FilteringView.cpp

```
void GaussianFilteringGPU(int flag){
        .
        .
    Do_Gaussian_on_GPU( ... , flag)
```

↓

Cuda_code.cu

```
float Do_Gaussian_on_GPU(          ){
  Set_Gaussian_kernel();

  if(flag=SHARED){
    Gaussian_kernel_shared(p_bitmaps, p_Gaussian,
                           width, height);
  }
  else{
    Gaussian_kernel_no_shared(p_bitmaps, p_Gaussian,
                              width, height);
  }
```

```
__global__ void Gaussian_kernel_shared ( //IN/OUT unsigned char *d_bitmaps
                                         OUT unsigned char *d_Gaussian
                                         long width, long height)
{
    int row = blockIdx.y * blockDim.y + threadIdx.y;
    int col = blockIdx.x * blockDim.x + threadIdx.x;
    int id = width * row + col; // image id
    int s_id = threadIdx.y * blockDim.y + threadIdx.x // shared memory id

    // 범위밖 -> 패딩처리
    if(row >= height // col >= width) return;

    // 초기화
    d_Gaussian[id] = 0;

    if (row < height && col < width) {
        shared buffer[threadIdx.y * blockDim.x + threadIdx.x]
            = d_bitmaps [row * width + col]; // input데이터 값을 shared memory에 저장
    }

    __syncthreads();
    if (threadIdx.x >= 5) && (threadIdx.x < blockDim.x - 5)
        && (threadIdx.y >= 5 ) && (threadIdx.y < blockDim.y - 5))   범위내 값만 연산

    {
        int sum = 0;
        for(int dy = -5; dy < 5; dy++) {
            for(int dx = -5; dx < 5; dx++) {
                int i = shared buffer [s_id + (dy * blockDim.y) + dx];
                sum += constant_gaussian_kernel [dy * 5 + dx] * i ;
            }
        }
        d_Gaussian [id] = sum;
    }
```

kernel이 5x5이므로 한 픽셀의 상하=5번의 연산 수행.

```
__global__ void Gaussian_kernel_no_shared(IN unsigned char *d_bitmaps,
                                          OUT unsigned char *d_Gaussian,
                                          long width, long height){
    int row = blockIdx.y * blockDim.y + threadIdx.y;
    int col = blockIdx.x * blockDim.x + threadIdx.x;
    int sum = 0;
    if (row <= 0 || row >= height-1 || col <= 0 || col >= width-1)
        d_Gaussian[row*width + col] = 0;
    else {
        for(int i = -2; i <= 2; i++){
            for(int j = -2; j <= 2; j++){
                int k = d_bitmaps[(row+i)*width + (col+j)];
                sum += k * constant_Gaussian_kernel[i+2][j+2];
            }
        }
        d_Gaussian[row*width + col] = sum;
    }
}
```

범위를 벗어날 경우 예외처리

kernel의 한가운데는 중심으로 인접스칸합함.

CPU

```
QueryPerformanceFrequency(&m_frequency);
QueryPerformanceCounter(&m_start);

for (r = 0; r < m_height; r++) {
    for (c = 0; c < m_width; c++) {
        sum = 0;
        for (i = -w; i <= w; i++) {
            for (j = -w; j <= w; j++) {
                if (r + i < 0 || c + j < 0 || r + i >= m_height || c + j >= m_width)
                    sum += 0;
                else
                    sum += m_imageBits[(r + i) * m_width + (c + j)] * p_gaussian_kernel[(i + 2) * 5 + (j + 2)];
            }
        }
        m_imageBitsFiltered[r * m_width + c] = sum;
    }
}

QueryPerformanceCounter(&m_end);
m_result = 1000 * (m_end.QuadPart - m_start.QuadPart) / m_frequency.QuadPart;
```

Filtering time: 13.00 (milliseconds)