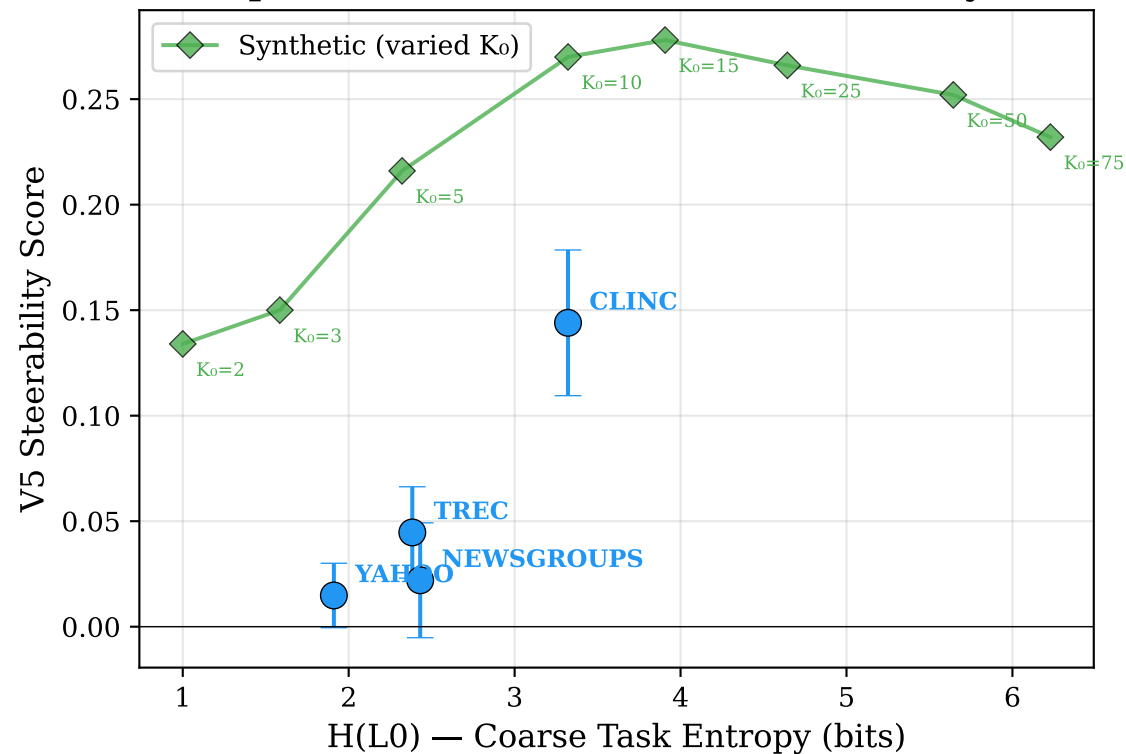


Disentangling the Scaling Law: $H(L0)$ is the True Driver

Mechanism: $S \sim H(L0)$
(prefix task demand drives steerability)



Observational Confound: S vs $H(L1|L0)$
(positive for real, NEGATIVE for synthetic)

