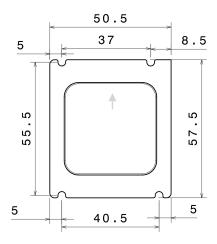


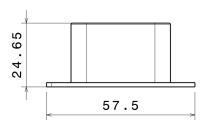
Cube mini carrier board v1.0 USER GUIDE

GENERAL:

The Airbot Systems Mini carrier board is one of the most simple way to install a Cube (aka Pixhawk 2.1) on a drone. The Mini carrier board encapsulate all the wiring in a 50.5x57.5mm board The carrier board allows saving space and weight for applications which have size limits.

DIMENSIONS:





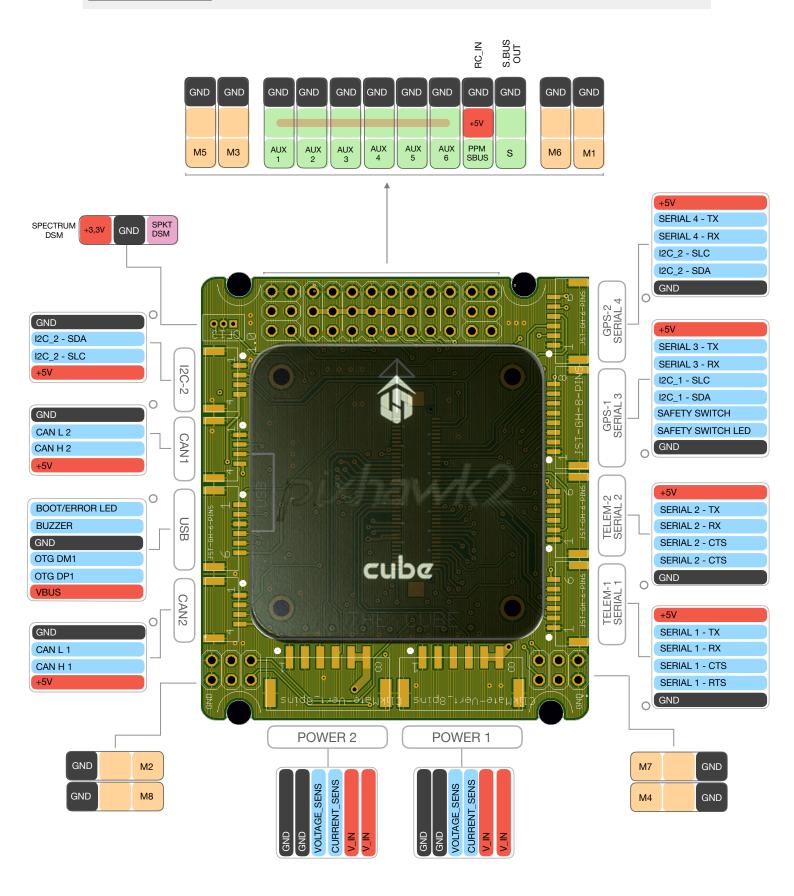
FEATURES:

- Dual power inputs (redundant power with automatic switch to the second power source when first one fails, thanks to the Proficnc-Hex Power Selection Module // Power inputs must be between 5v and 5.7v)
- Easy to install on a drone (see the mounting pattern above)
- Power distribution & voltage protection (providing the current to each connector)
- Motors PWM signal distribution (up to 8 motors distributed on board corners)
- Standard 2.54mm servo PPM/S.BUS RC input (+5v provided by the carrier board)
- Spectrum/DSM input (including +3.3v power supply)
- AUX center pins are connected together. It allows to power the AUX rail by adding external power supply.

CONNECTIVITY:

LABEL	CONNECTOR ON THE BOARD	CONNECTOR TO PLUG IN
I2C_2 - CAN1 - CAN2	JST GH: BM04B-GHS-TBT	GHR-04V-S
USB - TELEM1 - TELEM2 - GPS2	JST GH: BM06B-GHS-TBT	GHR-06V-S
GPS1	JST GH: BM08B-GHS-TBT	GHR-08V-S
POWER1 - POWER2	Molex CLIKMATE: 502443-0670	502439-0600
SPECTRUM		

PINOUT DIAGRAM:



HOW TO MOUNT IT:

You can make the fastener by yourself: if you have a 3D printer, you can download a 3D file to print the mounting bracket or download a .DXF file if you have a CNC milling machine. These files are downloadable from the product page on www.airbot-systems.com website.

We will manufacture fasteners and put on our website, for people who can not make it themselves.