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## 1 DataStructure

### 1.1 sparse table

```
int st[MAXLG][MAXN];
void build(){
    for(int i=1;i<MAXLG;i++){
        for(int j=0;j<MAXN;j++){
            if(j+(1<<(i-1)) >= MAXN) continue;
            st[i][j] = min(st[i-1][j],st[i-1][j+(1<<(i-1))]);
        }
    }
}

int query(int l,int r){ // [l,r]
    int E = __lg(r-l);
    return min(st[E][l],st[E][r-(1<<E)+1]);
}
```

### 1.2 zkw tree

```
#include <bits/stdc++.h>
using namespace std;

const int MAXN = 100005;

int n, zkw[MAXN*2];

/*
    query: range max
    add: single change value
*/
void build () {
    for (int i=n-1; i>0; i--) {
        zkw[i] = max(zkw[i<<1], zkw[i<<1|1]);
    }
}

void chg (int x, int val) {
    for (zkw[x+=n]=val; x>1; x>>=1) {
        zkw[x>>1] = max(zkw[x], zkw[x^1]);
    }
}

int qry (int l, int r) {
    int ret = -0x3f3f3f3f;
    for (l+=n,r+=n; l<r; l>>=1, r>>=1) {
        if (l&1) {
            ret = max(ret, zkw[l++]);
        }
        if (r&1) {
            ret = max(ret, zkw[--r]);
        }
    }
    return ret;
}

int main () {
    cin >> n;
    for (int i=0; i<n; i++) {
        cin >> zkw[i+n];
    }

    build();
    int cmd;
    while (cin >> cmd) {
        int l, r, x, v;
        if (cmd == 1) {
```

```

        cin >> l >> r;
        cout << qry(l, r) << endl;
    } else {
        cin >> x >> v;
        chg(x, v);
    }
}
}

```

### 1.3 2Dstructure

```

const int Zero = 0;
inline int opt(const int &a, const int &b){
    return a+b;
}

int height, width;
int qx, qy, qX, qY;

struct Seg{
    int val;
    Seg *lc, *rc;
};

struct Seg2D{
    Seg *O;
    Seg2D *lc, *rc;
};

Seg* build(int l, int r){
    Seg* ret = new Seg();
    if (l==r) {
        cin>>ret->val;
        return ret;
    }
    int mid = (l+r)>>1;
    ret->lc = build(l,mid);
    ret->rc = build(mid+1,r);
    ret->val=opt(ret->lc->val, ret->rc->val);
    return ret;
}

Seg* merge(int l, int r, Seg *tl, Seg *tr){
    Seg* ret = new Seg();
    ret->val = opt( tl->val, tr->val);

    if (l!=r){
        int mid = (l+r)>>1;
        ret->lc = merge(l,mid,tl->lc,tr->lc);
        ret->rc = merge(mid+1,r,tl->rc,tr->rc);
    }

    return ret;
}

Seg2D* build2D(int l, int r){
    Seg2D* ret = new Seg2D();
    if (l==r){
        ret->O = build(1,width);
        return ret;
    }
    int mid = (l+r)>>1;
    ret->lc = build2D(l,mid);
    ret->rc = build2D(mid+1,r);
    ret->O = merge(1,width,ret->lc->O,ret->rc->O);
    return ret;
}

int query(Seg* o, int l, int r, int L, int R){
    if (r<L || R<l) return Zero;
    if (L<=l && r<=R) return o->val;
    int mid = (l+r)>>1;
    int ql = query(o->lc,l,mid,L,R);
    int qr = query(o->rc,mid+1,r,L,R);
    return opt(ql,qr);
}

int query2D(Seg2D* o, int l, int r, int L, int R){

```

```

    if (r<L || R<l) return Zero;
    if (L<=l && r<=R) return query(o->O,l,width,qx,qX)
    ;
    int mid = (l+r)>>1;
    int ql = query2D(o->lc,l,mid,L,R);
    int qr = query2D(o->rc,mid+1,r,L,R);
    return opt(ql,qr);
}

```

```

int pX, pY, v;

void modify(Seg*o, int l, int r, int p, int v){
    if (l>p||r<p) return;
    if (l==r) {
        o->val=v;
        return;
    }
    int mid = (l+r)>>1;
    modify(o->lc,l,mid,p,v);
    modify(o->rc,mid+1,r,p,v);
    o->val = opt(o->lc->val, o->rc->val);
}

```

```

void modify2D(Seg2D*o, int l, int r, int p){
    if (l>p||r<p) return;
    if (l==r){
        modify(o->O, 1, width, pX,v);
        return;
    }
    int mid = (l+r)>>1;
    modify2D(o->lc,l,mid,p);
    modify2D(o->rc,mid+1,r,p);
    int ql = query(o->lc->O,1,width,pX,pX);
    int qr = query(o->rc->O,1,width,pX,pX);
    modify(o->O,1,width,pX, opt(ql,qr) );
}

```

```

int main(){
    ios::sync_with_stdio(false);
    cin.tie(0);
    int n, q; cin>>n>>q;
    width = n;
    height = n;
    Seg2D *S = build2D(1, height);
    while (q--){
        int cmd;
        cin>>cmd;
        if (cmd==1){
            cin>>qy>>qx>>qY>>qX;
            if (qY<qy) swap(qY, qy);
            if (qX<qx) swap(qx, qX);
            cout<<query2D(S, 1, height, qy, qY)<<'\n';
        }else{
            cin>>pY>>pX>>v;
            modify2D(S, 1, height, pY);
        }
    }
}

```

### 1.4 LiChaoTree

```

struct Vec {
    ll x, y;
    ll eval (ll pos) {
        return pos*x + y;
    }
};

struct Node {
    int l, r;
    Node *lc, *rc;
    Vec bst;

    Node (int _l, int _r) : l(_l), r(_r) {
        lc = rc = nullptr;
        bst = {0, INF};
    }
}

```

```

};
Node *root[MAXN];

Node *addLine (Vec nw, Node *nd) {
    int mid = (nd->l + nd->r) >> 1;
    bool lnw = nw.eval(nd->l) < nd->bst.eval(nd->l);
    bool mnw = nw.eval(mid) < nd->bst.eval(mid);

    Node *ret = new Node(*nd);
    if (mnw) {
        swap(nw, ret->bst);
    }
    if (ret->l == ret->r - 1) {
        return ret;
    } else if (lnw != mnw) { // left
        if (!ret->lc) {
            ret->lc = new Node(ret->l, mid);
        }
        ret->lc = addLine(nw, ret->lc);
    } else {
        if (!ret->rc) {
            ret->rc = new Node(mid, ret->r);
        }
        ret->rc = addLine(nw, ret->rc);
    }

    return ret;
}

ll eval (ll x, Node *nd) {
    if (!nd) {
        return INF;
    }
    ll ret = nd->bst.eval(x);
    int mid = (nd->l + nd->r) >> 1;
    if (x >= mid) {
        ret = min(ret, eval(x, nd->rc));
    } else {
        ret = min(ret, eval(x, nd->lc));
    }
    return ret;
}

```

## 1.5 LCT

```

// from https://github.com/edisonhello/
// waynedisonitau123
struct node {
    node *ch[2], *fa, *pfa;
    int sum, v, rev, id;
    node(int s, int id): id(id), v(s), sum(s), rev
    (0), fa(nullptr), pfa(nullptr) {
        ch[0] = nullptr;
        ch[1] = nullptr;
    }
    int relation() {
        return this == fa->ch[0] ? 0 : 1;
    }
    void push() {
        if (!rev) return;
        swap(ch[0], ch[1]);
        if (ch[0]) ch[0]->rev ^= 1;
        if (ch[1]) ch[1]->rev ^= 1;
        rev = 0;
    }
    void pull() {
        sum = v;
        if (ch[0]) sum += ch[0]->sum;
        if (ch[1]) sum += ch[1]->sum;
    }
    void rotate() {
        if (fa->fa) fa->fa->push();
        fa->push(), push(), swap(pfa, fa->pfa);
        int d = relation();
        node *t = fa;
        if (t->fa) t->fa->ch[t->relation()] = this;
        fa = t->fa, t->ch[d] = ch[d ^ 1];
        if (ch[d ^ 1]) ch[d ^ 1]->fa = t;
        ch[d ^ 1] = t, t->fa = this;
    }
}

```

```

    t->pull(), pull();
}
void splay() {
    while (fa) {
        if (!fa->fa) {
            rotate();
            continue;
        }
        fa->fa->push(), fa->push();
        if (relation() == fa->relation()) fa->
        rotate(), rotate();
        else rotate(), rotate();
    }
}
void evert() { access(), splay(), rev ^= 1; }
void expose() {
    splay(), push();
    if (ch[1]) {
        ch[1]->fa = nullptr, ch[1]->pfa = this;
        ch[1] = nullptr, pull();
    }
}
bool splice() {
    splay();
    if (!pfa) return false;
    pfa->expose(), pfa->ch[1] = this, fa = pfa;
    pfa = nullptr, fa->pull();
    return true;
}
void access() {
    expose();
    while (splice());
}
int query() { return sum; }
};

namespace lct {
node *sp[maxn];
void make(int u, int v) {
    // create node with id u and value v
    sp[u] = new node(v, u);
}
void link(int u, int v) {
    // u become v's parent
    sp[v]->evert();
    sp[v]->pfa = sp[u];
}
void cut(int u, int v) {
    // u was v's parent
    sp[u]->evert();
    sp[v]->access(), sp[v]->splay(), sp[v]->push();
    sp[v]->ch[0]->fa = nullptr;
    sp[v]->ch[0] = nullptr;
    sp[v]->pull();
}
void modify(int u, int v) {
    sp[u]->splay();
    sp[u]->v = v;
    sp[u]->pull();
}
int query(int u, int v) {
    sp[u]->evert(), sp[v]->access(), sp[v]->splay();
    return sp[v]->query();
}
int find(int u) {
    sp[u]->access();
    sp[u]->splay();
    node *p = sp[u];
    while (true) {
        p->push();
        if (p->ch[0]) p = p->ch[0];
        else break;
    }
    return p->id;
}
}

```

## 1.6 treap

```

struct Nd{

```

```

int pri = rand();
int val = 0, tag = 0, id = 0, idtg = 0, mx=0;
Nd * lc=0, *rc = 0;
Nd(int v, int pos) {
    val = mx=v; id = pos;
}
};

```

```

inline void push(Nd *&o) {
    if (!o) return;
    if (o->tag) {
        o->val += o->tag;
        o->mx += o->tag;
        if (o->lc) o->lc->tag += o->tag;
        if (o->rc) o->rc->tag += o->tag;
        o->tag=0;
    }
    if (o->idtg) {
        o->id += o->idtg;
        if (o->lc) o->lc->idtg += o->idtg;
        if (o->rc) o->rc->idtg += o->idtg;
        o->idtg = 0;
    }
}

```

```

inline void pull(Nd *&o) {
    if (!o) return;
    o->mx = o->val;
    if (o->lc) o->mx = max(o->mx, o->lc->mx);
    if (o->rc) o->mx = max(o->mx, o->rc->mx);
}

```

```

Nd * merge(Nd *&A, Nd*&B) {
    push(A); push(B);
    if (!A) return B;
    if (!B) return A;
    if (A->pri > B->pri) {
        A->rc = merge(A->rc, B);
        push(A->lc);
        pull(A);
        return A;
    } else {
        B->lc = merge(A, B->lc);
        push(B->rc);
        pull(B);
        return B;
    }
}

```

```

void split(Nd *o, Nd * & A, Nd *& B, int id) {
    A=B=0;
    if (!o) return;
    push(o);
    if (o->id < id) {
        A = o;
        split(o->rc, A->rc, B, id);
        push(A->lc);
        pull(A);
    } else {
        B = o;
        split(o->lc, A, B->lc, id);
        push(B->rc);
        pull(B);
    }
}

```

## 1.7 segment tree dynamic

```

struct Node {
    int l, r;
    Node *lc, *rc;
    int mx;
};
Node *root[MAXN];

int qry (int l, int r, Node *nd) {
    if (!nd) {
        return 0;
    } else if (nd->l == l && r == nd->r) {

```

```

        return nd->mx;
    } else {
        int mid = (nd->l + nd->r) >> 1;
        if (l >= mid) {
            return qry(l, r, nd->rc);
        } else if (r <= mid) {
            return qry(l, r, nd->lc);
        } else {
            return max(qry(l, mid, nd->lc), qry(mid,
            r, nd->rc));
        }
    }
}

```

```

void chg (int pos, int v, Node *nd) {
    if (nd->l == nd->r-1) {
        nd->mx = max(nd->mx, v);
    } else {
        int mid = (nd->l + nd->r) >> 1;
        if (pos >= mid) {
            if (!nd->rc) {
                nd->rc = new Node{mid, nd->r,
                nullptr, nullptr, 0};
            }
            chg(pos, v, nd->rc);
            nd->mx = max(nd->mx, nd->rc->mx);
        } else {
            if (!nd->lc) {
                nd->lc = new Node{nd->l, mid,
                nullptr, nullptr, 0};
            }
            chg(pos, v, nd->lc);
            nd->mx = max(nd->mx, nd->lc->mx);
        }
    }
}

```

## 1.8 segment tree array

```

#include <bits/stdc++.h>
using namespace std;
typedef long long ll;
#define REP(i, n) for(int i=0; i<n;i++)

const int MAXN = 100005;

int n, m, a[MAXN], len[MAXN*4], dt[MAXN*4], tag[MAXN*4];

void push (int o) {
    if (len[o] > 1 && tag[o] != 0) {
        tag[o<<1] += tag[o];
        tag[o<<1|1] += tag[o];
        dt[o] += tag[o] * len[o];
        tag[o] = 0;
    }
}

ll sum (int o) {
    return tag[o]*len[o] + dt[o];
}

void pull (int o) {
    dt[o] = sum(o<<1) + sum(o<<1|1);
}

void build (int o=1, int l=0, int r=n) {
    if (l == r - 1) {
        dt[o] = tag[o] = 0;
        len[o] = 1;
    } else {
        int mid = (l + r) >> 1;
        build(o<<1, l, mid);
        build(o<<1|1, mid, r);
        len[o] = len[o<<1] + len[o<<1|1];
        pull(o);
    }
}

```

```

11 query(int qL, int qR, int o=1, int nL=0, int nR=n
) {
    if (qR <= nL || qL >= nR || qL >= qR) {
        return 0;
    } else if (nL >= qL && nR <= qR) {
        return sum(o);
    } else {
        push(o);
        int mid = (nL + nR) >> 1;
        return query(qL, qR, o<<1, nL, mid) + query(
qL, qR, o<<1|1, mid, nR);
    }
}

void modify(int qL, int qR, int val, int o=1, int nL
=0, int nR=n) {
    if (qR <= nL || qL >= nR || qL >= qR) {
        return;
    } else if (nL >= qL && nR <= qR) {
        tag[o] += val;
    } else {
        push(o);
        int mid = (nL + nR) >> 1;
        modify(qL, qR, val, o<<1, nL, mid);
        modify(qL, qR, val, o<<1|1, mid, nR);
        pull(o);
    }
}

int main () {
    cin >> n;
    build();
    int cmd;
    while (cin >> cmd) {
        int l, r, v;
        if (cmd == 1) {
            cin >> l >> r >> v;
            modify(l, r, v);
        } else {
            cin >> l >> r;
            cout << query(l, r) << endl;
        }
    }
}

/*
10
1 0 3 3
0 0 5
1 2 4 2
0 0 5
*/

```

## 1.9 ConvexHull

```

// Lower Hull
bool QTYPE=0;
struct Line {
    mutable ll m, b, p;
    bool operator<(const Line& o) const {
        if (QTYPE) return p<o.p;
        return m < o.m;
    }
};

struct LineContainer : multiset<Line> {
    // (for doubles, use INF = 1/.0, div(a,b) = a/b)
    const ll INF = LLONG_MAX;
    ll div(ll A, ll B) { // floored division
        return A / B - ((A ^ B) < 0 && A % B); }
    bool isect(iterator x, iterator y) {
        if (y == end()) { x->p = INF; return false; }
        if (x->m == y->m) x->p = x->b > y->b ? INF :
-INF;
        else x->p = div(y->b - x->b, x->m - y->m);
        return x->p >= y->p;
    }
};

```

```

}
void add(ll m, ll b) {
    auto z = insert({m, b, 0}), y = z++, x = y;
    while (isect(y, z)) z = erase(z);
    if (x != begin() && isect(--x, y)) isect(x,
y = erase(y));
    while ((y = x) != begin() && (--x)->p >= y->
p)
        isect(x, erase(y));
}
ll query(ll x) {
    assert(!empty());
    QTYPE=1; auto l = *lower_bound({0,0,x});
    QTYPE = 0;
    return l.m * x + l.b;
}
};

```

## 2 Math

### 2.1 rho

```

#include <bits/stdc++.h>
using namespace std;
#define ll long long
#define pii pair<int, int>
#define ull unsigned ll
#define f first
#define s second
#define FOR(i,a,b) for (int i=(a); i<(b); i++)
#define REP(i,n) for (int i=0; i<(n); i++)
#define RREP(i,n) for (int i=(n-1); i>=0; i--)
#define ALL(x) x.begin(),x.end()
#define SZ(x) (int)x.size()
#define SQ(x) (x)*(x)
#define MN(a,b) a = min(a,(__typeof__(a))(b))
#define MX(a,b) a = max(a,(__typeof__(a))(b))
#define pb push_back
#define SORT_UNIQUE(c) (sort(c.begin(),c.end()), c.
resize(distance(c.begin(),unique(c.begin(),c.end
()))))
#ifdef BALBIT
#define IOS()
#define debug(...) do{\
    fprintf(stderr,"%s - %d (%s) = ",
__PRETTY_FUNCTION__, __LINE__, #__VA_ARGS__);\
    do(__VA_ARGS__); \
}while(0)
template<typename T>void _do(T &&x){cerr<<x<<endl
;};
template<typename T,typename ...S> void _do(T &&x,S
&&...t){cerr<<x<<" ";_do(t...);}
template<typename _a,typename _b> ostream& operator
<< (ostream &s,const pair<_a,_b> &p){return _s
<<("<<p.X<<","<<p.Y<<");}
template<typename It> ostream& _OUTC(ostream &s,It
_ita,It _itb)
{
    _s<<"{";
    for(It _it=_ita;_it!=_itb;_it++)
    {
        _s<<(_it==_ita?" ":"")<<*_it;
    }
    _s<<"}";
    return _s;
}
template<typename _a> ostream &operator << (ostream
&s,vector<_a> &c){return _OUTC(_s,ALL(_c));}
template<typename _a> ostream &operator << (ostream
&s,set<_a> &c){return _OUTC(_s,ALL(_c));}
template<typename _a> ostream &operator << (ostream
&s,deque<_a> &c){return _OUTC(_s,ALL(_c));}
template<typename _a,typename _b> ostream &operator
<< (ostream &s,map<_a,_b> &c){return _OUTC(_s,
ALL(_c));}
template<typename _t> void pary(_t _a,_t _b){_OUTC(
cerr,_a,_b);cerr<<endl;}
#else

```

```

#define IOS() ios_base::sync_with_stdio(0);cin.tie
(0);
#define endl '\n'
#define debug(...)
#define pary(...)
#endif

// #define int ll

const int iinf = 1<<29;
const ll inf = 1ll<<60;
const ll mod = 1e9+7;

void GG(){cout<<"-1\n"; exit(0);}

ll mpow(ll a, ll n, ll mo = mod){ // a^n % mod
    ll re=1;
    while (n>0){
        if (n&1) re = re*a %mo;
        a = a*a %mo;
        n>>=1;
    }
    return re;
}

ll inv (ll b, ll mo = mod){
    if (b==1) return b;
    return (mo-mo/b) * inv(mo%b) % mo;
}

const int maxn = 1e5+5;

#define lll __int128

lll c = 1;
lll g(lll x, lll n){
    return (x*x+c)%n;
}

lll gcd(lll a, lll b){
    if (b==0) return a;
    return gcd(b,a%b);
}

lll po(lll n){
    lll x = 2, y = 2, d = 1;
    while (d==1){
        x = g(x,n); y = g(y,n);
        d = gcd(x>y?x-y:y-x,n);
    }
    if (d==n) return -1;
    return d;
}

ll fac(ll n){
    if (n%2==0) return 2;
    lll ans = -1;
    for (int i = 0; i<5 && ans==-1; i++) {
        c++; if (c==2) c++;
        ans = po(n);
    }
    return ans;
}

main(){
    ll test = 1709049187;
    lll moo = test;
    ll ans = fac(moo);
    cout<<ans<<endl;
}

```

## 2.2 inversion

```

#include <bits/stdc++.h>
using namespace std;
typedef long long ll;

```

```

const ll mod = 100000007;

ll inv (ll b, ll mo = mod){
    if (b==1) return b;
    return (mo-mo/b) * inv(mo%b) % mo;
}

void extGCD(ll A,ll B,ll &x,ll &y) { // A p coprime
    if (B == 0) {
        x = 1;
        y = 0;
        assert(A == 1);
        return;
    }
    ll xx,yy;
    extGCD(B,A%B,xx,yy);
    x = yy;
    y = xx - A/B*yy;
    return;
}

ll ext_inv (ll a, ll p) { // a, p co-prime
    ll x, y;
    extGCD(a,p, x, y);
    x %= p;
    if (x < 0) {
        x += p;
    }
    assert(a * x % p);
    return x;
}

int main () {
    ll a, p;
    cin >> a >> p;
    ll ainv = ext_inv(a, p);
    cout << ainv << endl;
}

```

## 2.3 LL-Multiplication

```

ll mul1(ll a, ll b, ll n){
    __int128 x = a, y = b;
    return (ll)(x*y%n);
} // A little faster than mul2

ll mul2(ll a,ll b,ll n){
    a%=n,b%=n;
    ll y=(ll)((long double)a*b/n+0.5);
    ll r=(a*b-y*n)%n;
    return r<0?r+n:r;
}

```

## 2.4 CRT

```

ll mod;
ll mul(ll v1,ll v2,ll md=mod) {
    return v1 * v2 % md;
}

void normal(ll &v1) {
    v1 %= mod;
    if (v1 < 0) {
        v1 += mod;
    }
}

ll extGCD(ll n1,ll n2,ll &x1,ll &x2) {
    if (n1 == 0) {
        x2 = 1;
        x1 = 0;
        return n2;
    }
    ll cx1,cx2;
    ll ret = extGCD(n2%n1,n1,cx1,cx2);
    x2 = cx1;
    x1 = cx2 - n2/n1*cx1;
    return ret;
}

```

```

}

void crt (ll a, ll n, ll b, ll m) {
    ll r1,r2;
    ll gcd = extGCD(n,m,r1,r2);
    if ((b-a) % gcd != 0) {
        cout << "no solution" << endl;
        return;
    }
    mod = n * m / gcd;

    ll ans = mul(mul(r1,(b-a)/gcd,m/gcd),n) + a;
    normal(ans);
    cout << ans << " " << mod << endl;
}

```

## 2.5 geometry

```

const double PI = acos(-1);

struct Point{
    double x, y;

    bool operator < (const Point &b) const {
        return tie(x,y) < tie(b.x,b.y);
        //return atan2(y,x) < atan2(b.y,b.x);
    }
    Point operator + (const Point &b) const {
        return {x+b.x,y+b.y};
    }
    Point operator - (const Point &b) const {
        return {x-b.x,y-b.y};
    }
    Point operator * (const double d) const {
        return {x*d,y*d};
    }
    Point operator / (const double d) const {
        return {x/d,y/d};
    }
    double operator * (const Point &b) const {
        return x*b.x + y*b.y;
    }
    double operator % (const Point &b) const { //
        Cross!
        return x*b.y - y*b.x;
    }
    Point(double xx, double yy): x(xx), y(yy){ }
};

double Length( const Point &p ){
    return sqrt( p.x*p.x + p.y*p.y );
}

int ori(const Point &a, const Point &b, const Point
&c){
    int tmp = (c-a)%(b-a);
    if (tmp==0) return 0; //Collinear
    return tmp>0? 1: -1;
}

bool collinear(const Point &a, const Point &b, const
Point &c){
    return ori(a, b, c)==0;
}

bool btw(const Point &a, const Point &b, const Point
&c){
    return (a-c)*(b-c)<=0;
}

typedef Point Vector;

double Angle( const Vector &a, const Vector &b ){
    double A = Length(a);
    double B = Length(b);
    double v = a*b;
    double theta = acos( v/A/B );
    return theta;
}

```

```

Vector rot(Vector vec, double a){
    return Vector(cos(a)*vec.x-sin(a)*vec.y, sin(a)*
vec.x+cos(a)*vec.y);
}

Vector Normal(const Vector &v){
    return v / Length(v);
}

Point intersect_at(const Point &p, const Vector &v,
const Point &q, const Vector &w){
    Vector u = q-p;
    return p+v*(u%w)/(q%w);
}

bool cmp(const Point&a, const Point &b){
    return a<b;
    //Sort by x first, then by y.
}

vector<Point> convex_hull(vector<Point>arr){
    sort (arr.begin(), arr.end(), cmp);
    vector<Point> p;
    int m = 0; // size of p
    for (int i=0; i<arr.size(); i++){ // Lower hull
        //cout<<"On the "<<i<<"-th one. "<<arr[i].x<<
'<<arr[i].y<<'\n';
        while (m>=2&&(p[m-1]-p[m-2])%(arr[i]-p[m-2])<0){
            //Get rid of a previous point
            //cout<<"Got rid of "<<p[m-1].x<< ' '<<p[m-1].y
<<'\n';
            p.pop_back(); m--;
        }
        p.push_back(arr[i]); m++;
    }
    //cout<<"Onto upper hull"<<'\n';
    int tmp = m+1; //the size of lower hull +1
    for (int i=arr.size()-2; i>=0; i--){
        //cout<<"On the "<<i<<"-th one. "<<arr[i].x<<
'<<arr[i].y<<'\n';
        while (m>=tmp&&(p[m-1]-p[m-2])%(arr[i]-p[m-2])
<0){
            //cout<<"Got rid of "<<p[m-1].x<< ' '<<p[m-1].y
<<'\n';
            p.pop_back(); m--;
        }
        p.push_back(arr[i]); m++;
    }
    //cout<<m<<'\n';
    if (arr.size()>1) p.pop_back(); //Repeated
    return p;
}

//Segment banana

double signedArea(Point p[], int n){
    double re = 0.0;
    for (int i=0; i<n; i++){
        re+=p[i]%p[(i+1)%n];
    }
    return re/2.0; //Cross returns twice the triangle'
s area
}

bool intersect(const Point a, const Point b, const
Point c, const Point d){
    int abc = ori(a, b, c);
    int abd = ori(a, b, d);
    int cda = ori(c, d, a);
    int cdb = ori(c, d, b);
    if (abc==0&&abd==0){
        return btw(a,b,c)||btw(a,b,d)||btw(c,d,a)||btw(c
,d,b);
    }else return (abc*abd<=0&&cda*cdb<=0);
}

```

## 2.6 FWT

```
// from https://github.com/edisonhello/
// waynedisonitau123
void xorfwf(int v[], int l, int r) {
    if (r - l == 1) return;
    int m = l + r >> 1;
    xorfwf(v, l, m), xorfwf(v, m, r);
    for (int i = l, j = m; i < m; ++i, ++j) {
        int x = v[i] + v[j];
        v[j] = v[i] - v[j], v[i] = x;
    }
}

void xorifwt(int v[], int l, int r) {
    if (r - l == 1) return;
    int m = l + r >> 1;
    for (int i = l, j = m; i < m; ++i, ++j) {
        int x = (v[i] + v[j]) / 2;
        v[j] = (v[i] - v[j]) / 2, v[i] = x;
    }
    xorifwt(v, l, m), xorifwt(v, m, r);
}

void andfwf(int v[], int l, int r) {
    if (r - l == 1) return;
    int m = l + r >> 1;
    andfwf(v, l, m), andfwf(v, m, r);
    for (int i = l, j = m; i < m; ++i, ++j) v[i] +=
    v[j];
}

void andifwt(int v[], int l, int r) {
    if (r - l == 1) return;
    int m = l + r >> 1;
    andifwt(v, l, m), andifwt(v, m, r);
    for (int i = l, j = m; i < m; ++i, ++j) v[i] -=
    v[j];
}

void orfwf(int v[], int l, int r) {
    if (r - l == 1) return;
    int m = l + r >> 1;
    orfwf(v, l, m), orfwf(v, m, r);
    for (int i = l, j = m; i < m; ++i, ++j) v[j] +=
    v[i];
}

void orifwt(int v[], int l, int r) {
    if (r - l == 1) return;
    int m = l + r >> 1;
    orifwt(v, l, m), orifwt(v, m, r);
    for (int i = l, j = m; i < m; ++i, ++j) v[j] -=
    v[i];
}
```

## 2.7 FFT-precision

```
#include <bits/stdc++.h>
using namespace std;
#define SZ(v) int(v.size())
#define REP(i,n) for(int i=0;i<n;i++)
#define REP1(i,n) for(int i=1;i<=n;i++)

const int MAXN = 1<<20;
typedef complex<double> cd;

const double pi = acos(-1);
vector<int> bs;
cd omg[MAXN+3];

void FFT (vector<cd> &v, int d) {
    for (int i=1,j=SZ(v)>>1; i<SZ(v)-1; i++) {
        if (i < j) {
            swap(v[i], v[j]);
        }
        int k = SZ(v)>>1;
        while (k <= j) {
            j -= k;
            k >>= 1;
        }
    }
}
```

```
if (k > j) {
    j += k;
}

for (int h=2; h<=SZ(v); h<=1) {
    for (int i=0; i<SZ(v); i+=h) {
        for (int k=i; k<i+h/2; k++) {
            int idx = k-i;
            int r = k+h/2;
            cd x = v[k] - omg[d > 0 ? idx*(MAXN/
h) : MAXN-idx*(MAXN/h)] * v[r];
            v[k] = v[k] + omg[d > 0 ? idx*(MAXN/
h) : MAXN-idx*(MAXN/h)] * v[r];
            v[r] = x;
        }
    }
}

if (d < 0) {
    REP (i, SZ(v)) {
        v[i] /= SZ(v);
    }
}

void build_omg() {
    omg[0] = omg[MAXN] = 1;
    REP1 (i, MAXN-1) {
        omg[i] = polar(1.0, i*pi*2/MAXN);
    }
}

vector<int> mul (vector<int> &v1, vector<int> &v2) {
    int n = 1;
    while (n < SZ(v1) + SZ(v2)) {
        n <<= 1;
    }
    vector<cd> x(n), y(n);
    REP (i, SZ(v1)) {
        x[i] = v1[i];
    }
    REP (i, SZ(v2)) {
        y[i] = v2[i];
    }
    FFT(x, 1);
    FFT(y, 1);
    REP (i, n) {
        x[i] *= y[i];
    }
    FFT(x, -1);
    vector<int> ret(n);
    REP (i, n) {
        ret[i] = min(1, (int)round(x[i].real()));
    }
    while (SZ(ret)>1 && ret.back() == 0) {
        ret.pop_back();
    }
    return ret;
}

int main () {
}
```

## 2.8 FFT

```
const double PI = acos(-1.0);
#define cd complex<double>

void FFT(vector<cd> &a, bool rev=0){
    int n = SZ(a);
    for (int i = 1, j = 0; i<n; i++){
        int bit = n>>1;
        while (j>=bit) j-=bit, bit>>=1; j+=bit;
        if (i<j) swap(a[i], a[j]);
    }
    for (int B = 2; B<=n; B*=2){
        double ang = 2 * PI / B * (rev?-1:1);
```



```

        cd w0 (cos(ang), sin(ang));
        for (int i = 0; i < n; i += B) {
            cd w (1, 0);
            for (int j = 0; j < B/2; j++) {
                cd u = a[i+j], v = w*a[i+j+B/2];
                a[i+j] = u+v, a[i+j+B/2] = u-v;
                w *= w0;
            }
        }
        if (rev) REP(i, n) a[i] /= n;
    }

vector<ll> mul (vector<ll> a, vector<ll> b) {
    int n = 1; while (n < SZ(a) + SZ(b)) n *= 2;
    vector<cd> x(n), y(n);
    REP(i, SZ(a)) x[i] = cd(a[i], 0); REP(j, SZ(b)) y[j] = cd(b[j], 0);
    FFT(x); FFT(y);
    REP(i, n) x[i] *= y[i];
    FFT(x, 1);
    vector<ll> re(n);
    REP(i, n) re[i] = min((ll)(round(x[i].real()))), 1ll);
    while (re.size() > 1 && re.back() == 0) re.pop_back();
    return re;
}

```

## 2.9 linear sieve

```

#include <bits/stdc++.h>
using namespace std;

const int MAXC = 1000006;
bool sieve[MAXC];
vector<int> prime;

void linear_sieve() {
    for (int i = 2; i < MAXC; i++) {
        if (!sieve[i]) prime.emplace_back(i);
        for (int j = 0; i*prime[j] < MAXC; j++) {
            sieve[i*prime[j]] = true;
            if (i % prime[j] == 0) {
                break;
            }
        }
    }
}

int main () {
    linear_sieve();
    for (int i = 0; i < 20; i++) {
        cout << prime[i] << " \n"[i==19];
    }
}

```

## 2.10 NTT

```

void NTT(vector<ll> &a, ll mo, bool rev = 0) {
    // mo has to be 2^k * c + 1
    int n = SZ(a);
    while ((n & (-n)) != n) {
        a.pb(0); n++;
    }
    for (int i = 1, j = 0; i < n; i++) {
        int bit = n >> 1;
        while (j >= bit) j -= bit, bit >>= 1; j += bit;
        if (i < j) swap(a[i], a[j]);
    }
    for (int B = 2; B <= n; B *= 2) {
        ll w0 = mpow(3, (mo-1)/(B), mo);
        for (int i = 0; i < n; i += B) {
            ll w = 1;
            for (int j = 0; j < B/2; j++) {
                ll u = a[i+j], v = w*a[i+j+B/2] % mo;
                a[i+j] = u+v, a[i+j+B/2] = u-v;
            }
        }
    }
}

```

```

        if (a[i+j] >= mo) a[i+j] -= mo; if (a[i+j+B/2] < 0) a[i+j+B/2] += mo;
        w = w*w0 % mo;
    }
}
if (rev) {
    reverse(next(a.begin()), a.end());
    ll invn = inv(n, mo);
    REP(i, n) a[i] = a[i] * invn % mo;
}
}

vector<ll> mul (vector<ll> a, vector<ll> b, ll mo = mod) {
    int n = 1; while (n < SZ(a) + SZ(b)) n *= 2;
    vector<ll> x(n), y(n);
    REP(i, SZ(a)) x[i] = a[i]; REP(j, SZ(b)) y[j] = b[j];
    NTT(x, mo); NTT(y, mo);
    REP(i, n) x[i] = x[i] * y[i] % mo;
    NTT(x, mo, 1);
    while (x.size() > 1 && x.back() == 0) x.pop_back();
    return x;
}

```

## 2.11 miller rabin

```

ll mul1(ll a, ll b, ll n) { // Better
    __int128 x = a, y = b;
    return (ll)(x*y%n);
}

ll mul2(ll a, ll b, ll n) { // Slightly worse
    a %= n, b %= n;
    ll y = (ll)((long double)a*b/n + 0.5);
    ll r = (a*b - y*n) % n;
    return r < 0 ? r + n : r;
}

ll mpow(ll a, ll b, ll mod) { // a^b % mod
    ll ans = 1;
    for (; b; a = mul1(a, a, mod), b >>= 1)
        if (b & 1) ans = mul1(ans, a, mod);
    return ans;
}

int sprp[3] = {2, 7, 61}; // int
int llsprp[7] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022}; // unsigned long long

bool isprime(ll n) {
    if (n == 2) return 1;
    if (n < 2 || n % 2 == 0) return 0;
    int t = 0;
    ll u = n - 1;
    for (; u % 2 == 0; ++t) u >>= 1;
    for (int i = 0; i < 5; ++i) { // Increase for more accuracy
        ll a = llsprp[i] % n;
        if (a == 0 || a == 1 || a == n - 1) continue;
        ll x = mpow(a, u, n);
        if (x == 1 || x == n - 1) continue;
        for (int j = 1; j < t; ++j) {
            x = mul1(x, x, n);
            if (x == 1) return 0;
            if (x == n - 1) break;
        }
        if (x == n - 1) continue;
        return 0;
    }
    return 1;
}

```

## 3 String

### 3.1 ac automation

```

const int K = 26, MAXN = 100005;;
struct Trie {
    int nxt[K], go[K], pid, pch, leaf = -1, link =
    -1, lst = -1;
    Trie (int _pid=0, int _pch=0) {
        memset(nxt, -1, sizeof(nxt));
        memset(go, -1, sizeof(go));
        pid = _pid;
        pch = _pch;
    }
};
vector<Trie> trie(1);
vector<int> occ[MAXN];

void addString (string &str, int id) {
    int nd = 0;
    for (auto c : str) {
        int cid = c - 'a';
        if (trie[nd].nxt[cid] == -1) {
            trie[nd].nxt[cid] = SZ(trie);
            trie.emplace_back(nd, cid);
        }
        nd = trie[nd].nxt[cid];
    }
    trie[nd].leaf = id;
}

int go (int nd, int cid);

int getLink (int nd) {
    if (trie[nd].link == -1) {
        if (nd == 0 || trie[nd].pid == 0) {
            trie[nd].link = 0;
        } else {
            trie[nd].link = go(getLink(trie[nd].pid)
, trie[nd].pch);
        }
    }
    return trie[nd].link;
}

int getLast (int nd) {
    if (trie[nd].lst == -1) {
        if (trie[getLink(nd)].leaf == -1) {
            trie[nd].lst = nd == 0 ? 0 : getLast(
getLink(nd));
        } else {
            trie[nd].lst = getLink(nd);
        }
    }
    return trie[nd].lst;
}

int go (int nd, int cid) {
    if (trie[nd].go[cid] == -1) {
        if (trie[nd].nxt[cid] != -1) {
            trie[nd].go[cid] = trie[nd].nxt[cid];
        } else {
            trie[nd].go[cid] = nd == 0 ? 0 : go(
getLink(nd), cid);
        }
    }
    return trie[nd].go[cid];
}

void query (string &str) {
    int nd = 0;
    int sid = 0;
    for (auto c : str) {
        int cid = c - 'a';
        nd = go(nd, cid);

        int ptr = nd;
        while (ptr != 0) {
            if (trie[ptr].leaf != -1) {
                occ[trie[ptr].leaf].emplace_back(sid
);
            }
            ptr = getLast(ptr);
        }
    }
}

```

```

    }
    sid++;
}

3.2 zvalue

#include <bits/stdc++.h>
using namespace std;
const int MAXN = 2000006;

int z[MAXN];
string a;
void init(string x) {
    a = x;
    std::memset(z, 0, sizeof z);
}
void z_build() {
    z[0] = 0;
    for (int i = 1, bst = 0; a[i]; i++) {
        if (bst + z[bst] < i) {
            z[i] = 0;
        } else {
            z[i] = min(z[i - bst], bst + z[bst] - i)
;
        }
        while (a[z[i]] == a[z[i] + i]) {
            z[i]++;
        }
        if (i + z[i] > bst + z[bst]) {
            bst = i;
        }
    }
}

int mat(string x, string y) {
    int ret = 0;
    init(x+'$'+y);
    z_build();
    for (int i=int(x.size()+1); i<=int(x.size()+y.
size()); i++) {
        ret += (z[i] == int(x.size()));
    }
    return ret;
}

int main () {
    string a, b;
    cout << mat(a, b) << endl;
}

```

### 3.3 kmp

```

int app(string s, string t){ // Returns number of
times s appears in t
    int n = s.length(), m = t.length();
    if (n>m) return 0;
    vector<int> f(n); f[0]=-1;
    for (int i = 1; i<n; i++){
        f[i] = f[i-1];
        while (f[i]!=-1 && s[f[i]+1]!=s[i]) f[i] = f[f[i]
];
        if (s[f[i]+1]==s[i]) f[i]++;
    }
    int j = 0, re = 0;
    for (int i = 0; i<m; i++){
        if (t[i] == s[j]) j++;
        else if (j) j = f[j-1]+1, i--;
        if (j==n) re++, j = f[j-1]+1;
    }
    return re;
}

```

### 3.4 DC3

```

// from https://github.com/edisonhello/
waynedisonitau123
namespace DC3{

```

```

#pragma GCC diagnostic push
#pragma GCC diagnostic ignored "-Wsign-compare"

#define SG(v,i) ((i)>=int(v.size())?0:v[i])
inline bool smaller(int a, int b, vector<int> &r)
{
    if(SG(r,a+0) != SG(r,b+0)) return SG(r,a+0)<
SG(r,b+0);
    if(SG(r,a+1) != SG(r,b+1)) return SG(r,a+1)<
SG(r,b+1);
    return SG(r,a+2)<SG(r,b+2);
}

int cc[100005];
inline vector<int> sort(vector<int> &r, int o,
vector<int> &ix, int m){
    vector<int> rt(ix.size());
    for(int z=0;z<o;++z) r.push_back(0);
    for(int i=0;i<=m;++i) cc[i] = 0;
    for(int i=0;i<ix.size();++i) ++cc[r[ix[i]+o
]];
    for(int i=0;i<=m;++i) cc[i+1] += cc[i];
    for(int i=ix.size()-1;i>=0;--i) rt[--cc[r[ix
[i]+o]]] = ix[i];
    for(int z=0;z<o;++z) r.pop_back();
    return rt;
}

vector<int> dc3(vector<int> &v, int n, int m){
    int c1 = (n+1)/3;
    vector<int> i12;
    for(int i=0;i<n;++i){
        if(i%3==0) continue;
        i12.push_back(i);
    }
    i12 = sort(v, 2, i12, m);
    i12 = sort(v, 1, i12, m);
    i12 = sort(v, 0, i12, m);

    int nr = 1;
    vector<int> r12(i12.size());
#define GRI(x) ((x)/3 + ((x)%3==2?c1:0))
    r12[GRI(i12[0])] = 1;
    for(int i=1;i<i12.size();++i){
        if(smaller(i12[i-1], i12[i], v)) r12[GRI
(i12[i])] = ++nr;
        else r12[GRI(i12[i])] = nr;
    }

#define GEI(x) ((x)<c1?(x)*3+1:(x-c1)*3+2)
    if(nr != i12.size()){
        i12 = dc3(r12, i12.size(), nr);

        for(int i=0;i<i12.size();++i) r12[i12[i
]] = i+1;
        for(int &i: i12) i = GEI(i);
    }

    vector<int> i0;
    if(n%3==1) i0.push_back(n-1);
    for(int i=0;i<i12.size();++i) if(i12[i]%3 ==
1) i0.push_back(i12[i]-1);
    i0 = sort(v, 0, i0, m);

    vector<int> ret(v.size());
    int ptr12=0, ptr0=0, ptr=0;
    while(ptr12<i12.size() && ptr0<i0.size()){
        if(i12[ptr12]%3 == 1){
            if([&](int i, int j) -> bool{
                if(SG(v,i) != SG(v,j)) return SG
(v,i)<SG(v,j);
                return SG(r12,GRI(i+1))<SG(r12,
GRI(j+1));
            }(i12[ptr12], i0[ptr0]))ret[ptr++] =
i12[ptr12++];
            else ret[ptr++] = i0[ptr0++];
        }
        else{
            if([&](int i, int j) -> bool{

```

```

                if(SG(v,i+0) != SG(v,j+0))
return SG(v,i+0)<SG(v,j+0);
                if(SG(v,i+1) != SG(v,j+1))
return SG(v,i+1)<SG(v,j+1);
                return SG(r12,GRI(i+2))<SG(r12,
GRI(j+2));
            }(i12[ptr12], i0[ptr0]))ret[ptr++] =
i12[ptr12++];
            else ret[ptr++] = i0[ptr0++];
        }
    }
    while(ptr12<i12.size()) ret[ptr++] = i12[
ptr12++];
    while(ptr0<i0.size()) ret[ptr++] = i0[ptr0
++];

    return ret;
}
vector<int> build(string str){
    vector<int> val(str.size()+1, 0);
    for(int i=0;i<str.size();++i) val[i] = str[i
];
    return dc3(val, val.size(), 255);
}
#pragma GCC diagnostic pop
}

```

### 3.5 suffix array

```

struct SuffixArray {
    string s;
    ll n;
    vector<ll> sa,rk,hei,t;
    SuffixArray(string si): s(si),n(SZ(s)),sa(n),rk(
n),hei(n),t(n) {
        REP (i,n) {
            rk[sa[i]=i] = s[i];
        }
        t[n-1] = -1;
        for (ll h=1;t[n-1] != n-1; h <= 1) {
            auto cmp = [&](ll i,ll j) {
                if (rk[i] != rk[j]) {
                    return rk[i] < rk[j];
                } else {
                    return (i+h < n && j+h < n) ? (
rk[i+h] < rk[j+h]) : (i > j);
                }
            };
            sort(ALL(sa),cmp);
            t[0] = 0;
            REP1 (i,n-1) {
                t[i] = t[i-1] + cmp(sa[i-1],sa[i]);
            }
            REP (i,n) {
                rk[sa[i]] = t[i];
            }
        }
        ll con = 0;
        REP (i,n) {
            if (rk[i] == 0) {
                hei[0] = con = 0;
            } else {
                if (con) {
                    con--;
                }
                while (s[i+con] == s[sa[rk[i]-1]+con
]) {
                    con++;
                }
                hei[rk[i]] = con;
            }
        }
        ll operator [] (ll idx) {
            return sa[idx];
        }
    };
}

```

## 4 Graph

### 4.1 clique

```
typedef vector<bitset<200>> vb;
struct Maxclique {
    double limit=0.025, pk=0;
    struct Vertex { int i, d=0; };
    typedef vector<Vertex> vv;
    vb e;
    vv V;
    vector<vi> C;
    vi qmax, q, S, old;
    void init(vv& r) {
        trav(v,r) v.d = 0;
        trav(v, r) trav(j, r) v.d += e[v.i][j.i];
        sort(all(r), [](auto a, auto b) { return a.d > b.d; });
        int mxD = r[0].d;
        rep(i,0,sz(r)) r[i].d = min(i, mxD) + 1;
    }
    void expand(vv& R, int lev = 1) {
        S[lev] += S[lev - 1] - old[lev];
        old[lev] = S[lev - 1];
        while (sz(R)) {
            if (sz(q) + R.back().d <= sz(qmax)) return;
            q.push_back(R.back().i);
            vv T;
            trav(v,R) if (e[R.back().i][v.i]) T.push_back({v.i});
            if (sz(T)) {
                if (S[lev]++ / ++pk < limit) init(T);
                int j = 0, mxk = 1, mnk = max(sz(qmax) - sz(q) + 1, 1);
                C[1].clear(), C[2].clear();
                trav(v, T) {
                    int k = 1;
                    auto f = [&](int i) { return e[v.i][i]; };
                    while (any_of(all(C[k]), f)) k++;
                    if (k > mxk) mxk = k, C[mxk + 1].clear();
                    if (k < mnk) T[j++].i = v.i;
                    C[k].push_back(v.i);
                }
                if (j > 0) T[j - 1].d = 0;
                rep(k,mnk,mxk + 1) trav(i, C[k])
                    T[j].i = i, T[j++].d = k;
                expand(T, lev + 1);
            } else if (sz(q) > sz(qmax)) qmax = q;
            q.pop_back(), R.pop_back();
        }
    }
    vi maxClique() { init(V), expand(V); return qmax; }
    Maxclique(vb conn) : e(conn), C(sz(e)+1), S(sz(C)), old(S) {
        rep(i,0,sz(e)) V.push_back({i});
    }
};
```

### 4.2 steiner

```
// http://sunmoon-template.blogspot.com/2017/04/
// steiner-tree-problem-in-graphs.html
// choose r nodes in n nodes
// answer is max(dp[(1<r)-1][k]) k=0~n-1
// p is the terminal set
// 0( n^3 + n*3^r + n^2*2^r )
#define REP(i,n) for(int i=0;i<(int)n;++i)
const int MAXN=30,MAXM=8;// 0-base
const int INF=0x3f3f3f3f;
int dp[1<MAXM][MAXN];
int g[MAXN][MAXN];
void init(){memset(g,0x3f,sizeof(g));}
void add_edge(int u,int v,int w){
    g[u][v]=g[v][u]=min(g[v][u],w);
}
void steiner(int n,int r,int *p){
    REP(k,n)REP(i,n)REP(j,n)
        g[i][j]=min(g[i][j],g[i][k]+g[k][j]);
```

```
REP(i,n)g[i][i]=0;
REP(i,r)REP(j,n)dp[1<i][j]=g[p[i]][j];
for(int i=1;i<(1<r);++i){
    if(!(i&(i-1)))continue;
    REP(j,n)dp[i][j]=INF;
    REP(j,n){
        int tmp=INF;
        for(int s=i&(i-1);s;s=i&(s-1))
            tmp=min(tmp,dp[s][j]+dp[i^s][j]);
        REP(k,n)dp[i][k]=min(dp[i][k],g[j][k]+tmp);
    }
}
```

### 4.3 spfa

```
int spfa(vector<vector<pii>> &g){ // G contains
    pair<to, cost>
    int n = SZ(g);
    int s = 0, t = n-1; // Starting node, ending
    node
    queue<int> q ({s});
    vector<int> vis(n,0); // Don't use vector<bool>
    vector<int> dist(n,inf);
    fill(ALL(dist), inf); dist[s] = 0;
    while (!q.empty()){
        int v = q.front(); q.pop();
        vis[v] = 0;
        for (auto &xx : g[v]) {
            int u = xx.f, w = xx.s;
            if (dist[u] > dist[v] + w){
                dist[u] = dist[v] + w;
                if (!vis[u]){
                    q.push(u); vis[u] = 1;
                }
            }
        }
    }
    return dist[t];
}
```

### 4.4 global-min-cut

```
// from https://raw.githubusercontent.com/Jinkela-
// Xiao-Zuan-Feng-Mountaineer/Codebook/master/Graph
// E5%85%A8%E5%B1%80%E6%9C%80%E5%B0%8F%E5%89%B2.
// cpp
const int INF=0x3f3f3f3f;
template<typename T>
struct stoer_wagner{// 0-base
    static const int MAXN=150;
    T g[MAXN][MAXN],dis[MAXN];
    int nd[MAXN],n,s,t;
    void init(int _n){
        n=_n;
        for(int i=0;i<n;++i)
            for(int j=0;j<n;++j)g[i][j]=0;
    }
    void add_edge(int u,int v,T w){
        g[u][v]=g[v][u]+=w;
    }
    T min_cut(){
        T ans=INF;
        for(int i=0;i<n;++i)nd[i]=i;
        for(int ind,tn=n;tn>1;--tn){
            for(int i=1;i<tn;++i)dis[ind[i]]=0;
            for(int i=1;i<tn;++i){
                ind=i;
                for(int j=i;j<tn;++j){
                    dis[ind[j]]+=g[ind[i-1]][nd[j]];
                    if(dis[ind[ind]]<dis[ind[j]])ind=j;
                }
                swap(nd[ind],nd[i]);
            }
            if(ans>dis[ind])ans=dis[t=nd[ind]],s=nd[ind-1];
            for(int i=0;i<tn;++i)
```

```

        g[nd[ind-1]][nd[i]] = g[nd[i]][nd[ind-1]] + g[
nd[i]][nd[ind]];
    }
    return ans;
}
};

```

## 4.5 centroid decomp

```

int n;
vector<vector<pii>> > edge;
struct CentroidDecomp {
    struct Info {
        ll dis=0, sz=0, mi=0;
    };
    vector<Info> info;
    vector<int> dead, dep, anc, vis, sz;
    vector<vector<ll>> > dis;

    CentroidDecomp () : info(n), dead(n), dep(n),
anc(n), vis(n), sz(n) {
        int lgg = __lg(n) + 2;
        dis.resize(lgg, vector<ll>(n, 0));
        build(0, 0, -1);
    }

    int center (int nd) {
        vector<int> que = {nd};
        vis[nd] = true;
        int hd = 0;
        while (hd < SZ(que)) {
            int cur = que[hd++];
            for (auto e : edge[cur]) {
                if (!vis[e.X] && !dead[e.X]) {
                    que.pb(e.X);
                    vis[e.X] = true;
                }
            }
        }
        reverse(ALL(que));

        int cen = -1;
        for (int v : que) {
            sz[v] = 1;
            vis[v] = false;
            bool flag = true;
            for (auto e : edge[v]) {
                if (!dead[e.X] && !vis[e.X]) {
                    sz[v] += sz[e.X];
                    flag &= sz[e.X] * 2 <= SZ(que);
                }
            }
            flag &= sz[v] * 2 >= SZ(que);
            if (flag) cen = v;
        }
        return cen;
    }

    void build (int nd, int d, int rt) {
        int cen = center(nd);
        assert(cen != -1);
        dead[cen] = true;
        dep[cen] = d;
        anc[cen] = rt;

        vector<int> que = {cen};
        int hd = 0;
        while (hd < SZ(que)) {
            int cur = que[hd++];
            for (auto e : edge[cur]) {
                if (!vis[e.X] && !dead[e.X]) {
                    que.pb(e.X);
                    vis[e.X] = true;
                    dis[d][e.X] = dis[d][cur] + e.Y;
                }
            }
        }
        for (int v : que) vis[v] = false;
    }
};

```

```

        for (auto e : edge[cen]) {
            if (!dead[e.X]) {
                build(e.X, d+1, cen);
            }
        }
    }

    void upd (int nd) {
        for (int x=nd; x!=-1; x=anc[x]) {
            info[x].dis += dis[dep[x]][nd];
            info[x].sz += 1;
            if (anc[x] != -1) info[x].mi += dis[dep[
x]-1][nd];
        }
    }

    ll qry (int nd) {
        ll res = info[nd].dis;
        for (int x=nd; anc[x]!=-1; x=anc[x]) {
            res += dis[dep[x]-1][nd] * (info[anc[x
]].sz - info[x].sz);
            res += info[anc[x]].dis;
            res -= info[x].mi;
        }
        return res;
    }
};

```

## 4.6 lca

```

#include <bits/stdc++.h>
using namespace std;
const int MAXN = 15003;
const int MAXLG = __lg(MAXN) + 2;
int n,q,a,b;

int anc[MAXLG][MAXN];
int dep[MAXN];
vector<int> edge[MAXN];
void dfs(int nd,int par){
    anc[0][nd] = par;
    dep[nd] = dep[par] + 1;
    for(int v:edge[nd]){
        if(v!=par) dfs(v,nd);
    }
}
void build_lca(){
    for(int i=1;i<MAXLG;i++){
        for(int j=0;j<n;j++){
            anc[i][j] = anc[i-1][anc[i-1][j]];
        }
    }
}

int query(int u,int v){
    if(dep[u] < dep[v])swap(u,v);
    for(int i=MAXLG-1;i>=0;i--){
        if(dep[anc[i][u]] >= dep[v]) u = anc[i][u];
    }
    if(u==v)return u;

    for(int i=MAXLG-1;i>=0;i--){
        if(anc[i][u] != anc[i][v]) {
            u = anc[i][u];
            v = anc[i][v];
        }
    }
    return anc[0][u];
}

int main(){
    cin>>n>>q;
    for(int i=0;i<n-1;i++) cin>>a>>b,edge[a].
emplace_back(b),edge[b].emplace_back(a);

    dfs(0,0);
    build_lca();
    for(int i=0;i<q;i++){
        cin>>a>>b;
    }
}

```

```

        cout<<query(a,b)<<endl;
    }
}

// Doubling LCA

4.7 ap

/*
from: http://sunmoon-template.blogspot.com
*/
#include <bits/stdc++.h>
using namespace std;

const int MAXN = 100005;

std::vector<int> G[MAXN]; // 1-base
std::vector<int> bcc[MAXN];
int low[MAXN], vis[MAXN], Time;
int bcc_id[MAXN], bcc_cnt; // 1-base
bool is_cut[MAXN]; // bcc_id is undef if is_cut
int st[MAXN], top;
void dfs(int u, int pa=-1){
    int v, child=0;
    low[u]=vis[u]=++Time;
    st[top++]=u;
    for(size_t i=0; i<G[u].size(); ++i){
        if(!vis[v=G[u][i]]){
            dfs(v, u), ++child;
            low[u]=std::min(low[u], low[v]);
            if(vis[u]<=low[v]){
                is_cut[u]=1;
                bcc[++bcc_cnt].clear();
                int t;
                do{
                    bcc_id[t=st[--top]]=bcc_cnt;
                    bcc[bcc_cnt].push_back(t);
                }while(t!=v);
                bcc_id[u]=bcc_cnt;
                bcc[bcc_cnt].push_back(u);
            }
        }else if(vis[v]<vis[u]&&v!=pa) // reverse
            low[u]=std::min(low[u], vis[v]);
    }
    if(pa==-1&&child<2) is_cut[u]=0; // u for root
}

inline void bcc_init(int n){
    Time=bcc_cnt=top=0;
    for(int i=1; i<=n; ++i){
        G[i].clear();
        vis[i]=0;
        is_cut[i]=0;
        bcc_id[i]=0;
    }
}

int main () {
    int n, m;
    cin >> n >> m;
    bcc_init(n);
    for (int i=0; i<m; i++) {
        int u, v;
        cin >> u >> v;
        G[u].emplace_back(v);
        G[v].emplace_back(u);
    }

    dfs(1);
    for (int i=1; i<=n; i++) {
        cout << (is_cut[i] ? -1 : bcc_id[i]) << " \n"
        "[i==n];
    }
}

```

## 4.8 bridge

```

/*
from: http://sunmoon-template.blogspot.com

```

```

*/
#include <bits/stdc++.h>
using namespace std;

const int MAXN = 100005;
struct edge{
    int u, v;
    bool is_bridge;
    edge(int u=0, int v=0):u(u),v(v),is_bridge(0){}
};
std::vector<edge> E;
std::vector<int> G[MAXN]; // 1-base
int low[MAXN], vis[MAXN], Time;
int bcc_id[MAXN], bridge_cnt, bcc_cnt; // 1-base
int st[MAXN], top; // for bcc
inline void add_edge(int u, int v){
    G[u].push_back(E.size());
    E.push_back(edge(u, v));
    G[v].push_back(E.size());
    E.push_back(edge(v, u));
}
void dfs(int u, int re=-1){ // re is last edge
    int v;
    low[u]=vis[u]=++Time;
    st[top++]=u;
    for(size_t i=0; i<G[u].size(); ++i){
        int e=G[u][i]; v=E[e].v;
        if(!vis[v]){
            dfs(v, e^1); // e^1 reverse
            low[u]=std::min(low[u], low[v]);
            if(vis[u]<low[v]){
                E[e].is_bridge=E[e^1].is_bridge=1;
                ++bridge_cnt;
            }
        }else if(vis[v]<vis[u]&&e!=re)
            low[u]=std::min(low[u], vis[v]);
    }
    if(vis[u]==low[u]){ // build bcc
        ++bcc_cnt; // 1-base
        do bcc_id[v=st[--top]]=bcc_cnt;
        while(v!=u);
    }
}

inline void bcc_init(int n){
    Time=bcc_cnt=bridge_cnt=top=0;
    E.clear();
    for(int i=1; i<=n; ++i){
        G[i].clear();
        vis[i]=0;
        bcc_id[i]=0;
    }
}

int main () {
    int n, m;
    cin >> n >> m;
    bcc_init(n);
    for (int i=0; i<m; i++) {
        int u, v;
        cin >> u >> v;
        add_edge(u, v);
    }

    dfs(1);
    for (int i=1; i<=n; i++) {
        cout << bcc_id[i] << " \n" [i==n];
    }
}

```

## 4.9 scc

## 4.10 dijkstra

```

#include <bits/stdc++.h>
using namespace std;
typedef long long ll;
typedef pair<int, int> pii;
#define REP(i, n) for(int i=0; i<n; i++)

```

```

#define REP1(i,n) for(int i=1;i<=n;i++)
#define X first
#define Y second
const int MAXN = 1000003;
const int INF = (int)0x3f3f3f3f;
int n,m,s,g,a,b,v;

int dis[MAXN];
bool vis[MAXN];
vector<pii> e[MAXN];

int dijkstra (int s, int t) {
    memset(dis,INF,(n+1)*4);
    memset(vis,0,(n+1)*4);

    dis[s] = 0;
    priority_queue<pii,vector<pii>,greater<pii>> pq;
    pq.emplace(0,s);
    REP(i,n){
        int found = -1;
        while(pq.size() && vis[found=pq.top().Y]) pq.pop();
        if(found==-1) break;
        vis[found]=1;
        for(auto vp:e[found]){
            if(dis[vp.X]>dis[found]+vp.Y){
                dis[vp.X] = dis[found]+vp.Y;
                pq.emplace(dis[vp.X],vp.X);
            }
        }
    }
}

void add_edge (int f, int t, int w) {
    e[f].emplace_back(t, w);
}

int main(){
    ios_base::sync_with_stdio(0);cin.tie(0);
    while(cin>>n>>m>>s>>g){
        REP(i,m){
            cin>>a>>b>>v;
            add_edge(a, b, v);
        }

        cout<<(dis[g]==INF?-1:dis[g])<<'\n';
    }
}

```

## 4.11 DynamicConnectivity

```

template <typename pNode>
struct Emap {
    vector<map<int, pNode>> data;
    inline void init(int n) { data.resize(n); }
    inline pNode& operator[](const pii p) { return data[p.ff][p.ss]; }
    inline bool has(const pii p) { return data[p.ff].find(p.ss) != data[p.ff].end(); }
    inline void erase(const pii p) { data[p.ff].erase(p.ss); }
};

class ETT {
public:
    int n, llv;

private:
    struct Node;
    typedef Node* pNode;
    typedef pair<pNode, pNode> ppN;

    static int size(pNode p) { return p ? p->sz : 0; }

    struct Node {
        pii e;
        pNode L = NULL, R = NULL, P = NULL;
    };
}

```

```

int sz = 1;
int llv;
set<int> Edges[2];
bool hasE[2] = {};
inline bool isLeft() { return P && P->L == this; }
inline bool isRight() { return P && P->R == this; }
inline bool isRoot() { return !isLeft() && !isRight(); }
inline pNode& get(bool i) { return !i ? L : R; } // 0 - LEFT
inline pNode setCH(bool i, pNode ch) {
    ch->P = this;
    get(i) = ch;
    return this;
}

inline pNode getLast() { return R ? R->getLast() : this; }
inline pNode up() {
    sz = 1 + size(L) + size(R);
    for (int i = 0; i < 2; i++) {
        hasE[i] = !Edges[i].empty();
        if (L)
            hasE[i] |= L->hasE[i];
        if (R)
            hasE[i] |= R->hasE[i];
    }
    return this;
}

Node(pii p, int l) : e{ p }, llv{ l } {}
pNode find_first(bool lt) {
    if (L && L->hasE[lt])
        return L->find_first(lt);
    if (!Edges[lt].empty())
        return this;
    return R->find_first(lt);
}

inline void insertEdge(bool lt, int d) {
    splay();
    Edges[lt].insert(d);
    up();
}

inline void eraseEdge(bool lt, int d) {
    splay();
    Edges[lt].erase(d);
    up();
}

inline void rotate(const bool dir) {
    pNode x = get(!dir);
    get(!dir) = x->get(dir);
    x->get(dir) = this;
    x->P = P;
    if (P) {
        if (P->L == this) P->L = x;
        if (P->R == this) P->R = x;
    }
    P = x;
    if (get(!dir))
        get(!dir)->P = this;
    up();
    x->up();
}

inline void rotateTop() { P->rotate(isLeft()); }

inline void splay(pNode rt = NULL) {
    while (P != rt) {
        if (P->P != rt)
            ((P->isLeft() == isLeft()) ? P : this)->rotateTop();
        rotateTop();
    }
}

pNode setFirst(pNode p) {
    if (!p) return p;
    p->splay();
    if (!p->R) swap(p->R, p->L); // , p->up();
    else if (p->L) {

```



```

        p->getLast()->splay(p);
        p->R->setCH(1, p->L)->up();
        p->L = NULL;
        p->up();
    }
    return p;
}
Emap<pNode> Epos;
vector<Node> Ppos;
inline bool onSameTree(pNode a, pNode b) {
    return a && b && (a == b || (a->splay(), b->
splay(), a->P));
}
inline pNode create(pii e) {
    return Epos.has(e) ? Epos[e] : Epos[e] = new
Node(e, llv);
}

public:
ETT(int _n, int lv) : n{_n}, llv{lv} {
    Epos.init(n);
    for (int i = 0; i < n; i++)
        Ppos.emplace_back(make_pair(i, i), llv);
}
inline bool onSameTree(int a, int b) { return
onSameTree(&Ppos[a], &Ppos[b]); }
inline bool hasEdge(pii e) { return Epos.has(e);
}
inline void link(pii p) {
    pNode l = setFirst(&Ppos[p.ff]), r =
setFirst(&Ppos[p.ss]);
    create(swp(p))->setCH(0, create(p)->setCH(0,
l)->setCH(1, r)->up())->up();
}
int cnt = 0;
inline void link(int a, int b) { link({ a, b });
}
void cut(pii p) {
    if (!hasEdge(p))
        return;
    pNode fs = Epos[p], ls = Epos[swp(p)];
    setFirst(fs);
    if (fs->R)
        fs->R->P = NULL;
    fs->R = NULL;
    ls->splay();
    if (ls->L)
        ls->L->P = NULL;
    if (ls->R)
        ls->R->P = NULL;
    Epos.erase(p);
    Epos.erase(swp(p));
    delete fs;
    delete ls;
}
inline void cut(int a, int b) { cut({ a, b }); }
inline int size(int a) { return Ppos[a].splay(),
(Ppos[a].sz + 2) / 3; }
inline void addEdge(bool lt, pii e) {
    Ppos[e.ff].insertEdge(lt, e.ss);
    Ppos[e.ss].insertEdge(lt, e.ff);
    if (lt)
        link(e);
}
inline void remEdge(bool lt, pii e, bool ct =
true) {
    Ppos[e.ff].eraseEdge(lt, e.ss);
    Ppos[e.ss].eraseEdge(lt, e.ff);
    if (lt && ct)
        cut(e);
}
void forEach(bool lt, int start, function<bool(
pii)> func) {
    Ppos[start].splay();
    for (pNode i = &Ppos[start]; i && i->hasE[lt
]; i = i->R) {
        (i = i->find_first(lt))->splay();
        for (auto j : i->Edges[lt])
            if (func({ i->e.ff, j }))
                return;
    }
}

        return;
        i->splay();
    }
}

struct DyG {
    vector<ETT> ETts;
    map<pair<int, int>, int> lvl;
    int lgn, n;
    inline int& level(pii p) { return lvl[norm(p)];
}
    inline bool hasEdge(pii p) { return lvl.find(
norm(p)) != lvl.end(); }
    inline void eraselvl(pii p) { lvl.erase(norm(p))
; }
    DyG(int _n) : n{_n}, lgn{__lg(n)} {
        for (int i = 0; i <= lgn; i++)
            ETts.emplace_back(n, i);
    }
    inline bool isConnected(int a, int b) { return
ETts[lgn].onSameTree(a, b); }
    inline void decrlvl(bool lt, pii e, int l = -1)
{
        int& lv = level(e);
        ETts[lv].remEdge(lt, e, false);
        ETts[--lv].addEdge(lt, e);
    }
    inline void add(int a, int b) {
        if (hasEdge({ a, b })) return;
        level({ a, b }) = lgn;
        ETts[lgn].addEdge(!isConnected(a, b), { a, b
});
    }
    void remove(pii e) {
        if (!hasEdge(e)) return;
        int l = level(e);
        eraselvl(e);
        bool hasEdge = ETts[lgn].hasEdge(e);
        ETts[l].remEdge(hasEdge, e);
        if (!hasEdge) return;
        for (int i = l; i <= lgn; i++) {
            ETts[i].cut(e);
            if (ETts[i].size(e.ff) > ETts[i].size(e.
ss))
                e = { e.ss, e.ff };
            set<pii> tobe;
            ETts[i].forEach(true, e.ff, [&](pii p) {
                tobe.insert(norm(p));
                return false;
            });
            for (auto p : tobe)
                decrlvl(true, p, i);
            tobe.clear();
            pii ans = { -1, -1 };
            ETts[i].forEach(false, e.ff, [&](pii p)
{
                if (ETts[i].onSameTree(p.ss, e.ss))
                    return ans = p, true;
                tobe.insert(norm(p));
                return false;
            });
            for (auto p : tobe)
                decrlvl(false, p, i);
            if (ans != (pii) { -1, -1 }) {
                ETts[i].remEdge(false, ans);
                ETts[i].addEdge(true, ans);
                for (int lv = i + 1; lv <= lgn; lv
++)
                    ETts[lv].cut(e), ETts[lv].link(
ans);
                return;
            }
        }
    }
    inline void remove(int a, int b) { remove({ a, b
}); }
}

```



```
};
```

## 4.12 hld

```
#include <bits/stdc++.h>
using namespace std;

const int MAXN = 10003;

struct edge{
    int u,v,w,n;
}e[MAXN*2];

int t,n,a,b,c;
int dep[MAXN],sz[MAXN],fat[MAXN],son[MAXN],top[MAXN];
int in[MAXN],cnt,idx,head[MAXN];
int sg[MAXN*2];
char cmd[10];

void add_edge(int u,int v,int w){
    e[cnt].u = u;
    e[cnt].v = v;
    e[cnt].w = w;
    e[cnt].n = head[u];
    head[u] = cnt++;
}

void dfs1 (int nd,int par) {
    dep[nd] = dep[par] + 1;
    sz[nd] = 1;
    fat[nd] = par;
    son[nd] = 0;
    for (int i=head[nd];i!=-1;i=e[i].n) {
        if (e[i].v==par) continue;
        dfs1(e[i].v,nd);
        sz[nd] += sz[e[i].v];
        if(sz[e[i].v] > sz[son[nd]]) son[nd] = e[i].v;
    }
}

void dfs2 (int nd,int tp) {
    in[nd] = idx++;
    top[nd] = tp;
    if (son[nd]) dfs2(son[nd],tp);
    for (int i=head[nd];i!=-1;i=e[i].n) {
        if (e[i].v==fat[nd] || e[i].v==son[nd]) continue;
        dfs2(e[i].v,e[i].v);
    }
}

int qpath (int x,int y) {
    int ret = 0;
    while (top[x] != top[y]) {
        if (dep[top[x]] < dep[top[y]]) swap(x,y);
        // ret = max(ret,query(in[top[x]],in[x]+1));
        x = fat[top[x]];
    }
    if(x==y)return ret;
    if (dep[x] < dep[y]) swap(x,y);
    // ret = max(ret,query(in[son[y]],in[x]+1));
    return ret;
}
```

## 5 FlowAndMatching

### 5.1 hlpp

```
// from https://www.lagou.com/lgeduarticle/82099.
html
#include<bits/stdc++.h>
#define il inline
#define inc(i,j,k) for(int i=j;i<=k;++i)
#define ra(i,u) for(int i=head[u];i!=-1;i=a[i].nxt)
#define ll long long
#define inf 0x3f3f3f3f
using namespace std;
```

```
const int maxm=120010;
const int maxn=2010;
struct node
{
    int to,nxt,flow;
}a[maxm<<1];
int head[maxn],gap[maxn],h[maxn],e[maxn];
bool vis[maxn];
int cnt=-1,n,m,st,ed;
struct cmp {il bool operator () (int x,int y) const{
    return h[x]<h[y];}};
priority_queue<int,vector<int>,cmp> pq;
queue<int> q;
il void add(int u,int v,int w)
{
    a[++cnt].to=v;
    a[cnt].nxt=head[u];
    a[cnt].flow=w;
    head[u]=cnt;
}
il bool bfs()
{
    memset(h,inf,sizeof(h));
    h[ed]=0;
    q.push(ed);
    while(!q.empty())
    {
        int t=q.front();
        q.pop();
        ra(i,t)
        {
            int v=a[i].to;
            if(a[i].flow && h[v]>h[t]+1)
            {
                h[v]=h[t]+1;
                q.push(v);
            }
        }
    }
    return h[st]!=inf;
}
il void push(int u)
{
    ra(i,u)
    {
        int v=a[i].to;
        if((a[i].flow) && (h[v]+1==h[u]))
        {
            int df=min(e[u],a[i].flow);
            a[i].flow-=df;
            a[i].flow+=df;
            e[u]-=df;
            e[v]+=df;
            if((v!=st)&&(v!=ed)&&(!vis[v]))
            {
                pq.push(v);
                vis[v]=1;
            }
            if(!e[u])break;
        }
    }
}
il void relabel(int u)
{
    h[u]=inf;
    ra(i,u)
    {
        int v=a[i].to;
        if((a[i].flow)&&(h[v]+1<h[u]))h[u]=h[v]+1;
    }
}
inline int hlpp()
{
    if(!bfs())return 0;
    h[st]=n;
    memset(gap,0,sizeof(gap));
    inc(i,1,n) if(h[i]!=inf)gap[h[i]]++;
    ra(i,st)
    {
```

```

    int v=a[i].to;
    if(int f=a[i].flow)
    {
        a[i].flow-=f;a[i^1].flow+=f;
        e[st]-=f;e[v]+=f;
        if(v!=st&&v!=ed&&!vis[v])
        {
            pq.push(v);
            vis[v]=1;
        }
    }
}
while(!pq.empty())
{
    int t=pq.top();pq.pop();
    vis[t]=0;push(t);
    if(e[t])
    {
        gap[h[t]]--;
        if(!gap[h[t]])
        {
            inc(v,1,n)
            {
                if(v!=st&&v!=ed&&h[v]>h[t]&&h[v]
                <n+1)
                {
                    h[v]=n+1;
                }
            }
            relabel(t);gap[h[t]]++;
            pq.push(t);vis[t]=1;
        }
    }
    return e[ed];
}
signed main()
{
    memset(head,-1,sizeof(head));
    scanf("%d%d%d%d",&n,&m,&st,&ed);
    inc(i,1,m)
    {
        int x,y;
        ll f;
        scanf("%d%d%lld",&x,&y,&f);
        add(x,y,f);
        add(y,x,0);
    }
    ll maxf=hlpp();
    printf("%lld",maxf);
    return 0;
}

```

## 5.2 dinic

```

struct Dinic{
    struct Edge{
        int to, rev; ll cap, flow=0;
        Edge(int to,int rev, ll cap) : to(to), rev(
        rev), cap(cap) {}
    };

    vector<vector<Edge> > g;
    int n;
    int s, t;
    vector<int> level, ptr;
    Dinic(int n, int s, int t):n(n),s(s),t(t){
        level.resize(n,-1); ptr.resize(n); g.resize(
        n);
    }
    void add(int v, int u, ll cap){
        g[v].pb({u,SZ(g[u]),cap});
        g[u].pb({v,SZ(g[v])-1,0});
    }
    bool bfs(){ // Build layers with edges on the
    residual graph that aren't full
        queue<int> q({s});
        level[s] = 0;
        while (!q.empty() && level[t] == -1){

```

```

            int v = q.front(); q.pop();
            for (auto &e : g[v]){
                if (e.cap - e.flow ==0) continue;
                int u = e.to;
                if (level[u]==-1){
                    level[u] = level[v]+1; q.push(u)
                }
            }
            return level[t]!=-1;
        }
    }
    ll dfs(int v, ll amt){ // Returns flow amount of
    any flow on bfs graph
        if (amt == 0 || v==t) return amt;
        for (; ptr[v] <SZ(g[v]); ptr[v]++){
            Edge &e = g[v][ptr[v]];
            int u = e.to;
            if (level[u] == level[v]+1){
                ll tt = dfs(u,min(amt, e.cap - e.
                flow));
                if (tt==0) continue;
                e.flow+=tt; g[e.to][e.rev].flow-=tt;
                return tt;
            }
        }
        return 0;
    }
    ll mf(){
        ll re = 0;
        while (bfs()){
            while (ll amt = dfs(s,inf)) re += amt;
        }
        // Basically ford fulkerson, but on layered
        graph
        fill(ALL(level), -1); fill(ALL(ptr), 0);
        return re;
    }
};

signed main(){
    int n = 100;
    int N = n+5; int s = N-1, t = N-2;
    Dinic dd (N,s,t);
    int mf = dd.mf();
}

```

## 5.3 km o3

```

// from http://sunmoon-template.blogspot.com
//2016/05/kuhn-munkres-algorithm.html
#define MAXN 100
#define INF INT_MAX
int g[MAXN][MAXN],lx[MAXN],ly[MAXN],slack_y[MAXN];
int px[MAXN],py[MAXN],match_y[MAXN],par[MAXN];
int n;
void adjust(int y){
    match_y[y]=py[y];
    if(px[match_y[y]]!=-2)
        adjust(px[match_y[y]]);
}
bool dfs(int x){
    for(int y=0;y<n;++y){
        if(py[y]!=-1)continue;
        int t=lx[x]+ly[y]-g[x][y];
        if(t==0){
            py[y]=x;
            if(match_y[y]==-1){
                adjust(y);
                return 1;
            }
            if(px[match_y[y]]!=-1)continue;
            px[match_y[y]]=y;
            if(dfs(match_y[y]))return 1;
        }else if(slack_y[y]>t){
            slack_y[y]=t;
            par[y]=x;
        }
    }
    return 0;
}
inline int km(){

```

```

memset(ly,0,sizeof(int)*n);
memset(match_y,-1,sizeof(int)*n);
for(int x=0;x<n;++x){
    lx[x]=-INF;
    for(int y=0;y<n;++y){
        lx[x]=max(lx[x],g[x][y]);
    }
}
for(int x=0;x<n;++x){
    for(int y=0;y<n;++y) slack_y[y]=INF;
    memset(px,-1,sizeof(int)*n);
    memset(py,-1,sizeof(int)*n);
    px[x]=-2;
    if(dfs(x)) continue;
    bool flag=1;
    while(flag){
        int cut=INF;
        for(int y=0;y<n;++y)
            if(py[y]==-1&&cut>slack_y[y]) cut=slack_y[y];
        for(int j=0;j<n;++j){
            if(px[j]!=-1) lx[j]-=cut;
            if(py[j]!=-1) ly[j]+=cut;
            else slack_y[j]-=cut;
        }
        for(int y=0;y<n;++y){
            if(py[y]==-1&&slack_y[y]==0){
                py[y]=par[y];
                if(match_y[y]==-1){
                    adjust(y);
                    flag=0;
                    break;
                }
                px[match_y[y]]=y;
                if(dfs(match_y[y])){
                    flag=0;
                    break;
                }
            }
        }
    }
}
int ans=0;
for(int y=0;y<n;++y) if(g[match_y[y]][y]!=-INF) ans
    +=g[match_y[y]][y];
return ans;
}

```

## 5.4 bipartite matching

```

#include <bits/stdc++.h>
using namespace std;

const int MAXN = 1003;
int mx[MAXN],my[MAXN];
bool vy[MAXN];
vector<int> edge[MAXN];

int n, m;
int greedy_matching()
{
    int c = 0;
    for (int x=1; x<=n; ++x) {
        if (mx[x] == -1) {
            for (auto y : edge[x]) {
                if (my[y] == -1) {
                    mx[x] = y; my[y] = x;
                    c++;
                    break;
                }
            }
        }
    }
    return c;
}

bool DFS(int x)
{
    for (auto y : edge[x]) {
        if (!vy[y]) {

```

```

            vy[y] = true;
            if (my[y] == -1 || DFS(my[y]))
            {
                mx[x] = y; my[y] = x;
                return true;
            }
        }
    }
    return false;
}

int bipartite_matching()
{
    memset(mx, -1, sizeof(mx));
    memset(my, -1, sizeof(my));

    int c = greedy_matching();

    for (int x=1; x<=n; ++x)
        if (mx[x] == -1)
        {
            memset(vy, false, sizeof(vy));
            if (DFS(x)) c++;
        }
    return c;
}

int main () {
    cin >> n >> m;
    int ecnt;
    cin >> ecnt;
    while (ecnt--) {
        int f,t;
        cin >> f >> t;
        edge[f].emplace_back(t);
    }

    cout << bipartite_matching() << endl;
}

```

## 5.5 LowerBoundFlow

```

// Determining solution for bounded flow system
// without source and sink
int n, m; cin>>n>>m;
vector<int> sumin(n,0), sumout(n,0);
int N = n+5; int SS = N-1, TT = N-2; // New source
// and new sink
Dinic dd(N,SS,TT); // Need to call Dinic
// implementation
ll totlow = 0;
REP(cnt, m){
    int a, b, l, u; cin>>a>>b>>l>>u; a--; b--; // l
    // is lower bound, u is upper bound
    sumout[a] += l; sumin[b] += l;
    dd.add(a,b,u-l); totlow+=l;
}
// For bounded flow with source and sink, simply add
// edge from t to s with infinite capacity and do
// the same thing
REP(i,n){
    dd.add(SS,i,sumin[i]); dd.add(i,TT,sumout[i]);
}
ll f = dd.mf();
if (f == totlow)
    cout<<"YES\n";
else
    cout<<"NO\n";
}

```

## 5.6 matching

## 5.7 km o4

```

const int mxn = 100;

bool vx[mxn], vy[mxn]; // Visited x or y
int my[mxn]; // Match of y

```

```

ll slk[mxn], lx[mxn], ly[mxn]; // Slack (on y),
    value on x, value on y
int g[mxn][mxn]; // Adjacency matrix with weights
int n;

bool dfs(int v){
    vx[v] = 1;
    REP(i,n){
        if (vy[i]) continue;
        if (g[v][i] == lx[v] + ly[i]) {
            vy[i] = 1;
            if (my[i]==-1 || dfs(my[i])){
                my[i] = v; return 1;
            }
        }else{
            MN(slk[i], lx[v] + ly[i] - g[v][i]);
        }
    }
    return 0;
}

ll mxmch(){
    REP(i,n) REP(j,n) MX[lx[i], g[i][j]];
    fill(my, my+n, -1);
    REP(i,n){
        while (1){
            fill(vx, vx+n, 0); fill(vy, vy+n, 0);
            fill(slk, slk+n, inf);
            if (dfs(i)) break;
            ll hv = *min_element(slk, slk+n);
            REP(i,n) if (vx[i]) lx[i] -= hv;
            REP(i,n) if (vy[i]) ly[i] += hv;
        }
    }
    ll re = 0;
    REP(i,n) re += g[my[i]][i];
    return re;
}

```

## 5.8 VKMV

```

const int MX = 507;

ll a[MX][MX];

using T = ll;
T hungary(int n, int m) { // N is size of left set,
    M is size of right set
    vector<T> u(n + 1), v(m + 1);
    vector<int> p(m + 1), way(m + 1);
    for (int i = 1; i <= n; ++i) {
        p[0] = i;
        int j0 = 0;
        vector<T> minv (m + 1, INF);
        vector<char> used (m + 1, 0);
        while (p[j0] != 0) {
            used[j0] = 1;
            int i0 = p[j0], j1 = 0;
            T d = INF;
            for (int j = 1; j <= m; ++j)
                if (!used[j]) {
                    T cur = a[i0][j] - u[i0] - v[j];
                    if (cur < minv[j])
                        minv[j] = cur, way[j] = j0;
                    if (minv[j] < d)
                        d = minv[j], j1 = j;
                }
            for (int j = 0; j <= m; ++j)
                if (used[j])
                    u[p[j]] += d, v[j] -= d;
                else
                    minv[j] -= d;
            j0 = j1;
        }
        do {
            int j1 = way[j0];
            p[j0] = p[j1];
            j0 = j1;
        } while (j0);
    }
}

```

```

}

vector<int> ans (n + 1);
for (int j = 1; j <= m; ++j)
    ans[p[j]] = j;
T cost = -v[0];
return cost;
}

```

## 5.9 mcmf

```

struct MCMF{
    int n, s, t;
    struct Edge{
        int to, rev;
        ll cost, cap, flow=0; // Can have negative
        flow!!!!
        Edge(int to, int rev, ll cost, ll cap): to(
            to), rev(rev), cost(cost), cap(cap) {}
    };
    vector<int> par, id;
    vector<ll> dist;
    vector<vector<Edge>> g;
    MCMF(int n,int s,int t): n(n), s(s), t(t){
        par.resize(n); id.resize(n); dist.resize(n,
            inf);
        g.resize(n);
    }
    void add(int v, int u, ll f, ll c){
        g[v].pb({u,SZ(g[u]),c,f});
        g[u].pb({v,SZ(g[v])-1,-c,0});
    }
    bool spfa(){ // SPFA
        queue<int> q ({s});
        vector<int> vis(n,0);
        fill(ALL(dist), inf); dist[s] = 0;
        while (!q.empty()){
            int v = q.front(); q.pop();
            vis[v] = 0;
            for (int i = 0; i<SZ(g[v]); i++){
                Edge &e = g[v][i];
                if (e.cap - e.flow==0) continue;
                if (dist[e.to] > dist[v] + e.cost){
                    dist[e.to] = dist[v] + e.cost;
                    par[e.to] = v; id[e.to] = i;
                    if (!vis[e.to]){
                        q.push(e.to); vis[e.to] = 1;
                    }
                }
            }
        }
        return dist[t] != inf;
    }
    pair<ll, ll> mf(){
        pair<ll, ll> re = {0,0};
        while (spfa()){
            ll famt = inf;
            for (int v = t; v!=s; v = par[v]){
                Edge &e = g[par[v]][id[v]];
                MN(famt, e.cap - e.flow);
            }
            for (int v = t; v!=s; v = par[v]){
                Edge &e = g[par[v]][id[v]];
                e.flow += famt;
                g[e.to][e.rev].flow -= famt;
            }
            re.f += famt;
            re.s += dist[t] * famt;
        }
        return re;
    }
};

```

## 5.10 blossom

```

// from sunmoon template
#define MAXN 505
vector<int> g[MAXN];
int pa[MAXN], match[MAXN], st[MAXN], S[MAXN], vis[MAXN];

```

```

int t,n;
inline int lca(int u,int v){
    for(++t;;swap(u,v)){
        if(u==0) continue;
        if(vis[u]==t) return u;
        vis[u]=t;
        u=st[pa[match[u]]];
    }
}
#define qpush(u) q.push(u),S[u]=0
inline void flower(int u,int v,int l,queue<int> &q){
    while(st[u]!=1){
        pa[u]=v;
        if(S[v==match[u]]==1) qpush(v);
        st[u]=st[v]=1,u=pa[v];
    }
}
inline bool bfs(int u){
    for(int i=1;i<=n;++i) st[i]=i;
    memset(S+1,-1,sizeof(int)*n);
    queue<int> q; qpush(u);
    while(q.size()){
        u=q.front(),q.pop();
        for(size_t i=0;i<g[u].size();++i){
            int v=g[u][i];
            if(S[v]==-1){
                pa[v]=u,S[v]=1;
                if(!match[v]){
                    for(int lst=u;v!=lst,u=pa[v]){
                        lst=match[u],match[u]=v,match[v]=u;
                        return 1;
                    }
                }
                qpush(match[v]);
            } else if(!S[v]&&st[v]!=st[u]){
                int l=lca(st[v],st[u]);
                flower(v,u,l,q),flower(u,v,l,q);
            }
        }
    }
    return 0;
}
inline int blossom(){
    memset(pa+1,0,sizeof(int)*n);
    memset(match+1,0,sizeof(int)*n);
    int ans=0;
    for(int i=1;i<=n;++i)
        if(!match[i]&&bfs(i)) ++ans;
    return ans;
}

```

## 6 MISC

### 6.1 template

```

#include <bits/stdc++.h>
#pragma GCC optimize("unroll-loops,no-stack-
    protector")
using namespace std;
typedef long long ll;
typedef long long lld;
typedef long double ld;
typedef pair<int,int> pii;
typedef pair<ll,ll> pll;
typedef pair<ld,ld> pdd;
#define ALL(a) a.begin(),a.end()
#define all(a) (a).begin(),(a).end()
#define SZ(a) ((int)a.size())
#define F first
#define S second
#define ff first
#define ss second
#define REP(i,n) for(int i=0;i<((int)n);i++)
#define eb emplace_back
#define pb push_back
#define MP(a,b) make_pair(a,b)
#define SORT_UNIQUE(c) (sort(c.begin(),c.end()), c.
    resize(distance(c.begin(),unique(c.begin(),c.end()
    ())))))

```

```

#define GET_POS(c,x) (int)(lower_bound(c.begin(),c.
    end(),x)-c.begin())
#define EL cout<<'\\n'
#define BS(a,x) binary_search(ALL(a),x)

template<typename T> void _do(T &&x){cerr<<x<<endl;}
template<typename T, typename ...S> void _do(T &&x,
    S &&...y){cerr<<x<<" ";_do(y...);}
template<typename It> ostream& _printRng(ostream &os
    ,It bg,It ed)
{
    for(It it=bg;it!=ed;it++) {
        os<<(it==bg?" ":" ")<<*it;
    }
    return os;
}
template<typename T1,typename T2>
ostream& operator<<(ostream& out,pair<T1,T2> P){
    out<<'('<<P.F<<" ", "<<P.S<<'>';
    return out;
}
template<typename T> ostream &operator << (ostream &
    os,vector<T> &v){return _printRng(os,v.begin(),
    v.end());}
#define ifdef uta
#define debug(...) fprintf(stderr,"%d: %s = ",
    __LINE__,__VA_ARGS__),_do(__VA_ARGS__);
#define IOS
#define else
#define debug(...)
#define IOS ios_base::sync_with_stdio(0); cin.tie(0)
#define endl '\\n'
#define endif

const ll maxn=300005;
const ll maxlg=20;
const ll INF64=1e18;
const int INF=0x3f3f3f3f;
const ll MOD=11(1e9+7);
const ld PI=acos(-1);
const ld eps=1e-9;
//const ll p=880301;
//const ll P=31;

ll mypow(ll a,ll b){
    ll res=1LL;
    while(b){
        if(b&1) res=res*a%MOD;
        a=a*a%MOD;
        b>>=1;
    }
    return res;
}

```

```

int main(){
    IOS;

    return 0;
}

```

### 6.2 raw string

```

#include <bits/stdc++.h>
using namespace std;
int main () {
    string str1 = R"("\'\"^&*())");
    cout << str1 << endl;
}

```

### 6.3 pb ds

```

#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace __gnu_pbds;
tree<int,null_type,less<int>, rb_tree_tag,
    tree_order_statistics_node_update> rk_tree;

```

## 6.4 Random

```
main(){
    IOS();
    mt19937 rng(chrono::steady_clock::now().
time_since_epoch().count());
    // Basically the same as rand()
    vector<int> v(10); iota(ALL(v),1);
    shuffle(ALL(v), rng); // Use instead of
    random_shuffle
    for (int x : v) cout<<x<<' ';
    cout<<"Random number [0,100): "<<rng()%100<<endl
    ;
}
```

## 6.5 vimrc

```
set nu rnu bs=2 cin cul et sw=4 sts=4 ts=4 hls
syntax on
inoremap {<CR> {<CR>}<Esc>O
nnoremap <Space> :noh<CR>
```