PROJECT 2: HEUN'S METHOD

Abstract

In this project, I modelled the projectile motion of a baseball including the effect of drag force, using the Heun's method. The maximum altitude and range calculated by this model turned out to be 107.3m and 609.45m respectively. I decided to confirm the validity of Heun's method by comparing it to the analytical physics results. To accomplish this, the drag coefficient, C, was set to zero because the analytical physics method doesn't take drag force into consideration. With this i got a percentage error of maximum altitude and range to be 0.0023% and 0.59% respectively when comparing the results from Heun's method to the analytical physics results.

Description

Heun's method may refer to the improved or modified Euler's method, or a similar two-stage Runge-Kutta method. It is named after Karl Heun and is a numerical procedure for solving ordinary differential equations with a given initial value. The Euler method has a serious flaw in its approach to determining the slope to use in taking each step of the iteration. The iteration step from x_i to x_{i+1} uses only the slope at the endpoint x_i of the interval. Heun's Method has a general formula:

 $s_3 = s_1 + rac{1}{2}(f_1 + f_2)\Delta x$ Heun's method involves evaluating the slope, f(s,x), at s_0 , extrapolating out to $x_1+\Delta x$, finding s_1 , using the value of s_1 evaluate the slope, $f(s_1, x_1)$. One would notice that the value of the first slope underestimated the change in s, while the value of the second slope overestimated the change in s. Heun's method requires you to find the average of these slopes and use it to find the actual next value of s.

Algorithm and Discussion

I am modeling a baseball in flight, but including the effect of air drag. I assumed the baseball was launched with an initial speed of 80 m/s in

This method is more accurate the Euler's.

a direction 35 degrees above the horizontal. The magnitude of the drag force is given by: $f_d = rac{1}{2} C_d A
ho v^2$

Where
$$C_d$$
 is the drag coefficient (around 1), A is the cross sectional area of the ball, ρ is the density of the air and v is the speed of the ball (magnitude of velocity).

(magnitude of velocity). I used Heun's method to find the trajectory of the ball and, in particular, the maximum altitude and range (distance from the batter where the

ball reaches the ground). In addition to the velocity of the baseball, i also want to track the position. I did this by applying the concept of coupled equations. Where i defined the state as not just the velocity, but include both the velocity and the position. Position and the velocity are related by yet another first order differential equation:

ation to outcome,
$$s = a$$

So introduced the position y by adding a second first order equation to our system. Position and velocity will both be two component vectors because the baseball was launched at an angle, so the state vector, s = array([y, v]), will have four components over all.

%matplotlib inline

In [1]:

Implementation and code

```
import pandas as pd
        import matplotlib.pyplot as pl
        import numpy as np
In [2]: y0 = 0.0
        x0 = 0.0
                              #m
        v0 = 80.0
                             #m/s
        vx = v0*np.cos(35.0 * (np.pi/180.0))
                                                  #m/s
        vy = v0*np.sin(35.0 * (np.pi/180.0))
                                                 #m/s
        m = 0.145 \# kg
        dt = 0.1
        C = 1
        t = 0.0
        A = 0.0042
                   #kg/m^3
        rho = 1.3
        g = np.array([0, -9.81])
        s = np.array([x0, y0, vx, vy])
        def derivs(s, t):
            Position = s[0:2]
            Velocity = s[2:4]
            drdt = Velocity
            f_drag = -0.5 * C * A * rho * np.sqrt((Velocity * Velocity).sum()) * Velocity
            dvdt = ((m * g) + f drag) / m
            return np.array([Velocity[0], Velocity[1], dvdt[0], dvdt[1]])
        ylist = [y0]
        tlist = [t]
        y2list = [y0]
        xlist = [x0]
        maxhmaxt = [0, 0]
        def HeunStep(s, t, derivs, dt):
            f1=derivs(s,t)
            f2=derivs(s+f1*dt,t+dt)
            return s + 0.5*(f1+f2)*dt
        while s[1] >= 0:
            s = HeunStep(s, t, derivs, dt)
            y = (0.5*g[1]*t*t)+(vy*t)
            x = vx*t
            t = t + dt
            ylist.append(s[1])
            y2list.append(y)
            tlist.append(t)
            if (s[1] > maxhmaxt[0]):
                maxhmaxt = [s[1],t]
```

Projectile Motion of a Baseball Heun's 100 Analytical

Out[2]: <matplotlib.legend.Legend at 0x20b552e9c08>

Maximum altitude: 29.68278074336941

if $(s[1] \le 0)$:

pl.xlabel("Time (seconds)") pl.ylabel("Height (meters)")

Range: 308.00116865266085

print("Range: ",x)

def derivs(s, t):

60

40

In [4]:

In [5]:

In [6]:

Position = s[0:2]

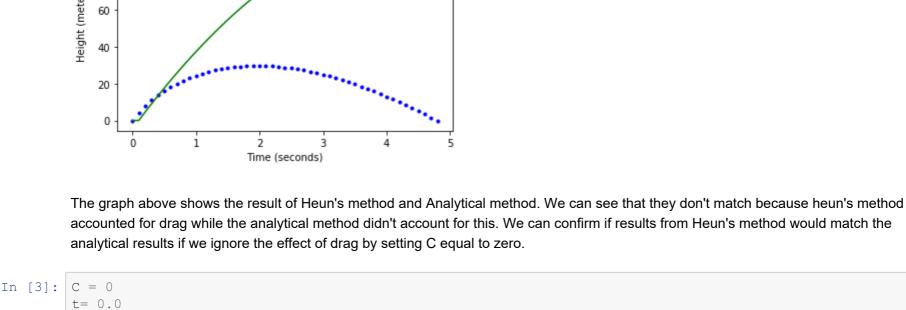
pl.legend()

print("Total time: ",t) print("Maximum altitude: ", maxhmaxt[0])

pl.title("Projectile Motion of a Baseball") pl.plot(tlist, ylist, 'b.', label = "Heun's")

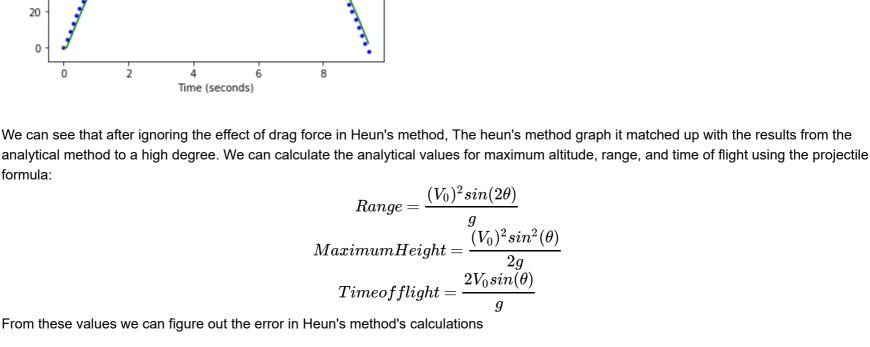
pl.plot(tlist, y2list, 'g-', label = "Analytical")

80



A = 0.0042 $rho = 1.3 \#kg/m^3$ g = np.array([0, -9.81])s = np.array([x0, y0, vx, vy])

```
Velocity = s[2:4]
            drdt = Velocity
            f_drag = -0.5 * C * A * rho * np.sqrt((Velocity * Velocity).sum()) * Velocity
             dvdt = ((m * g) + f_drag) / m
             return np.array([Velocity[0], Velocity[1], dvdt[0], dvdt[1]])
        ylist = [y0]
        tlist = [t]
        y2list = [y0]
        xlist = [x0]
        maxhmaxt = [0, 0]
        def HeunStep(s, t, derivs, dt):
            f1=derivs(s,t)
             f2=derivs(s+f1*dt,t+dt)
            return s + 0.5*(f1+f2)*dt
        while s[1] >= 0:
             s = HeunStep(s, t, derivs, dt)
             y = (0.5*g[1]*t*t)+(vy*t)
            x = vx*t
             t = t + dt
             ylist.append(s[1])
             y2list.append(y)
             tlist.append(t)
             if (s[1] > maxhmaxt[0]):
                 maxhmaxt = [s[1],t]
            if (s[1] <= 0):
                 print("Total time: ",t)
        print("Maximum altitude: ", maxhmaxt[0])
        print("Range: ",x)
        pl.xlabel("Time (seconds)")
        pl.ylabel("Height (meters)")
        pl.title("Projectile Motion of a Baseball")
        pl.plot(tlist, ylist, 'b.', label = "Heun's")
        pl.plot(tlist, y2list, 'g-', label = "Analytical")
        pl.legend()
        Total time: 9.39999999999983
        Maximum altitude: 107.31329006799318
        Range: 609.4491209510087
Out[3]: <matplotlib.legend.Legend at 0x20b552dbe88>
                        Projectile Motion of a Baseball
                                                Heun's
           100
                                                 Analytical
            80
```



Range analytical = np.abs(v0**2*np.sin((35.0*2) * (np.pi/180.0)) / (g[1]))

 $\max_{\text{heightanalytical}} = \text{np.abs}((v0**2)*\text{np.sin}(35.0 * (np.pi/180.0))**2 / (2 * g[1]))$

Time_analytical = np.abs((2 * v0) * np.sin(35.0 * (np.pi/180.0)) / (g[1]))

```
In [7]: print (Range analytical)
        print (max_heightanalytical)
        print (Time_analytical)
        613.0512510733754
        107.31577682761771
        9.35496736148495
In [8]: error range = Range analytical - x
        error_maxheight = max_heightanalytical - maxhmaxt[0]
        error_time = Time_analytical - t
        print(error_range)
```

```
print(error maxheight)
        print(abs(error_time))
        3.6021301223667024
        0.002486759624531487
        0.04503263851503192
In [9]: error percentrange = ((error range)/(Range analytical))*100
        error_percentmaxheight = ((error_maxheight)/(max_heightanalytical))*100
```

print("Percentage error in Time: ", error percenttime) Percentage error in Range: 0.5875740594379062 Percentage error in Maximum Height: 0.002317235823140889

Percentage error in Time: 0.48137675712728206

error_percenttime = ((abs(error_time))/(Time_analytical))*100

print("Percentage error in Maximum Height: ", error percentmaxheight)

print ("Percentage error in Range:", error_percentrange)

Conclusion

physics results.

The purpose of this lab was to predict a baseball's motion, including the effect of drag, with Heun's method and confirm its validity. I used Analytical physics formulas to confirm its validity, but because analytical physics in kinetics neglects the effect of drag force i had to check Heun's method with drag force neglected and see if results obtained were close to the results from analytical physics. I got a percentage error of maximum altitude and range to be 0.0023% and 0.59% respectively when comparing Heun's method's results to the analytical