

Homework 5: Dimitri Lezcano

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$$1) J = \frac{1}{2} x(1)^2 + \int_0^1 \underbrace{\frac{1}{2} [x(t)u(t)]^2}_{L} dt$$

s.t.

$$\dot{x} = x u$$

$$x(0) = 1$$

HJB

$$-J_t V = \min_u \left\{ L(x, u, t) + J_x V \cdot f(x, u) \right\}$$

$$\min_u \left\{ \frac{1}{2} x^2 u^2 + J_x V \cdot x u \right\}$$

↓

$$\frac{d}{du} \left(\frac{1}{2} x^2 u^2 + J_x V \cdot x u \right) = 0$$

$$x^2 u^* + V_x \cdot x = 0$$

$$u^* = - \frac{V_x}{x}$$

↓

$$-J_t V = \frac{1}{2} x^2 u^{*2} + V_x \cdot x u^*$$

$$= \frac{1}{2} x^2 \frac{V_x^2}{x^2} + V_x \cdot x \left(-\frac{V_x}{x} \right)$$

$$-J_t V = -\frac{1}{2} V_x^2$$

$$\frac{1}{2} V_x^2 = J_t V \Rightarrow$$

$$\frac{1}{2} V_x^2 = J_t V$$

$$V(x, t) = X(x) T(t)$$

$$\frac{1}{2} \dot{x}^T T^T = \dot{x} T$$

$$\frac{1}{2} \frac{\dot{x}^T}{\dot{x}} = \frac{T^T}{T} = K \quad K \text{ is a scalar}$$

$$\frac{1}{2} \dot{x}^T = K \dot{x}$$

$$X(x) = C x^2$$

$$\dot{x}'(x) = 2 C x$$

↓

$$\frac{1}{2} (2 C x)^2 = K (C x^2)$$

$$2 C^2 x^2 = K C x^2$$

$$C = K/2$$

$$\text{If } X(x) = \frac{1}{2} K x^2$$

$$\dot{x}'(x) = K x$$

$$\frac{1}{2} (\dot{x}')^2 = \frac{1}{2} (K x)^2 = \frac{1}{2} K^2 x^2 = K X \checkmark$$

$$\text{So } V(x, t) = \left(\frac{1}{2} K x^2 \right) T(t)$$

$$u^* = - \frac{\nabla_x V}{x} = - \frac{K x T(t)}{x} = - K T(t)$$

$$2) J = \frac{1}{2} x_f^T P_f x_f + \frac{1}{2} \int_0^t \underbrace{(x^T Q x + u^T R u)}_{L} dt \quad R > 0$$

$$\dot{x}(t) = A(t)x(t) + B(t)u(t) + w(t) \quad R \succ 0, Q, P_f \succeq 0$$

$w(t)$ is known disturbances

a) CTS time of HJB

$$J_+ V = \min_u \left\{ L(x, u, t) + \nabla_x V^T f(x, u, t) \right\}$$

$$\nabla_u \left(L(x, u, t) + \nabla_x V^T f(x, u, t) \right)$$

$$= \nabla_u \left(\frac{1}{2} x^T Q x + \frac{1}{2} u^T R u + \nabla_x V^T (Ax + Bu + w) \right)$$

$$R u + B^T \nabla_x V = 0$$

$$\textcircled{1} u^* = -R^{-1} B^T \nabla_x V$$

So then

$$\begin{aligned} J_+ V &= \frac{1}{2} x^T Q x + \frac{1}{2} \nabla_x V^T B R B^T \nabla_x V + \nabla_x V^T A x - \nabla_x V^T B R^{-1} B^T \nabla_x V + \nabla_x V^T w \\ &= \frac{1}{2} x^T Q x - \frac{1}{2} \nabla_x V^T B R B^T \nabla_x V + \nabla_x V^T (Ax + w) \end{aligned}$$

$$\text{Suppose } V = \frac{1}{2} x^T P(t) x + b(t)^T x + c(t)$$

Then we have

$$J_+ V = \frac{1}{2} x^T \dot{P} x + \dot{b}^T x + \dot{c}$$

$$\nabla_x V = P x + b(t)$$

HJB becomes

$$-\frac{1}{2} x^T \dot{P} x - \dot{b}^T x - \dot{c} =$$

$$-\frac{1}{2} \dot{x}^T P x - \dot{b}^T x - \dot{c} =$$

$$\frac{1}{2} x^T Q x - \frac{1}{2} (Px+b)^T B R B^T (Px+b) + (Px+b)^T (Ax+u)$$

$$= \frac{1}{2} x^T Q x - \frac{1}{2} x^T P B R B^T P x - x^T P B R B^T b$$

$$- \frac{1}{2} b^T B R B^T b + x^T P A x + b^T A x + x^T P u + b^T u$$

Group Like Terms!

Quadratics

$$\frac{1}{2} x^T \dot{P} x = -\frac{1}{2} x^T Q x + \frac{1}{2} x^T P B R B^T P x - x^T P A x$$

Single x

$$\dot{b}^T x = x^T P B R B^T b - b^T A x - x^T P u$$

$$x^T \dot{b} = x^T (P B R B^T b) - x^T (A^T b) - x^T (P u)$$

No x

$$\dot{c} = \frac{1}{2} b^T B R B^T b - b^T u$$

So Quadratics are satisfied if

$$\underline{\dot{P} = -Q + P B R B^T P - P A - A^T P}$$

The "single x" are satisfied if

$$\underline{\dot{b} = P B R B^T b - A^T b - P u}$$

And "no x" is satisfied if

And "no x " is satisfied it

$$\dot{c} = \frac{1}{2} b^T B B^T b - b^T w$$

Now we want

$$V(t_f) = \frac{1}{2} x_f^T P_f x_f$$

$$\text{So } V(t_f) = \frac{1}{2} x_f^T P(t_f) x_f + b(t_f)^T x_f + c(t_f) = \frac{1}{2} x_f^T P_f x_f$$

so boundary conditions are

$$\begin{cases} \bullet P(t_f) = P_f \\ \bullet b(t_f) = 0 \\ \bullet c(t_f) = 0 \end{cases}$$

$$\begin{aligned} \Rightarrow u^{\phi} &= -R^{-1} B^T \nabla_x V \\ &= -R^{-1} B^T (P x + b) \end{aligned}$$

$$u^{\phi}(t) = \underbrace{-R^{-1}(t) B^T P(t) x(t)}_{K(t)} + \underbrace{-R^{-1}(t) B^T b(t)}_{h(t)}$$

$$\underline{u^{\phi}(t) = K(t) x(t) + h(t)}$$

b) Discrete - time

$$x_{i+1} = A_i x_i + B_i u_i + w_i$$

$$L_i(x_i, u) = \frac{1}{2} x_i^T Q_i x_i + \frac{1}{2} u_i^T R_i u_i$$

$$\Phi_f = \frac{1}{2} x_N^T P_f x_N$$

By Bellman eqs.

$$V_i = \min_u \{ L_i(x_i, u) + V_{i+1} f_i(x_i, u) \}$$

and

$$V_N = \Phi_f = \frac{1}{2} x_N^T P_f x_N$$

$$\min_u \left\{ \frac{1}{2} x_i^T Q_i x_i + \frac{1}{2} u_i^T R_i u_i + V_{i+1} (A_i x_i + B_i u_i + w_i) \right\}$$

$$\Rightarrow \nabla_u \left(\frac{1}{2} x_i^T Q_i x_i + \frac{1}{2} u_i^T R_i u_i + V_{i+1} (A_i x_i + B_i u_i + w_i) \right) = 0$$

$$R u^* + \nabla_u [V_{i+1} (A_i x_i + B_i u_i + w_i)] \Big|_{u=u^*} = 0$$

Suppose $V_i(x) = \frac{1}{2} x^T P_i x + b_i^T x + c_i$

Then $V_{i+1}(A_i x + B_i u + w_i) =$

$$\frac{1}{2} (A_i x + B_i u + w_i)^T P_{i+1} (A_i x + B_i u + w_i) + b_{i+1}^T (A_i x + B_i u + w_i) + c_{i+1}$$

$$= \frac{1}{2} (A_i x + w_i)^T \underbrace{P_{i+1}}_x (A_i x + w_i) + u^T B_i^T P_{i+1} (A_i x + w_i)$$

$$+ \frac{1}{2} u^T B_i^T P_{i+1} B_i u + \underbrace{b_{i+1}^T (A_i x + w_i)}_x + \underbrace{b_{i+1}^T B_i u}_x + c_{i+1}$$

∴

$$\nabla_u V_{i+1} = B_i^T P_{i+1} (A_i x + w_i) + B_i^T P_{i+1} B_i u + B_i^T b_{i+1}$$

↓

$$R_i u^* + B_i^T P_{i+1} (A_i x + w_i) + B_i^T P_{i+1} B_i u^* + B_i^T b_{i+1} = 0$$

$$\Rightarrow [R_i + B_i^T P_{i+1} B_i] u^* = -B_i^T P_{i+1} (A_i x + w_i) - B_i^T b_{i+1}$$

$$u^* = -[R_i + B_i^T P_{i+1} B_i]^{-1} B_i^T (P_{i+1} A_i x + P_{i+1} w_i + b_{i+1})$$

$$u^* = K_i x + h_i$$

$$K_i = -[R_i + B_i^T P_{i+1} B_i]^{-1} B_i^T P_{i+1} A_i$$

and

$$h_i = -[R_i + B_i^T P_{i+1} B_i]^{-1} B_i^T (P_{i+1} w_i + b_{i+1})$$

Finally conditions for P_i, b_i, c_i .

$$V_i = L_i(x, u^*) + V_{i+1}(f_i(x, u^*))$$

$$\begin{aligned} \frac{1}{2} x^T P_i x + b_i^T x + c_i &= \frac{1}{2} x^T Q_i x + \frac{1}{2} u^{*T} R_i u^* \\ &\quad + \frac{1}{2} (A_i x + B_i u^* + w_i)^T P_{i+1} (A_i x + B_i u^* + w_i) \\ &\quad + b_{i+1}^T (A_i x + B_i u^* + w_i) \\ &\quad + c_{i+1} \end{aligned}$$

$$\begin{aligned} &= \frac{1}{2} \left[(A_i + B_i K_i) x + (w_i + B_i h_i) \right]^T P_{i+1} \left[(A_i + B_i K_i) x + (w_i + B_i h_i) \right] \\ &\quad + b_{i+1}^T \left[(A_i + B_i K_i) x + (w_i + B_i h_i) \right] + c_{i+1} \\ &\quad + \frac{1}{2} x^T Q_i x + \frac{1}{2} (K_i x + h_i)^T R_i (K_i x + h_i) \end{aligned}$$

(Quadratics)

$$\frac{1}{2} x^T P_i x = \frac{1}{2} x^T (A_i + B_i K_i)^T P_{i+1} (A_i + B_i K_i) x + \frac{1}{2} x^T Q_i x + \frac{1}{2} x^T K_i^T R_i K_i x$$

$$\downarrow$$
$$P_i = (A_i + B_i K_i)^T P_{i+1} (A_i + B_i K_i) + Q_i + K_i^T R_i K_i$$

(Single x)

$$x^T b_i = x^T (A_i + B_i K_i)^T P_{i+1} (w_i + B_i h_i) + x^T (A_i + B_i K_i)^T b_{i+1} + x^T K_i^T R_i h_i$$

$$\downarrow$$
$$b_i = (A_i + B_i K_i)^T [P_{i+1} (w_i + B_i h_i) + b_{i+1}] + K_i^T R_i h_i$$

(No x)

$$L_i = \frac{1}{2} (w_i + B_i h_i)^T P_{i+1} (w_i + B_i h_i) + b_{i+1}^T (w_i + B_i h_i) + c_{i+1} + \frac{1}{2} h_i^T R_i h_i$$

with Boundary conditions

$$V_N = \frac{1}{2} x_N^T P_N x_N + b_N^T x_N + c_N = \frac{1}{2} x_N^T P_f x_N$$

$$\hookrightarrow \begin{cases} \cdot P_N = P_f \\ \cdot b_N = 0 \\ \cdot c_N = 0 \end{cases}$$

$$3) \quad \begin{aligned} p_{i+1} &= p_i + \Delta t u_i \\ v_{i+1} &= v_i + \Delta t (-0.5 v_i + 0.2 p_i + u_i + 0.1) \end{aligned}$$

$$x_{i+1} = \begin{pmatrix} p_{i+1} \\ u_{i+1} \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & \Delta t \\ 0.2\Delta t & 1 - 0.5\Delta t \end{pmatrix}}_{A_i} x_i + \underbrace{\begin{pmatrix} 0 \\ 1 \end{pmatrix}}_{B_i} u_i + \underbrace{\begin{pmatrix} 0 \\ 0.1 \end{pmatrix}}_{w_i}$$

$$J = \frac{1}{2} (p_N^2 + u_N^2) + \sum_{i=0}^N \frac{1}{2} (R u_i^2)$$

$$= \frac{1}{2} x_N^T P_f x_N + \sum_{i=0}^N \frac{1}{2} R u_i^2$$

$$P_f = I_2 \quad Q_i = 0_{2 \times 2} \quad R_i = R$$

So we have that

$$V_i(x) = \frac{1}{2} x^T P_i x + b_i^T x + c_i$$

$$K_i = -(R_i + B_i^T P_{i+1} B_i)^{-1} B_i^T P_{i+1} A$$

$$* K_i = -(R + e_2^T P_{i+1} e_2)^{-1} e_2^T P_{i+1} A \quad (1 \times 2 \text{ - row vector})$$

$$h_i = -(R_i + B_i^T P_{i+1} B_i)^{-1} B_i^T (P_{i+1} w_i + b_{i+1})$$

$$* h_i = -(R + e_2^T P_{i+1} e_2)^{-1} e_2^T (P_{i+1} w_i + b_{i+1}) \quad (\text{scalar})$$

Where

$$P_i = (A_i + B_i K_i)^T P_{i+1} (A_i + B_i K_i) + Q_i + K_i^T R_i K_i$$

$$* P_i = (A + e_2 K_i)^T P_{i+1} (A + e_2 K_i) + K_i^T R K_i$$

$$P_N = P_f = I_2$$

$$b_i = (A_i + B_i K_i)^T [P_{i+1} (w_i + B_i K_i) + b_{i+1}] + K_i^T R_i K_i$$

$$* b_i = (A + e_2^T K_i)^T [P_{i+1} (w + e_2 K_i) + b_{i+1}] + K_i^T R K_i$$

$$b_N = 0 \quad (2 \times 1 \text{ col. vector})$$

$$c_i = \frac{1}{2} (w_i + B_i k_i)^T P_{i+1} (w_i + B_i k_i) + b_{i+1}^T (w_i + B_i k_i) + c_{i+1} + \frac{1}{2} k_i^T R_i k_i$$

$$* c_i = \frac{1}{2} (w + e_i k_i)^T P_{i+1} (w + e_i k_i) + b_{i+1}^T (w + e_i k_i) + c_{i+1} + \frac{1}{2} k_i^T R_i k_i$$

$$c_N = 0 \quad (\text{scalar})$$