

# Support Vector Machines (SVM): Intuition, Math, Primal–Dual, Lagrange Multipliers, Kernels, KKT, and Simulation

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# Learning Goals

- SVM - Early Foundations
- Build intuition for SVMs: hyperplanes, margins, support vectors
- Understand **primal** and **dual** formulations
- Learn **Lagrange multipliers** and their role
- Derive and interpret the **KKT** conditions
- See the **kernel trick** and decision function
- Practice-ready guidance + **simulation code**

# What is an SVM?

- Support Vector Machine (SVM) is a supervised learning algorithm used for classification and regression.
- It finds the **optimal separating hyperplane** that maximizes the **margin** between classes.
- Originally designed for **linear separation**, later extended using the **kernel trick** for nonlinear data.

Core idea :

$$\max_{\text{margin}} \Rightarrow \min \frac{1}{2} \|w\|^2$$

# 1960s–1970s: Theoretical Foundations

- **Vladimir Vapnik** and **Alexey Chervonenkis** (Moscow, USSR) developed the foundations of **statistical learning theory**.
- Introduced:
  - **VC dimension** — a measure of model complexity.
  - **Optimal hyperplane** for linearly separable data.
- Laid groundwork for modern SVM theory.

Vapnik & Chervonenkis (1963): “A note on one class of perceptrons.”

# 1980s: Computational Era Begins

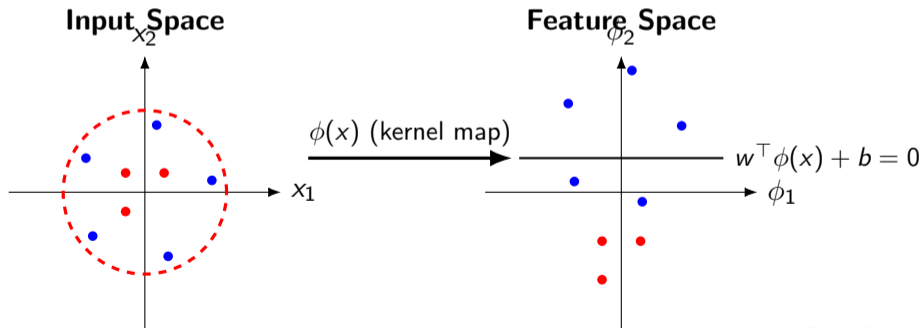
- Advances in optimization made it feasible to compute separating hyperplanes.
- Early algorithms could now handle small datasets using quadratic programming.
- Focus: improving **generalization** and introducing **soft margins**.

# 1992: The Kernel Trick is Born

- **Boser, Guyon, and Vapnik (1992):** “A Training Algorithm for Optimal Margin Classifiers.”
- Introduced the **kernel trick**:

$$K(x_i, x_j) = \phi(x_i)^\top \phi(x_j)$$

- Enabled nonlinear classification by mapping data into higher dimensions implicitly.



# 1995: Soft-Margin SVM

- **Cortes & Vapnik (1995):** “Support-Vector Networks.”
- Introduced:
  - **Soft margins** – allow misclassifications via slack variables  $\xi_i$ .
  - Regularization parameter  $C$  to balance margin width and error.
- Made SVMs practical for noisy, real-world data.

Optimization problem :

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + C \sum_i \xi_i \quad \text{s.t.} \quad y_i(w^\top x_i + b) \geq 1 - \xi_i$$

- Widely adopted for:
  - Handwritten digit recognition (MNIST)
  - Text and document classification
  - Bioinformatics (gene expression data)
  - Image recognition
- Popular kernels:
  - Polynomial kernel
  - RBF (Gaussian) kernel
  - Sigmoid kernel

# 2000s: Competing with Neural Networks

- Early 2000s: SVMs became the gold standard for small-to-medium datasets.
- Outperformed neural networks in many tasks due to:
  - Convex optimization (no local minima)
  - Strong generalization guarantees
- Still used heavily in text mining, genomics, and medical data.

# Major Contributors to SVM Development

| Year      | Contributors          | Contribution                  |
|-----------|-----------------------|-------------------------------|
| 1963      | Vapnik & Chervonenkis | Optimal hyperplane, VC theory |
| 1979      | Vapnik                | Statistical learning theory   |
| 1992      | Boser, Guyon, Vapnik  | Kernel trick introduced       |
| 1995      | Cortes & Vapnik       | Soft-margin SVMs              |
| 1998–2000 | Scholkopf & Smola     | Kernel methods, SVM theory    |

# SVM in the Deep Learning Era

- Deep neural networks now dominate large-scale image and speech tasks.
- SVMs remain powerful for:
  - Small datasets
  - High-dimensional data (e.g., text, bioinformatics)
  - Outlier and novelty detection (one-class SVM)
- The SVM's theoretical legacy continues in modern margin-based learning.

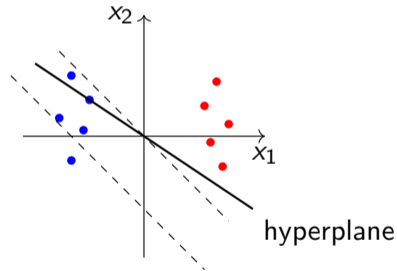
# What is an SVM?

Find a separating **hyperplane** that maximizes the **margin** between classes.

Decision function (binary classification):

$$f(x) = \text{sign}(w^T x + b)$$

- $w$  controls the orientation of the hyperplane.
- $b$  shifts it.



# Margin and Support Vectors

- Margin = distance from hyperplane to nearest points of either class.
- For a hyperplane  $w^\top x + b = 0$ , the (signed) distance of  $x$  is  $\frac{w^\top x + b}{\|w\|}$ .
- The closest points that *touch* the margin are the **support vectors**.

Maximize margin  $\iff$  minimize  $\frac{1}{2}\|w\|^2$  under appropriate constraints.

# Hard-Margin SVM (Separable Data)

$$\begin{aligned} \min_{w,b} \quad & \frac{1}{2} \|w\|^2 \\ \text{s.t.} \quad & y_i (w^\top x_i + b) \geq 1, \quad \forall i. \end{aligned}$$

- All points must be correctly classified and lie **outside** the margin.

# Soft-Margin SVM (Real Data)

Introduce slacks  $\xi_i \geq 0$ :

$$\begin{aligned} \min_{w, b, \xi} \quad & \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \\ \text{s.t.} \quad & y_i (w^\top x_i + b) \geq 1 - \xi_i, \quad \xi_i \geq 0. \end{aligned}$$

- $C$  controls trade-off between large margin and training violations.
- Hinge-loss view:  $\max\{0, 1 - y_i(w^\top x_i + b)\}$ .

# Lagrange Multipliers (Idea)

- For constrained optimization, build the **Lagrangian** to merge objective and constraints.
- Equality case:  $L(x, \lambda) = f(x) - \lambda g(x)$ ; optimality requires stationarity.
- Inequalities use KKT conditions (next).

# SVM Lagrangian (Soft-Margin)

Let  $\alpha_i \geq 0$  for margin constraints and  $\mu_i \geq 0$  for  $\xi_i \geq 0$ :

$$L(w, b, \xi, \alpha, \mu) = \frac{1}{2} \|w\|^2 + C \sum_i \xi_i \\ - \sum_i \alpha_i [y_i (w^\top x_i + b) - 1 + \xi_i] - \sum_i \mu_i \xi_i.$$

Stationarity gives

$$w = \sum_i \alpha_i y_i x_i, \quad \sum_i \alpha_i y_i = 0, \quad \alpha_i + \mu_i = C.$$

# Dual Problem (Soft-Margin)

Eliminating  $w, b, \xi$  yields the dual:

$$\begin{aligned} \max_{\alpha} \quad & \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j (x_i^\top x_j) \\ \text{s.t.} \quad & 0 \leq \alpha_i \leq C, \quad \sum_i \alpha_i y_i = 0. \end{aligned}$$

- Only samples with  $\alpha_i > 0$  are **support vectors**.
- Recover  $w^* = \sum_i \alpha_i^* y_i x_i$ ; find  $b^*$  from any margin SV.

# KKT Conditions at Optimum

- **Primal feasibility:**  $y_i(w^\top x_i + b) - 1 + \xi_i \geq 0, \xi_i \geq 0$ .
  - **Dual feasibility:**  $\alpha_i \geq 0, \mu_i \geq 0$ .
  - **Stationarity:**  $w = \sum_i \alpha_i y_i x_i$ .
  - **Complementary slackness:**  $\alpha_i [y_i(w^\top x_i + b) - 1 + \xi_i] = 0, \mu_i \xi_i = 0$ .
- $0 < \alpha_i < C$ : points on the margin  $\Rightarrow$  support vectors.
  - $\alpha_i = 0$ : points strictly outside the margin (no influence).
  - $\alpha_i = C$ : violations (inside margin / misclassified).

# Kernel Trick

Replace dot products with kernels  $K(x_i, x_j) = \phi(x_i)^\top \phi(x_j)$ :

$$\begin{aligned} \max_{\alpha} \quad & \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j K(x_i, x_j) \\ \text{s.t.} \quad & 0 \leq \alpha_i \leq C, \sum_i \alpha_i y_i = 0. \end{aligned}$$

Common kernels:

- Linear:  $K(x, z) = x^\top z$
- Polynomial:  $K(x, z) = (x^\top z + c)^d$
- RBF (Gaussian):  $K(x, z) = \exp(-\gamma \|x - z\|^2)$
- Sigmoid:  $K(x, z) = \tanh(\alpha x^\top z + c)$

$$f(x) = \text{sign}\left(\sum_{i \in \text{SV}} \alpha_i y_i K(x_i, x) + b\right).$$

- **Sparsity:** the sum involves only SVs.
- **Confidence:** distance to hyperplane  $\propto \frac{w^\top x + b}{\|w\|}$  (linear case).

# Training Recipe (Classification)

- 1 **Scale** features (zero-mean, unit variance).
- 2 Choose kernel: start with **linear**; try **RBF** for nonlinearity.
- 3 Tune hyperparameters via cross-validation:
  - Linear:  $C$
  - RBF:  $C$  and  $\gamma$
- 4 Handle class imbalance with weights or resampling.
- 5 Watch % of support vectors as a sanity check for overfitting.

# Multiclass and Complexity

- **Multiclass:** One-vs-Rest (OvR) or One-vs-One (OvO).
- **Complexity:** Kernel SVM training scales roughly between  $O(N^2)$  and  $O(N^3)$ ; linear SVM scales much better for large  $N$  and sparse features.

# Tiny 1D Example (Hard-Margin)

Data:  $-2, -1$  labeled  $-1$  and  $1, 2$  labeled  $+1$ .

A separating hyperplane at  $x = 0$  (i.e.,  $w = 1, b = 0$ ) satisfies  $y_i(wx_i + b) \geq 1$ .

Margin width =  $\frac{2}{\|w\|} = 2$ , nearest points at  $\pm 1$  are the SVs.

# Key Equations (Summary)

| Concept            | Equation   |
|--------------------|--|
| Boundary           | $w^\top x + b = 0$   |
| Margin width       | $2/\ w\ $  |
| Hard-margin primal | $\min \frac{1}{2} \ w\ ^2 \text{ s.t. } y_i(w^\top x_i + b) \geq 1$                    |
| Soft-margin primal | $\min \frac{1}{2} \ w\ ^2 + C \sum \xi_i$  |
| Dual objective     | $\max_{\alpha} \sum \alpha_i - \frac{1}{2} \sum_{ij} \alpha_i \alpha_j y_i y_j K_{ij}$ |
| Decision function  | $\text{sign}(\sum_{i \in SV} \alpha_i y_i K(x_i, x) + b)$                              |

# The SVM Objective

**Goal:** Find a hyperplane that separates data with the largest possible margin.

Hyperplane equation

$$w^T x + b = 0$$

**Margin:** the distance between the support vectors (the nearest points) and the separating hyperplane.

$$\text{Margin width} = \frac{2}{\|w\|}$$

**We want to maximize this margin.**

$$\max \frac{2}{\|w\|} \iff \min \|w\|$$

To make differentiation easier

$$\min \frac{1}{2} \|w\|^2$$

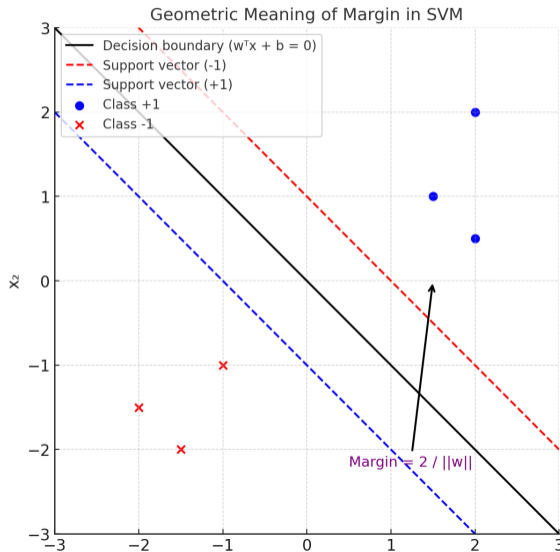
# Why Minimizing $\frac{1}{2}\|w\|^2$ Maximizes the Margin ?

- The SVM tries to make the separating hyperplane as “flat” as possible.
- The vector  $w$  is perpendicular to the hyperplane.
- Smaller  $\|w\|$  means a gentler slope — hence a **wider margin**.
- The margin width is inversely proportional to  $\|w\|$ :

$$\text{Margin} = \frac{2}{\|w\|}$$

- So minimizing  $\|w\|$  (or equivalently  $\frac{1}{2}\|w\|^2$ ) directly maximizes the margin.

# Geometric Meaning of Margin in SVM



# Hard-Margin Primal Problem (Separable Data)

Given  $(x_i, y_i)$  with  $y_i \in \{\pm 1\}$ ,

$$\begin{aligned} \min_{w,b} \quad & \frac{1}{2} \|w\|^2 \\ \text{s.t.} \quad & y_i (w^\top x_i + b) \geq 1, \quad i = 1, \dots, n. \end{aligned}$$

**Intuition:** enforce perfect separation while making  $\|w\|$  small  $\Rightarrow$  large margin.

# Soft-Margin Primal Problem (Non-separable Data)

Introduce slacks  $\xi_i \geq 0$  and penalty  $C > 0$ :

$$\begin{aligned} \min_{w, b, \xi} \quad & \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i \\ \text{s.t.} \quad & y_i (w^\top x_i + b) \geq 1 - \xi_i, \quad \xi_i \geq 0. \end{aligned}$$

**Trade-off:** large  $C \Rightarrow$  fewer violations; small  $C \Rightarrow$  wider margin but more slack.

# Lagrangian and KKT Conditions (Soft-Margin)

Lagrangian with multipliers  $\alpha_i \geq 0$  and  $\mu_i \geq 0$ :

$$\mathcal{L}(w, b, \xi, \alpha, \mu) = \frac{1}{2} \|w\|^2 + C \sum_i \xi_i - \sum_i \alpha_i [y_i(w^\top x_i + b) - 1 + \xi_i] - \sum_i \mu_i \xi_i.$$

**Stationarity:**

$$\frac{\partial \mathcal{L}}{\partial w} = 0 \Rightarrow \boxed{w = \sum_i \alpha_i y_i x_i}, \quad \frac{\partial \mathcal{L}}{\partial b} = 0 \Rightarrow \sum_i \alpha_i y_i = 0,$$

$$\frac{\partial \mathcal{L}}{\partial \xi_i} = 0 \Rightarrow \alpha_i + \mu_i = C \Rightarrow 0 \leq \alpha_i \leq C.$$

**Complementary slackness:**

$$\alpha_i [y_i(w^\top x_i + b) - 1 + \xi_i] = 0, \quad \mu_i \xi_i = 0.$$

# Dual Quadratic Program (Soft-Margin)

Eliminate  $w, b, \xi$  using stationarity:

$$\begin{aligned} \max_{\alpha} \quad & \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j x_i^\top x_j \\ \text{s.t.} \quad & \sum_{i=1}^n \alpha_i y_i = 0, \quad \boxed{0 \leq \alpha_i \leq C}. \end{aligned}$$

**Hard-margin** is the special case  $C \rightarrow \infty$  (effectively  $\alpha_i \geq 0$  without upper bound).

# Kernel Trick and Decision Function

Replace dot products with a kernel  $K(x_i, x_j) = \phi(x_i)^\top \phi(x_j)$ :

$$\begin{aligned} \max_{\alpha} \quad & \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j K(x_i, x_j) \\ \text{s.t.} \quad & \sum_i \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C. \end{aligned}$$

**Classifier:**

$$f(x) = \text{sign} \left( \sum_{i=1}^n \alpha_i y_i K(x_i, x) + b \right).$$

**Recovering  $b$ :** choose any support vector  $x_s$  with  $0 < \alpha_s < C$ ,

$$b = y_s - \sum_{i=1}^n \alpha_i y_i K(x_i, x_s).$$

# Strong Duality & Support Vectors

- The primal is convex with linear constraints  $\Rightarrow$  **strong duality** holds.
- Only points with  $\alpha_i > 0$  contribute to  $w$  (or the decision function): these are the **support vectors**.
- If  $0 < \alpha_i < C$  then point  $i$  lies exactly on the margin ( $y_i(w^\top x_i + b) = 1$ ).
- If  $\alpha_i = C$  the point either violates the margin or is misclassified (active slack).

# Primal vs Dual: A Quick Map

| Aspect        | Primal   | Dual   |
|---------------|--|--|
| Objective     | $\min \frac{1}{2} \ w\ ^2 + C \sum \xi_i$          | $\max \sum \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j K_{ij}$ |
| Vars          | $w, b, \xi$  | $\alpha$   |
| Constraints   | $y_i(w^\top x_i + b) \geq 1 - \xi_i, \xi_i \geq 0$ | $\sum_i \alpha_i y_i = 0, 0 \leq \alpha_i \leq C$                              |
| Kernelization | Implicit via $w$                                   | Natural via $K(x_i, x_j)$  |
| Sparsity      | Not explicit                                       | Explicit: only $\alpha_i > 0$ matter   |

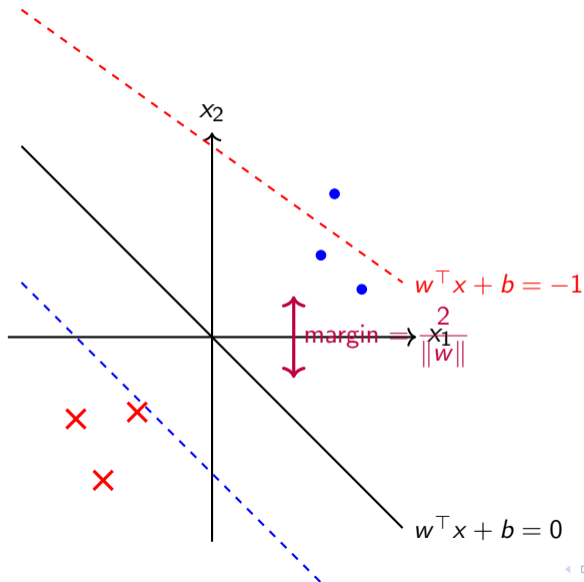
- Dual QP often solved by **SMO** (Sequential Minimal Optimization) or modern QP solvers.
- Common kernels: linear, polynomial, RBF, sigmoid.
- Hyperparameters:  $C$  (soft-margin), kernel params (e.g.,  $\gamma$  in RBF).

# Goal of an SVM (in plain words)

- We have points labeled  $+1$  and  $-1$ .
- We want a line/plane (a **hyperplane**) that separates them.
- Not just any separator — we want the one with the **largest gap** (the **margin**).

$$\text{Hyperplane: } w^T x + b = 0$$

# Margin picture (2D)



# Hard-margin Primal (perfectly separable data)

$$\begin{aligned} \min_{w,b} \quad & \frac{1}{2} \|w\|^2 \\ \text{s.t.} \quad & y_i (w^\top x_i + b) \geq 1, \quad i = 1, \dots, n. \end{aligned}$$

- Minimizing  $\frac{1}{2} \|w\|^2 \iff$  **maximizing the margin**  $\left(\frac{2}{\|w\|}\right)$ .
- Constraints keep points on the correct side of the margin.

# Soft-margin Primal (real data is messy)

Allow some violations using slacks  $\xi_i \geq 0$  and a trade-off  $C > 0$ :

$$\begin{aligned} \min_{w, b, \xi} \quad & \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i \\ \text{s.t.} \quad & y_i (w^\top x_i + b) \geq 1 - \xi_i, \quad \xi_i \geq 0. \end{aligned}$$

- $C$  large  $\Rightarrow$  fewer mistakes, possibly smaller margin.
- $C$  small  $\Rightarrow$  wider margin, more tolerance to mistakes.

# Why build a Dual?

- Handling constraints directly can be harder.
- The **Dual** becomes a nice Quadratic Program (QP).
- In the Dual, dot products  $x_i^\top x_j$  allow the **kernel trick** for non-linear boundaries.

# Lagrangian (soft-margin form)

Introduce multipliers  $\alpha_i \geq 0$  (for margin constraints) and  $\mu_i \geq 0$  (for slacks):

$$\mathcal{L}(w, b, \xi, \alpha, \mu) = \frac{1}{2} \|w\|^2 + C \sum_i \xi_i - \sum_i \alpha_i [y_i(w^\top x_i + b) - 1 + \xi_i] - \sum_i \mu_i \xi_i.$$

**Stationarity gives**

$$w = \sum_i \alpha_i y_i x_i, \quad \sum_i \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C.$$

# Dual QP (soft-margin)

Eliminating  $w, b, \xi$ :

$$\begin{aligned} \max_{\alpha} \quad & \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j x_i^\top x_j \\ \text{s.t.} \quad & \sum_{i=1}^n \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C. \end{aligned}$$

**Classifier after solving:**

$$f(x) = \text{sign} \left( \sum_i \alpha_i y_i x_i^\top x + b \right).$$

(Replace  $x_i^\top x$  by kernel  $K(x_i, x)$  for non-linear SVM.)

# Two views of the same goal

| Aspect        | Primal   | Dual  |
|---------------|--|---|
| Objective     | $\min \frac{1}{2} \ w\ ^2 + C \sum \xi_i$          | $\max \sum \alpha_i$ —<br>$\frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j K_{ij}$ |
| Variables     | $w, b, \xi$  | $\alpha$  |
| Constraints   | $y_i(w^\top x_i + b) \geq 1 - \xi_i, \xi_i \geq 0$ | $\sum_i \alpha_i y_i = 0, 0 \leq \alpha_i \leq C$                                   |
| Kernelization | Implicit via $w$                                   | Natural via $K(x_i, x_j)$   |
| Sparsity      | Not explicit                                       | Only $\alpha_i > 0$ (support vectors) matter  |

# Setup: two 2D points, one per class

**Data (hard-margin, linearly separable):**

$$x_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, y_1 = +1, \quad x_2 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}, y_2 = -1.$$

- Symmetric about the origin along  $x_1$ -axis.
- The separating hyperplane should be the vertical line through the origin.

# Dual formulation for this toy data

With two points and hard margin, the Dual becomes:

$$\max_{\alpha_1, \alpha_2} \alpha_1 + \alpha_2 - \frac{1}{2} \left( \alpha_1^2 y_1^2 \|x_1\|^2 + \alpha_2^2 y_2^2 \|x_2\|^2 + 2\alpha_1 \alpha_2 y_1 y_2 x_1^\top x_2 \right)$$

Numbers:

$$\|x_1\|^2 = \|x_2\|^2 = 1, \quad x_1^\top x_2 = -1, \quad y_1 = +1, \quad y_2 = -1.$$

Constraint  $\sum_i \alpha_i y_i = 0 \Rightarrow \alpha_1 = \alpha_2 (= a)$ .

$$\Rightarrow \max_a 2a - \frac{1}{2} (a^2 + a^2 - 2a^2(-1)) = 2a - \frac{1}{2} (4a^2) = 2a - 2a^2.$$

$$\frac{d}{da} (2a - 2a^2) = 2 - 4a = 0 \Rightarrow \boxed{a = \frac{1}{2}}.$$

So  $\boxed{\alpha_1 = \alpha_2 = \frac{1}{2}}.$

# Recovering $w$ and $b$ (KKT stationarity)

From  $w = \sum_i \alpha_i y_i x_i$ :

$$w = \frac{1}{2} \cdot (+1) \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \frac{1}{2} \cdot (-1) \begin{bmatrix} -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

Use a support vector with  $0 < \alpha_i$  to get  $b$ :

$$y_1(w^\top x_1 + b) = 1 \Rightarrow 1 \cdot (1 \cdot 1 + b) = 1 \Rightarrow \boxed{b = 0}.$$

**Decision function:**

$$f(x) = \text{sign}(w^\top x + b) = \text{sign}(x_1).$$

So the boundary is  $x_1 = 0$  (vertical line through the origin).

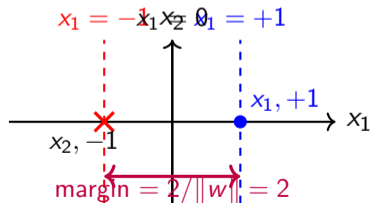
# Margin check (does it match theory?)

$$\|w\| = \left\| \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\| = 1 \Rightarrow \text{margin} = \frac{2}{\|w\|} = 2.$$

Support hyperplanes:

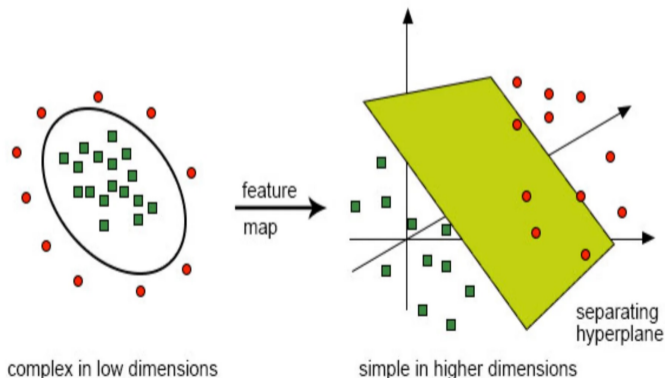
$$w^T x + b = \pm 1 \Rightarrow x_1 = \pm 1,$$

whose distance along the  $x_1$ -axis is 2, matching  $\frac{2}{\|w\|}$ .



# Kernel Trick: From Input Space to Feature Space

- The key idea behind kernel methods is to transform data into a higher-dimensional space using a kernel function, making it easier to perform linear separation in this new space.
- This approach is particularly useful for dealing with non-linear data.



# Key ideas to remember

- SVM = max-margin + convex optimization + kernels.
- Lagrange multipliers  $\alpha_i$  link constraints to solution; nonzero  $\alpha_i$  mark SVs.
- KKT ties primal and dual; kernel trick enables nonlinear boundaries.
- **Primal:** “Find the flattest separator that keeps points on the right side.”
- **Dual:** “Find weights  $\alpha_i$  on data so that their influence defines the separator.”
- **KKT:** Glue between the two; gives  $w = \sum_i \alpha_i y_i x_i$ .
- **Support vectors:** Only points with  $\alpha_i > 0$  matter.
- **Kernel trick:** Replace dot products with  $K(x_i, x_j)$  for curved boundaries.

Questions?