```
process command
    features
        pedalvalue: in data port common::command.pedal;
        brake: out data port common::command.brake;
        skid: out data port common::command.skid;
end command;

process implementation command.i
    annex EMV2 {**
        use types      error_library;
        use behavior   error_library::simple;
        error propagations
            pedalvalue          : in propagation {NoService};
            brake               : out propagation{NoValue};
            skid                : out propagation{NoValue};
        flows
            nopedal             : error sink pedalvalue{NoService};
            noskid              : error source skid{NoValue};
            nobrake             : error source brake{NoValue};
        end propagations;

        component error behavior
            transitions
                terrfrompedal : Operational -[pedalvalue{NoService}]-> Failed;
            propagations
                p1 : Failed -[]-> brake{NoValue};
                p2 : Failed -[]-> skid{NoValue};
        end component;
    **};
end command.i;
```