1

CONTENTS

1

1

2

- 1 Stability
- 2 Routh Hurwitz Criterion
- **3** Compensators
- 4 Nyquist Plot

Abstract—This manual is an introduction to control systems based on GATE problems.Links to sample Python codes are available in the text.

Download python codes using

1 STABILITY

2 Routh Hurwitz Criterion

The number of roots of the polynomial, $s^7 + s^6 + 7s^5 + 14s^4 + 31s^3 + 73s^2 + 25s + 200$, in the open left half of the complex plane is

- (A) 3
- (B) 4
- (C) 5
- (D) 6

We will be using the concept of Routh-Hurwitz Criterion.

Routh-Hurwitz Criterion: The number of roots of the polynomial that are in the right half-plane is equal to the number of sign changes in the first column.

RouthHurwitz stability criterion is a mathematical test that is a necessary and sufficient condition for the stability of a linear time invariant control system.

Rules for generating Routh-Hurwitz Table.

- 1) Label the rows of Routh table from highest power to the lowest power.
- 2) List alternative coefficients starting with the highest order coefficients in the first row.
- 3) List alternative coefficients starting with the next highest order coefficients in the second row
- 4) Each entry is the negative of determinant of the previous two entries in the previous two rows divided by the entry in the first column directly above the row.
- 5) The left hand column of the determinant is always the first column of the previous two rows.

- 6) The right hand column is the elements of the column above and to the right.
- 7) The table is complete when all of the rows are completed down to s^0 .

The Routh-Hurwitz Table for given equation $s^7 + s^6 + 7s^5 + 14s^4 + 31s^3 + 73s^2 + 25s + 200$, is calculated as follows

$$\begin{vmatrix} s^7 \\ s^6 \\ 1 & 14 & 73 & 200 \\ s^5 \\ -7 & -42 & -175 & 0 \end{vmatrix}$$
 (2.0.1)

$$\begin{vmatrix} s^{7} \\ s^{6} \\ s^{5} \\ s^{4} \end{vmatrix} \begin{vmatrix} 1 & 7 & 31 & 25 \\ 1 & 14 & 73 & 200 \\ -7 & -42 & -175 & 0 \\ 8 & 48 & 200 & 0 \end{vmatrix}$$
 (2.0.2)

$$\begin{vmatrix} s^7 \\ s^6 \\ s^5 \\ s^5 \\ s^4 \\ s^3 \end{vmatrix} \begin{vmatrix} 1 & 7 & 31 & 25 \\ 1 & 14 & 73 & 200 \\ -7 & -42 & -175 & 0 \\ 8 & 48 & 200 & 0 \\ 0 & 0 & 0 \end{vmatrix}$$
 (2.0.3)

When such a case is encountered, we take the derivative of the expression formed the the coefficients above it i.e derivative of $8s^4 + 48s^2 + 200$.

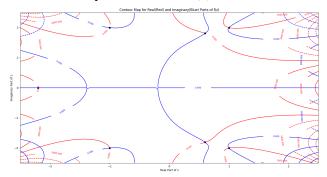
$$\frac{d}{dx}(8s^4 + 48s^2 + 200) = 32s^3 + 96s$$

The coefficients of obtained expression are placed in the table.

$$\begin{vmatrix}
s^7 \\
s^6 \\
s^5 \\
s^4 \\
s^3
\end{vmatrix}
\begin{vmatrix}
1 & 7 & 31 & 25 \\
1 & 14 & 73 & 200 \\
-7 & -42 & -175 & 0 \\
8 & 48 & 200 & 0 \\
32 & 96 & 0
\end{vmatrix}$$
(2.0.4)

$$\begin{vmatrix}
s^7 \\
s^6 \\
s^5 \\
s^5 \\
s^4 \\
s^3 \\
s^2 \\
s^3 \\
s^2 \\
s^3 \\
s^4 \\
s^5 \\
s^6 \\
s^7 \\
s$$

simultaneously are roots of f(z).

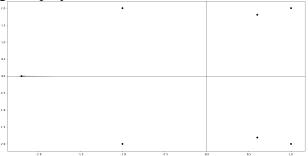


- 3 Compensators
- 4 Nyquist Plot

So, the above one is the Routh-Hurwitz Table. The no.of sign changes in first column of RouthHurwitz Table is the no.of roots on right side of imaginary axis.

So, for the given equation 4 roots lie on right-side of Imaginary Axis. Given equation has a total of 7 roots in which 4 lie on right side of Imaginary Axis. So there will be 3 roots on left of Imaginary Axis.

The below image is the location of Roots of given polynomial.



The below image is finding out the roots of given polynomial by substituting z = x + iy and obtaining the Real and Imaginary Parts of f(z). The values of z where Real and Imaginary parts f(z) becomes zero