

DL using OpenCV

Dmitry Kurtaev, IOTG Computer Vision

<dmitry.kurtaev@intel.com>

Internet of Things Group

Agenda

- General DL pipeline
- Face recognition on Raspberry Pi (C++)
- Image classification on Android (Java)
- Style transfer in browser (JavaScript)
- Edges2Cats on Windows (Python)







General DL pipeline

- An every sample consists of the following steps:
 - 1. Load deep learning network
 - 2. Get an input image
 - 3. Prepare a blob from image (normalize, resize, deinterleave)
 - 4. Make a forward pass through a network
 - 5. Interpret predictions and show it
- There are differences as for samples as for programming languages.



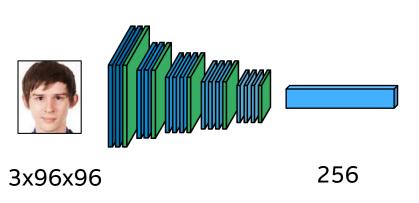
- Raspberry Pi is a single board computer with ARM CPU.
- Default OS Raspbian (Debian based, Linux).
- Get OpenCV libraries by apt-get or build from source
- Download OpenCV's face detection and OpenFace face recognition networks
 - https://github.com/dkurt/icv_sunday_school_2019_spring/tree/master/face_recognition

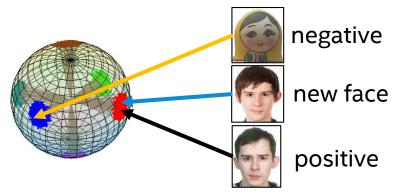
Read more about cross compilation of OpenCV:

article: https://habr.com/ru/post/430906/ (Ночью спит спокойно мама — мы собираем OpenCV для Raspbian'a) wiki: https://github.com/opency/opency/wiki/Intel%27s-Deep-Learning-Inference-Engine-backend#raspbian-stretch



- Get a frame from a camera
- Pass it to face detection network to predict bounding boxes
- Crop faces and predict embedding vectors for them (second network)
- Save an embedding for a single person and then recognize only him or her





OpenFace project: https://github.com/cmusatyalab/openface



Load net



```
cv::VideoCapture cap(0); // Open a USB camera device
cv::Mat frame;
while (cap.read(frame)) {
   // do something with frame
}
```

ED: Load net Input

FD: Load net Input Blob



FD: Load net Input Blob Forward



```
float* detections = (float*)out.data; // out has shape 1x1xNx7
// Detections are [batchId(0),classId(0),confidence,left,top,right,bottom]
for (int i = 0; i < out.total() / 7; ++i) {</pre>
  float confidence = detections[i * 7 + 2];
  if (confidence < 0.7)</pre>
    continue;
  int 1 = detections[i * 7 + 3] * frame.cols;
  int t = detections[i * 7 + 4] * frame.rows;
  int r = detections[i * 7 + 5] * frame.cols;
  int b = detections[i * 7 + 6] * frame.rows;
  cv::rectangle(frame, cv::Point(1, t), cv::Point(r, b), cv::Scalar(0,255,0));
cv::imshow("Face detection", frame);
```

FD: > Load net > Input > Blob > Forward > Show

```
cv::Mat face = frame.rowRange(t, b).colRange(l, r);
cv::Mat blob = cv::dnn::blobFromImage(face, 1.0 / 255 /*scale*/,
                                            cv::Size(96, 96) /*resize*/,
                                            cv::Scalar() /*no mean*/,
                                            true /*swap red and blue*/);
faceRecogn.setInput(blob);
cv::Mat embedding = faceRecogn.forward();
if (embedding.dot(targetEmbedding) > 0.8)
  cv::rectangle(frame, cv::Point(1, t), cv::Point(r, b), cv::Scalar(0,255,0));
else
 cv::rectangle(frame, cv::Point(l, t), cv::Point(r, b), cv::Scalar(0,0,255));
```

It's time for demo!







- You can build OpenCV for Android. It's a native library with Java wrappers.
- Getting started guide for Android Studio:
 - https://docs.opencv.org/master/d0/d6c/tutorial_dnn_android.html
- An article at Habrahabr: the force will be with me to finish it! (#opencv4arts)

```
public class MainActivity extends AppCompatActivity implements CvCameraViewListener2 {
 @Override
 public void onResume() {
    super.onResume();
    System.loadLibrary("opencv java4");
   mOpenCvCameraView.enableView();
 @Override
 protected void onCreate(Bundle savedInstanceState) {
    super.onCreate(savedInstanceState);
    setContentView(R.layout.activity main);
    mOpenCvCameraView = (CameraBridgeViewBase) findViewById(R.id.CameraView); // Set up camera listener.
    mOpenCvCameraView.setVisibility(CameraBridgeViewBase.VISIBLE);
    mOpenCvCameraView.setCvCameraViewListener(this);
 @Override
 public void onCameraViewStarted(int width, int height) {}
 @Override
 public void onCameraViewStopped() {}
 public Mat onCameraFrame(CvCameraViewFrame inputFrame) {}
 private CameraBridgeViewBase mOpenCvCameraView;
```

```
@Override
public void onCameraViewStarted(int width, int height) {
   String prefix = "/sdcard/Android/data/org.opencv.samples.icvdemo/";
   String weights = prefix + "squeezenet_v1.1.caffemodel";
   String config = prefix + "squeezenet_v1.1.prototxt";
   net = Dnn.readNet(weights, config);
}

private Net net;
```

Load net

```
public Mat onCameraFrame(CvCameraViewFrame inputFrame) {
   Mat frame = inputFrame.rgba();
   return frame;
}
```

Load net

Input

Load net > Input > Blob

```
public Mat onCameraFrame(CvCameraViewFrame inputFrame) {
 Mat frame = inputFrame.rgba();
 Mat frameBGR = new Mat();
  Imgproc.cvtColor(frame, frameBGR, Imgproc.COLOR RGBA2BGR);
 Mat blob = Dnn.blobFromImage(frameBGR, 1.0, new Size(227, 227),
                               new Scalar(104, 117, 123));
 net.setInput(blob);
 Mat out = net.forward();
 return frame;
     Load net
                                  Blob
                                              Forward
                    Input
```

```
Core.MinMaxLocResult loc = Core.minMaxLoc(out);
if (loc.maxVal > 0.5)
  Log.i("mytag", "class id: " + loc.maxLoc.x);
```

Load net > Input > Blob > Forward > Show

















- You can build OpenCV which is C++ library to JavaScript code! Using Emscripten.
- OpenCV.js reads images data from <canvas> and

Read more about OpenCV.js: https://habr.com/ru/company/intel/blog/437600/ (opencv4arts: Нарисуй мой город, Винсент) Sample source code: https://github.com/dkurtaev/dkurtaev/dkurtaev.github.io/tree/master/opencv4arts

```
<!DOCTYPE html>
<html>
<head>
  <script async src="https://docs.opencv.org/master/opencv.js"></script>
  <script src="https://docs.opencv.org/master/utils.js"></script>
  <script type='text/javascript'>
    function main() {
      document.getElementById('title').innerHTML += ' 2019';
                                                                                </script>
                                                       ① File | C:/Users/dkurtaev/icv_sunday_school_2019_spring/index.html
</head>
                                                ICV Sunday School 2019
<body onload="main()">
  ICV Sunday School
</body>
</html>
```

```
<script type='text/javascript'>
 var utils = new Utils('');
 var net;
 var url = "https://people.eecs.berkeley.edu/~taesung park/" +
            "CycleGAN/models/style vangogh.t7";
  utils.createFileFromUrl("style vangogh.t7", url, () => {
    net = cv.readNet("style vangogh.t7");
   // add a callback
 });
</script>
```

Load net

```
<head>
<script type='text/javascript'>
 // Read an image from canvas and convert it to BGR.
 var imgRGBA = cv.imread('canvasInput');
 var imgBGR = new cv.Mat(imgRGBA.rows, imgRGBA.cols, cv.CV 8UC3);
  cv.cvtColor(imgRGBA, imgBGR, cv.COLOR RGBA2BGR);
</script>
</head>
<body>
 <canvas id="canvasInput"></canvas>
</body>
     Load net
                    Input
```

Load net > Input > Blob

Load net > Input > Blob > Forward

```
// Output values are in range [-1, 1]. Normalize it to [0, 255] of UInt8.
var outNorm = new cv.Mat();
out.convertTo(outNorm, cv.CV 8U, 127.5, 127.5);
// Postprocessing: create an interleaved image from planar.
var outHeight = out.matSize[2];
var outWidth = out.matSize[3];
var planeSize = outHeight * outWidth;
var data = outNorm.data;
var b = cv.matFromArray(outHeight, outWidth, cv.CV 8UC1, data.slice(0, planeSize));
var g = cv.matFromArray(outHeight, outWidth, cv.CV 8UC1, data.slice(planeSize, 2 * planeSize));
                                                                                       Call to action!
var r = cv.matFromArray(outHeight, outWidth, cv.CV 8UC1, data.slice(2 * planeSize, 3 * planeSize));
var vec = new cv.MatVector();
vec.push back(r);
vec.push back(g);
vec.push back(b);
var rgb = new cv.Mat();
cv.merge(vec, rgb);
cv.imshow("canvasOutput", rgb); // Also canvas
       Load net
                                                                                    Show
                                               Blob
                                                               Forward
                            Input
```



It's time for demo!









https://dkurtaev.github.io/opencv4arts

- It's a fun derivative of pix2pix approach.
 - original (Torch): https://github.com/phillipi/pix2pix
 - ported (TensorFlow): https://github.com/affinelayer/pix2pix-tensorflow
- Besides cats there are models which can translate:
 - Satellite photos to maps
 - Day photos to night ones
 - Grayscale images to colored



```
import cv2 as cv
net = cv.dnn.readNet('edges2cats.pb')
```

Load net

```
import numpy as np
size = 256

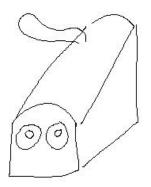
# canvas is filled by ones and we'll draw contours by zeros
canvas = np.ones([size, size, 3], dtype=np.float32)
```

Load net > Input

Load net > Input > Blob

Load net > Input > Blob > Forward

```
# [-1, 1] to [0, 1]
out += 1
out /= 2
# NCHW to HWC
res = out.transpose(0, 2, 3, 1).reshape(size, size, 3)
# RGB to BGR
res = res[:,:,[2, 1, 0]]
cv.imshow('Edges2Cats', res)
    Load net
                               Blob
                                          Forward
                                                       Show
                  Input
```

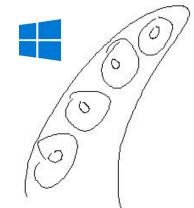


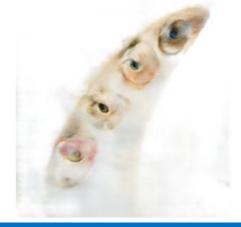


It's time for demo!









OpenCV's deep learning module summary

```
C++
                                Java
cv::dnn::Net net =
                                Net net = Dnn.readNet(...);
    cv::dnn::readNet(...);
net.setInput(blob);
                                net.setInput(blob);
cv::Mat out = net.forward();
                               Mat out = net.forward();
JavaScript
                                Python
var net = cv.readNet(...);
                                net = cv.dnn.readNet(...)
net.setInput(blob);
                                net.setInput(blob)
var out = net.forward();
                                out = net.forward()
```

Calls to action

- Experiment!
- Try https://freecodecamp.org (interactive JavaScript tutorials)