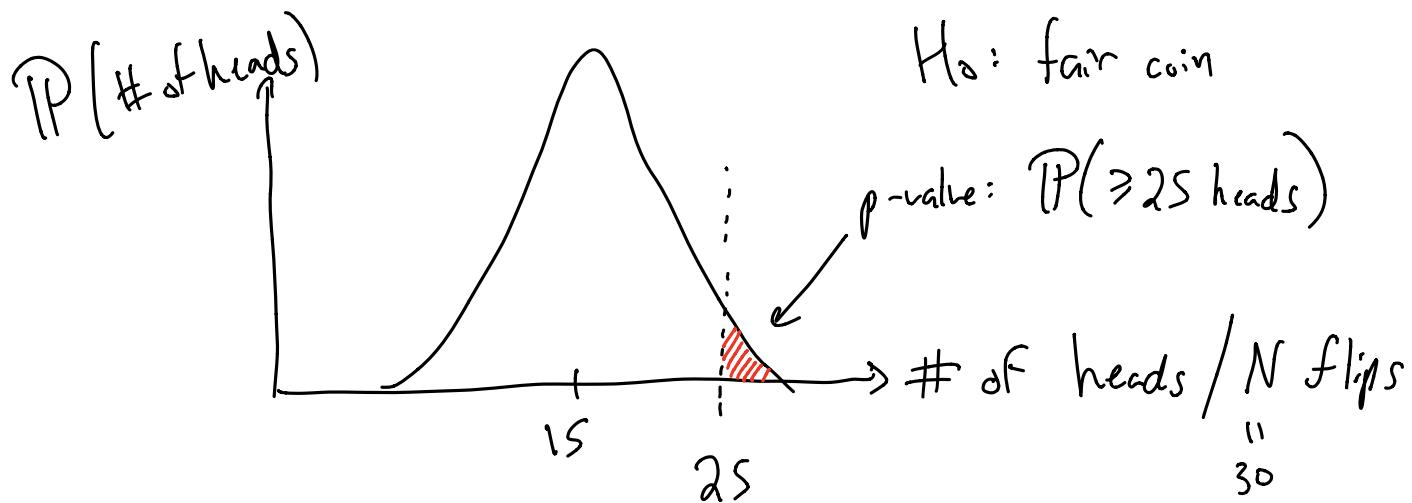


Week 6 Section

Danylo L Week 6
MCB 112

Some of what we discussed in lecture:

→ given some null hypothesis on how data is generated, how surprising is a particular observation of data?



For section today, a mix of things but they're all connected--

→ given data, how do we make a new hypothesis?

→ revisit Bayes Rule

→ estimation of parameters for binomial & normal

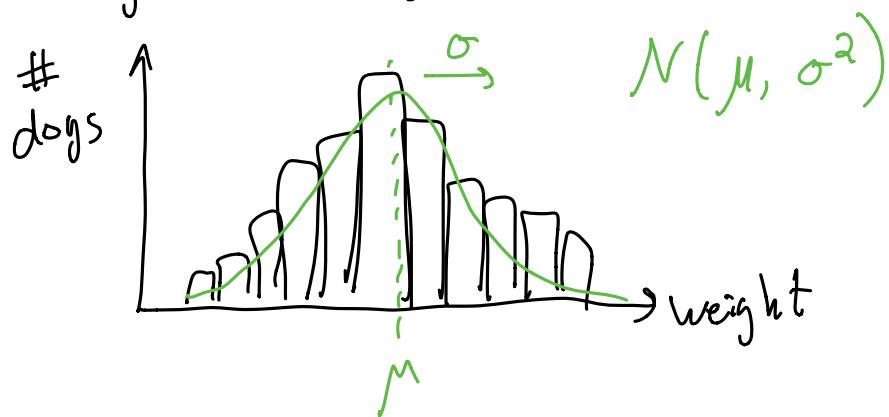
→ see how T scores arise from estimation of μ

→ concepts behind p-set

Parameter Estimation / Inference

Given some data, X_1, \dots, X_N , we'd like to describe the process that produced the data.

Ex. 1: Weights of Siberian huskies



\Rightarrow what particular μ, σ describe X_1, \dots, X_N ?

Ex. 2: # of heads out of N flips of a coin?

H w/ prob p
T w/ prob $1-p$ } \Rightarrow N times

\Rightarrow what particular p describes # of heads / flips?

Notation: θ is a hypothesis on how the data was generated
↳ particular values of the parameters of the underlying probability distribution.

Ex. for dog weights: $\theta = \{\mu = 15 \text{ kg}, \sigma = 5 \text{ kg}\}$

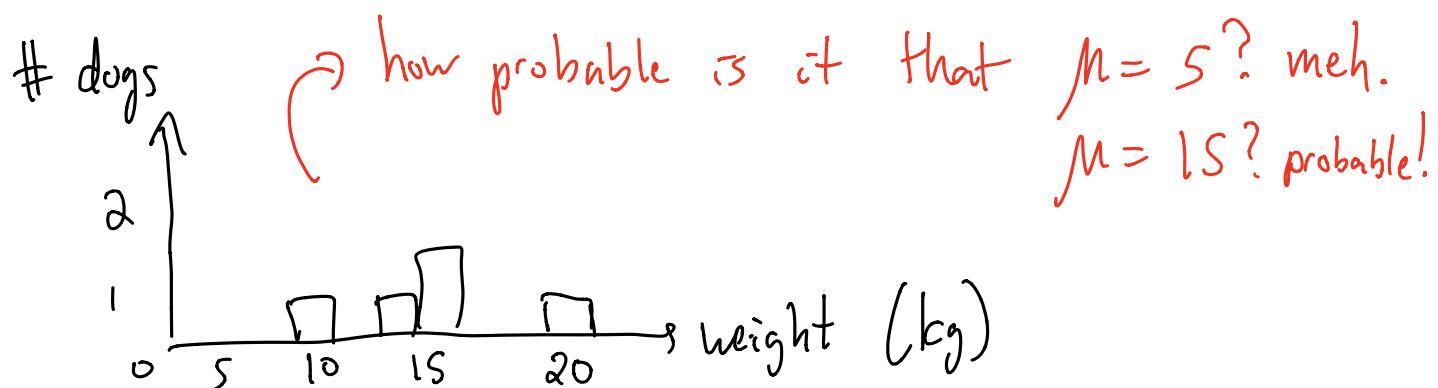
Ex. for an unbiased coin: $\theta = \{p = 0.5\}$

The big question we'd like to answer:

given data D , what's the most probable θ ?

(θ : a hypothesis on how data D was generated)

Ex. I weigh 5 dogs and make a histogram:



Ex. I get 25 heads in 30 flips

↳ "fair" hypothesis: how probable is it that $p = P(\text{heads}) = 0.5$?

Suppose we had some set of hypotheses, $\Theta_1, \dots, \Theta_M$

Given data, how probable is a particular hypothesis Θ_k ?

Likelihood:

how probable is the data
given our hypothesis is true

Prior:

how probable is our
hypothesis prior to
seeing data?

$$P(\Theta_k | D) = \frac{P(D | \Theta_k) P(\Theta_k)}{P(D)}$$

Posterior:

how probable is our hypothesis Θ_k
post seeing the data?

Marginal:

how probable is the data
under all possible
hypotheses?

Marginal recap:

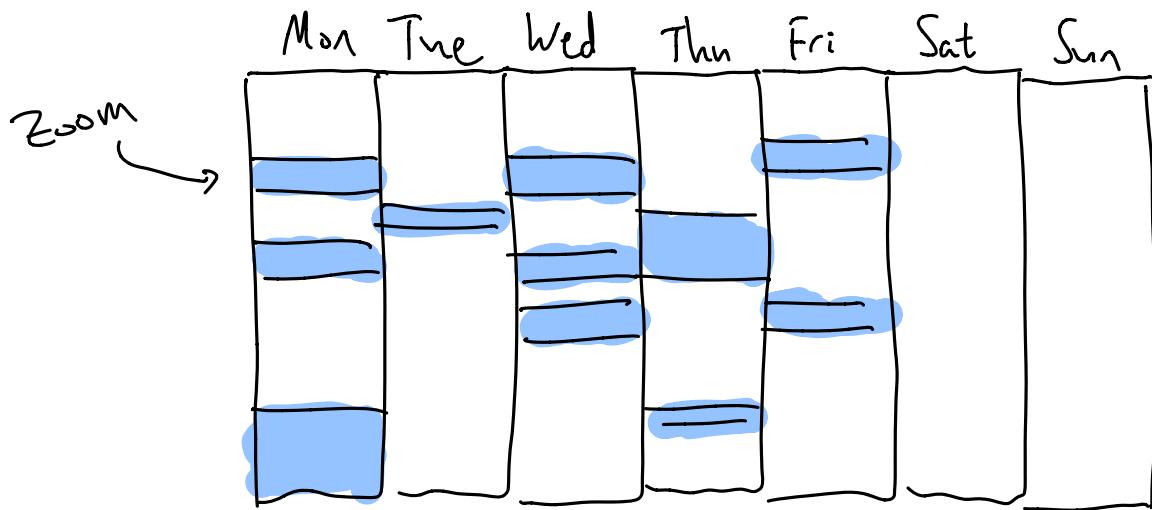
$$P(D) = \sum_{i=1}^M P(D \text{ AND } \Theta_i \text{ true}) \quad \leftarrow \text{add over all possible hypotheses}$$

$$= \sum_{i=1}^M P(D | \Theta_i) P(\Theta_i) \quad \leftarrow P(X \text{ AND } Y) \\ = P(X|Y) P(Y)$$

$$= \int P(D | \theta) P(\theta) d\theta$$

if an ∞ number of Θ 's

In example: My Weekly Schedule



θ : What day it is. Monday, Thursday, who knows...

Data: how many Zoom meetings I had today.

$\theta \xrightarrow{\text{generates}}$ data, but also data $\xrightarrow{\text{infer}} \theta$

Ex. Marginal:

$$\begin{aligned} P(3 \text{ meetings}) &= P(3 \text{ meetings AND it's Monday}) \\ &\quad + \dots + \\ &P(3 \text{ meetings AND it's Sunday}) \\ &= \sum_{i=1}^7 P(3 \text{ meetings AND it's } i^{\text{th}} \text{ day of week}) \\ &= \sum_{i=1}^7 P(3 \text{ meetings } | i^{\text{th}} \text{ day}) P(i^{\text{th}} \text{ day}) \end{aligned}$$

Comparing two posteriors / hypotheses

$$P(\text{Monday} \mid 3 \text{ meetings}) = \frac{P(3 \text{ meetings} \mid \text{Mon}) P(\text{Mon})}{P(3 \text{ meetings})}$$

$$P(\text{Thursday} \mid 3 \text{ meetings}) = \frac{P(3 \text{ meetings} \mid \text{Thu}) P(\text{Thu})}{P(3 \text{ meetings})}$$

To compare these two, I can take a ratio.

The denominator cancels out!

Back to our g :

given data D , what's the most probable θ ?

We can scan over a lot of θ 's to look for a particular θ w/ the highest $P(\theta|D)$,

$$P(\theta|D) = \frac{P(D|\theta) P(\theta)}{\cancel{P(D)}}$$

(can ignore denom when comparing posteriors generally)

If we have some prior beliefs $P(\theta)$,
(it just feels like a Thursday...)

The θ that maximizes $P(D|\theta) P(\theta)$ is
the maximum a posteriori (MAP) estimate.

If we further assume uniform priors on θ ...

$$P(\theta|D) = \frac{P(D|\theta) P(\theta)}{P(D)}$$

then... the most probable θ given the data
is the θ that maximizes the likelihood

$$P(\theta|D) \propto P(D|\theta)$$

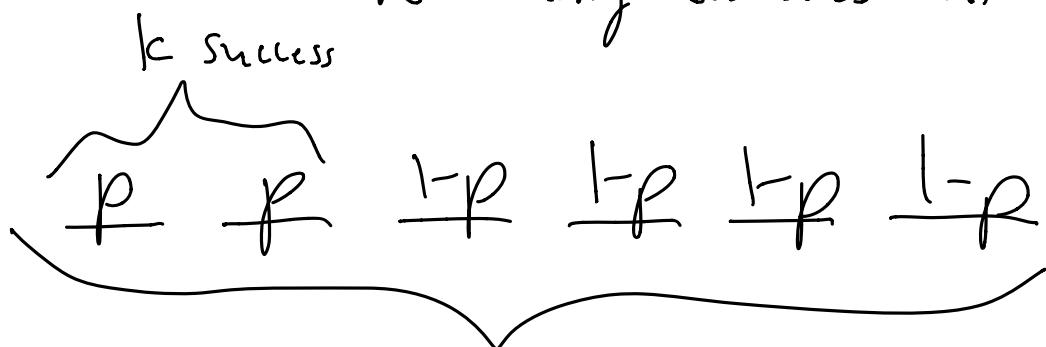
This is Maximum Likelihood Estimation!

Concept behind likelihood $P(D|\theta)$ w/ binomial

binomial process: N trials

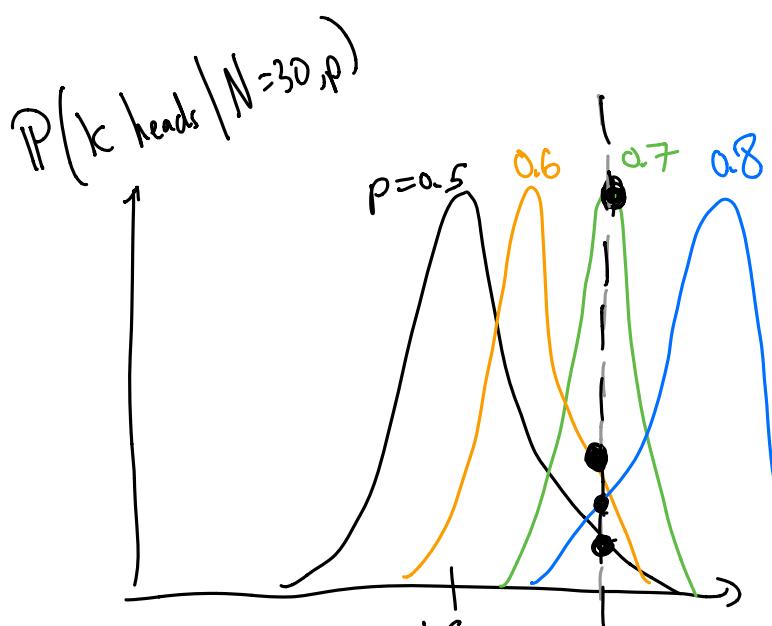
each trial has success prob. p

how many successes out of N trials?



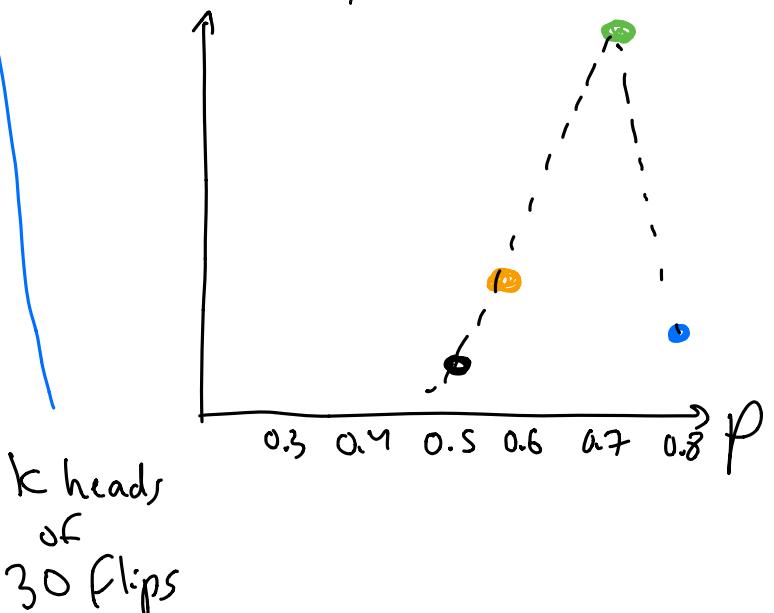
N trials

$$P(X=k \text{ successes} | N, p) = \binom{N}{k} p^k (1-p)^{N-k}$$



$$L(p) = P(k=25 | N=30, p)$$

describes
↓ data
best.



Key point: the likelihood measures overlap of data w/
a data generation/probability process parameterized by θ .

Max likelihood of Binomial

Observed data: 25 heads / 30 flips.

What's the max. likelihood estimate of p ?

The p that maximizes the likelihood.

$$P(k | N, p) = L(p) = \binom{N}{k} p^k (1-p)^{N-k}$$

This is a function of p . We can maximize it

by finding p s.t. $\frac{\partial}{\partial p} L(p) = 0$.

$$\frac{\partial}{\partial p} L(p) = \frac{\partial}{\partial p} \left[\binom{N}{k} p^k (1-p)^{N-k} \right]$$

gross... chain rule... take the log!

$$\log L(p) = \log \binom{N}{k} + k \log p + (N-k) \log(1-p)$$

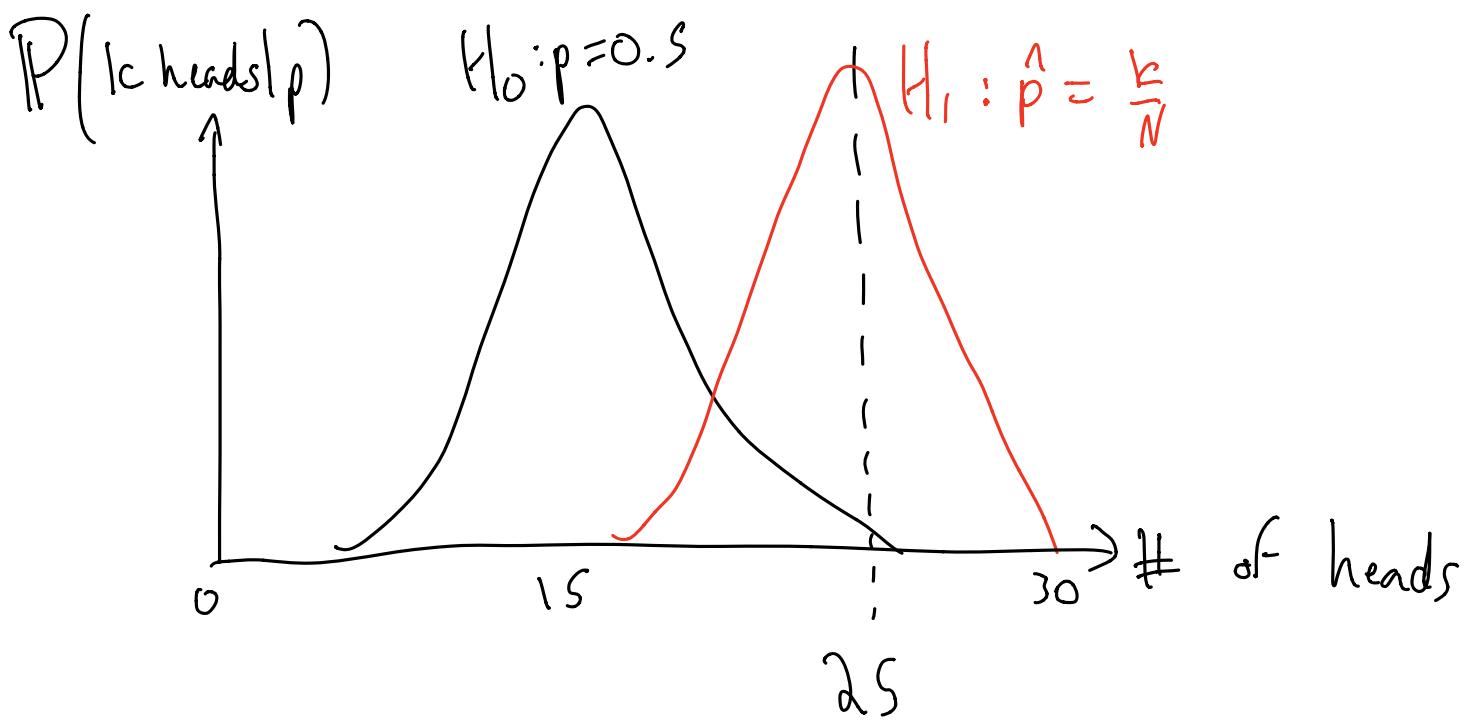
$$\frac{\partial}{\partial p} \log L(p) = \frac{k}{p} - \frac{N-k}{1-p} = 0$$

$$\Rightarrow \frac{k}{p} = \frac{N-k}{1-p}$$

$$\Rightarrow k - kp = Np - kp \Rightarrow$$

$$\hat{p} = \frac{k}{N}$$

So, given we observe k heads out of N flips,
 the max. likelihood estimate of p is $\frac{k}{N}$.



Things to consider:

- is H_0 invalidated?
- does this mean H_1 has to be the correct model?
- what if we had prior beliefs on
 $P(\theta) = P(\text{prob. of heads})$?
 (maybe we really trust the coin is fair)

MLE for a normal: $X_1, \dots, X_n \sim N(\mu, \sigma^2)$

For one data point,

$$P(X=x \mid \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

For n data points, write the joint likelihood:

$$\begin{aligned} L(\mu, \sigma^2) &= P(X_1=x_1, \dots, X_n=x_n \mid \mu, \sigma^2) \\ &= P(X_1=x_1 \mid \mu, \sigma^2) \cdot \dots \cdot P(X_n=x_n \mid \mu, \sigma^2) \\ &= \prod_{i=1}^n P(X_i=x_i \mid \mu, \sigma^2) \\ &= \prod_{i=1}^n (2\pi\sigma^2)^{-\frac{1}{2}} \exp\left(-\frac{(x_i-\mu)^2}{2\sigma^2}\right) \\ &= (2\pi\sigma^2)^{-\frac{n}{2}} \prod_{i=1}^n \exp\left(-\frac{(x_i-\mu)^2}{2\sigma^2}\right) \\ &= (2\pi\sigma^2)^{-\frac{n}{2}} \exp\left(-\sum_{i=1}^n \frac{(x_i-\mu)^2}{2\sigma^2}\right) \end{aligned}$$

Take the log:

$$\log L(\mu, \sigma^2) = -\frac{n}{2} \log(2\pi\sigma^2) - \sum_{i=1}^n \frac{(x_i-\mu)^2}{2\sigma^2}$$

↳ we'll find MLE again by taking derivatives

MLE for μ :

$$\frac{\partial}{\partial \mu} \log L(\mu, \sigma^2) = \sum_{i=1}^n \frac{2(x_i - \mu)}{2\sigma^2} = 0$$

$$\Rightarrow \hat{\mu} = \frac{\sum_{i=1}^n x_i}{n}$$

The MLE for μ is just the sample mean.

MLE for σ^2 :

$$\frac{\partial}{\partial \sigma^2} \log L(\mu, \sigma^2) = -\frac{n}{2\sigma^2} + \sum_{i=1}^n \frac{(x_i - \mu)^2}{2(\sigma^2)^2} = 0$$

Skipping some steps---

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2$$

But wait... if we only observe x_1, \dots, x_n , we don't know μ !

Replacing μ w/ \bar{x} : $\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$

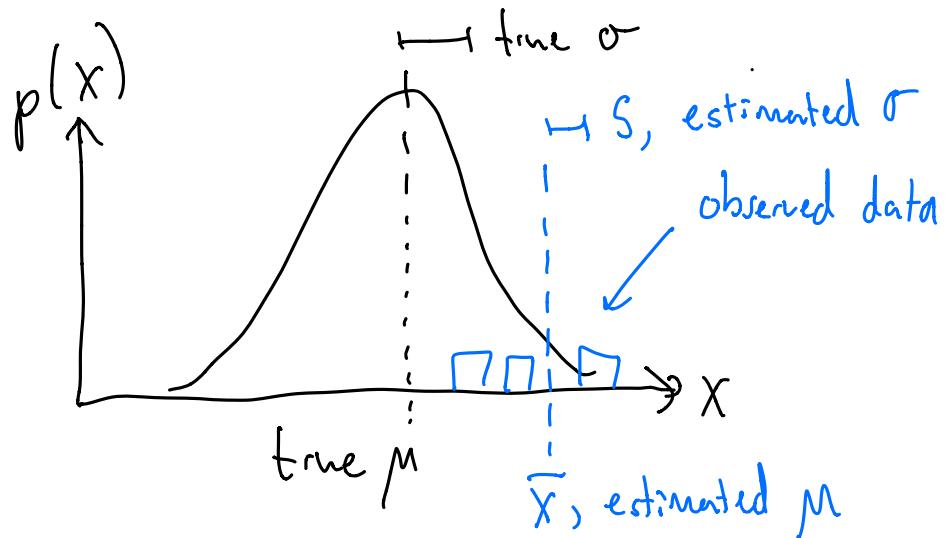
It turns out this is a biased estimator of the population σ^2 . (see Bessel's correction)

Unbiased estimate of population Variance:

$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

Hypothesis testing on \bar{X}

$X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma)$, n small



Q: How likely is it that μ is the population mean?

Compute distance b/w μ and \bar{X} , scaled by

typical fluctuation in \bar{X} , which is $\frac{\sigma}{\sqrt{n}}$. ("standard error" of the mean)

$$\Rightarrow \text{Standard Score: } \frac{\bar{X} - \mu}{\sigma / \sqrt{n}}$$

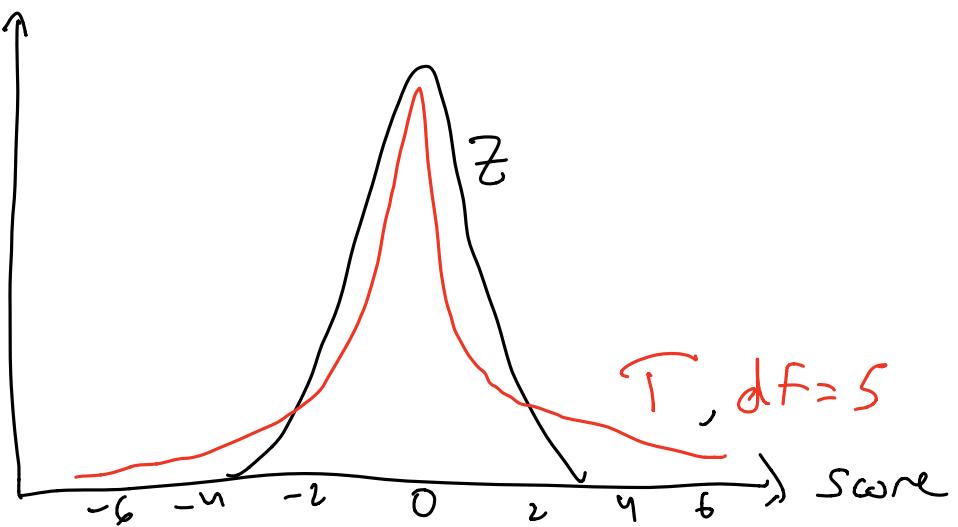
If σ is known, this is a Z score,

$$Z = \frac{\bar{X} - \mu}{\sigma / \sqrt{n}}$$

If σ is unknown, we estimate it with S ,

this is a T score: $T = \frac{\bar{X} - \mu}{S / \sqrt{n}}$, w/ -1 degrees of freedom

Distribution of
 T , Z scores
(when μ really is
population mean)



$\Rightarrow T$ distribution has fatter tails.

It allows for \bar{X} to be "far away" from μ

because we had to estimate σ^2 from the data.

\Rightarrow We could have estimated too small a σ^2 , which means the T score would be larger than it should be \rightarrow hence more probability of big T scores

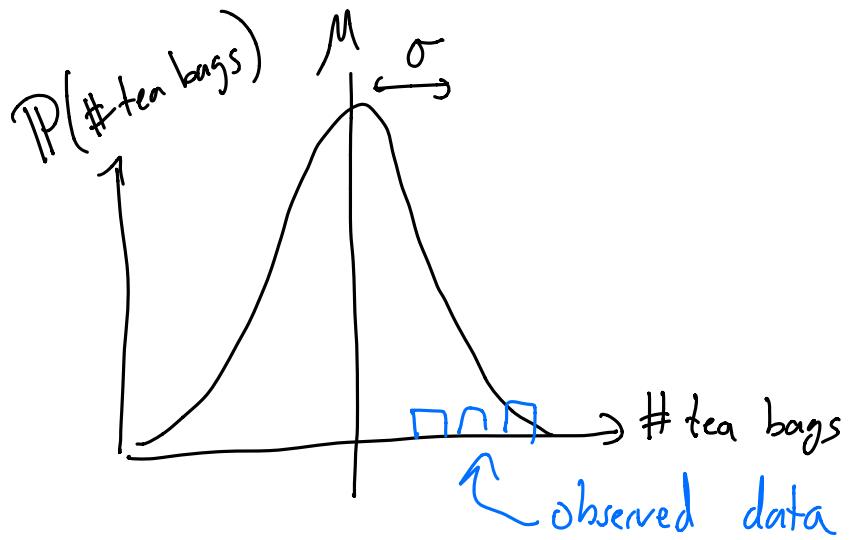
\Rightarrow At large n , we estimate σ^2 well,
 T dist converges to Z dist.

So the T dist can arise from estimation of an uncertain σ^2 given data.

On the p-set we will marginalize over many potential σ^2 's.

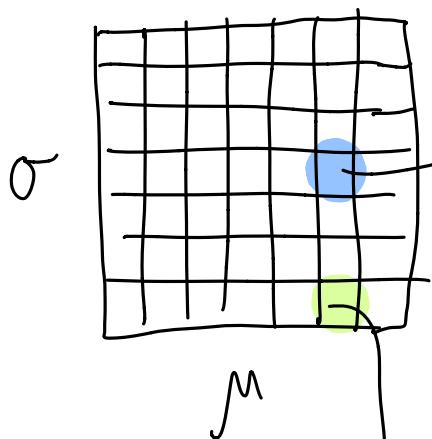
Concept for P-Set

There's a true $N(\mu, \sigma^2)$,
but we only see
a few data points



→ Goal: bet on candidate (μ, σ^2)
given only a few observed datapoints

How? Will assume a grid of possible (μ, σ) :



one of these (μ, σ) pairs
generated the data
we observe, X_1, \dots, X_n

for any candidate (μ, σ^2)
we can compute
how probable they are
given our data...

with a posterior, $P(\mu, \sigma^2 | X_1, \dots, X_n)$

$$\begin{aligned} & \mathbb{P}(M, \sigma^2 \mid X_1, \dots, X_n) \\ &= \frac{\mathbb{P}(X_1, \dots, X_n \mid M, \sigma^2) \mathbb{P}(M, \sigma^2)}{\mathbb{P}(X_1, \dots, X_n)} \end{aligned}$$

① likelihood: (Independent observations)

$$\begin{aligned} \mathbb{P}(X_1, \dots, X_n \mid M, \sigma^2) &= \mathbb{P}(X_1 \mid M, \sigma^2) \times \dots \times \mathbb{P}(X_n \mid M, \sigma^2) \\ &= \prod_{i=1}^n \mathbb{P}(X_i \mid M, \sigma^2) \\ &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}} \end{aligned}$$

② prior: $\mathbb{P}(M, \sigma^2) = \mathbb{P}(\mu) \mathbb{P}(\sigma^2)$

③ marginal: $\mathbb{P}(X_1, \dots, X_n) = \sum_M \sum_{\sigma} \mathbb{P}(X_1, \dots, X_n \text{ AND } M, \sigma)$

$$= \sum_M \sum_{\sigma} \mathbb{P}(X_1, \dots, X_n \mid M, \sigma) \mathbb{P}(M, \sigma)$$

Extra: distribution of a sample mean.

The expectation, or average, of \bar{X} :

$$\begin{aligned} E(\bar{X}) &= E\left[\frac{1}{N} \sum_{i=1}^N X_i\right] = \frac{1}{N} \sum_{i=1}^N E(X_i) && (\text{mean of sum} \\ &= \frac{1}{N}(N\mu) && \text{sum of means}) \\ &= \mu. \end{aligned}$$

So the average \bar{X} is indeed μ , the population average.

Now for the spread in \bar{X} ? Its variance:

$$\text{Var}(\bar{X}) = \text{Var}\left(\frac{1}{N} \sum_{i=1}^N X_i\right)$$

$$= \frac{1}{N^2} \text{Var}\left(\sum_{i=1}^N X_i\right)$$

$$= \frac{1}{N^2} \sum_{i=1}^N \text{Var}(X_i)$$

$$= \frac{1}{N^2} \sum_{i=1}^N \sigma^2$$

$$= \frac{1}{N^2} N \sigma^2$$

$$= \frac{\sigma^2}{N}$$

$$\text{Var}(aX) = a^2 \text{Var}(X)$$

independent variables

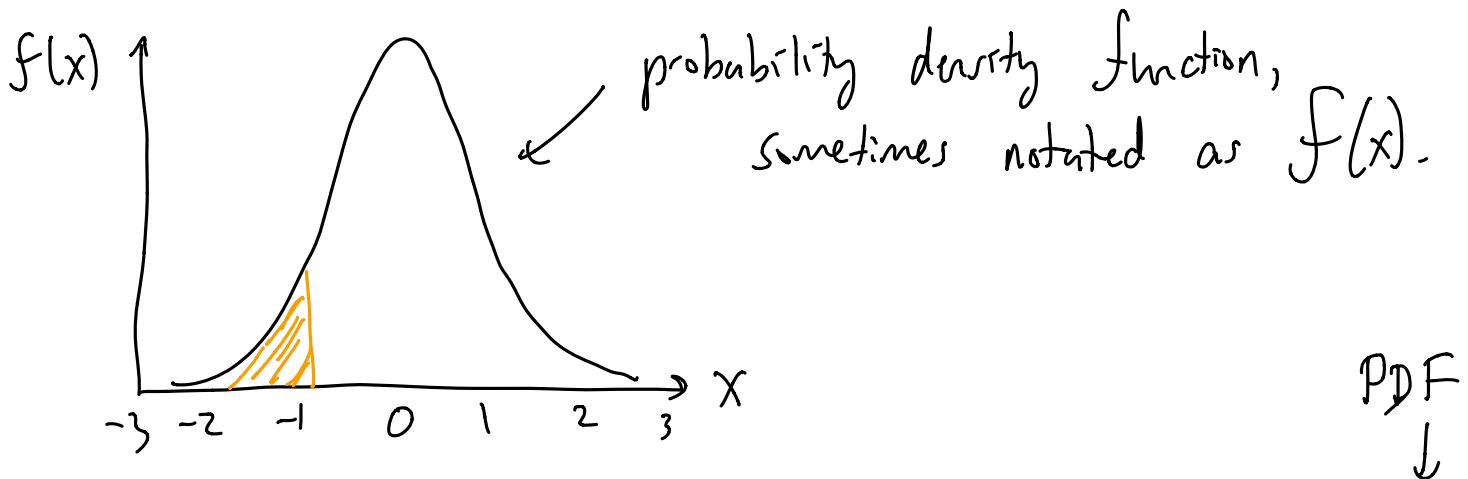
Each $X_i \sim N(\mu, \sigma^2)$

$$\Rightarrow \text{SD}(\bar{X}) = \sqrt{\frac{\sigma^2}{N}} = \frac{\sigma}{\sqrt{N}}$$

the more N we observe, the closer \bar{X} is to μ

Extra: CDF example

Say we have a normal:



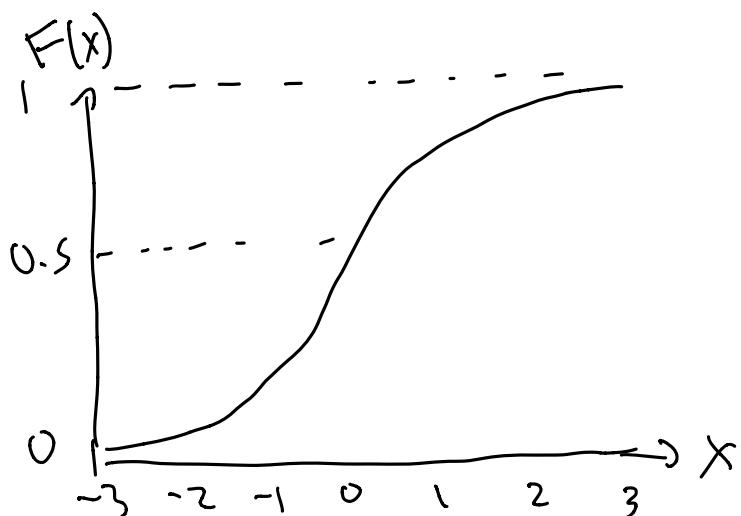
$P(X \leq -1)$ is the integral from $-\infty$ to -1 of $f(x)$

A CDF is an integral from $-\infty$ to (some place) of $f(x)$

$$CDF(x) = \int_{-\infty}^x f(x') dx', \text{ often notated as } F(x).$$

$$\text{So } P(X \leq -1) = CDF(-1)$$

The further right we integrate to, we can only add to the integral, so $CDF(x)$ cannot decrease w/ x.



Q: draw the CDF of a uniform distribution

$f(x)$

x

(Hint: integrate up to x)