LP Formulation of the Supplier Production Plan

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1 Notation & Problem Data

The total operational horizon of the supply chain and the supplier planning horizon will be denoted as $T \in \mathbb{N}^+$ and $H \in \mathbb{N}^+$, respectively and, by convention, *time will be measured in days*. For notational simplicity, since all suppliers receive and generate the same *type* of information, every day, we may employ generic notation, common to all suppliers, without the use of an explicit "supplier index". Suppose that we are on the *t*-th day, for some *fixed* $t \in \mathbb{N}_T^+$, and suppose that *Joe* is a supplier. Intuitively, we will call the *t*-th day *today*. We also make the following explicit assumptions:

• First, we take into account the inevitable existence of non-zero travel times between suppliers; let $\tau_{c_j} \in \mathbb{N}^+$ denote the travel time (in days) between Joe's location and that of *child* supplier $c_j \in \mathcal{N}_{Joe}$, for all $j \in \mathbb{N}^+_{|\mathcal{N}_{Joe}|}$. We also define the *lag vector*

$$oldsymbol{ au} riangleq \left[au_{c_1} \dots au_{c_{\left|\mathcal{N}_{loe}
ight|}}
ight]^T \in \left[\mathbb{N}^+
ight]^{\left|\mathcal{N}_{loe}
ight|}.$$
 (1)

Likewise, we let $\tau_p \in \mathbb{N}^+$ be the travel time between Joe and his *parent supplier*.

- Second, we constrain each supplier (and thus, also Joe), so that an incoming part may be used for production *at least one day after its arrival* to the supplier's location.
- Third, implementation of today's production plan (decision) and shipment of produced parts to the parent supplier *both* take place on the *same day* (*today*).

Under those considerations, every day, Joe receives the following information:

• From *downstream* (closer to the final product), the *current*, *temporally adjusted* production *forecast* of his parent (the supplier using Joe's produced part). This production plan is denoted by a vector

$$\widetilde{\mathbf{x}}_{t-1}^{D} \triangleq \left[\widetilde{\mathbf{x}}_{t-1,t+\tau_{p}+1}^{D} \, \widetilde{\mathbf{x}}_{t-1,t+\tau_{p}+2}^{D} \, \dots \, \widetilde{\mathbf{x}}_{t-1,t+\tau_{p}+H}^{D} \right]^{T} \in \mathbb{N}^{H}, \tag{2}$$

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where $\widetilde{x}_{t-1,t'}^D$ constitutes the demand in number of parts on the $(t'-t-\tau_p-1)$ -th day from today, for each $t' \in \mathbb{N}_{t+\tau_p+H}^{t+\tau_p+1}$.

• From *upstream* (closer to basic supplies - leafs of the supply chain tree), the *current*, *temporally adjusted* production *forecasts* from *all* of his children (the suppliers that supply Joe with parts). Those production plans are denoted as

$$\widetilde{\boldsymbol{x}}_{c,t-1}^{S} \triangleq \left[\widetilde{\boldsymbol{x}}_{c,t-1,t-1}^{S} \widetilde{\boldsymbol{x}}_{c,t-1,t}^{S} \dots \widetilde{\boldsymbol{x}}_{c,t-1,t+H-\tau_{c}-2}^{S}\right]^{T} \in \mathbb{N}^{H-\tau_{c}}, \quad c \in \mathcal{N}_{Joe}^{-},$$
(3)

where \mathcal{N}_{Joe}^- is the set containing the *labels* of Joe's children suppliers (of course, this set can be made bijective to a subset of the naturals), where $\widetilde{x}_{c,t-1,t'}$ constitutes the *projected supply* in number of parts from the child supplier c, on the $(t'-t-\tau_c-1)$ -th day from today, for each $t' \in \mathbb{N}_{t+H-2}^{t+\tau_c+1}$. For convenience, we may also define the zero-padded, extended plans

$$\widetilde{\boldsymbol{x}}_{c,t-1}^{S,E} \triangleq \begin{bmatrix} \mathbf{0}_{\tau_c} \widetilde{\boldsymbol{x}}_{c,t-1}^S \end{bmatrix}^T \in \mathbb{N}^H, \quad c \in \mathcal{N}_{Joe}^-,$$
 (4)

as well as the vectors of extended plans across children suppliers

$$\widetilde{\boldsymbol{x}}_{t-1,t'}^{S,E} \triangleq \left[\widetilde{\boldsymbol{x}}_{c_1,t-1,t'}^{S,E} \, \widetilde{\boldsymbol{x}}_{c_2,t-1,t'}^{S,E} \, \dots \, \widetilde{\boldsymbol{x}}_{c_{\left|\mathcal{N}_{loe}\right|},t-1,t'}^{S,E} \right]^T \in \mathbb{N}^{\left|\mathcal{N}_{loe}\right|}, \quad t' \in \mathbb{N}_{t+H-1}^t, \tag{5}$$

where, for finite set \mathcal{A} , $|\mathcal{A}|$ denotes its cardinality, and $c_j \in \mathcal{N}_{Joe}$, for all $j \in \mathbb{N}_{|\mathcal{N}_{Joe}|}^+$.

At the *t*-th day, implementing some policy, Joe generates his own production plan, denoted as

$$\widetilde{\mathbf{x}}_{t} \triangleq \left[\widetilde{\mathbf{x}}_{tt}\,\widetilde{\mathbf{x}}_{t,t+1}\,\ldots\,\widetilde{\mathbf{x}}_{t,t+H-1}\right]^{T} \in \mathbb{N}^{H},$$
(6)

where $x_{tt'}$ is the *number of parts to be produced* on the (t'-t)-th day from today, for all $t' \in \mathbb{N}_{t+H-1}^t$. In order to produce, Joe needs certain quantities of parts from his children suppliers. Those quantities are assumed to be fixed in time, known and stored in the *quantity vector*, defined as

$$Q \triangleq \left[Q_{c_1} Q_{c_2} \dots Q_{c_{\left| \mathcal{N}_{Ioe} \right|}} \right]^T \in \left[\mathbb{N}^+ \right]^{\left| \mathcal{N}_{Ioe} \right|}, \tag{7}$$

where Q_{c_j} denotes the quantity of parts required from child supplier $c_j \in \mathcal{N}_{Joe}$, $j \in \mathbb{N}^+_{|\mathcal{N}_{Joe}|}$, required so that Joe can produce *precisely one* of his parts.

Additionally, Joe maintains an *input* (or part) inventory for the parts that have arrived and are available for production. In particular, under the setting established above, if the vector $\mathbf{R}_t^I \triangleq \widetilde{\mathbf{R}}_{tt}^I \in \mathbb{N}^{|\mathcal{N}_{Joe}|}$ stacks the resources (per part) available on the current day (or the 0-th day from today), both from the previous day and including any additions of incoming parts shipped to Joe earlier, Joe's input inventory evolves deterministically, according to the differential equation

$$\widetilde{\boldsymbol{R}}_{t,t'+1}^{I} \equiv \widetilde{\boldsymbol{R}}_{tt'}^{I} - \boldsymbol{Q}\widetilde{\boldsymbol{x}}_{tt'} + \widetilde{\boldsymbol{x}}_{t-1,t'}^{S,E} \in \mathbb{Z}^{|\mathcal{N}_{loe}|}, \quad \forall t' \in \mathbb{N}_{t+H-1}^{t}.$$
(8)

Note that $\widetilde{R}_{tt'}^I$ denotes the inventory levels at the *start* of day t', *before* all production and part additions due to (projected) arrivals have taken place. Also, we do not require $\widetilde{R}_{tt'}^I$ to be nonnegative by definition; instead, this requirement will be imposed as a constraint while designing the plan \widetilde{x}_t (see below).

Except for the input inventory, Joe maintains an *output* (or production, or stock) inventory, for the parts that have been produced by Joe, but have not yet shipped downstream. Similarly to the description of the input inventory, if $R_t^O \triangleq \widetilde{R}_{tt}^O \in \mathbb{N}$ denotes the stock available on the current day, Joe's stock inventory is assumed to evolve according to the differential equation

$$\widetilde{R}_{t,t'+1}^{O} \equiv \widetilde{R}_{tt'}^{O} + \widetilde{x}_{tt'} - \left(\widetilde{x}_{t-1,t'}^{D} - \widetilde{x}_{tt'}^{UD}\right) \in \mathbb{Z}, \quad \forall t' \in \mathbb{N}_{t+H-1}^{t}, \tag{9}$$

where $\widetilde{x}_{tt'}^{UD} \in \mathbb{N}$ constitutes the *projected unmet demand* on the (t'-t)-th day from today, for each $t' \in \mathbb{N}_{t+H-1}^t$. Therefore, the difference $\widetilde{x}_{t-1,t'}^D - \widetilde{x}_{tt'}^{UD}$ expresses the *projected met demand*, for each $t' \in \mathbb{N}_{t+H-1}^t$. Except for the requirement that $\widetilde{x}_{tt'}^{UD}$ is a nonnegative integer, we must also have that $\widetilde{x}_{t-1,t'}^D - \widetilde{x}_{tt'}^{UD} \in \mathbb{N}$, for all $t' \in \mathbb{N}_{t+H-1}^t$, and that $\widetilde{R}_{t,t'+1}^O \in \mathbb{N}$, for all $t' \in \mathbb{N}_{t+H-1}^t$, which is trivially equivalent to the constraint

$$\mathbb{Z} \ni \widetilde{x}_{tt'}^{UD} \ge \widetilde{x}_{tt'}^{D} - \widetilde{R}_{tt'}^{O} - \widetilde{x}_{tt'}, \quad \forall t' \in \mathbb{N}_{t+H-1}^{t}. \tag{10}$$

Finally, it would not be reasonable to assume that Joe has an infinite production capacity. Instead, we assume that Joe's production capacity is fixed on a *per day basis*; for simplicity, this capacity is taken as constant relative to time, and will be denoted by $C \in \mathbb{N}$.

2 Production Policy

Every day, Joe's objective will be to come up will a *feasible* production plan, not only for today, but also for all remaining days in a horizon of length *H*, so that, in general, some combination of downstream demand and inventory maintenance costs are somehow meaningfully optimized.

For simplicity, let us first *relax integer constraints*, for all problem variables. Then, based on the our definitions above, and imposing the aforementioned suitable requirements on the values of the inventories over time, one possible formulation could be

$$\begin{array}{ll} \underset{\widetilde{R}_{tt'}^{I},\widetilde{R}_{tt'}^{O}\widetilde{x}_{tt'},\widetilde{x}_{tt'}^{UD}}{\text{minimize}} & \sum_{t'\in\mathbb{N}_{t+H-1}^{t}} \theta_{tt'}\widetilde{x}_{tt'}^{UD} + \sum_{t'\in\mathbb{N}_{t+H-1}^{t}} \kappa^{O}\widetilde{R}_{t,t'+1}^{O} + \sum_{t'\in\mathbb{N}_{t+H-1}^{t}} \left(\kappa^{I}\right)^{T}\widetilde{R}_{t,t'+1}^{I} \\ \text{subject to} & \widetilde{R}_{t,t'+1}^{I} \equiv \widetilde{R}_{tt'}^{I} - Q\widetilde{x}_{tt'} + \widetilde{x}_{t-1,t'}^{S,E} \\ & \widetilde{R}_{t,t'+1}^{I} \geq \mathbf{0} \\ & 0 \leq \widetilde{x}_{tt'} \leq C \\ & \widetilde{R}_{t,t'+1}^{O} \equiv \widetilde{R}_{tt'}^{O} + \widetilde{x}_{tt'} - \left(\widetilde{x}_{t-1,t'}^{D} - \widetilde{x}_{tt'}^{UD}\right) \\ & \widetilde{R}_{t,t'+1}^{O} \geq 0 \\ & 0 \leq \widetilde{x}_{tt'}^{UD} \leq \widetilde{x}_{tt'}^{D}, \quad \forall t' \in \mathbb{N}_{t+H-1}^{t} \\ & 0 \leq \widetilde{x}_{tt'}^{UD} \leq \widetilde{x}_{tt'}^{D}, \quad \forall t' \in \mathbb{N}_{t+H-1}^{t} \\ \end{array}$$

where $\theta_{tt'} \geq 0$ is a tunable parameter, penalizing unmet demand $\widetilde{x}_{tt'}^{UD}$, for all $t' \in \mathbb{N}_{t+H-1}^t$, $\kappa^S \geq 0$ denotes the *stock inventory storage cost per unit* and, likewise,

$$\boldsymbol{\kappa}^{I} \triangleq \left[\kappa_{1}^{I} \dots \kappa_{\left|\mathcal{N}_{Joe}\right|}^{I}\right]^{T} \in \mathbb{R}_{+}^{\left|\mathcal{N}_{Joe}\right|},$$
(12)

with κ_j^I being the *input inventory storage cost per unit of the j-th part,* $j \in \mathbb{N}_{|\mathcal{N}_{Joe}|}^+$. OK

References

[1] R. B. Ash and C. Doléans-Dade, Probability and Measure Theory. Academic Press, 2000.

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