

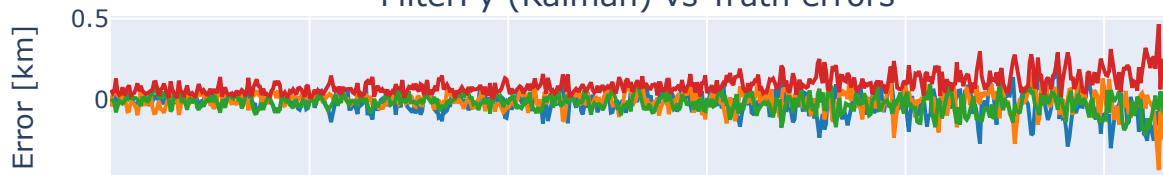
# Errors vs Truth - HGV 330

- Triangulation X err
- Triangulation Y err
- Triangulation Z err
- Triangulation NORM err
- FilterPy (Kalman) X err
- FilterPy (Kalman) Y err
- FilterPy (Kalman) Z err
- FilterPy (Kalman) NORM err
- FilterPy (Kalman) NIS

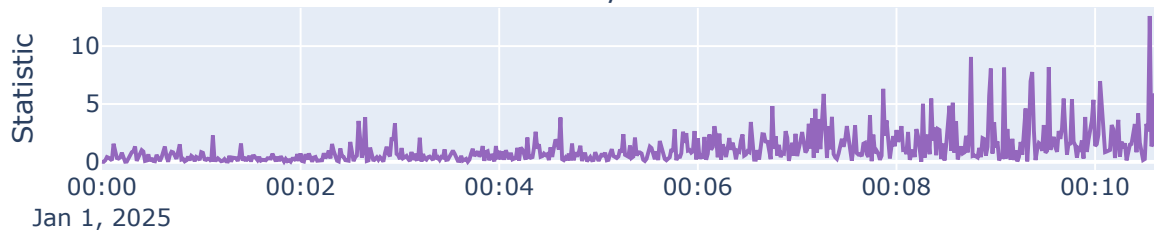
## Triangulation vs Truth errors



## FilterPy (Kalman) vs Truth errors



## NIS / NEES



Epoch UTC