# Control Systems

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Abstract—This manual is an introduction to control systems based on GATE problems. Links to sample Python codes are available in the text.

Download python codes using

**PID Controller** 

svn co https://github.com/gadepall/school/trunk/ control/codes

#### 1 Signal Flow Graph

## 2 Gain of Feedback Circuits

# 2.1 Estimation of Voltage Gain

<sup>1</sup> 2.1.1. Consider the Magnitude Bode Plot and Phase Bode Plot 2.1.1 of Open-Loop Transfer Function of an Amplifier. Estimate the Open-Loop Transfer Function. (Assume 'A' as 'G' and ' $\beta$ ' as 'H')

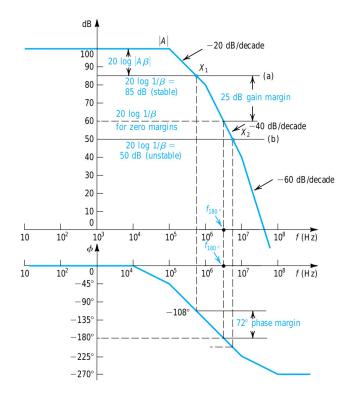


Fig. 2.1.1: Magnitude and Phase Bode Plot

**Solution:** Let G(f) be the Open-Loop Transfer Function,

$$G(f) = \begin{cases} 100 & 0 < f < 10^5 \\ 200 - 20log(f) & 10^5 < f < 10^6 \\ 320 - 40log(f) & 10^6 < f < 10^7 \\ 460 - 60log(f) & 10^7 < f \end{cases}$$

$$(2.1.1.1)$$

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$$\nabla G(f) = \frac{d(G(f))}{d(\log(f))} = \begin{cases} 0 & 0 < f < 10^5 \\ -20 & 10^5 < f < 10^6 \\ -40 & 10^6 < f < 10^7 \\ -60 & 10^7 < f \end{cases}$$
(2.1.1.2)

As we know that, When a pole is encountered the slope always decreases by 20 dB/decade and When a zero is encountered the slope always increases by 20 dB/decade. So, by observing 2.1.1 it can be concluded that we are having Poles at  $f = 10^5 Hz$ ,  $10^6 Hz$ ,  $10^7 Hz$  and No Zeros.

So, the Open-Loop Transfer Function G(f) is

$$G(f) = \frac{10^5}{\left(1 + j\frac{f}{10^5}\right)\left(1 + j\frac{f}{10^6}\right)\left(1 + j\frac{f}{10^7}\right)}$$
(2.1.1.3)

2.1.2. Calculate the Phase of Open-Loop Transfer Function.

### **Solution:**

Phase of Open-Loop Transfer Function =  $\phi$ 

$$\phi = -\left[\tan^{-1}\left(f/10^{5}\right) + \tan^{-1}\left(f/10^{6}\right) + \tan^{-1}\left(f/10^{7}\right)\right]$$
(2.1.2.1)

2.1.3. Determine the Closed-Loop Voltage Gain of the System assuming  $|GH| \gg 1$  and also assuming the block diagram of Control System is 2.1.3

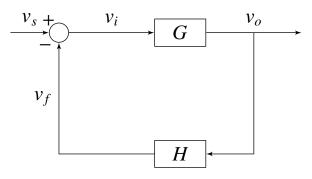


Fig. 2.1.3

# **Solution:**

The Closed-Loop Voltage Gain of the Control System is

$$T = \frac{V_o}{V_s} = \frac{G}{1 + GH} \tag{2.1.3.1}$$

$$20\log(T) = 20\log(G) - 20\log(1 + GH)$$
(2.1.3.2)

Considering the assumption  $|GH| \gg 1$ , It can be written as

$$20\log(1+GH) = 20\log(GH) \qquad (2.1.3.3)$$

So.

$$20\log(T) = 20\log(G) - 20\log(GH) \quad (2.1.3.4)$$

$$20\log(T) = -20\log(H) \ (2.1.3.5)$$

$$20\log(T) = 20\log(\frac{1}{H}) \ (2.1.3.6)$$

$$T = \frac{1}{H} \ (2.1.3.7)$$

So, The value of Closed-Loop Voltage Gain of the Control System under the assumption,  $|GH| \gg 1$  is  $T = \frac{1}{H}$ 

2.1.4. What is the value of Loop-Gain?

#### **Solution:**

The value of Loop-Gain can be calculated by the difference of 2-curves  $20 \log |A|$  and  $20 \log (\frac{1}{H})$ . The difference between the two curves will be

$$20\log|G| - 20\log\frac{1}{H} = 20\log|GH| \quad (2.1.4.1)$$

2.1.5. Define Phase-Margin

### **Solution:**

**Phase-Margin:** The phase margin is defined as the angle in degrees by which the phase angle is smaller than  $-180^{\circ}$  at the gain crossover, the gain crossover being the frequency at which the open-loop gain first reaches 1.

2.1.6. Find the frequencies for which phase margins are 90° and 45° respectively?

# **Solution:**

Let Phase Margin be  $\alpha = 90^{\circ}$ . Then,

$$\alpha = \phi - (-180^{\circ}) \tag{2.1.6.1}$$

$$\phi = -180^{\circ} + \alpha \tag{2.1.6.2}$$

$$\phi = -90^{\circ} \tag{2.1.6.3}$$

So, by the definition of Phase-Margin, at  $\phi = -90^{\circ}$ , |GH| = 1. The value of  $\phi = -90^{\circ}$  between poles  $f = 10^{5}Hz$ ,  $10^{6}Hz$ . Assuming the Poles are farther apart,

$$\tan^{-1}(\frac{f}{10^7}) \approx 0 \tag{2.1.6.4}$$

where  $10^5 < f < 10^6$ So,

$$-\tan^{-1}(f/10^{5}) - \tan^{-1}(f/10^{6}) = -90$$

$$(2.1.6.5)$$

$$\tan^{-1}(f/10^{5}) + \tan^{-1}(f/10^{6}) = 90$$

$$(2.1.6.6)$$

$$\tan^{-1}(f/10^{5}) = 90 - \tan^{-1}(f/10^{6})$$

$$(2.1.6.7)$$

$$\tan^{-1}(f/10^{5}) = \cot^{-1}(f/10^{6})$$

$$(2.1.6.8)$$

$$\tan^{-1}(f/10^{5}) = \tan^{-1}(10^{6}/f)$$

$$(2.1.6.9)$$

$$f^{2} = 10^{11}$$

$$(2.1.6.10)$$

$$f = 3.162 \times 10^{5}$$

$$(2.1.6.11)$$

So, the approximate value of f at which Phase Margin is  $90^{\circ}$  is  $f = 3.162 \times 10^{5} Hz$ .

Similarly let Phase Margin be  $\alpha = 45^{\circ}$ . Then,

$$\alpha = \phi - (-180^{\circ}) \tag{2.1.6.12}$$

$$\phi = -180^{\circ} + \alpha \tag{2.1.6.13}$$

$$\phi = -135^{\circ} \tag{2.1.6.14}$$

So, by the definition of Phase-Margin, at  $\phi = -135^{\circ}$ , |GH| = 1. The value of  $\phi = -135^{\circ}$  approximately at poles  $f = 10^{6}Hz$ .

So, the approximate value of f at which Phase Margin is  $45^{\circ}$  is  $f = 10^{6}$ .

2.1.7. Find the minimum values of Closed-Loop Voltage Gain for which phase margins are 90° and 45° respectively

# **Solution:**

For  $\alpha = 90^{\circ}$ .

$$f = 3.162 \times 10^5$$
 (2.1.7.1) 2.1.3

By substituting f in Open-Loop Gain G(f)

(assuming poles are far part),

$$G(f) = 200 - 20log(3.162 \times 10^5)$$
 (2.1.7.2)

$$G(f) = 90dB$$
 (2.1.7.3)

$$G = 3.1625 \times 10^4 \quad (2.1.7.4)$$

At that  $f = 3.162 \times 10^5$ ,

$$H = \frac{1}{G}$$
 (2.1.7.5)

$$H = 3.162 \times 10^{-5} \tag{2.1.7.6}$$

The minimum value of Closed-Loop Gain occurs at  $|GH| \gg 1$  and the value of Closed-Loop Gain is  $T = \frac{1}{H}$ 

$$T = \frac{1}{H} = 3.1625 \times 10^4 \tag{2.1.7.7}$$

So, The minimum value of Closed-Loop Gain with Phase Margin equal to  $\alpha = 90^{\circ}$  is  $T_{min} = 3.1625 \times 10^{4}$ .

For  $\alpha = 45^{\circ}$ ,

$$f = 10^6 \tag{2.1.7.8}$$

By substituting f in Open-Loop Gain G(f) (assuming poles are far part),

$$G(f) = 200 - 20log(10^6)$$
 (2.1.7.9)

$$G(f) = 80dB (2.1.7.10)$$

$$G = 10^4 \qquad (2.1.7.11)$$

At that  $f = 10^6$ ,

$$H = \frac{1}{G} \tag{2.1.7.12}$$

$$H = 10^{-4} \tag{2.1.7.13}$$

The minimum value of Closed-Loop Gain occurs at  $|GH| \gg 1$  and the value of Closed-Loop Gain is  $T = \frac{1}{H}$ 

$$T = \frac{1}{H} = 10^4 \tag{2.1.7.14}$$

So, The minimum value of Closed-Loop Gain with Phase Margin equal to  $\alpha = 45^{\circ}$  is  $T_{min} = 10^4$ .

(2.1.7.1) 2.1.8. Design a Circuit Model that follows the Transfer Function G(f)

**Solution:** 

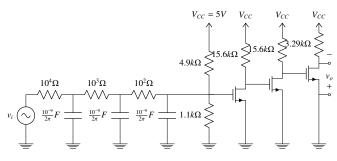


Fig. 2.1.8

Assuming, N-MOSFETs are identical and properties of N-MOSFET are,

$$\mu_n C_{ox} = 100 \mu A/V^2 \tag{2.1.8.1}$$

$$\frac{W}{L} = 500$$
 (2.1.8.2)

$$V_T = 1V (2.1.8.3)$$

 $V_{CC}$  is divided across  $4.9 \times 10^3 \Omega$  and  $1.1 \times 10^3 \Omega$ 

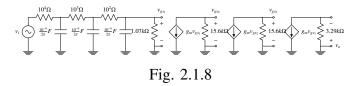
$$V_{GS} = 1.1V (2.1.8.4)$$

Small Signal Parameter  $g_m$ ,

$$g_m = \mu_n C_{ox} \frac{W}{I} (V_{GS} - V_{TH})$$
 (2.1.8.5)

$$g_m = 5 \times 10^{-3} \Omega^{-1} \tag{2.1.8.6}$$

Small Signal Model of the circuit is



The cascade of RC Circuits introduces poles in 2.1.9. Design a Circuit Model that follows the Transthe circuit. The RC Circuits introduces poles at  $f = 10^5 Hz$ ,  $10^6 Hz$ ,  $10^7 Hz$  respectively from left to right. So, the value of  $v_{gs_1}$  is

$$v_{gs_1} = \frac{v_s}{\left(1 + j\frac{f}{10^5}\right)\left(1 + j\frac{f}{10^6}\right)\left(1 + j\frac{f}{10^7}\right)}$$
(2.1.8.7)

The MOSFETs used in the circuit are Self-Biased with  $V_{GS} = 1.1V$  for all 3 N-MOSFETs. 3 N-MOSFETs are used to achieve a large gain of 10<sup>5</sup>. At 3rd N-MOSFET, Terminals of output are swaped, inorder to compensate for the negetive sign of gain.

At the first N-MOSFET,

$$v_{gs_2} = -g_m v_{gs_1} \times 15.6 \times 10^3$$
 (2.1.8.8)

$$v_{gs_2} = -78 \times v_{gs_1} \tag{2.1.8.9}$$

$$v_{gs_2} = \frac{-78 \times v_s}{\left(1 + j\frac{f}{10^5}\right)\left(1 + j\frac{f}{10^6}\right)\left(1 + j\frac{f}{10^7}\right)}$$
(2.1.8.10)

Similarly, at the second N-MOSFET,

$$v_{gs_3} = -g_m v_{gs_2} \times 15.6 \times 10^3$$
 (2.1.8.11)

$$v_{gs_3} = -78 \times v_{gs_2} \tag{2.1.8.12}$$

$$v_{gs_3} = \frac{6084 \times v_s}{\left(1 + j\frac{f}{10^5}\right)\left(1 + j\frac{f}{10^6}\right)\left(1 + j\frac{f}{10^7}\right)}$$
(2.1.8.13)  
(2.1.8.14)

Similarly, at the third N-MOSFET,

$$-v_o = -g_m v_{gs_3} \times 3.29 \times 10^3 \qquad (2.1.8.15)$$

$$v_o = 16.45 \times v_{gs_3}$$
 (2.1.8.16)

$$v_o = \frac{10^5 \times v_s}{\left(1 + j\frac{f}{10^5}\right)\left(1 + j\frac{f}{10^6}\right)\left(1 + j\frac{f}{10^7}\right)}$$
(2.1.8.17)

$$\frac{v_o}{v_s} = \frac{10^5}{\left(1 + j\frac{f}{10^5}\right)\left(1 + j\frac{f}{10^6}\right)\left(1 + j\frac{f}{10^7}\right)}$$
(2.1.8.18)

$$G(f) = \frac{10^5}{\left(1 + j\frac{f}{10^5}\right)\left(1 + j\frac{f}{10^6}\right)\left(1 + j\frac{f}{10^7}\right)}$$
(2.1.8.19)

fer Function H(f)

#### **Solution:**

On Bode Plot is H is independent of frequency. So, H should not involve any Reactive Elements. So, H is a combination of Resistors or a Voltage Divider.

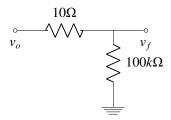


Fig. 2.1.9

$$v_f = \frac{10}{10 + 10^5} \times v_o \qquad (2.1.9.1)$$

$$v_f \approx 10^{-4} v_o \qquad (2.1.9.2)$$

$$\frac{v_f}{v_o} \approx 10^{-4} \qquad (2.1.9.3)$$

$$v_f \approx 10^{-4} v_o$$
 (2.1.9.2)

$$\frac{v_f}{v_c} \approx 10^{-4}$$
 (2.1.9.3)

$$H(f) = 10^{-4}$$
 (2.1.9.4)

- 3 Bode Plot
- 4 Second order System
- 5 Routh Hurwitz Criterion
  - 6 STATE-SPACE MODEL
    - 7 Nyquist Plot
    - 8 Compensators
    - 9 Gain Margin
    - 10 Phase Margin
      - 11 Oscillator
    - 12 Root Locus
    - 13 Polar Plot
    - 14 PID Controller