[SREES] Seminarski - SystemModel Dokumentacija

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Namespace Index

1.1 Namespace List

Here is a list of all namespaces with brief descriptions:	
SystemModel	

2 Namespace Index

Class Index

2.1 Class List

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Here are the classes, structs, unions and interfaces with brief descriptions:

Systemiviodel::Bus		 	 	 - 11
SystemModel::Syste	mModel	 	 	 15

4 Class Index

File Index

3.1 File List

Here is a list of all files with brief descriptions:

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6 File Index

Namespace Documentation

4.1 SystemModel Namespace Reference

Classes

- class Bus
- class SystemModel

Typedefs

- using fi = std::pair< std::function< double(std::vector< double>)>, std::function< double(std::vector< double)
- using dfidx = std::pair< std::vector< std::function< double(std::vector< double >)> >, std::vector< std↔ ::function< double(std::vector< double >)> >>
- using AdmittanceMatrix = std::vector < std::tuple < uint8 t, uint8 t, std::complex < double >> >

Enumerations

- enum class TypeOfBus { Slack , PV , PQ }
- enum class ThreePhaseLoadConfigurationsType { Star , GroundedStar , Delta }

Functions

std::ostream & operator << (std::ostream & stream, const SystemModel & systemModel)
 Output stream operator overload

4.1.1 Typedef Documentation

4.1.1.1 AdmittanceMatrix

 $\label{lem:systemModel::AdmittanceMatrix = typedef std::vector < std::tuple < uint 8_t, uint 8_t, std \\ :: complex < double > >>$

4.1.1.2 dfidx

using SystemModel::dfidx = typedef std::pair<std::vector<std::function<double(std::vector<double>)>
>, std::vector<std::function<double(std::vector<double>)> >>

4.1.1.3 fi

using SystemModel::fi = typedef std::pair<std::function<double(std::vector<double>)>, std←
::function<double(std::vector<double>)> >

4.1.2 Enumeration Type Documentation

4.1.2.1 ThreePhaseLoadConfigurationsType

 $\verb"enum class SystemModel::ThreePhaseLoadConfigurationsType" [strong]$

Enumerator

Star	
GroundedStar	
Delta	

4.1.2.2 TypeOfBus

enum class SystemModel::TypeOfBus [strong]

Enumerator

Slack	
PV	
PQ	

4.1.3 Function Documentation

4.1.3.1 operator<<()

Output stream operator overload

Parameters

stream	Output stream object
systemModel	SystemModel object to be printed to the stream

Returns

Class Documentation

5.1 SystemModel::Bus Class Reference

#include <systemModel.h>

Collaboration diagram for SystemModel::Bus:

SystemModel::Bus

- + Bus()
- + getTypeOfBus()
- + setVoltageMagnitude()
- + setVoltagePhase()
- + setActivePower()
- + setReactivePower()
- + getVoltageMagnitude()
- + getVoltagePhase()
- + getActivePower()
- + getReactivePower()

Public Member Functions

- Bus (TypeOfBus typeOfBus)
- TypeOfBus getTypeOfBus () const
- void setVoltageMagnitude (double voltageMagnitude)

Sets the value at which the voltage amplitude for the given bus should be maintained.

void setVoltagePhase (double voltagePhase)

Sets the value at which the voltage phase for the given bus should be maintained.

• void setActivePower (double activePower)

Sets the value at which the active power for the given bus should be maintained.

void setReactivePower (double reactivePower)

Sets the value at which the rective power for the given bus should be maintained.

• std::optional< double > getVoltageMagnitude () const

Gets the value at which the voltage magnitude for the given bus should be maintained.

std::optional < double > getVoltagePhase () const

Gets the value at which the voltage phase for the given bus should be maintained.

std::optional < double > getActivePower () const

Gets the value at which the active power for the given bus should be maintained.

std::optional< double > getReactivePower () const

Gets the value at which the rective power for the given bus should be maintained.

5.1.1 Constructor & Destructor Documentation

5.1.1.1 Bus()

5.1.2 Member Function Documentation

5.1.2.1 getActivePower()

```
std::optional< double > SystemModel::Bus::getActivePower ( ) const
```

Gets the value at which the active power for the given bus should be maintained.

Returns

Value of active power for the bus

5.1.2.2 getReactivePower()

```
std::optional< double > SystemModel::Bus::getReactivePower ( ) const
```

Gets the value at which the rective power for the given bus should be maintained.

Returns

Value of reactive power for the bus

5.1.2.3 getTypeOfBus()

```
TypeOfBus SystemModel::Bus::getTypeOfBus ( ) const [inline]
```

5.1.2.4 getVoltageMagnitude()

```
std::optional< double > SystemModel::Bus::getVoltageMagnitude ( ) const
```

Gets the value at which the voltage magnitude for the given bus should be maintained.

Returns

Value of voltage magnitude of the bus

5.1.2.5 getVoltagePhase()

```
std::optional< double > SystemModel::Bus::getVoltagePhase ( ) const
```

Gets the value at which the voltage phase for the given bus should be maintained.

Returns

Value of voltage phase of the bus

5.1.2.6 setActivePower()

Sets the value at which the active power for the given bus should be maintained.

Parameters

active power for	ver Value of	ctive power for the bus
------------------	--------------	-------------------------

5.1.2.7 setReactivePower()

Sets the value at which the rective power for the given bus should be maintained.

Parameters

reactivePower	Value of reactive power for the bus	
---------------	-------------------------------------	--

5.1.2.8 setVoltageMagnitude()

Sets the value at which the voltage amplitude for the given bus should be maintained.

Parameters

voltageMagnitude Value of voltage m

5.1.2.9 setVoltagePhase()

```
\begin{tabular}{ll} \begin{tabular}{ll} void & SystemModel::Bus::setVoltagePhase ( \\ & double & voltagePhase ) \end{tabular}
```

Sets the value at which the voltage phase for the given bus should be maintained.

Parameters

, DI	Value of voltage phase of the bus
voitagePhase	value of voltage phase of the bus
ronago. naoc	raide of restage prides of the sas

The documentation for this class was generated from the following files:

- systemModel.h
- systemModel.cpp

5.2 SystemModel::SystemModel Class Reference

```
#include <systemModel.h>
```

Collaboration diagram for SystemModel::SystemModel:

SystemModel::SystemModel

- + SystemModel()
- + getAdmittanceMatrix()
- + getNumberOfBuses()
- + getBus()
- + addBus()
- + addLoad()
- + addLine()
- + addGenerator()
- + addSlackGenerator()
- + hasSlackBeenAssigned()
- + addTransformer()
- + addCapacitorBank()
- + getBusFunctions()
- + getDerivativesOfBusFunctions()

Public Member Functions

- SystemModel (uint8 t maxNumberOfBuses)
- · AdmittanceMatrix getAdmittanceMatrix () const
- uint8_t getNumberOfBuses () const
- Bus & getBus (uint8 t busNumber)

Gets the bus with the given bus number

void addBus (TypeOfBus typeOfBus)

Adds a bus to the system

void addLoad (uint8 t busNumber, double activePower, double reactivePower)

Adds a load to a bus

void addLine (uint8_t busNumber1, uint8_t busNumber2, double r, double x, double b)

Adds a line between buses

• void addGenerator (uint8 t busNumber, double voltageMagnitude, double activePower)

Adds a generator to a bus

• void addSlackGenerator (uint8_t busNumber, double voltageMagnitude, double voltagePhase)

Adds a generator to the slack bus

• bool hasSlackBeenAssigned () const

Check whether the slack bus has been assigned

• void addTransformer (uint8_t busNumber1, uint8_t busNumber2, double r, double x, double g, double b, double n)

Adds a transformer between buses

void addCapacitorBank (uint8_t busNumber, double c, ThreePhaseLoadConfigurationsType configuration ← Type)

Adds a capacitor bank to a bus

• fi getBusFunctions (uint8 t busNumber) const

Gets the bus functions (fi_P and fi_Q) for the desired bus

dfidx getDerivativesOfBusFunctions (uint8_t busNumber) const

Gets the derivates of the bus functions (dfi_Q/dx) for the desired bus (two rows of the Jacobian associated with the given bus functions)

Friends

• std::ostream & operator<< (std::ostream &stream, const SystemModel &systemModel)

5.2.1 Constructor & Destructor Documentation

5.2.1.1 SystemModel()

5.2.2 Member Function Documentation

5.2.2.1 addBus()

Adds a bus to the system

Parameters

```
typeOfBus Type of the bus (Slack, PV, PQ) to be added to the system
```

5.2.2.2 addCapacitorBank()

Adds a capacitor bank to a bus

Parameters

busNumber	Ordinal number of the desired bus	
С	One phase capacitance of the bank	
configurationType	Three phase load configuration type (delta, star, grounded star) of the bank	

5.2.2.3 addGenerator()

Adds a generator to a bus

Parameters

busNumber	Ordinal number of the desired bus
voltageMagnitude	Voltage magnitude on which the given bus should be maintained

<param name="activePower"Active power on which the given bus should be maintained>

5.2.2.4 addLine()

```
void SystemModel::SystemModel::addLine (
          uint8_t busNumber1,
          uint8_t busNumber2,
          double r,
          double x,
          double b)
```

Adds a line between buses

Parameters

busNumber1	Ordinal number of the first bus
busNumber2	Ordinal number of the second bus
r	Series resistance of the transmission line PI equivalent
X	Series reactance of the transmission line PI equivalent
b	Shunt susceptance of the transmission line PI equivalent

5.2.2.5 addLoad()

```
double activePower,
double reactivePower )
```

Adds a load to a bus

Parameters

busNumber	Ordinal number of the desired bus
activePower	Active power drawn by the load
reactivePower	Reactive power drawn by the load

5.2.2.6 addSlackGenerator()

Adds a generator to the slack bus

Parameters

busNumber Ordinal number of the desired bus voltageMagnitude Voltage magnitude on which the given bus should be		Ordinal number of the desired bus
		Voltage magnitude on which the given bus should be maintained
İ	voltagePhase	Voltage phase on which the given bus should be maintained

5.2.2.7 addTransformer()

Adds a transformer between buses

Parameters

busNumber1	Ordinal number of the first bus
busNumber2	Ordinal number of the second bus
r	Series resistance of the transformer PI equivalent
X	Series reactance of the transformer PI equivalent
g	Shunt conductance of the transformer PI equivalent
b	Shunt susceptance of the transformer PI equivalent
п	Transformer turns ratio

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5.2.2.8 getAdmittanceMatrix()

```
AdmittanceMatrix SystemModel::getAdmittanceMatrix ( ) const [inline]
```

5.2.2.9 getBus()

Gets the bus with the given bus number

Parameters

the desired bus	busNumber Ordinal number
-----------------	--------------------------

Returns

Bus with the given bus number

5.2.2.10 getBusFunctions()

Gets the bus functions (fi_P and fi_Q) for the desired bus

Parameters

Returns

Bus functions for the given bus in the form of std::pair of functions, where both functions have a std::vector of doubles as parameters and return a double

5.2.2.11 getDerivativesOfBusFunctions()

Gets the derivates of the bus functions (dfi_P/dx and dfi_Q/dx) for the desired bus (two rows of the Jacobian associated with the given bus functions)

Parameters

busNumber	Ordinal number of the desired bus
-----------	-----------------------------------

Returns

Derivatives of the bus functions for the given bus in the form of std::pair of std::vector-s of functions, where both functions have a std::vector of doubles as parameters and return a double

5.2.2.12 getNumberOfBuses()

```
uint8_t SystemModel::getNumberOfBuses ( ) const [inline]
```

5.2.2.13 hasSlackBeenAssigned()

```
bool SystemModel::SystemModel::hasSlackBeenAssigned ( ) const
```

Check whether the slack bus has been assigned

Returns

True if the slack bus has been assigned and false otherwise

5.2.3 Friends And Related Function Documentation

5.2.3.1 operator<<

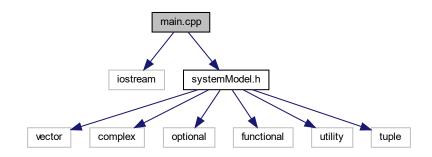
The documentation for this class was generated from the following files:

- systemModel.h
- systemModel.cpp

File Documentation

6.1 main.cpp File Reference

```
#include <iostream>
#include "systemModel.h"
Include dependency graph for main.cpp:
```



Functions

• int main ()

6.1.1 Function Documentation

6.1.1.1 main()

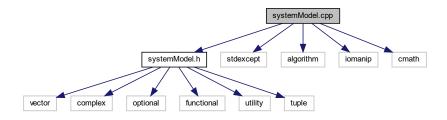
int main ()

24 File Documentation

6.2 systemModel.cpp File Reference

```
#include "systemModel.h"
#include <stdexcept>
#include <algorithm>
#include <iomanip>
#include <cmath>
```

Include dependency graph for systemModel.cpp:



Macros

• #define PI 4 * std::atan(1.0)

6.2.1 Macro Definition Documentation

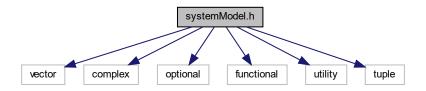
6.2.1.1 PI

#define PI 4 * std::atan(1.0)

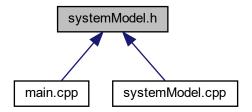
6.3 systemModel.h File Reference

```
#include <vector>
#include <complex>
#include <optional>
#include <functional>
#include <utility>
#include <tuple>
```

Include dependency graph for systemModel.h:



This graph shows which files directly or indirectly include this file:



Classes

- class SystemModel::Bus
- · class SystemModel::SystemModel

Namespaces

• namespace SystemModel

Typedefs

- using SystemModel::fi = std::pair< std::function< double(std::vector< double >)>, std::function
 double(std::vector< double >)>>
- using SystemModel::dfidx = std::pair< std::vector< std::function< double(std::vector< double >)> >, std
 ::vector< std::function< double(std::vector< double >)> >
- using SystemModel::AdmittanceMatrix = std::vector< std::tuple< uint8_t, uint8_t, std::complex< double > > >

Enumerations

- enum class SystemModel::TypeOfBus { SystemModel::PQ }
- enum class SystemModel::ThreePhaseLoadConfigurationsType { SystemModel::Star , SystemModel::GroundedStar , SystemModel::Delta }

Functions

• std::ostream & SystemModel::operator<< (std::ostream &stream, const SystemModel &systemModel)

Output stream operator overload

26 File Documentation

6.4 systemModel.h

Go to the documentation of this file.

```
2 #include <vector>
3 #include <complex>
4 #include <optional>
5 #include <functional>
6 #include <utility>
7 #include <tuple>
10
11 namespace SystemModel {
       using fi = std::pair<std::function<double(std::vector<double>)>,
       std::function<double(std::vector<double>)»;
13
14
15
       using dfidx = std::pair<std::vector<std::function<double(std::vector<double>)»,
16
       std::vector<std::function<double(std::vector<double>) >>;
17
18
19
20
       using AdmittanceMatrix = std::vector<std::tuple<uint8_t, uint8_t, std::complex<double>>;
23
2.4
       enum class TypeOfBus { Slack, PV, PQ };
2.5
26
       enum class ThreePhaseLoadConfigurationsType { Star, GroundedStar, Delta };
29
30
31
       class Bus {
32
33
           TypeOfBus typeOfBus;
           std::optional<double> voltageMagnitude;
35
           std::optional<double> voltagePhase;
36
           std::optional<double> activePower;
           std::optional<double> reactivePower;
37
       public:
38
39
           Bus(TypeOfBus typeOfBus) : typeOfBus{ typeOfBus } {}
           TypeOfBus getTypeOfBus() const {
42
               return typeOfBus;
4.3
44
45
           void setVoltageMagnitude(double voltageMagnitude);
46
47
           void setVoltagePhase(double voltagePhase);
48
49
           void setActivePower(double activePower);
50
51
           void setReactivePower(double reactivePower);
           std::optional<double> getVoltageMagnitude() const;
54
5.5
           std::optional<double> getVoltagePhase() const;
56
           std::optional<double> getActivePower() const;
57
58
           std::optional<double> getReactivePower() const;
60
61
62
6.3
64
       class SystemModel {
               AdmittanceMatrix admittanceMatrix;
65
               uint8_t numberOfBuses{};
67
               std::vector<Bus> buses;
68
               const uint8_t maxNumberOfBuses;
               bool checkForConnectionBetweenToBuses(uint8_t busNumber1, uint8_t busNumber2) const;
69
70
           public:
               SystemModel(uint8_t maxNumberOfBuses) : maxNumberOfBuses{ maxNumberOfBuses } {}
72
73
               AdmittanceMatrix getAdmittanceMatrix() const {
74
                   return admittanceMatrix;
75
76
               uint8_t getNumberOfBuses() const {
                   return numberOfBuses;
79
80
```

6.4 systemModel.h 27

```
Bus& getBus(uint8_t busNumber);
83
               void addBus(TypeOfBus typeOfBus);
84
8.5
               void addLoad(uint8_t busNumber, double activePower, double reactivePower);
86
               void addLine(uint8_t busNumber1, uint8_t busNumber2, double r, double x, double b);
88
89
               friend std::ostream& operator «(std::ostream& stream, const SystemModel& systemModel);
90
               void addGenerator(uint8_t busNumber, double voltageMagnitude, double activePower);
91
92
93
               void addSlackGenerator(uint8_t busNumber, double voltageMagnitude, double voltagePhase);
95
               bool hasSlackBeenAssigned() const;
96
97
               \verb|void| \verb| addTransformer(uint8_t busNumber1, uint8_t busNumber2, double r, double x, double g, \\
       double b, double n);
98
99
               void addCapacitorBank(uint8_t busNumber, double c, ThreePhaseLoadConfigurationsType
       configurationType);
100
101
                fi getBusFunctions(uint8_t busNumber) const;
102
103
                dfidx getDerivativesOfBusFunctions(uint8_t busNumber) const;
104
        };
105
106
107
108
        std::ostream& operator «(std::ostream& stream, const SystemModel& systemModel);
109 }
```

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