

last time:

Def A linear transformation $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a function satisfying the following conditions

$$\left. \begin{aligned} - f(v+w) &= f(v) + f(w) \\ - f(\lambda v) &= \lambda f(v) \end{aligned} \right\} \text{"linearity"}$$

Note: if T is an $m \times n$ matrix, it defines a linear transformation via $f(v) = Tv$ where we write v as a column vector

We showed: If f is a linear transformation, it comes from a (unique) matrix T as above.

To find the matrix T :
the columns of T are f applied to the basis vectors

$$e_i = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow i\text{th position.}$$

$$3x_1 + 2x_2 = y_1$$

$$2x_1 - 4x_2 = y_2$$

Sai

- i th row of a matrix T
tells you how to combine the entries of input to get i th coordinate in target

$$\begin{bmatrix} 3 & 2 \\ 2 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

- j th column of matrix T
tells you where the j th basis vector goes $\begin{bmatrix} 3 \\ 2 \end{bmatrix} = \text{image of } \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

Prachin:

$$f(x, y) = (x, x+y) \xrightarrow{\text{matrix}} \begin{matrix} \text{column} \nearrow \\ f(1,0) = (1, 1+0) = (1,1) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ f(0,1) = (0, 0+1) = (0,1) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{matrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} x \\ x+y \end{bmatrix} \quad \text{row} \searrow$$

$$\begin{matrix} \text{1st entry } x = 1x + 0y = \begin{bmatrix} 1 & 0 \end{bmatrix} \\ \text{2nd entry } x+y = 1x + 1y = \begin{bmatrix} 1 & 1 \end{bmatrix} \end{matrix} \left. \vphantom{\begin{matrix} \text{1st entry} \\ \text{2nd entry} \end{matrix}} \right\} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$$

Rotate 90° clock wise

column: $\begin{bmatrix} 1 \\ 0 \end{bmatrix} = (1,0) \xrightarrow{\text{rotate}} (0,-1) \downarrow \begin{bmatrix} 0 \\ -1 \end{bmatrix}$

$\begin{bmatrix} 0 \\ 1 \end{bmatrix} = (0,1) \uparrow \begin{bmatrix} 0 \\ 1 \end{bmatrix} \xrightarrow{\text{rotate}} (1,0) \rightarrow \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$$T = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

Elementary matrix that takes a system of 5 equations and adds the 2nd to the 4th.

= transformation that changes the 4th coord. by adding the 2nd to it.

1st entry of target = 1st entry of source

2nd entry of target = 2nd entry of source

...

4th entry of target = 2nd + 4th entry of source

5th : same.

entries x_1, x_2, \dots, x_5

$$\left. \begin{array}{l} \text{first: } 1x_1 + 0x_2 + 0x_3 + \dots + 0x_5 \\ \text{second: } 0 - 1x_2 \quad 0 \\ \quad \quad 0 \quad \quad 1x_3 \quad \dots 0 \\ \text{fourth: } 0 + 1x_2 + 0x_3 + 1x_4 + 0x_5 \\ \quad \quad \quad \quad -0 \quad \quad -1x_5 \end{array} \right\} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ 2 \\ 7 \\ 1 \\ -1 \end{bmatrix} \begin{array}{l} \text{entries of column} \\ \text{and } (3, 2, 7, 1, -1) \\ \uparrow \uparrow \\ \text{coords of vector} \end{array}$$

"Multiplication is composition"

If A, B are matrices, A has n columns & B has n rows

then we can multiply AB

If B_i = i th column of B

$$B = \left[\begin{array}{c|c|c|c} B_1 & B_2 & B_3 & \dots \end{array} \right]$$

AB_i is a matrix \cdot column

$$AB = \left[AB_1 \mid AB_2 \mid \dots \mid AB_n \right] \leftarrow$$

if $A \rightsquigarrow$ lin. trans. f
 $B \rightsquigarrow$ " " g

let $C \rightsquigarrow fg$.

what's the matrix for C ?

i th column of $C = fg(i$ th basis vector)

$$= f(g(i$$
th basis vector))

$$= f(i$$
th column of $B) = f(B_i)$

$$= AB_i$$

$= i$ th column of matrix product AB !

ex:

$$A(BC) = (AB)C$$

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$$f \circ (g \circ h)$$

$$(f \circ g) \circ h$$

$$(f \circ (g \circ h))(v) = f(g(h(v)))$$

$$= f(g(h(v)))$$

$$A \rightsquigarrow f$$

$$B \rightsquigarrow g$$

$$C \rightsquigarrow h$$

$$((f \circ g) \circ h)(v)$$

$$= f \circ g(h(v))$$

$$= f(g(h(v)))$$

Row operations, factorizations & inversion.

If A, B non matrices, we say B is the ^{inverse} of A
if $BA = I_n$ _{left}

I_n = "identity matrix"

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \longleftrightarrow \text{Inv transformation} \\ f(x) = x$$

and write $B = A^{-1}$

Question: if $BA = I_n$ is it true that $AB = I_n$
in other words, if $A^{-1}A = I_n$, is $AA^{-1} = I_n$
or is $A = (A^{-1})^{-1}$

ex: $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$

$$BA = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2.$$

$$AB = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \neq I_3$$

Fact: if A is an $n \times n$ matrix & B is also $n \times n$ &

$$BA = I_n \text{ then } AB = I_n \text{ also}$$

One way to find inverses & understand matrix better is via factorization / row operations

Suppose we have a matrix A , $n \times n$ & we do row ops corresponding to elementary matrices E_1, E_2, E_3, E_4 to transform A to the identity matrix

$$A \rightsquigarrow E_1 A \rightsquigarrow E_2 E_1 A \rightsquigarrow E_3 E_2 E_1 A \\ \downarrow \\ E_4 E_3 E_2 E_1 A = I_n$$

tells you,
product $E_4 E_3 E_2 E_1 = A^{-1}$

also, matrix row ops is very easy.

$$E_4 E_3 E_2 E_1 A = I_n \\ \downarrow$$

$$\cancel{E_4}^{-1} \cancel{E_4} E_3 E_2 E_1 A = \cancel{E_4}^{-1} I_n = \cancel{E_4}^{-1} \\ E_2^{-1} \quad \vdots \quad E_3^{-1}$$

$$A = E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1}$$

$$A = E_1^{-1} \dots E_k^{-1} \quad \text{"factoring"}$$

$$Ax = b$$

$$E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1} x = b$$

$$E_1^{-1} (E_2^{-1} E_3^{-1} E_4^{-1} x) = b$$

$$E_1^{-1} y = b$$

$$\leadsto y = a$$

$$E_2^{-1} E_3^{-1} E_4^{-1} x = a$$