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| Task | Expected Completion Date |
| Begin Construction | June 17th |
| Circuit Layout for H-Bridge, IR Sensor, Motors, QRD, comparators, and other major circuits. | June 20th |
| Testing the amplification ratio required for IR sensors, hall sensors, QRD | June 23th |
| Pseudo code and function calls, function diagrams relating functions to each other | June 23th |
| Wheels, gears and motor parts | June 30th |
| Functioning tape follower and tape follower calibration | July 1th |
| Testing wheels on rocks and adjustments | July 3th |
| Artifact retrieval arm | July 4th |
| Beacon Follower | July 11th |
| PCBs completed | July 12th |
| Zip line attachment arm | July 17th |
| Combining all the parts of the robot | July 19th |
| Thorough Testing and Debugging | July 24th |
| Time Trials | July 26th |