# Control Systems

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Signal Flow Graph

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Abstract—This manual is an introduction to control systems based on GATE problems.Links to sample Python codes are available in the text.

Download python codes using

svn co https://github.com/gadepall/school/trunk/control/codes

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#### 1 Signal Flow Graph

2 Gain of Feedback Circuits

## 2.1 Current Amplifiers

2.1.1. For the feedback current amplifier shown in 2.1.1, Draw the Small-Signal Model eglect the Early effect in  $Q_1$  and  $Q_2$ .

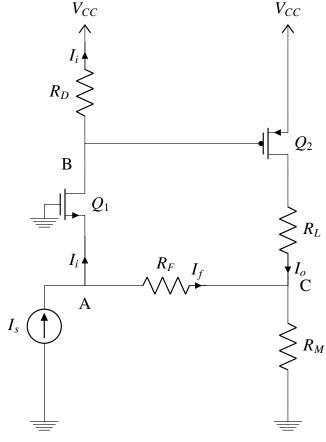


Fig. 2.1.1

**Solution:** While drawing a Small-Signal Model, we ground all constant voltage sources and open all constant current sources. All Small-Signal paramters are obtained from DC-Analysis of the circuit. Neglecting Early effect, in Small-Signal Analysis a N-MOSFET is modelled as a Current Source with value of current equal to  $g_m v_{gs}$  flowing from Drain to

Source. Whereas a P-MOSFET is modelled as a Current Source with value of current equal to  $g_m v_{sg}$  flowing from Source to Drain.

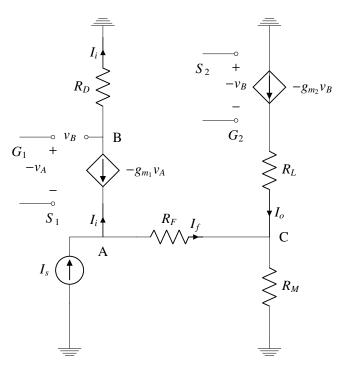


Fig. 2.1.1: Small Signal Model

2.1.2. Describe how the given circuit is a Negetive Feedback Current Amplifier.

> **Solution:** For the feedback to be negative,  $I_f$ must have the same polarity as  $I_s$ . To ascertain that this is the case, we assume an increase in  $I_s$  and follow the change around the loop: An increase in  $I_s$  causes  $I_i$  to increase and the drain voltage of  $Q_1$  will increase. Since this voltage is applied to the gate of the p-channel device  $Q_2$ , its increase will cause  $I_o$ , the drain current of  $Q_2$ , to decrease. Thus, the voltage across  $R_M$  will decrease, which will cause  $I_f$  to increase. This is the same polarity assumed for the initial change in  $I_s$ , verifying 2.1.6. Find the Expression for the Closed-Loop Gain that the feedback is indeed negative.

2.1.3. Write all KVL and KCL Equations **Solution:** 

$$I_i = g_{m_1} v_A (2.1.3.1)$$

$$v_B = I_i R_D (2.1.3.2)$$

$$I_o = -g_{m_2} v_B (2.1.3.3)$$

$$v_A = I_F R_F - (I_F + I_o) R_M (2.1.3.4)$$

2.1.4. Find the Expression for the Open-Loop Gain

 $G = \frac{I_o}{I_i}$ , from the Small-Signal Model. For simplicity, neglect the Early effect in  $Q_1$  and  $Q_2$ .

Solution: In Small-Signal Model,

$$v_B = I_i R_D \tag{2.1.4.1}$$

$$v_{gs_2} = v_B = I_i R_D (2.1.4.2)$$

In Small-Signal Analysis, P-MOSFET is modelled as a current source where current flows from Source to Drain. So, the value of current flowing from Source to Drain in P-MOSFET

$$I_o = -g_{m_2} v_{gs_2} = -g_{m_2} I_i R_D (2.1.4.3)$$

So, the Open-Circuit Gain is

$$G = \frac{I_o}{I_i} = -g_{m_2} R_D (2.1.4.4)$$

2.1.5. Find the Expression of the Feedback Factor  $H = \frac{I_f}{I_c}$ , from Small-Signal Model. For simplicity, neglect the Early effect in  $Q_1$  and  $Q_2$ . **Solution:** 

> $I_o$  is fed to a current divider formed by  $R_M$  and  $R_F$ . Assuming system has Good Gain, Most part of  $I_s$  flows as  $I_F$  leaving behind small  $I_i$ . As  $I_i$  is small, the voltage at point 'A' is very small and is considered,  $v_A \simeq 0$ . So  $R_F$  and  $R_M$ are parallel and Voltage Drop across them is same.

From (2.1.3.4),

$$(I_o + I_f)R_M \simeq -I_f R_F$$
 (2.1.5.1)

$$\frac{I_f}{I_o} \simeq -\frac{R_M}{R_F + R_M} \tag{2.1.5.2}$$

So, the Feedback Factor,

$$H \equiv \frac{I_f}{I_o} \simeq -\frac{R_M}{R_F + R_M} \tag{2.1.5.3}$$

 $T = \frac{I_o}{I}$ . For simplicity, neglect the Early effect in  $Q_1$  and  $Q_2$ .

**Solution:** 

From Open-Loop Gain and Feedback Factor,

$$I_s = I_i + I_f (2.1.6.1)$$

$$I_s = \frac{I_o}{G} + HI_o {(2.1.6.2)}$$

$$GI_s = I_o(1 + GH)$$
 (2.1.6.3)

$$\frac{I_o}{I_s} = \frac{G}{1 + GH} \tag{2.1.6.4}$$

$$\frac{I_o}{I_s} = \frac{G}{1 + GH}$$
 (2.1.6.4)  

$$\frac{I_o}{I_s} = -\frac{g_{m_2} R_D}{1 + g_{m_2} R_D / \left(1 + \frac{R_F}{R_M}\right)}$$
 (2.1.6.5)

Amplifier is

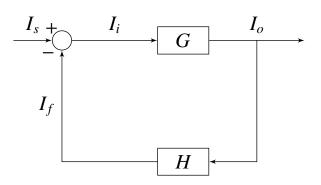


Fig. 2.1.6

where  $G = -g_{m_2}R_D$  and  $H = -\frac{R_M}{R_E + R_M}$ 

So, the value of Closed-Loop Gain is

$$T = \frac{I_o}{I_s} = -\frac{g_{m_2}R_D}{1 + g_{m_2}R_D/\left(1 + \frac{R_F}{R_M}\right)}$$
 (2.1.6.6)

2.1.7. Draw the Circuit Diagram of Feedback Net-2.1.9. Draw the Circuit Diagram of Open-Loop Net-

Solution: The Circuit Diagram of Feedback Network is 2.1.7

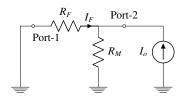


Fig. 2.1.7: Feedback Network

By KVL and KCL,

$$(I_o + I_f)R_M = -I_f R_F (2.1.7.1)$$

$$\frac{I_f}{I_o} = -\frac{R_M}{R_F + R_M} \tag{2.1.7.2}$$

So, Gain of Feedback Network is

$$H = -\frac{R_M}{R_F + R_M} \tag{2.1.7.3}$$

The Block Diagram of Feedback Network is

$$\underbrace{I_F} H = -\frac{R_M}{R_F + R_M} \underbrace{I_O}$$

Fig. 2.1.7: Feedback Block Diagram

So the Block Diagram of Feedback Current 2.1.8. Find  $R_{11}$  and  $R_{22}$  of Feedback Network where  $R_{11}$  is input resistance through Port-1 and  $R_{22}$ is Input Resistance through Port-2.

#### **Solution:**

While calculating  $R_{11}$ , Port-2 should be Opened. So, Net-Resistance seen through Port-1 is

$$R_{11} = R_F + R_M \tag{2.1.8.1}$$

While calculating  $R_{22}$ , Port-1 should be Shorted. So, Net-Resistance seen through Port-2 is

$$R_{22} = R_F || R_M \tag{2.1.8.2}$$

$$R_{22} = \frac{R_F R_M}{R_E + R_M} \tag{2.1.8.3}$$

So,

$$R_{11} = R_F + R_M (2.1.8.4)$$

$$R_{22} = \frac{R_F R_M}{R_E + R_M} \tag{2.1.8.5}$$

work.

### **Solution:**

As the ciruit is Shunt-Series Topology,  $R_{11}$  is shunted across the Input Terminal and  $R_{22}$  is added in series to Output Terminal.

Current Flowing through  $R_D$  is approximately same as  $I_i$ , as  $R_F$  is a Large Resistance.

The Circuit Diagram of Open-Loop Network is 2.1.9

By KVL and KCL,

$$v_B = I_i R_D (2.1.9.1)$$

$$v_{gs_2} = v_B = I_i R_D (2.1.9.2)$$

$$I_o = -g_{m_2} v_{gs_2} = -g_{m_2} I_i R_D (2.1.9.3)$$

$$\frac{I_o}{I_i} = -g_{m_2} R_D (2.1.9.4)$$

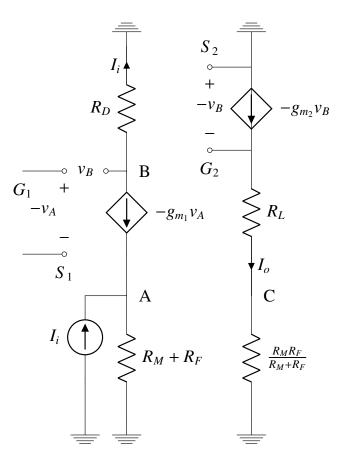


Fig. 2.1.9: Open-Loop Network

So, Open-Loop Gain is

$$G = \frac{I_o}{I_i} = -g_{m_2} R_D (2.1.9.5)$$

The Block Diagram of Open-Loop Network is

$$I_i$$
  $G = I_o$ 

Fig. 2.1.9: Open-Loop Block Diagram

- 3 Bode Plot
- 4 Second order System
- 5 ROUTH HURWITZ CRITERION
  - 6 STATE-SPACE MODEL
    - 7 Nyquist Plot
    - 8 Compensators
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  - 14 PID Controller