

Experiment for HW 4 notebook

September 29, 2020

1 Experimental data for Homework 4

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```
[1]: %load_ext autoreload
      %autoreload 2
```

```
[2]: import generator as gen
      import optimizer as opt
      import numpy as np
      import scipy

      import matplotlib.pyplot as plt
      %matplotlib inline
```

```
[3]: kappa = 100
      n = 20
      d = 5
      A = gen.generate_A(n, d)
      alpha = 0.9
      sigma0 = 1
      sigma1 = 0.1
      sigma2 = 2.0

      tracking_errs0 = opt.gradient_descent_experiment(A, alpha, n, d, sigma0,
      ↪iters=50, projected=False)
      tracking_errs1 = opt.gradient_descent_experiment(A, alpha, n, d, sigma1,
      ↪iters=50, projected=False)
      tracking_errs2 = opt.gradient_descent_experiment(A, alpha, n, d, sigma2,
      ↪iters=50, projected=False)
      tracking_errs_proj = opt.gradient_descent_experiment(A, alpha, n, d, sigma0,
      ↪iters=50, projected=True)
```

```
[4]: rho = max([np.abs(1 - alpha/np.sqrt(kappa)), np.abs(1 - alpha)])
      err0 = np.linalg.norm(tracking_errs0[0])
      err1 = np.linalg.norm(tracking_errs1[0])
      err2 = np.linalg.norm(tracking_errs2[0])
```

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err_proj = np.linalg.norm(tracking_errs_proj[0])

bounds0 = [rho**t * err0 + sigma0 * (1 - rho**t)/(1-rho) for t in
    ↪range(len(tracking_errs0))]
bounds1 = [rho**t * err1 + sigma1 * (1 - rho**t)/(1-rho) for t in
    ↪range(len(tracking_errs1))]
bounds2 = [rho**t * err2 + sigma2 * (1 - rho**t)/(1-rho) for t in
    ↪range(len(tracking_errs2))]

bounds_proj = [rho**t * err_proj + sigma0 * (1 - rho**t)/(1-rho) for t in
    ↪range(len(tracking_errs_proj))]

```

1.0.1 Results for $\sigma = 1$

```

[5]: plt.plot(range(len(tracking_errs0)), tracking_errs0, label="Tracking error_
    ↪ $\sigma = 1$ ")
plt.plot(range(len(tracking_errs0)), bounds0, label="Finite bound  $\sigma = 1$ ")

#plt.axhline(1/(1-rho), linestyle='--', label="Asymptotic bound")
plt.grid()
plt.ylim([0, max(tracking_errs0)*2])
plt.legend()

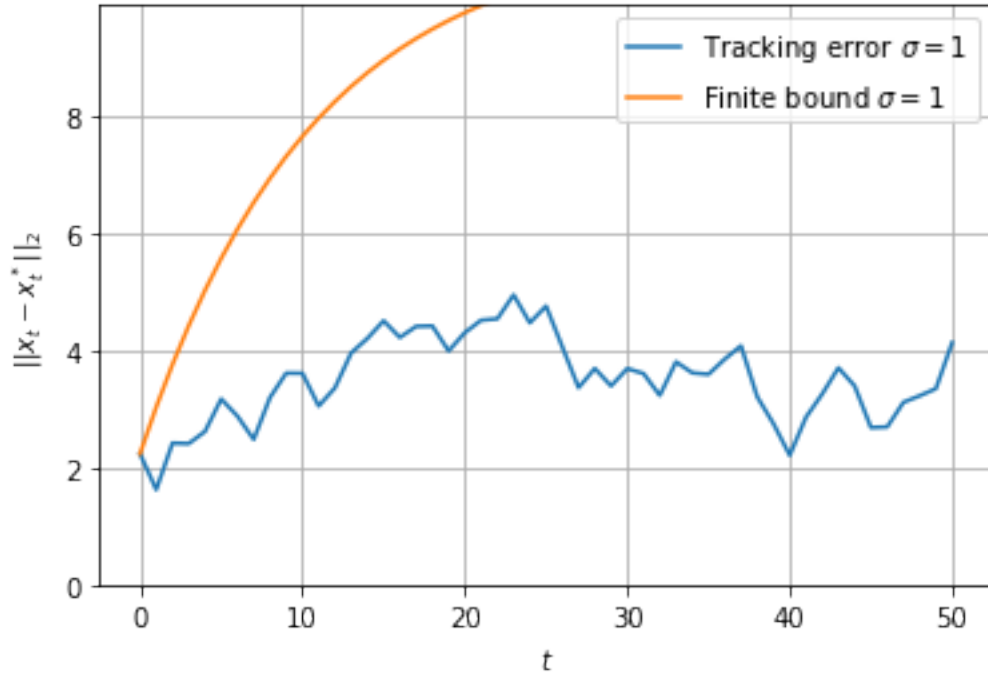
plt.xlabel(" $t$ ")
plt.ylabel(" $\|x_t - x_t^*\|_2$ ")

```

```

[5]: Text(0, 0.5, ' $\|x_t - x_t^*\|_2$ ')

```



1.0.2 Results for $\sigma = 0.1, \sigma = 2$

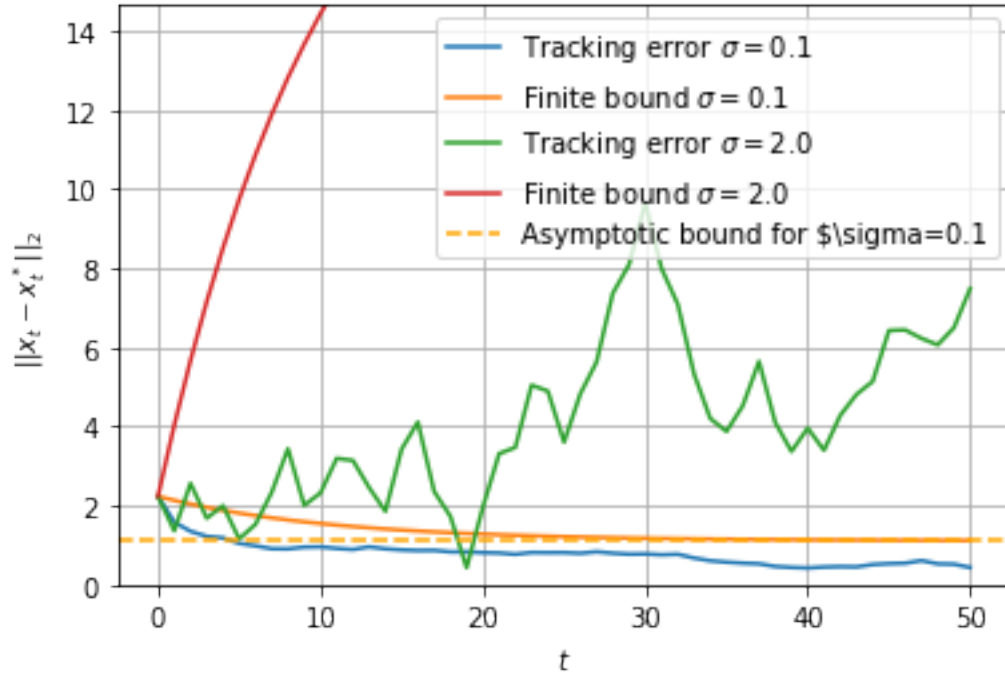
```
[10]: plt.plot(range(len(tracking_errs1)), tracking_errs1, label="Tracking error_
      ↪ $\sigma = 0.1$")
      plt.plot(range(len(tracking_errs1)), bounds1, label="Finite bound $\sigma = 0.
      ↪ 1$")

      plt.plot(range(len(tracking_errs1)), tracking_errs2, label="Tracking error_
      ↪ $\sigma = 2.0$")
      plt.plot(range(len(tracking_errs1)), bounds2, label="Finite bound $\sigma = 2.
      ↪ 0$")

      plt.axhline(sigma1/(1-rho), linestyle='--', c='orange', label="Asymptotic bound_
      ↪ for $\sigma=0.1$")
      plt.grid()
      plt.ylim([0, max(tracking_errs2)+5])
      plt.legend()

      plt.xlabel("$t$")
      plt.ylabel("$||x_t - x_t^*||_2$")
```

```
[10]: Text(0, 0.5, '$||x_t - x_t^*||_2$')
```



1.0.3 Results for projected GD

```
[7]: plt.plot(range(len(tracking_errs_proj)), tracking_errs_proj, label="Tracking_
      ↪error (projected)")
plt.plot(range(len(tracking_errs_proj)), bounds_proj, label="Finite bound")
#plt.axhline(1/(1-rho), linestyle='--', label="Asymptotic bound")
plt.axhline(2, linestyle='--', label="Max distance between two points")
plt.axhline(1.3796796759881553, linestyle=':', label="Expected distance between_
      ↪two points")
plt.grid()
plt.ylim([0, 3])
plt.legend()

plt.xlabel("$t$")
plt.ylabel("$||x_t - x_t^*||_2$")
```

```
[7]: Text(0, 0.5, '$||x_t - x_t^*||_2$')
```

