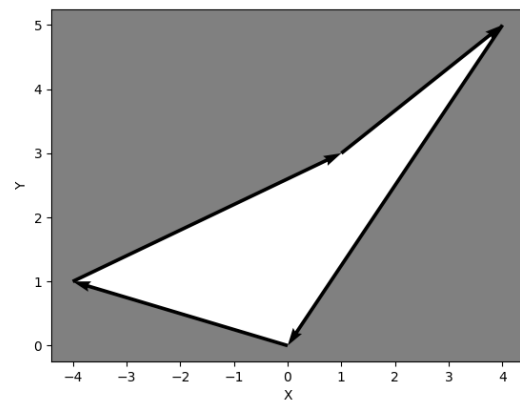
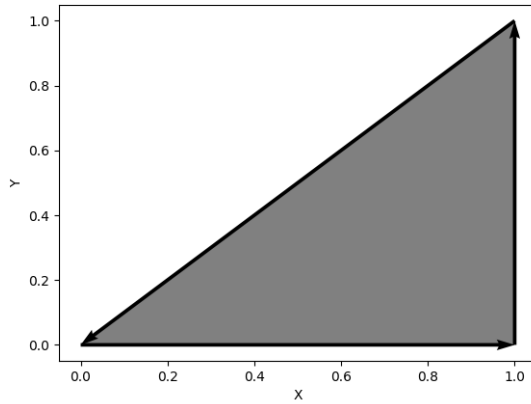
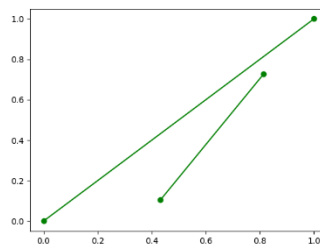
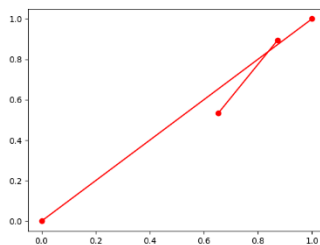
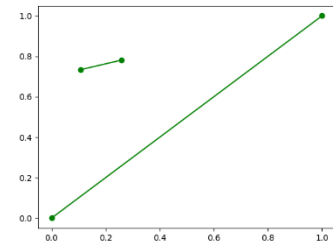
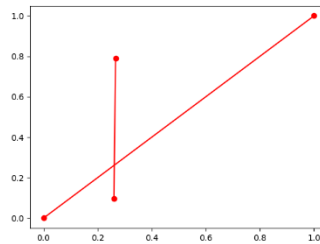
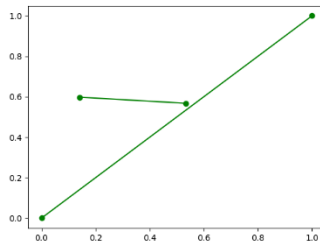


I am using 2 late homework credits for this assignment

1.1) 2 Polygons, one filled and one hollow

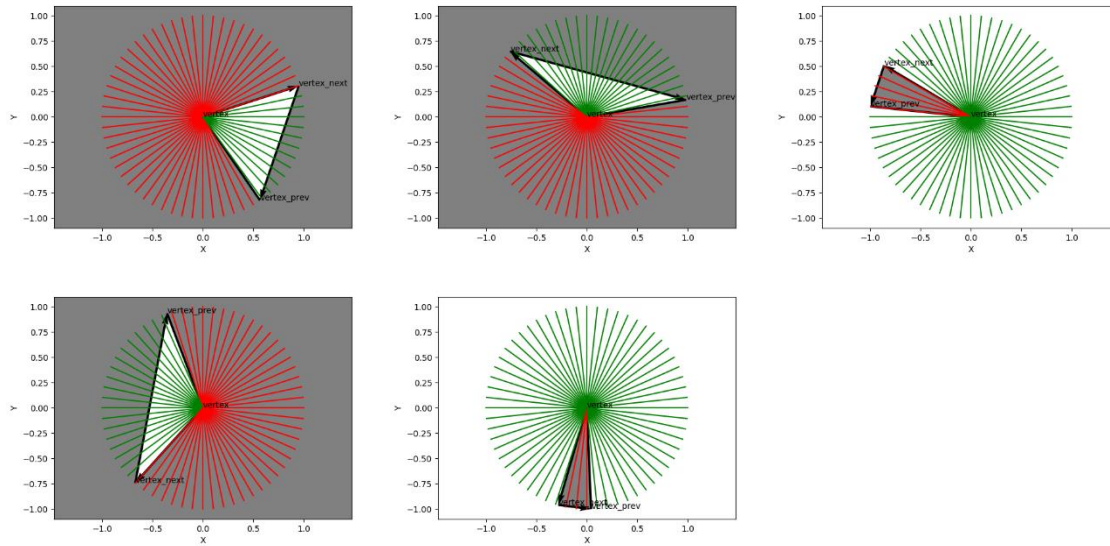


1.2) Call the provided function `edge_is_collision_test()` five times

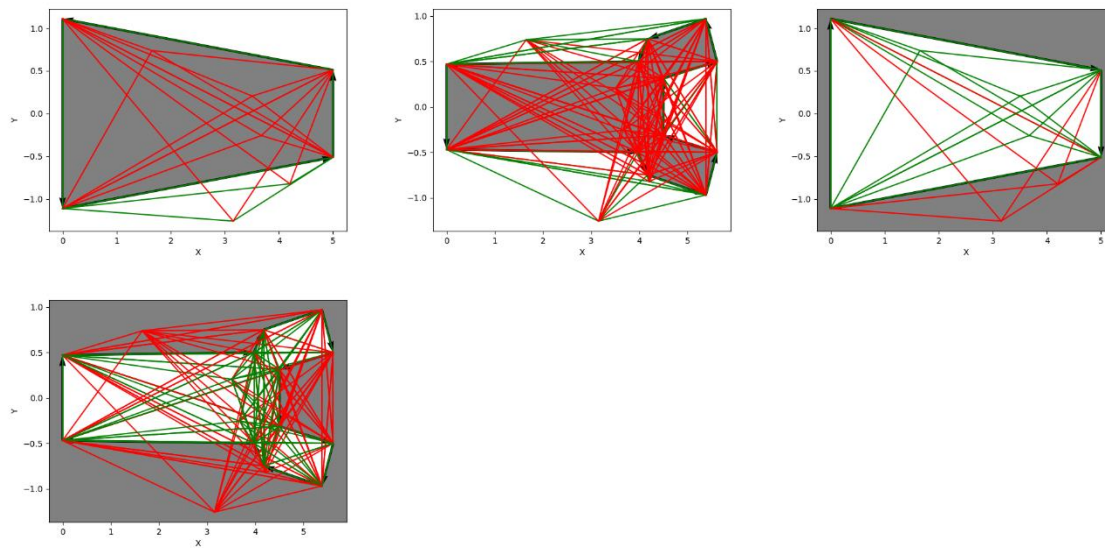


1.3) `c_angle` is the value of $\cos(\theta)$ and `s_angle` is the value of $\sin(\theta)$. Taking the arctangent of the sine and cosine values gives us the lengths of the vectors, which we can use to get the angle between the two vectors in radians

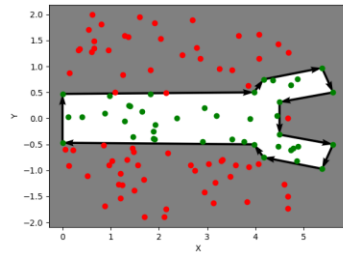
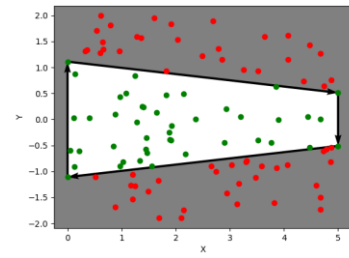
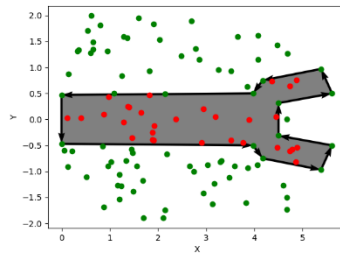
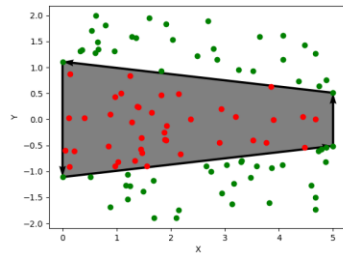
1.4) Run the provided function `polygon_is_self_occluded_test()` five times



1.5) Display four separate figures in total, each one with a single polygon and lines from each vertex in the polygon, to each point.



1.6) Run the function `polygon_is_collision_test()`



2.1) Run `priority_test()` and include a copy of the outputs from the command window into your report.

```
# 1
# 2
('Oranges', 4.5)
('Apples', 1)
('Bananas', 2.7)
# 3
('Apples', 1)
('Oranges', 4.5)
('Bananas', 2.7)
# 4
('Oranges', 4.5)
('Bananas', 2.7)
('Cantaloupe', 3)
# 5
False
True
False
('Oranges', 4.5)
('Bananas', 2.7)
('Cantaloupe', 3)
# 6
('Bananas', 2.7)
('Cantaloupe', 3)
('Oranges', 4.5)
(None, None)
```

2.2) It depends a bit how we want our end data to look, but if we want a list of coordinates in descending order, we can use `priority_queue` as follows

`P_queueX = ((x, y), cost)` where key `(x, y)` is the coordinate and `cost` is the associated cost

From here, we can loop `min_extract()` to get the lowest cost coordinates in an ordered list

To have a list descending by cost, we can either take the `min_extract()` loop in order and reverse it, or insert the new values at the front of a list

3.1)

$$\begin{aligned}x(t) &= \begin{bmatrix} \cos(t^2) \\ \sin(t^2) \end{bmatrix} & \dot{x}(t) &= \begin{bmatrix} -2t \sin(t^2) \\ 2t \cos(t^2) \end{bmatrix} \\ \mathbf{x}(t)^T \cdot \dot{\mathbf{x}}(t) &= \begin{bmatrix} \cos(t^2) \\ \sin(t^2) \end{bmatrix}^T \cdot \begin{bmatrix} -2t \sin(t^2) \\ 2t \cos(t^2) \end{bmatrix} \\ &= \cos(t^2) * 2t \sin(t^2) + \sin(t^2) * (-2t) \cos(t^2) \\ &= 2t \sin(t^2) \cos(t^2) - 2t \sin(t^2) \cos(t^2) \\ &= 0\end{aligned}$$

Since the dot product of these two matrices is 0, they will always be perpendicular with each other