Review of "Neuron Shapley: Discovering the Responsible Neurons"

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Background: Literatures and Contributions

Neuron Shapley: Concept and Algorithm

3 Applications: Interpretation and Repair of Networks

Interpretation of Neural Networks

- **I** Feature importance: contribution of each input feature
 - Integrated Gradient [1], DeepLIFT [2], LIME [3], etc.
- 2 Sample importance: contribution of each training example
 - Data valuation based on Shapley values [4, 5], etc.
- **Blement importance:** contribution of each neuron/filter
 - Neuron conductance [6], extension of feature importance methods [7], etc.

Contributions of the Paper

- Conceptual: develop Neuron Shapley framework to quantify the contribution of each neuron/filter.
- **Algorithmic:** introduce multi-arm bandit based algorithm to efficiently estimate Shapley values.
- **Empirical:** apply the results to facilitate model interpretation and repair regarding accuracy, fairness, robustness, etc.

Preliminaries

Notation

- **Model:** network \mathcal{M} with L layers each with $n_{l \in \{1, \dots, L\}}$ neurons/filters. $N = \{m_i\}_{i=1}^n$ includes the $n = \sum_{l=1}^L n_l$ individual elements of \mathcal{M} .
- **Performance:** V(N) assigns score to trained network, e.g. accuracy, loss.
- Contribution: m_i 's contribution towards V(N) is denoted as $\phi_i(V,N)$, satisfying $\sum_{i=1}^n \phi_i(V,N) = V(N)$ with $\phi_i = \phi_i(V,N)$ for simplicity.

Desirable Properties for ϕ_i

- **Zero Contribution:** $\phi_i = 0$ if $V(S \cup \{i\}) = V(S)$ for all $S \subset N \{i\}$.
- **Symmetry:** $\phi_i = \phi_j$ if $V(S \cup \{i\}) = V(S \cup \{j\})$ for all $S \subset N \{i, j\}$.
- **Additivity:** when $V = V_1 + V_2$, $\phi_i(V, N) = \phi_i(V_1, N) + \phi_i(V_2, N)$.

Shapley Value in Neuron Evaluation

The authors propose the **Neuron Shapley** ϕ_i as

$$\phi_i = \frac{1}{|N|} \sum_{S \subset N - \{i\}} [V(S \cup \{i\}) - V(S)] / \binom{|N| - 1}{|S|}.$$

- Computation of V(S): for neurons, output of $N \setminus S$ can be replaced by zeros. For filters, output of $N \setminus S$ are replaced by mean outputs for validation images.
- Take into account the interactions between neurons.
- Uniquely satisfy the three aforementioned desirable properties.

Shapley Value in Game Theory [8]

Cooperative game with a set N of n players and reward function $v:2^n\to\mathbb{R}$.

- $lue{v}(S)$: reward the members of S can obtain by cooperation with $S\subset N$.
- lacksquare ϕ_i distributes the group reward among players in an equitable way.
- Equitable way means the aforementioned desirable properties are satisfied.

Estimation of Shapley Value

Monte-Carlo Estimation

■ The Shapley value of the *i*-th element [4] can be written as

$$\phi_i = \mathbb{E}_{\pi \sim \Pi}[V(S_{\pi}^i \cup \{i\}) - V(S_{\pi}^i)],$$

 π : permutation of $\{1,\cdots,n\}$, Π : uniform distribution over n! permutations, S^i_π : set of elements that appear after i in given permutation π .

lacktriangle Approximating ϕ_i can be transformed to estimating the mean of certain r.v..

Early Truncation Technique

- When $S^i_\pi \cup \{i\}$ is small, $V(S^i_\pi \cup \{i\})$ can degenerate to negligible due to loss of connections, i.e. $V(S^i_\pi \cup \{i\}) V(S^i_\pi) \approx 0$ in this case.
- Alternatively, choose a performance threshold v_T , and if $V(S^i_\pi \cup \{i\}) < v_T$, set $V(S^i_\pi \cup \{i\}) V(S^i_\pi) = 0$.

Algorithm: Truncated Multi Armed Bandit Shapley (TMAB-Shapley)

```
Input: Elements N = \{1, \dots, n\}, metric V(\cdot), tolerance \epsilon, number of
               important elements k, performance threshold v_T
    Initialization: \{\phi_i\}_{i=1}^n = 0, \{\sigma_i\}_{i=1}^n = 0, \mathcal{U} = N, t = 0
 1 while \mathcal{U} \neq \emptyset do
         t=t+1, random permutation \pi^t of \{1,\cdots,n\}
          for j \in \mathcal{U} do
               if V(S^j_{\pi^t} \cup \{j\}) < v_T then
                \phi_i^t = 0
               else
                \phi_{i}^{t} = V(S_{\pi t}^{j} \cup \{j\}) - V(S_{\pi t}^{j})
               end
              \phi_j = \text{Moving Average}(\phi_i^t), \ \sigma_j = \text{Moving Variance}(\phi_i^t)
               (\phi_i^{lb}, \phi_i^{ub}) = \text{Confidence Bound}(\phi_i, \sigma_i)
         end
         \mathcal{U} = \{i : \phi_i^{lb} + \epsilon < \text{top } k \text{ largest } \phi_i < \phi_i^{ub} - \epsilon\}
13 end
```

Output: Shapley values $\{\phi_i\}_{i=1}^n$

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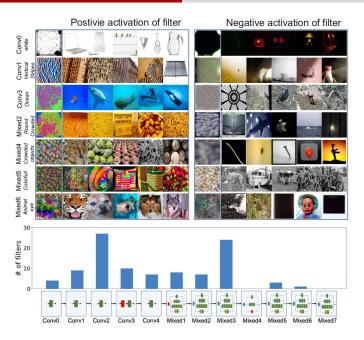
Application I: Identifying Critical Filters for Overall Accuracy

Implementation details

- **Model:** Inception-v3 network [9] with 17216 filters preceding the logit layer trained on ImageNet [10]. Its validation set is divided into two parts (25000 images each) to serve as validation (for zero out) and test sets.
- **Method:** TMAB-Shapley with $V(\cdot)$ set to the overall accuracy of the network on a randomly sampled batch of images and k=100.

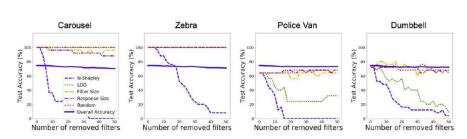
Interpretation Results

- Neuron Shapley values are very sparse, most of them are close to zero.
- Remove top 10 filters, overall test accuracy drops from 74% to 38%; Remove top 20 filters it drops to 8%. Random removal does not change the accuracy.
- Visualize the filter with the highest Shapley value in 7 of the layers applying:
 - Deep Dream [11]: image optimized by gradient ascend to highly activate filter.
 - Five images in the validation set that highly activate the filter.



Application II: Identifying Critical Filters for Chosen Class

- Aim: Identify filters that highly contribute to the chosen class but are not crucial for the overall performance.
- **Method:** TMAB-Shapley with $V(\cdot)$ set to class recall. Exclude the top 20% filters that contribute mostly to the overall accuracy from above experiment.
- **Results:** Removing top 40 filters leads to a dramatic decline in the network's ability to detect that class, but the overall performance remains intact.



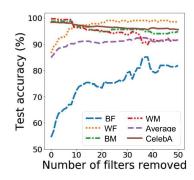
Visualization of Filters with the Highest Shapley Values

- Deep Dream: Image optimized to achieve the positive activation of filters.
- Top five images in the training set that highly activate the filters.



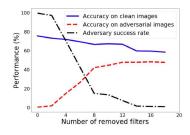
Application III: Discovering Unfair Filters

- **Motivation:** Gender detection models have certain biases towards minorities, e.g., they are less accurate on black female faces.
- Model: SqueezeNet [12] with 2976 filters trained on the celebA [13] dataset.
- **Method:** $V(\cdot)$ is set to accuracy on the PPB dataset [14].
- Results: Zeroing out filters with most negative Shapley values greatly increases the accuracy on black female (BF) faces from 54.7% to 81.9%, and also improves that for white females (WF).
- The average accuracy on PPB increased from 84.9% to 91.7%.
- The performance on male faces and CelebA data only drops a little after modification.



Application IV: Improving Adversarial Robustness

- **Goal:** Identify filters vulnerable to adversaries in the Inception-v3 model.
- Adversaries: Use iterative PGD attack [15] as an adversary to perturb each validation image so it's misclassified as a randomly chosen class.
- **Method:** $V(\cdot) = \text{Adversary's success rate} \text{Accuracy on clean images}.$ Former is the rate of fooling the network predicting randomly chosen labels.
- **Results:** Zeroing out the filters with the top 16 Shapley values, the adversary's attack success rate drops from nearly 100% to 0.1%, while the model's performance on clean images drops from 74% to 67%.
- The network is robust to the original adversary, but still vulnerable to new adversaries designed for the new model.
- For black-box adversaries created by different architectures, their attack success rate drops by 37% on average.



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