Dong-Ki Kim

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Education

Massachusetts Institute of Technology *Cambridge, MA*

Ph.D. in Aeronautics and Astronautics *Jan. 2020 – Present*

- Focus: Multi-Agent Reinforcement Learning
- Advisor: Professor Jonathan P. How
- Cumulative GPA: 5.0 / 5.0

Massachusetts Institute of Technology *Cambridge, MA*

S.M. in Aeronautics and Astronautics *Graduated Jan. 2020*

- Thesis: "Learning to Teach and Meta-Learning for Sample-Efficient Multiagent Reinforcement Learning"
- Focus: Multi-Agent Reinforcement Learning
- Advisor: Professor Jonathan P. How
- Cumulative GPA: 5.0 / 5.0

Cornell University *Ithaca, NY*

B.S. in Electrical and Computer Engineering *Graduated Jan. 2016*

- Focus: Robot Perception
- Advisor: Professor Tsuhan Chen
- Highest Honors: *Summa Cum Laude*

Experience

Laboratory for Information and Decision Systems, MIT *Cambridge, MA*

Graduate Researcher, Advisor: Professor Jonathan P. How *Sep. 2017 - Present*

- Derived new meta-multiagent policy gradient theorem that directly models learning processes of all agents within meta-learning optimization, which enables fast adaptation to new fellow agents across spectrum of mixed incentive, competitive, and cooperative multiagent settings [1, 12].
- Developed safe reinforcement learning framework by learning neural network-based meta-optimizer with projection onto polytope for optimizing objective while satisfying constraints [11].
- Developed peer-to-peer teaching frameworks for enabling agents to learn to teach or share knowledge in cooperative multiagent reinforcement learning settings [2, 3, 4, 13, 14].
- Built attention-based hierarchical reinforcement learning framework that identifies useful latent features across multiple sensory inputs and accelerates in transfer learning tasks [5, 9, 15].
- Led demo preparation of package delivery using multiple drones for annual Boeing visit at MIT. Contributed to collision avoidance algorithm, onboard perception system for classification, and projection system for visualization. **[Video]**

Air Lab, CMU-Robotics Institute *Pittsburgh, PA*

Research Intern, Advisor: Professor Sebastian Scherer *Aug. 2016 - Jul. 2017*

- Developed deep multimodal network that improves segmentation robustness to appearance variations (e.g., Summer vs Winter) by combining image and LiDAR sensor data [6, 16].
- Built ROS-based system that estimates terrain roughness from 3D LiDAR sensor data in real-time. **[Video]**

Robot Intelligence through Perception Lab, TTIC *Chicago, IL*

Research Intern, Advisor: Professor Matthew R. Walter *Jan. 2016 - Jul. 2016*

- Developed cross-view localization system that estimates vehicle's pose on georeferenced satellite map given sequence of ground-level images [7].
- Improved LSD-SLAM's pose estimation by incorporating ORB-SLAM's pose-graph keyframe constraints.

Advanced Multimedia Processing Lab, Cornell University *Ithaca, NY*

Undergraduate Researcher, Advisor: Professor Tsuhan Chen *May. 2014 - Jan. 2016*

- Developed indoor localization algorithm based on floor plan and camera [8].
- Built vision-based system that enables drone to navigate indoors autonomously and find specific target [17].

Skill

Programming Language: Python, C/C++, Matlab

Tools/Library/Software: PyTorch, TensorFlow, Theano, Caffe, Keras, OpenCV, ROS, Point Cloud Library

Honor & Award

Outstanding Student Paper Award Honorable Mention for AAAI *Jan. 2019*

Kwanjeong Education Foundation Scholarship *Sep. 2017 - Present*

- Receiving $30,000 / year for 4-5 years for graduate studies

Merrill Presidential Scholar *Sep. 2015*

- Nominated for Cornell University's prestigious award given to top 1% graduating seniors

Publication

Preprint

[1] **A Policy Gradient Algorithm for Learning to Learn in Multiagent Reinforcement Learning**
Dong-Ki Kim, Miao Liu, Matthew Riemer, Chuangchuang Sun, Marwa Abdulhai, Golnaz Habibi, Sebastian Lopez-Cot, Gerald Tesauro, Jonathan P. How
Under Review as Conference Paper, 2020 **[Paper] [Code]**

Conference Proceeding

[2] **Learning Hierarchical Teaching Policies for Cooperative Agents**
Dong-Ki Kim, Miao Liu, Shayegan Omidshafiei, Sebastian Lopez-Cot, Matthew Riemer, Golnaz Habibi, Gerald Tesauro, Sami Mourad, Murray Campbell, Jonathan P. How
International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2020 **[Paper] [WIRED News]**

[3] **Policy Distillation and Value Matching in Multiagent Reinforcement Learning**
Samir Wadhwania, **Dong-Ki Kim,** Shayegan Omidshafiei, Jonathan P. How
International Conference on Intelligent Robots and Systems (IROS), 2019 **[Paper] [Video]**

[4] **Learning to Teach in Cooperative Multiagent Reinforcement Learning**
Shayegan Omidshafiei, **Dong-Ki Kim,** Miao Liu, Gerald Tesauro, Matthew Riemer, Christopher Amato, Murray Campbell, Jonathan P. How
Association for the Advancement of Artificial Intelligence (AAAI), 2019 **[Outstanding Student Paper Honorable Mention] [Paper] [MIT News]**

[5] **Crossmodal Attentive Skill Learner**
Shayegan Omidshafiei, **Dong-Ki Kim,** Jazon Pazis, Jonathan P. How
International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2018 **[Paper] [Video]**

[6] **Season-Invariant Semantic Segmentation with A Deep Multimodal Network**
Dong-Ki Kim, Daniel Maturana, Masashi Uenoyama, Sebastian Scherer
Field and Service Robotics (FSR), 2017 **[Paper]**

[7] **Satellite Image-based Localization via Learned Embeddings**
Dong-Ki Kim, Matthew R. Walter
International Conference on Robotics and Automation (ICRA), 2017 **[Paper] [Video] [NVIDIA News]**

[8] **You Are Here: Mimicking the Human Thinking Process in Reading Floor-Plans**
Hang Chu, **Dong-Ki Kim,** Tsuhan Chen
International Conference on Computer Vision (ICCV), 2015 **[Paper] [Video]**

Journal Article

[9] **Crossmodal Attentive Skill Learner: Learning in Atari and Beyond with Audio-Video Inputs**
Dong-Ki Kim, Shayegan Omidshafiei, Jazon Pazis, Jonathan P. How
Journal of Autonomous Agents and Multiagent Systems (JAAMAS), 2020 **[Paper]**

Book Chapter

[10] **Multiagent Reinforcement Learning**
Jonathan P. How, **Dong-Ki Kim,** Samir Wadhwania
Encyclopedia of Systems and Control, 2nd Ed. **[Chapter]**

Workshop and Symposium Paper

[11] **Set-Invariant Constrained Reinforcement Learning with a Meta-Optimizer**
Chuangchuang Sun, **Dong-Ki Kim,** Jonathan P. How
International Conference on Machine Learning (ICML) Workshop, 2020 **[Paper]**

[12] **A Policy Gradient Theorem for Learning to Learn in Multiagent Reinforcement Learning**
Dong-Ki Kim, Miao Liu, Matthew Riemer, Golnaz Habibi, Sebastian Lopez-Cot, Samir Wadhwania, Gerald Tesauro, Jonathan P. How
Association for the Advancement of Artificial Intelligence (AAAI) Spring Symposium, 2020 **[Paper]**

[13] **Heterogeneous Knowledge Transfer via Hierarchical Teaching in Cooperative Multiagent Reinforcement Learning**
Dong-Ki Kim, Miao Liu, Shayegan Omidshafiei, Sebastian Lopez-Cot, Matthew Riemer, Gerald Tesauro, Murray Campbell, Golnaz Habibi, Jonathan P. How
Association for the Advancement of Artificial Intelligence (AAAI) Workshop, 2019

[14] **Learning to Teach in Cooperative Multiagent Reinforcement Learning**
Shayegan Omidshafiei, **Dong-Ki Kim,** Miao Liu, Gerald Tesauro, Matthew Riemer, Christopher Amato, Murray Campbell, Jonathan P. How
International Conference on Machine Learning (ICML) Workshop, 2018

[15] **Crossmodal Attentive Skill Learner**
Shayegan Omidshafiei, **Dong-Ki Kim,** Jazon Pazis, Jonathan P. How
Neural Information Processing Systems (NeurIPS) Symposium, 2017

[16] **Online Semantic Mapping for Autonomous Navigation and Scouting**
Daniel Maturana, Sankalp Arora, Po-Wei Chou, **Dong-Ki Kim,** Masashi Uenoyama, Sebastian Scherer
Robotics: Science and Systems (RSS) Workshop, 2017 **[Paper]**

Technical Report

[17] **Deep Neural Network for Real-Time Autonomous Indoor Navigation**
Dong-Ki Kim, Tsuhan Chen
arXiv preprint arXiv:1511.04668, 2015 **[Paper] [Video]**