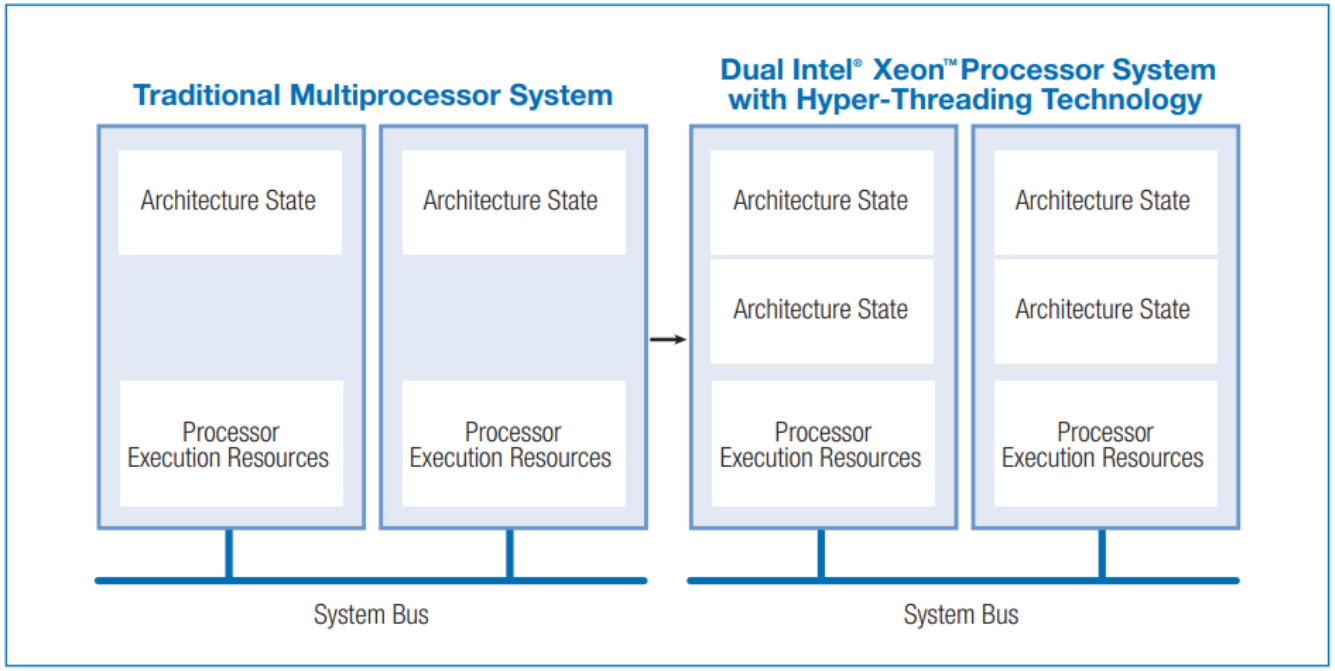
Utilizes both instruction and thread level parallelism

Processors often have more resources than one single thread can use

# HYPERTHREADING

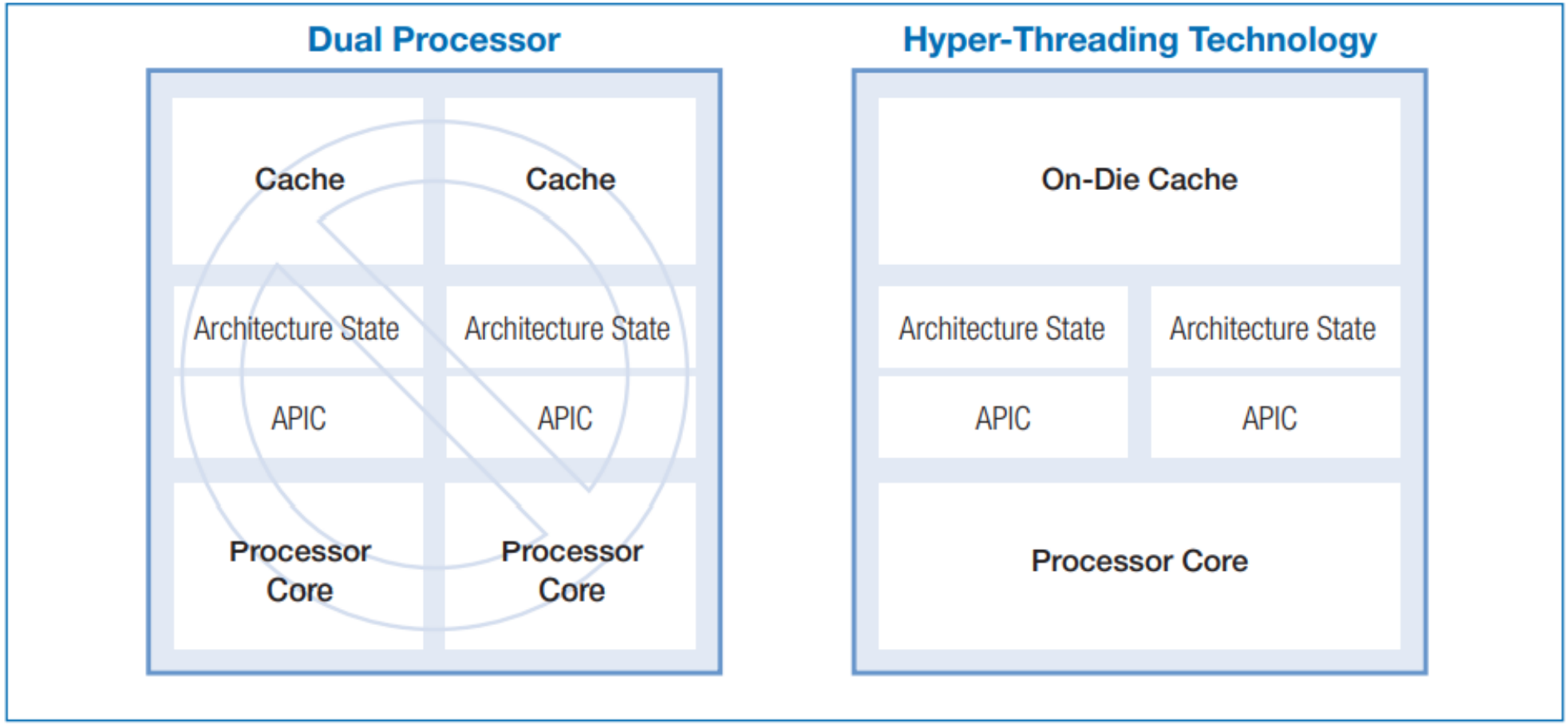
- CPU core "split" into two
  - Uses second set of registers
- Access two logical processors from one core
  - Process idle threads
  - Share resources



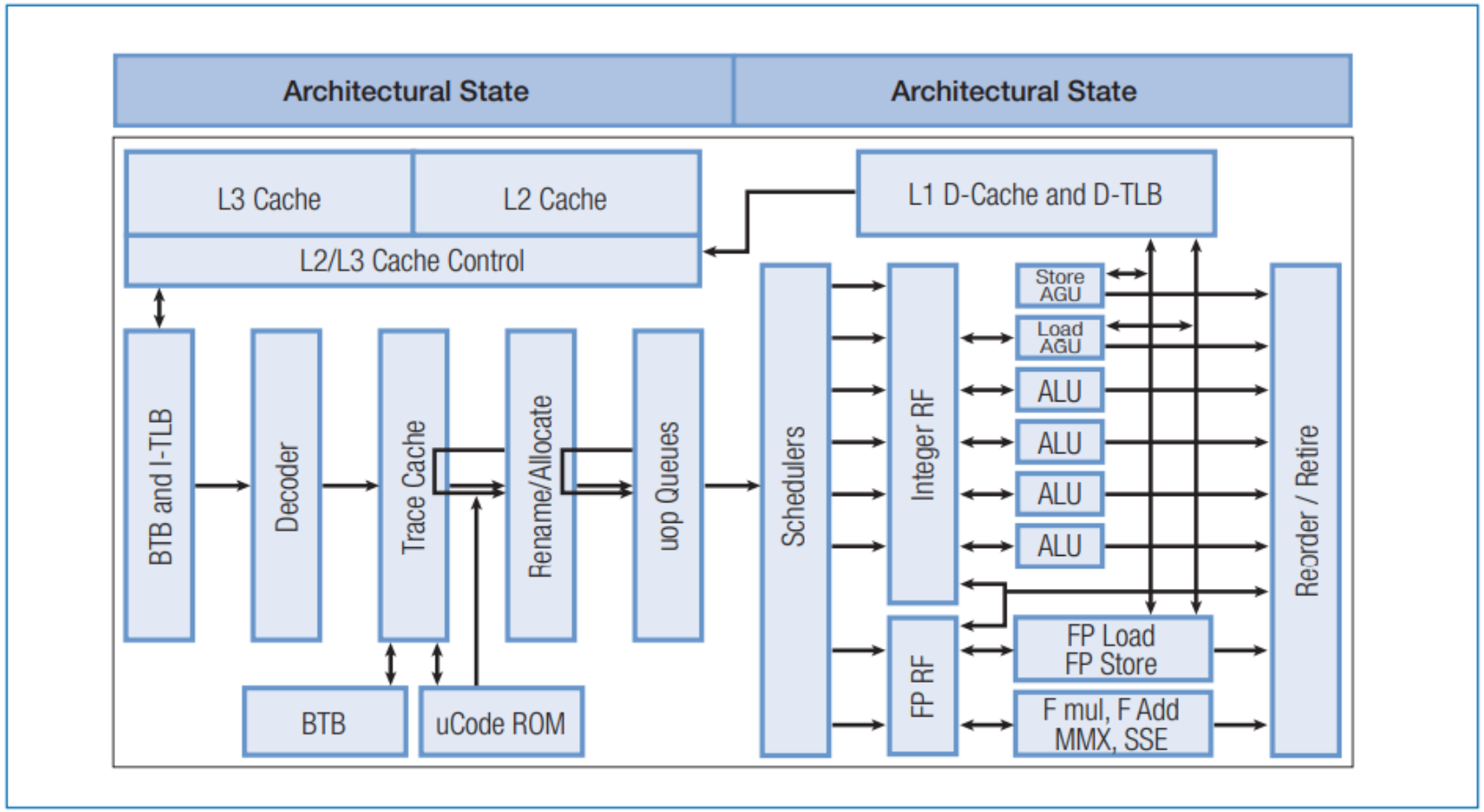



- A processor with Hyper-Threading technology consists of two logical processors, each with its own architectural state
- Shared resources: Execution engine, caches, system-bus interface, firmware

# HYPERTHREADING



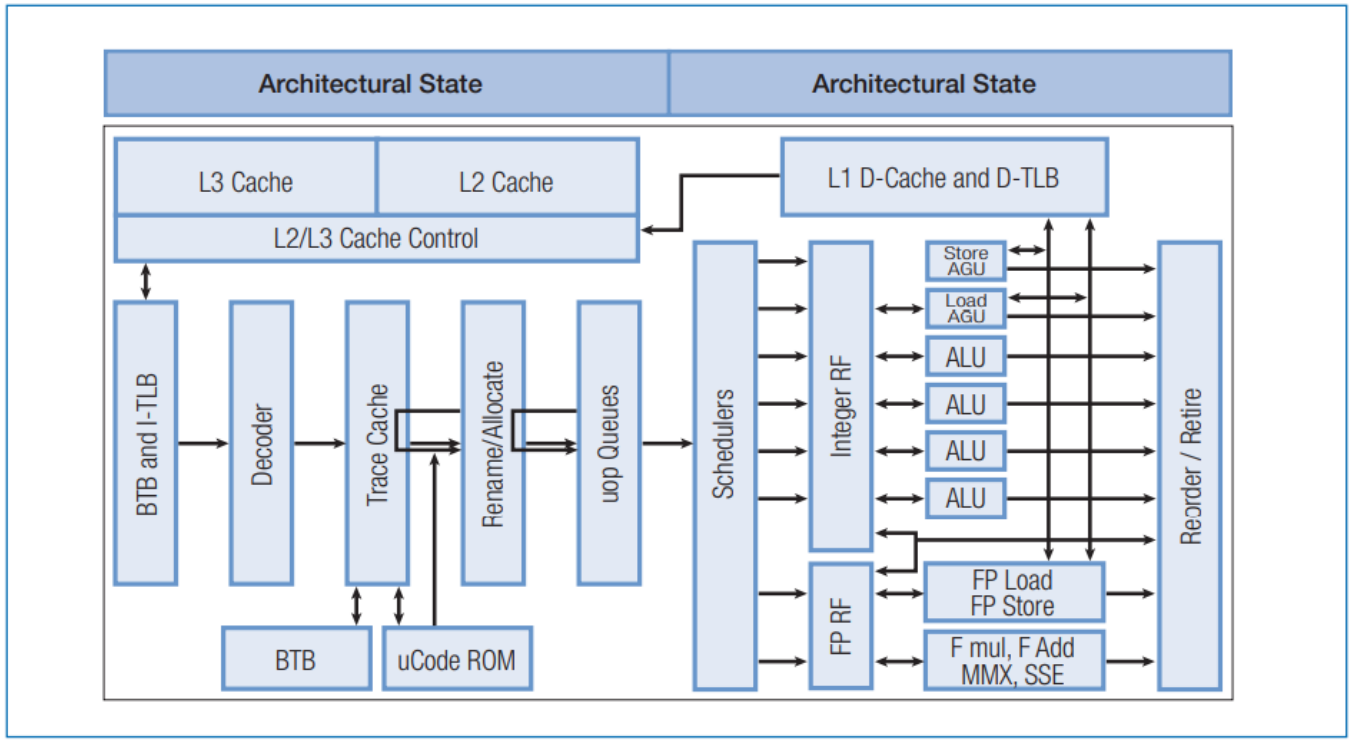

# LOGICAL PROCESSORS != PHYSICAL CORE




# SHARED RESOURCES

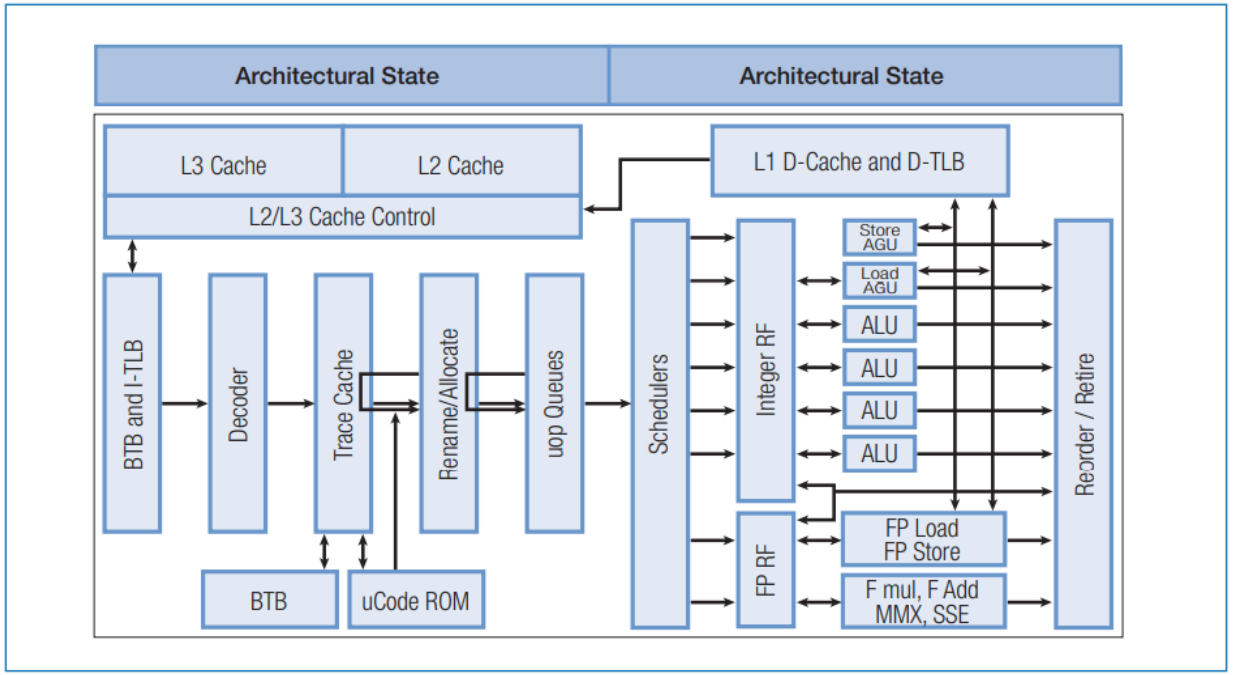
# SIMULTANEOUS INSTRUCTION EXECUTION

- Floating point arithmetic, integer arithmetic
- Bottleneck if both need floating point
- If one thread is performing lots of pointer arithmetic other threads cannot
    - Revert to time slices

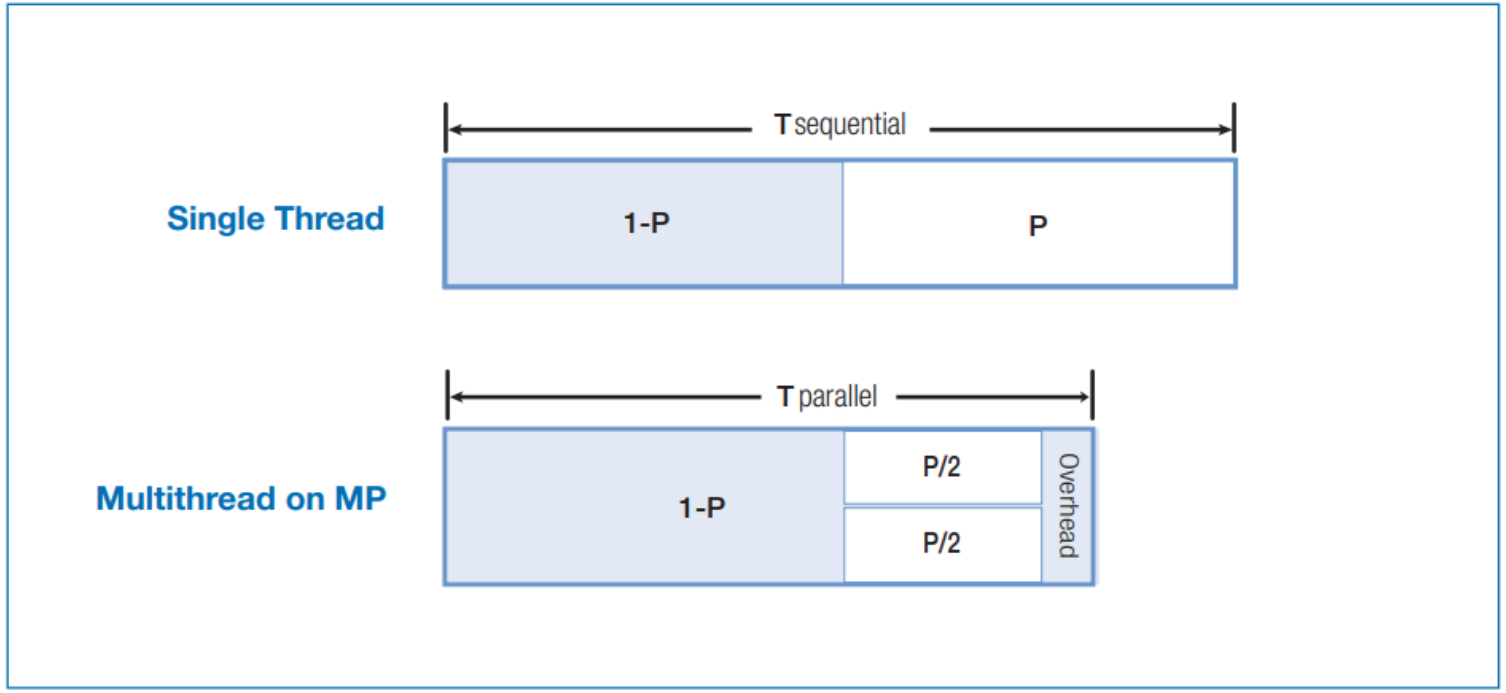


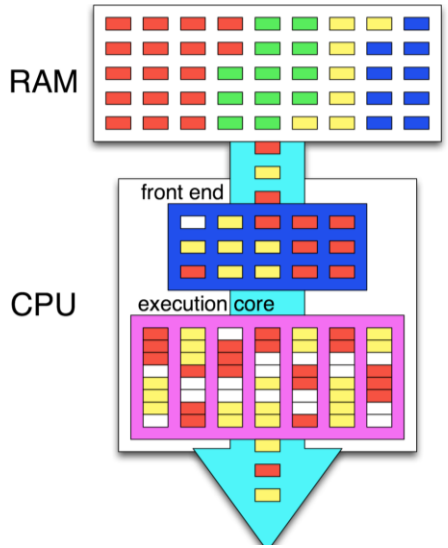
# SHARED CACHE

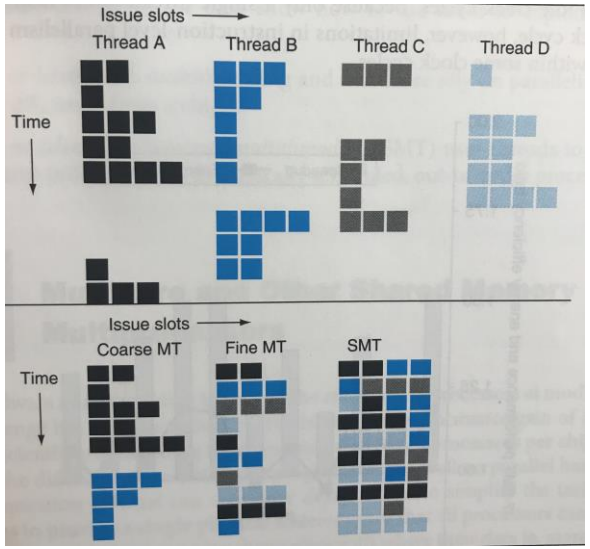
- Thread from processor 0 can access data cached by processor 1
- Cache can't tell the difference between one thread or another
- Locality – Threads can be accessing different areas of memory
- Cache is forced to fetch data for each thread – reducing performance



# OVERHEAD


Tsequential
Single Thread
1-P
P
Tparallel
Multithread on MP
1-P
P/2
P/2
Overhead




# STRENGTHS

- Maximum flexibility in scheduling
- Use all available execution resources – keeping core busy

# CONS

- Potential to hinder performance
- Possibly less secure
  - Access shared cache
  - Jump from virtual core to virtual core
  - More susceptible to Spectre attacks

# BENCHMARKING MULTITHREADING

1 thread

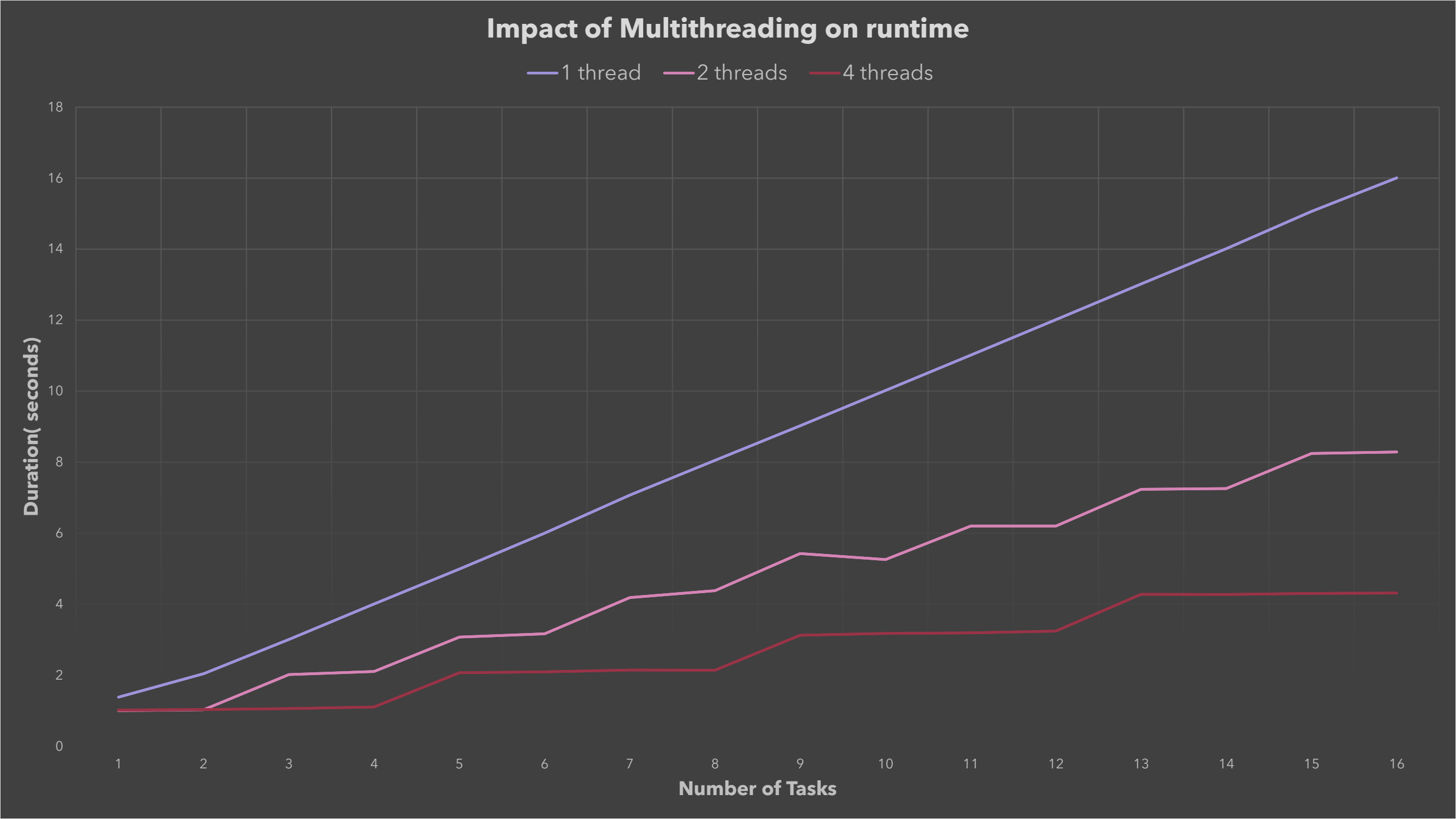
```
started task 1
Finished task 1, int sum is 600000000
started task 2
Finished task 2, int sum is 600000000
started task 3
Finished task 3, int sum is 600000000
started task 4
Finished task 4, int sum is 600000000

1 threads, 4 tasks: 3.90687 seconds
```

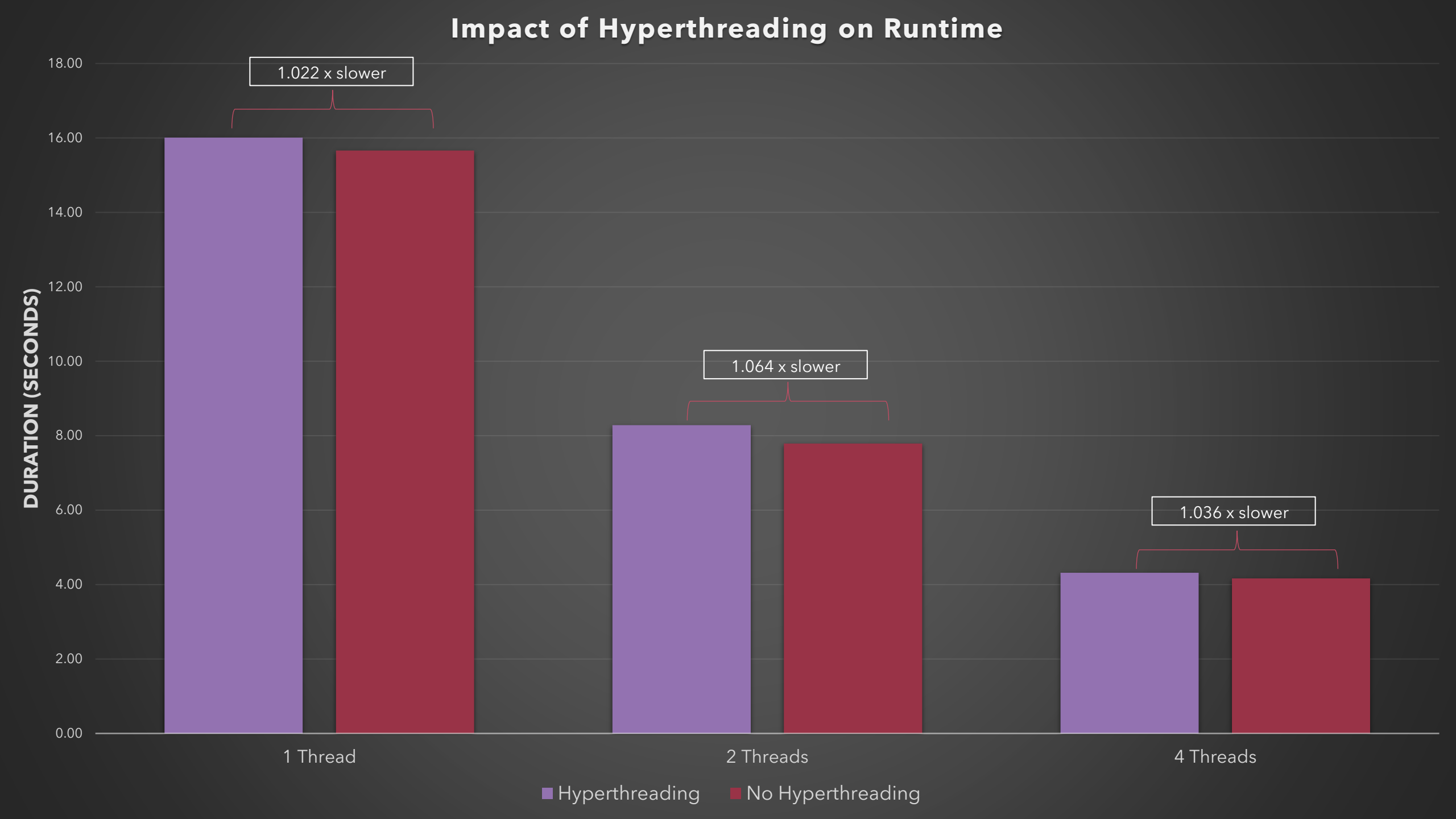
2 threads

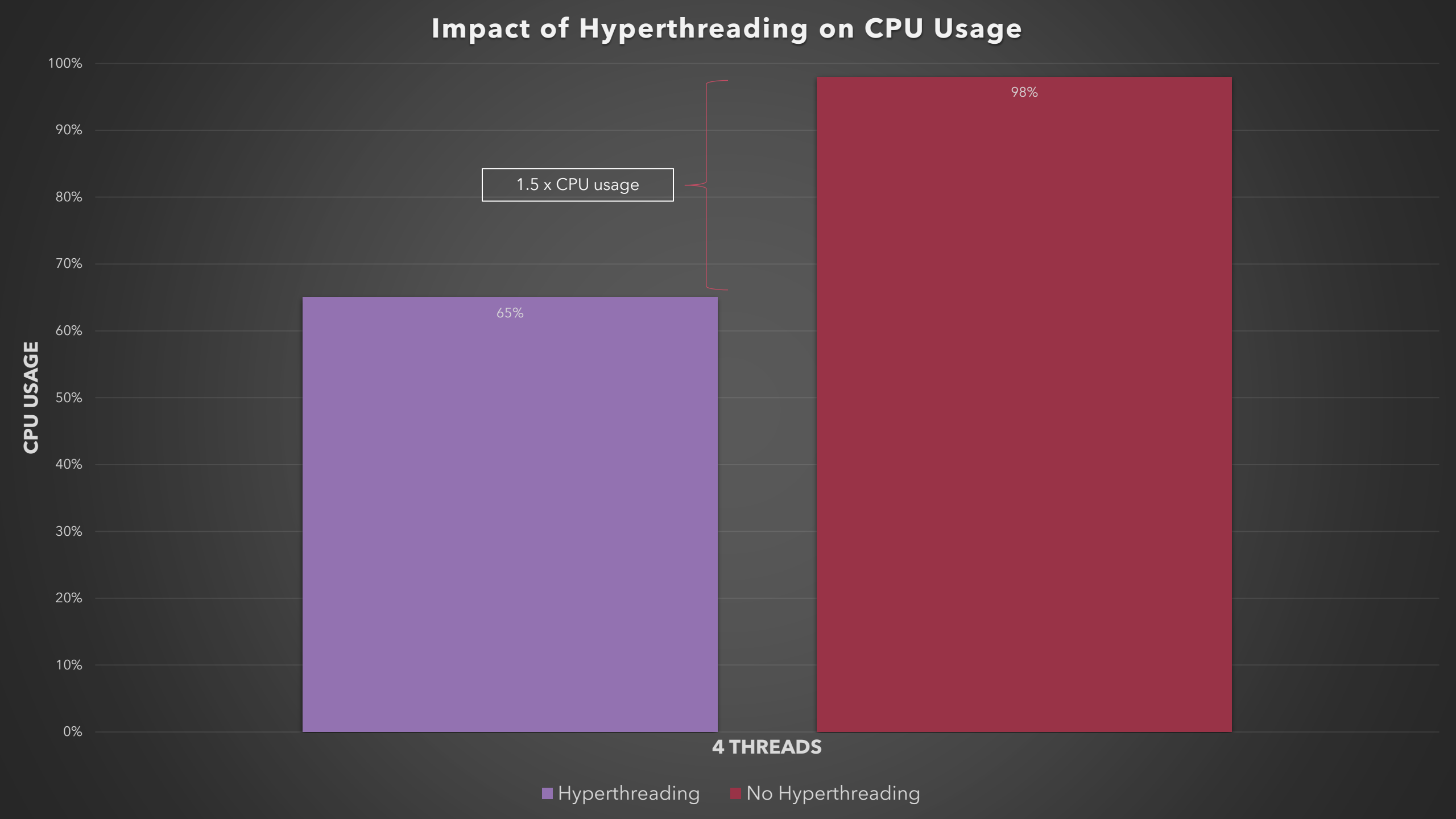
```
started task 1
started task 2
Finished task 1, int sum is 600000000
started task 3
Finished task 2, int sum is 600000000
started task 4
Finished task 3, int sum is 600000000
Finished task 4, int sum is 600000000

2 threads, 4 tasks: 1.96998 seconds
```

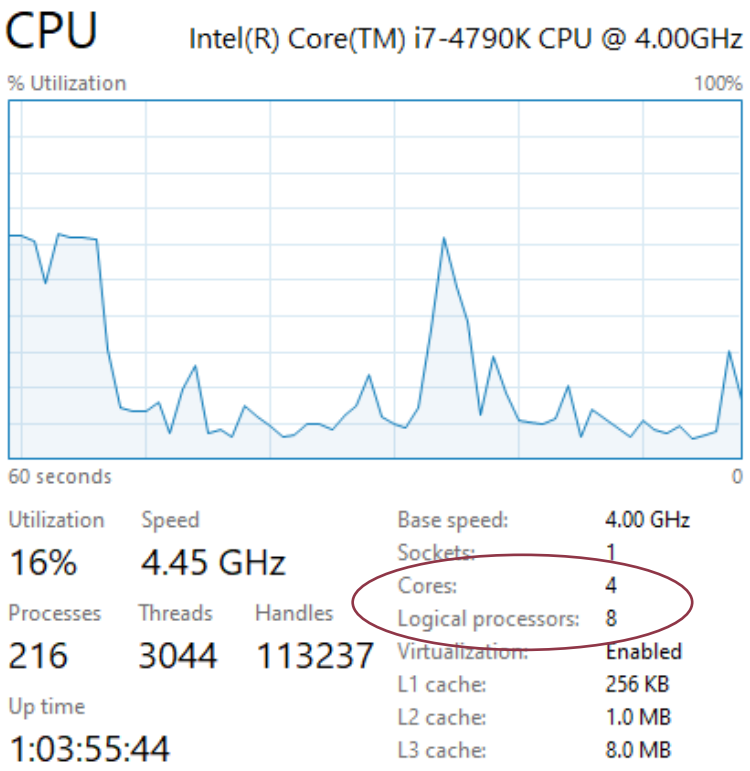

Impact of Multithreading on runtime
1 thread
2 threads
4 threads
Duration( seconds)
0
2
4
6
8
10
12
14
16
18
1
2
3
4
5
6
7
8
9
10
11
12
13
14
15
16
Number of Tasks

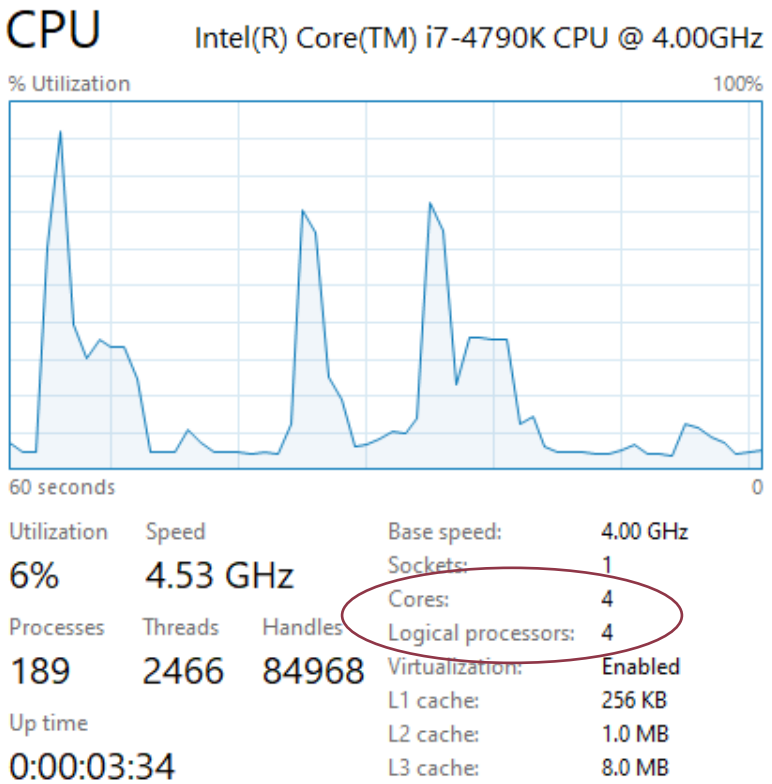

UEFI BIOS Utility – Advanced Mode
2021 17:23
English
MyFavorite(F3)
Qfan Control(F6)
EZ Tuning Wizard(F11)
Quick Not
My Favorites
Main
Ai Tweaker
Advanced
Monitor
Boot
Tool
Exit
Intel VT-x Technology
Supported
Intel SMX Technology
Not Supported
64-bit
Supported
EIST Technology
Supported
CPU C3 state
Supported
CPU C6 state
Supported
CPU C7 state
Supported
L1 Data Cache
32 kB x 4
L1 Code Cache
32 kB x 4
L2 Cache
256 kB x 4
L3 Cache
8 MB
L4 Cache
Not Supported
Intel Adaptive Thermal Monitor
Enabled
Hyper-threading
Disabled


Impact of Hyperthreading on Runtime
DURATION (SECONDS)
18.00
16.00
14.00
12.00
10.00
8.00
6.00
4.00
2.00
0.00
1.022 x slower
1.064 x slower
1.036 x slower
1 Thread
2 Threads
4 Threads
Hyperthreading
No Hyperthreading

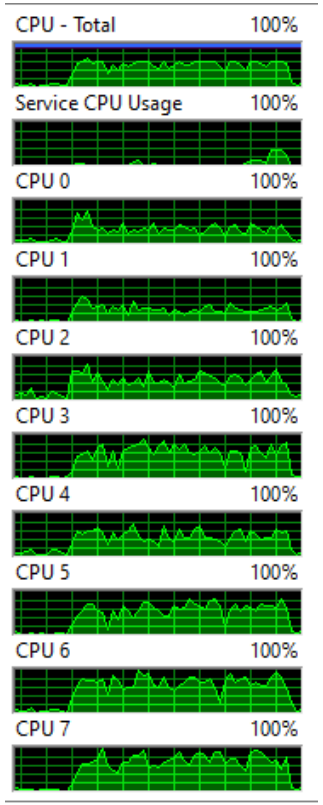

Impact of Hyperthreading on CPU Usage
100%
90%
80%
70%
60%
50%
40%
30%
20%
10%
0%
CPU USAGE
1.5 x CPU usage
65%
98%
4 THREADS
Hyperthreading
No Hyperthreading

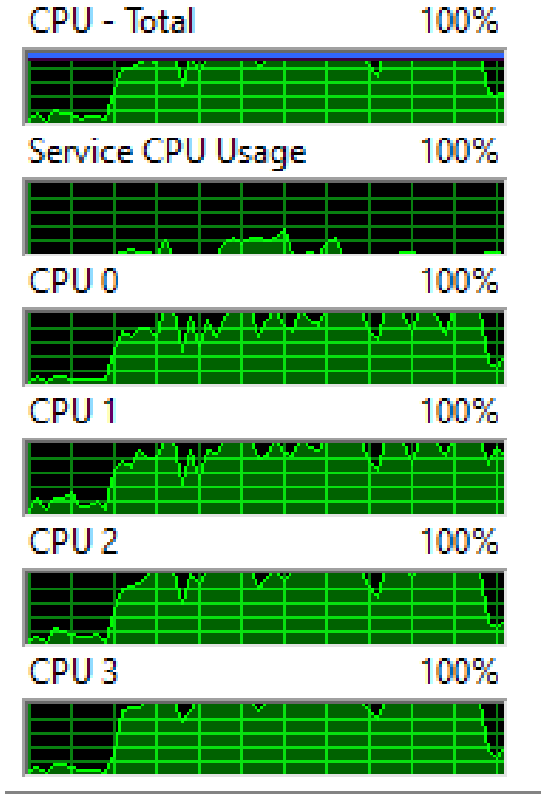
# LOGICAL PROCESSORS



# CPU USAGE (DURING TEST)



# SOURCES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- Patterson, David A, and John L. Hennessy. *COMPUTER ORGANIZATION AND DESIGN MIPS EDITION: the Hardware/Software Interface*. MORGAN KAUFMANN PUBLISHER, 2020.
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- Gigabyte GA-7PESH1 Visual Inspection, Board Features - Gigabyte GA-7PESH1 Review: A Dual Processor Motherboard through a Scientist's Eyes (anandtech.com) – (motherboard Image)
- Multicore processors terminology (microcontrollertips.com) – (multicore cpu image)

# GITHUB SOURCE CODE

- https://github.com/djperrone/Hyperthreading.git