

```
annex safety {**
  fault SensorPedalPosition_ErroneousData
    "Inverted boolean fault" : faults.inverted_fail {
      inputs: val_in <- elec_pedal_position;
      outputs: elec_pedal_position <- val_out;
      probability: 5.0E-6 ;
      duration: permanent;
    }
};
```