PID UML: Pair B

PID

- Kp: double
- _Ki: double
- _Kd: double
- _dt: double
- _min: double
- max: double
- prev error: double
- integral: double
- + calculatePID(double, double): double
- + getKp(): double
- + getKi(): double
- + getKd(): double
- + getdt(): double