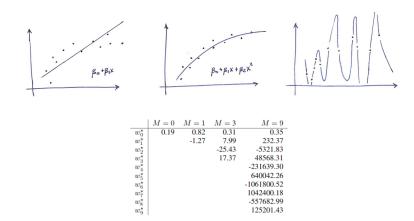
Overfitting



Bishop, Pattern Recognition and Machine Learning



Regularization

Idea: penalize large coefficients. (Occam's razor!)

$$\mathcal{L} = \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda R(\boldsymbol{\beta})$$

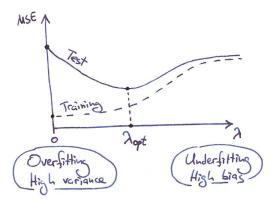
Here $\lambda R(\beta)$ is a penalty term and λ is called regularization parameter.

Some common choices are (all convex):

$$R(oldsymbol{eta}) = \|oldsymbol{eta}\|^2 = \sum_i eta_i^2$$
 ridge $R(oldsymbol{eta}) = \|oldsymbol{eta}\|_1 = \sum_i |eta_i|$ lasso $R(oldsymbol{eta}) = \lambda_1 \|oldsymbol{eta}\|_1 + \lambda_2 \|oldsymbol{eta}\|_2^2$ elastic net

Bias-variance tradeoff

Loss function: $\mathcal{L} = \frac{1}{n} ||\mathbf{y} - \mathbf{X}\boldsymbol{\beta}||^2 + \lambda R(\boldsymbol{\beta}).$



Ridge regression

Ridge regression

Loss function:

$$\mathcal{L} = \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda \|\boldsymbol{\beta}\|^2.$$

Gradient:

$$\nabla \mathcal{L} = -\frac{2}{n} \mathbf{X}^{\top} (\mathbf{y} - \mathbf{X}\boldsymbol{\beta}) + \frac{2\lambda \boldsymbol{\beta}}{n}.$$

Gradient descent:

$$\beta \leftarrow \beta - \eta \nabla \mathcal{L} = \beta + \eta \frac{2}{n} \mathbf{X}^{\top} (\mathbf{y} - \mathbf{X}\beta) - 2\eta \lambda \beta =$$

$$= \underbrace{(1 - 2\eta \lambda)}_{\text{"weight decay"}} \beta + \eta \frac{2}{n} \mathbf{X}^{\top} (\mathbf{y} - \mathbf{X}\beta).$$

Analytic solution for ridge regression

Gradient is equal to zero at the minimum:

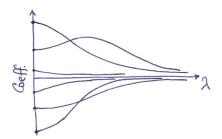
$$-\frac{2}{n}\mathbf{X}^{\top}(\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}}) + 2\lambda\hat{\boldsymbol{\beta}} = 0$$
$$\mathbf{X}^{\top}\mathbf{X}\hat{\boldsymbol{\beta}} + n\lambda\hat{\boldsymbol{\beta}} = \mathbf{X}^{\top}\mathbf{y}$$
$$(\mathbf{X}^{\top}\mathbf{X} + n\lambda\mathbf{I})\hat{\boldsymbol{\beta}} = \mathbf{X}^{\top}\mathbf{y}$$
$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^{\top}\mathbf{X} + n\lambda\mathbf{I})^{-1}\mathbf{X}^{\top}\mathbf{y}$$

This is an example of a *shrinkage* estimator.

One can prove that if $\mathbf{X}^{\top}\mathbf{X}$ has full rank, then $\lambda_{\mathrm{opt}} > 0$ (Hoerl and Kennard, 1970).

Shrinkage in action

Ridge estimator: $\hat{\boldsymbol{\beta}}_{\lambda} = (\mathbf{X}^{\top}\mathbf{X} + n\lambda\mathbf{I})^{-1}\mathbf{X}^{\top}\mathbf{y}$.



A note on not penalizing the intercept

Loss function:

$$\mathcal{L} = \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda \|\boldsymbol{\beta}\|^2$$

What happens with \hat{y} when $\lambda \to \infty$? It is convenient if $\hat{y}_i \to \bar{y}$ and not to 0. This will be the case if both \mathbf{X} and \mathbf{y} have been centered (and \mathbf{X} does not contain \mathbf{x}_0). Otherwise we need to write explicitly

$$\mathcal{L} = \frac{1}{n} \sum_{i=1}^{n} \left(y_i - \beta_0 - \sum_{j=1}^{p} \beta_j X_{ij} \right)^2 + \lambda \sum_{j=1}^{p} \beta_j^2.$$

Another note: there may be no $\frac{1}{n}$ factor in some implementations.



SVD perspective

Consider singular value decomposition $\mathbf{X} = \mathbf{U}\mathbf{S}\mathbf{V}^{\top}$.

We previously showed that in OLS regression

$$\hat{\mathbf{y}} = \mathbf{U}\mathbf{U}^{\mathsf{T}}\mathbf{y}.$$

In ridge regression,

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\beta}} = \underbrace{\mathbf{X}(\mathbf{X}^{\top}\mathbf{X} + n\lambda\mathbf{I})^{-1}\mathbf{X}^{\top}\mathbf{y}}_{\text{hat matrix}}$$

$$= \mathbf{U}\mathbf{S}\mathbf{V}^{\top}(\mathbf{V}\mathbf{S}^{2}\mathbf{V}^{\top} + n\lambda\mathbf{V}\mathbf{V}^{\top})^{-1}\mathbf{V}\mathbf{S}\mathbf{U}^{\top}\mathbf{y}$$

$$= \mathbf{U}\operatorname{diag}\left\{\frac{s_{i}^{2}}{s_{i}^{2} + n\lambda}\right\}\mathbf{U}^{\top}\mathbf{y}.$$

I.e. ridge regression stronger affects small singular values.



Bayesian perspective

Previously we showed that \hat{eta}_{OLS} is the maximum likelihood solution of

$$y = \boldsymbol{\beta}^{\top} \mathbf{x} + \epsilon,$$

$$\epsilon \sim \mathcal{N}(0, \sigma^2).$$

This treats β as fixed. What if we treat it as random and assume a *prior* distribution $\beta \sim \mathcal{N}(\mathbf{0}, \tau^2 \mathbf{I})$?..

It turns out that $\hat{\beta}_{\lambda}$ with $\lambda = \sigma^2/(n\tau^2)$ is the mean of the *posterior* distribution, i.e. it is a *maximum a posteriori* (MAP) estimator.

Bayes theorem, prior, and posterior

Joint and conditional probabilities:

$$P(A,B) = P(A \mid B)P(B) = P(B \mid A)P(A).$$

 \Rightarrow Bayes theorem:

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}.$$

Example:

$$\begin{split} P(\text{pandemics} \mid \text{mask}) &= \frac{P(\text{mask} \mid \text{pandemics})P(\text{pandemics})}{P(\text{mask})} = \\ &= \frac{P(\text{mask} \mid \text{pandemics})P(\text{pandemics})}{P(\text{mask} \mid \text{pand.})P(\text{pand.}) + P(\text{mask} \mid \neg \text{pand.})P(\neg \text{pand.})} \end{split}$$

Bayes theorem, prior, and posterior

$$P(\text{pandemics} \mid \text{mask}) = \frac{P(\text{mask} \mid \text{pandemics})P(\text{pandemics})}{P(\text{mask})}$$

$$P(\text{Halloween} \mid \text{mask}) = \frac{P(\text{mask} \mid \text{Halloween})P(\text{Halloween})}{P(\text{mask})}$$

$$P(\text{diving} \mid \text{mask}) = \frac{P(\text{mask} \mid \text{diving})P(\text{diving})}{P(\text{mask})}$$

So when there are many options, it is often enough to write

$$P(A \mid B) \sim P(B \mid A)P(A)$$
.

Prior, posterior, and likelihood

For continuous random variables:

$$p(x \mid y) \sim p(y \mid x)p(x).$$

In our case of a generative model:

$$\underbrace{p(\text{params} \mid \text{data})}_{\text{posterior}} \sim \underbrace{p(\text{data} \mid \text{params})}_{\text{likelihood}} \underbrace{p(\text{params})}_{\text{prior}}.$$

Taking the logarithm:

$$\underbrace{\log p(\mathsf{params} \mid \mathsf{data})}_{\mathsf{log-posterior}} \sim \underbrace{\log p(\mathsf{data} \mid \mathsf{params})}_{\mathsf{log-likelihood}} + \underbrace{\log p(\mathsf{params})}_{\mathsf{log-prior}}.$$

Bayesian linear regression

Probabilistic model and prior:

$$y = \boldsymbol{\beta}^{\top} \mathbf{x} + \epsilon,$$

$$\epsilon \sim \mathcal{N}(0, \sigma^2),$$

$$\boldsymbol{\beta} \sim \mathcal{N}(0, \tau^2 \mathbf{I}).$$

Log-likelihood (last lecture):

$$-\frac{n}{2}\log(2\pi\sigma^2) - \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2.$$

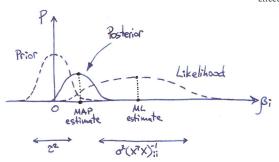
Log-prior:

$$-\frac{p}{2}\log(2\pi\tau^2) - \frac{1}{2\pi^2} \|\beta\|^2.$$

Bayesian linear regression

Hence negative log-posterior:

$$\dots + \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \frac{1}{2\tau^2} \|\boldsymbol{\beta}\|^2 \sim \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \underbrace{\frac{\sigma^2}{n\tau^2}}_{\text{effective } \lambda} \|\boldsymbol{\beta}\|^2.$$



Exercise: product of two Gaussians is a Gaussian.

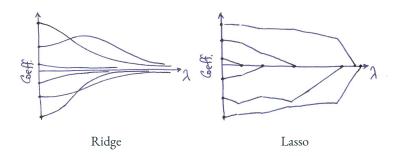


Lasso regression

Lasso regression

$$\mathcal{L} = \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda \|\boldsymbol{\beta}\|_1.$$

No analytic solution. But one can show that solutions are *sparse*.



Lagrange multipliers

Theorem: minimizing a loss $\mathcal{L}(\mathbf{w})$ subject to constraints $C(\mathbf{w}) = 0$ is equivalent to minimizing $\mathcal{L}(\mathbf{w}) + \lambda C(\mathbf{w})$ over \mathbf{w} and λ . Here λ is called Lagrange multiplier.

The same is true for inequality constraints $C(\mathbf{w}) \leq 0$ (with some extra conditions that I omit here for simplicity).

This means that the following two formulations are equivalent:

$$\mathcal{L} = \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda \|\boldsymbol{\beta}\|_1,$$

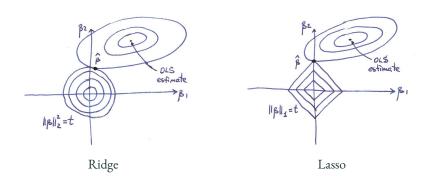
$$\mathcal{L} = \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 \text{ s.t. } \|\boldsymbol{\beta}\|_1 \le t.$$

And the same is true for ridge regression with $\lambda \|\boldsymbol{\beta}\|_2^2$.

Ridge vs. lasso

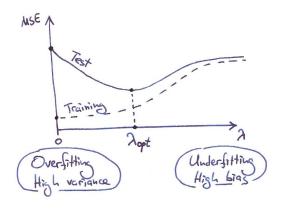
$$\begin{split} \text{Ridge:} \quad \mathcal{L} &= \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 \text{ s.t. } \|\boldsymbol{\beta}\|_2^2 \leq t. \\ \text{Lasso:} \quad \mathcal{L} &= \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 \text{ s.t. } \|\boldsymbol{\beta}\|_1 \leq t. \end{split}$$

Lasso:
$$\mathcal{L} = \frac{1}{n} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2$$
 s.t. $\|\boldsymbol{\beta}\|_1 \leq t$



Model selection

Bias-variance tradeoff





Training, test, and validation sets

Split the dataset into:

- Training set: used for model fitting;
- Test set: used for model evaluation.

Note: there is a tradeoff between training and test set sizes. Rule of thumb: \sim 90% training, \sim 10% test.

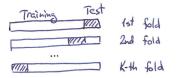
If we need to tune some hyper-parameters, e.g. λ , it is more appropriate to use three sets:

- Training set: used for model fitting;
- Validation set: used for hyper-parameter tuning;
- Test set: used for final model evaluation.



Cross-validation

Often the dataset is not large enough for a reliable training/test split. Then one could use *cross-validation* (CV):



K-fold cross-validation. n-fold CV is called *leave-one-out* CV (LOOCV). Rule of thumb: K=10.

Note that cross-validation measures the performance not of a given model, but of a model building procedure.

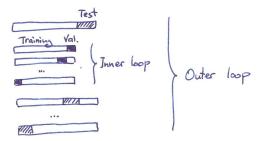
If you need a final model (for production or for inspection), then afterwards fit the model using the chosen λ on all of the available data.



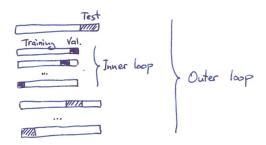
Nested cross-validation

What if we need training, validation, and test? Nested cross-validation!

- Outer loop: puts aside a test set.
- Inner loop: puts aside a validation test.
- After each inner loop: fit the model with chosen λ on all 'inner' data.



Nested cross-validation



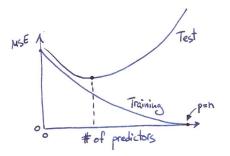
If you need a final model (for production or for inspection), then fit the model using the "inner loop" on the entire dataset.

Exercise: if you use K=10 for the outer loop, K=5 for the inner loop, and 100 values of λ as your grid search, how many models will be built?



Beyond the interpolation threshold

Back to polynomial regression



If p > n, the regression problem is *undertermined*: there are infinitely many β values yielding zero loss $\mathcal{L}(\beta) = 0$.

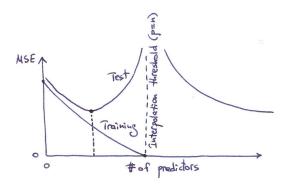
Minimum-norm solution

Using $\mathbf{X} = \mathbf{U}\mathbf{S}\mathbf{V}^{\top}$, we previously obtained $\hat{\boldsymbol{\beta}}_{OLS} = \mathbf{V}\mathbf{S}^{-1}\mathbf{U}^{\top}\mathbf{y}$.

This formula still makes sense if p > n (now \mathbf{S} is $n \times n$, not $p \times p$) and yields the minimum-norm $\hat{\boldsymbol{\beta}}$ among all possible ones satisfying $\mathcal{L}(\boldsymbol{\beta}) = 0$.

Implicit regularization

Here is what can happen if we use the minimum-norm solution beyond the *interpolation threshold*:



Implicit regularization.

