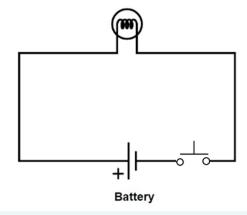
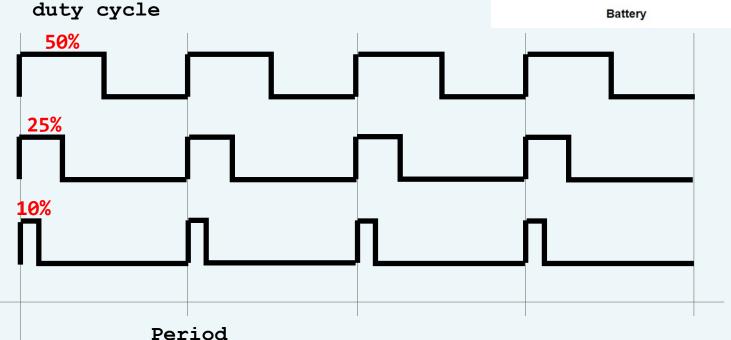
Internet of Things class 4

ESP32 PWM, ADC, Analog Input, Analog Sensors

Pulse-Width Modulation (PWM)

- PWM: Pulse Width Modulation
 - Adjust output voltage
 - Adjust brightness of lamp,
 control speed of motor





Increase Duty → Same effect as increasing Voltage

ESP32 Pulse-Width Modulation (PWM)

- 16 independent channels with different properties
- Steps (EX: to dim an LED with PWM)
 - Choose a PWM channel (0 ~ 15)
 - Set the PWM signal frequency (ex: 5000Hz for an LED)
 - Set the signal's duty cycle resolution (1 ~ 16bits)
 - Ex: 8-bit resolution controls LED brightness from 0 to 255

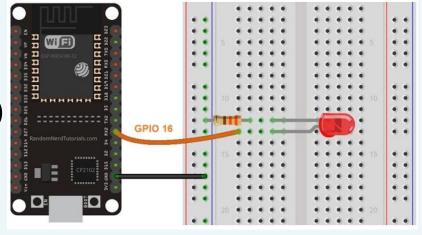
ledcSetup(channel, freq, resolution)

Specify GPIO to output the signal

ledcAttachPin(GPIO, channel)

Control PWM with dutycycleledcWrite(channel, dutycycle)

What effect for High Frequecy?



Pulse-Width Modulation (PWM)

<Task04-1>

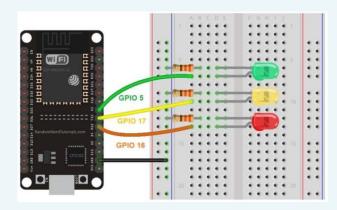
```
// <Task 04-1>
// the number of the LED pin
  const int ledPin = 16: // GPIO16
// setting PWM properties
  const int freq = 5000;
  const int ledChannel = 0;
  const int resolution = 8:
                                         void loop() {
                                          // increase the LED brightness
void setup() {
                                            for(int dutyCycle = 0; dutyCycle <= 255; dutyCycle++) {
// configure LED PWM functionalitites
                                               // changing the LED brightness with PWM
  ledcSetup(ledChannel, freq, resolution);
                                               ledcWrite(ledChannel, dutyCycle);
// attach the channel to the GPIO
                                               delay(15);
  ledcAttachPin(ledPin, ledChannel);
                                          // decrease the LED brightness
                                            for(int dutyCycle = 255; dutyCycle >= 0; dutyCycle--) {
                                               // changing the LED brightness with PWM
                                               ledcWrite(ledChannel, dutyCycle);
                                               delay(15);
```

Same Signal on Different GPIOs

- Attach GPIOs to the same channel on the setup()
 Steps (EX: to dim three LEDs with a PWM value)
 - Choose a PWM channel (0 ~ 15)
 - Set the PWM signal frequency (ex: 5000Hz for an LED)
 - Set the signal's duty cycle resolution (1 ~ 16bits)
 - Ex: 8-bit resolution controls LED brightness from 0 to 255

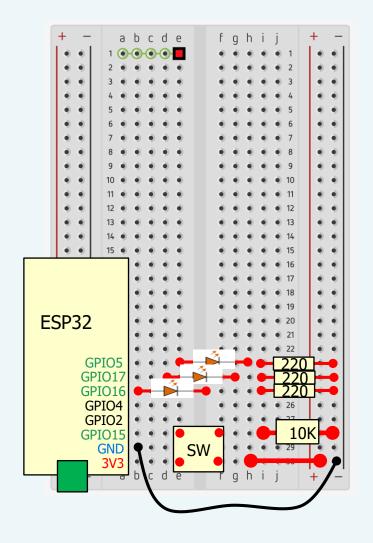
ledcSetup(channel, freq, resolution)

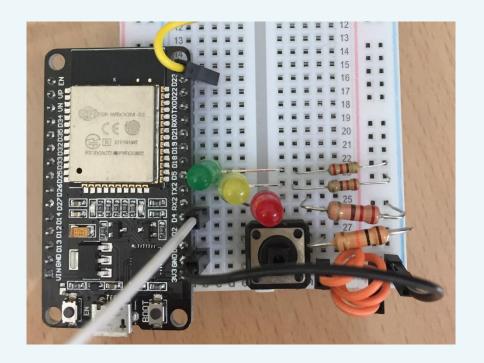
- Specify GPIO to output the signal ledcAttachPin(GPIO, channel) X 3
- Control PWM with dutycycle
 ledcWrite(channel, dutycycle)



Same Signal on Different GPIOs

** 두개의 LED와 저항 추가: GPIO5, 17 **





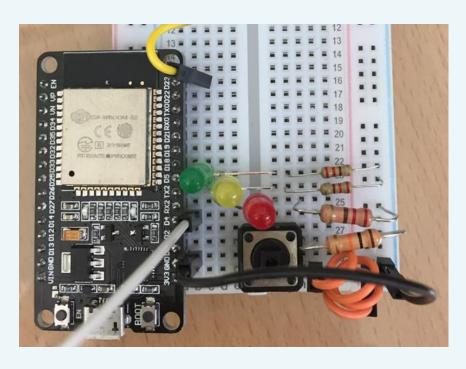
Same Signal on Different GPIOs

<Task04-2>

```
// the number of the LED pin
const int ledPin = 16; // 16 corresponds to GPIO16
const int ledPin2 = 17; // 17 corresponds to GPIO17
const int ledPin3 = 5; // 5 corresponds to GPIO5
// setting PWM properties
const int freq = 5000;
                                           void loop(){
const int ledChannel = 0:
                                           // increase the LED brightness
const int resolution = 8:
                                             for(int dutyCycle = 0; dutyCycle <= 255; dutyCycle++) {</pre>
                                                // changing the LED brightness with PWM
void setup() {
                                                ledcWrite(ledChannel, dutyCycle);
// configure LED PWM functionalitites
                                                delay(15);
  ledcSetup(ledChannel, freq, resolution);
// attach the channel to the GPIOs
  ledcAttachPin(ledPin, ledChannel);
                                           // decrease the LED brightness
  ledcAttachPin(ledPin2, ledChannel);
                                             for(int dutyCycle = 255; dutyCycle >= 0; dutyCycle--) {
  ledcAttachPin(ledPin3, ledChannel);
                                                // changing the LED brightness with PWM
                                                ledcWrite(ledChannel, dutyCycle);
                                                delay(15);
```

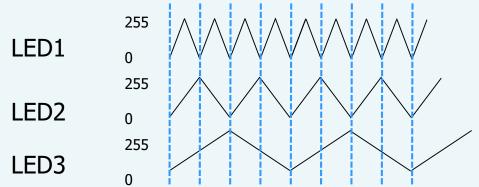
Different Signals on Different GPIOs

■ 3개의 PWM 채널을 3개의 LED에 연결하자



<Task04-3>

- 3개의 PWM 채널로 3개의 LED 제어
- freq = 5000, duty-res = 8bits
- pwm 값: 다음과 같은 주기로 0~255
- 스위치로 Pause 기능



Different Signals on Different GPIOs

<Task04-3>

```
// the number of the LED pin
const int ledPin = 16; // 16 corresponds to GPIO16
const int ledPin2 = 17; // 17 corresponds to GPIO17
const int ledPin3 = 5; // 5 corresponds to GPIO5
const int buttonPin = 15:
// setting PWM properties
const int freq = 5000;
const int ledChannel = 0:
const int ledChannel1 = 1:
const int ledChannel2 = 2:
const int resolution = 8:
void setup() {
  Serial.begin(115200);
// configure LED PWM functionalitites
  ledcSetup(ledChannel, freq, resolution);
// attach the channel to the GPIOs
  ledcAttachPin(ledPin, ledChannel);
  ledcAttachPin(ledPin2, ledChannel1);
  ledcAttachPin(ledPin3, ledChannel2);
  pinMode(buttonPin, INPUT);
```

Different Signals on Different GPIOs

```
void loop(){
// increase the LED brightness
  int j = 0, k = 0, jd = 1, kd = 1;
  for(int i = 0; i <= 1023; i++) {
     // changing the LED brightness with PWM
     ledcWrite(ledChannel, i/4);
     ledcWrite(ledChannel1, j/2);
     if ((j += jd) == 512) jd = -1, j = 511;
     ledcWrite(ledChannel2, k);
     if ((k += kd) >= 256) kd = -1, k = 255;
                                                          void checkPause() {
     else if (k < 0) kd = 1, k = 0;
                                                            // toggle pause state if button pressed
     checkPause(); delay(5);
                                                            if (digitalRead(buttonPin)) {
                                                              Serial.println("in pause..");
// decrease the LED brightness
                                                              delay(250); // skip glitch
  j = 0, k = 0, jd = 1, kd = 1;
                                                              while (!digitalRead(buttonPin));
  for(int i = 1023; i \ge 0; i - 1) {
                                                              delay(250); // skip glitch
     // changing the LED brightness with PWM
                                                              Serial.println("exit from pause..");
     ledcWrite(ledChannel, i/4);
     ledcWrite(ledChannel1, j/2);
     if ((j += jd) == 512) jd = -1, j = 511;
     ledcWrite(ledChannel2, k);
     if ((k += kd) \ge 256) kd = -1, k = 255;
     else if (k < 0) kd = 1, k = 0;
     checkPause(); delay(5);
```

Making tones with PWM

- PWM을 이용한 Tone 발생
 - 부저 출력 (수동부저)
 - Tone별 설정 주파수
 - 극성이 있다:
 - +: GPIO23에 연결
 - -: GND에 연결



```
음별 주파수
               C4 262 - 도
                                  523
 C3 131
                               C5
                              CS5 554
 CS3 139
               CS4 277
                                   587
 D3 147
               D4 294 - 레
                               D5
 DS3 156
               DS4 311
                               DS5 622
 E3 165
               E4 330 - II
                               E5
                                  659
 F3 175
                   349 - 파
                                  698
 FS3 185
               FS4 370
                              FS5 740
 G3 196
                   392 - 솔
                              G5
                                  784
 GS3 208
               GS4 415
                              GS5 831
 A3 220
                   440 - 라
                               A5
                                   880
 AS3 233
               AS4 466
                              AS5 932
 B3 247
                   494 - 시
                               B5
               B4
                                  988
```

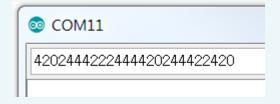
<Task04-4>

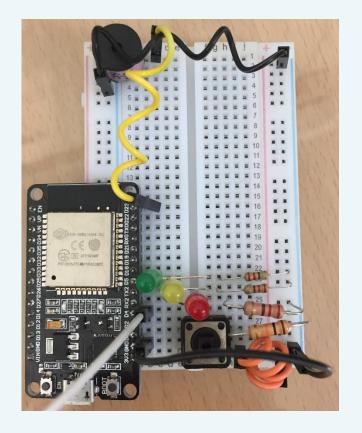
```
// make tones by using pwm
// freq -> pitch
// duty -> volume (?)
// setting PWM properties
//const int freq = 5000;
const int ledChannel = 0:
const int resolution = 8:
const int buzPin = 23:
const int duty = 128;
// variables
int sVal;
// notes
//enum Notes {C3=0, C53, D3, D53, E3, F3};
int nFrq[] = {/*131, 139, 147, 156, 165, 175*/
        262, 277, 294, 311, 330, 349};
```

Making tones with PWM

- Serial 입력을 통해 연주
 - 모든 음의 재생 시간을 250ms로 한다

```
void playNote(int note, int dur) {
  ledcSetup(ledChannel, nFrq[note], resolution);
  ledcWrite(ledChannel, duty);
  Serial.println(note);
  delay(dur);
void setup() {
  Serial.begin(115200);
  ledcAttachPin(buzPin, ledChannel);
void loop(){
  if (Serial.available() > 0) {
     sVal = Serial.read();
     playNote(sVal-0x30, 250);
```





Analog Sensors

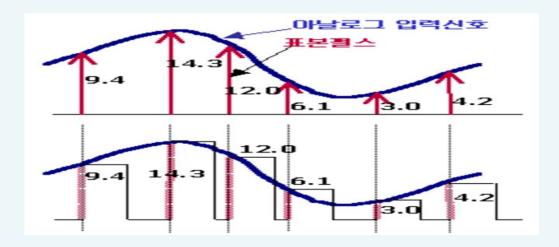
Analog Sensors

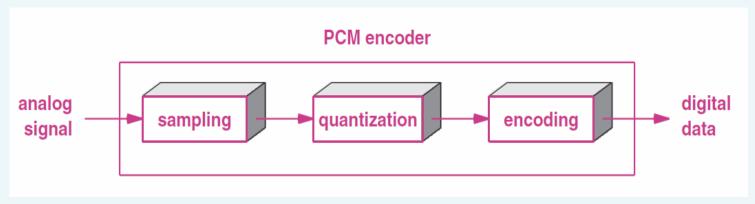
 Illuminance, Temperature(TMP35/36/37), Gas, Sound, Accelerometer, Potentiometer, joystick, etc.



Analog Input - Pulse Code Modulation

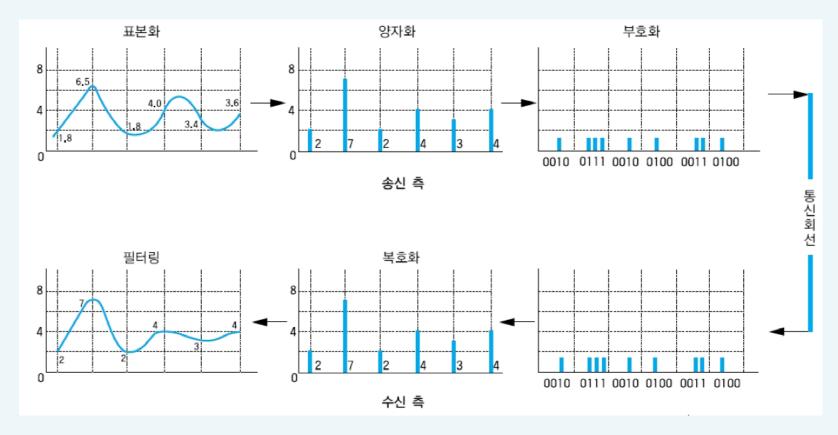
- Analog Signal
 - Pulse Code Modulation (PCM)





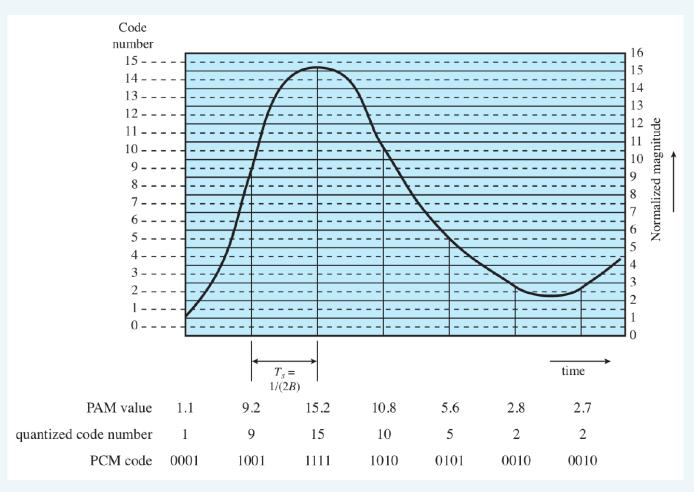
Pulse Code Modulation

- Analog Signal
 - Pulse Code Modulation (PCM)
 - Sampling -> Quantizing -> Encoding -> Send/Receive
 - -> Decoding -> Filtering



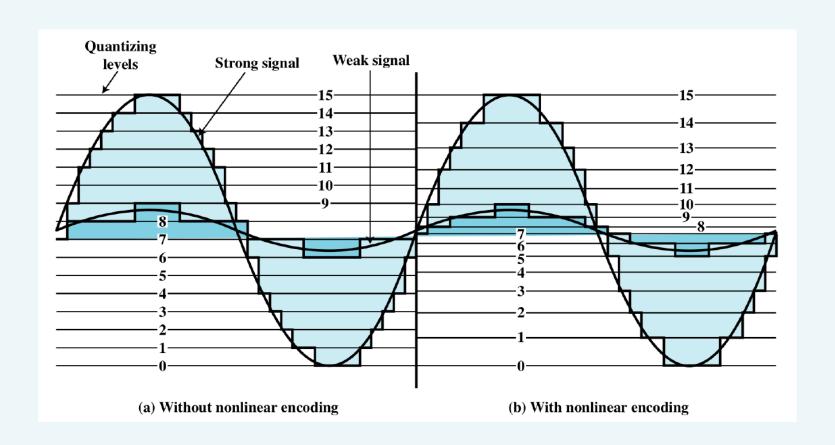
Pulse Code Modulation

- Analog Signal
 - PCM Example



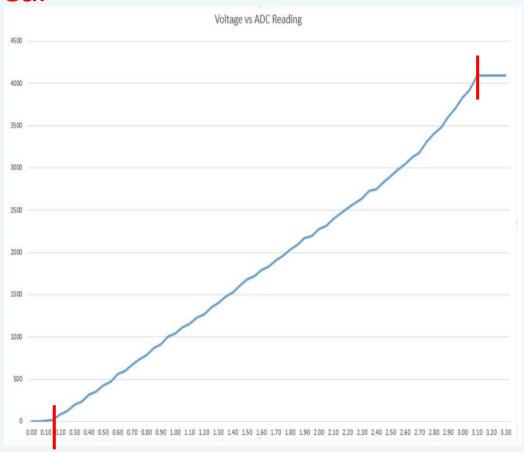
Pulse Code Modulation

- Analog Signal
 - PCM with Nonlinear Coding



ESP32 Analog Inputs

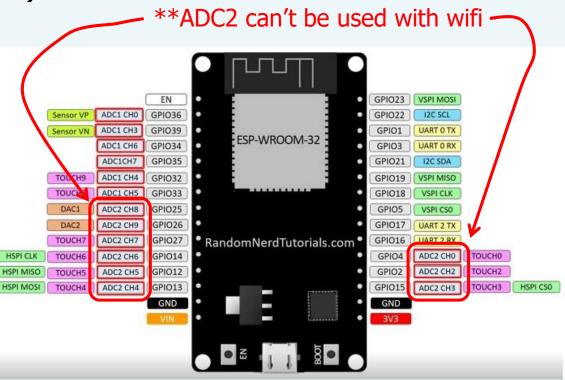
- Can measure Voltage 0V ~ 3.3V
- Assigned to a value 0 ~ 4095
- ESP32 ADC is not linear
 - cannot distinguish:
 - $0V \sim 0.1V$ (value = 0)
 - $3.2V \sim 3.3V$ (value = 4095)
 - Keep in mind!!



Reading Analog Inputs

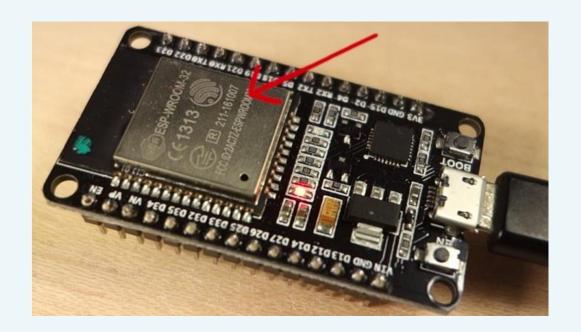
- ESP32 has 18 different channels
- But only 15 are available in DEVKIT V1 DOIT
- 12 bits resolution: 0 ~ 4095
- analogRead(GPIO)





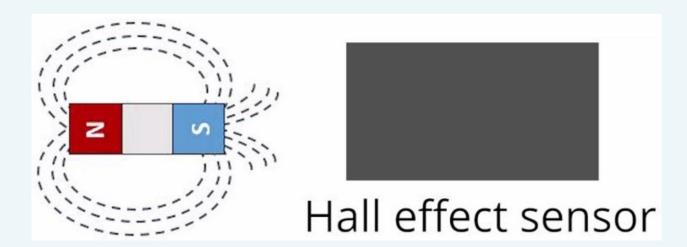
Analog Input - Hall Effect Sensor

- ESP32 has a built-in hall effect sensor
 - can detect variations in the magnetic field
 - greater the magnetic field, the greater the output voltage
 - Increase or become negative depending on the magnet pole facing the sensor



Hall Effect Sensor

- Threshold detection to act as a switch
- Hall effect sensors are mainly used to:
 - Detect proximity
 - Calculate positioning
 - Count the number of revolutions of a wheel
 - Detect a door closing;



Analog Input - Hall Effect Sensor

hallRead()

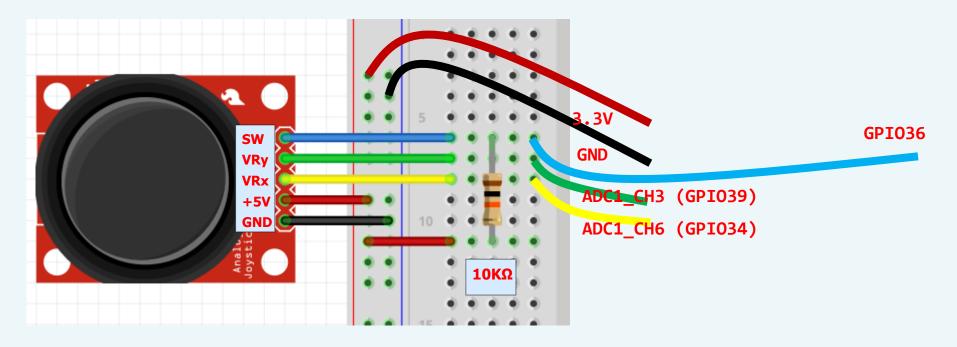
Examples> ESP32> HallSensor

```
<Task04-5>
```

```
// Simple sketch to access the internal hall effect detector on the esp32.
// values can be quite low.
// Brian Degger / @sctv
int val = 0:
                                                   26
void setup() {
                                                   28 Positive
Serial.begin(115200);
                                                     Readings
                                                   89
// put your main code here, to run repeatedly
                                                   163
void loop() {
  // read hall effect sensor value
  val = hallRead();
  // print the results to the serial monitor
  Serial.println(val);
  delay(1000);
```

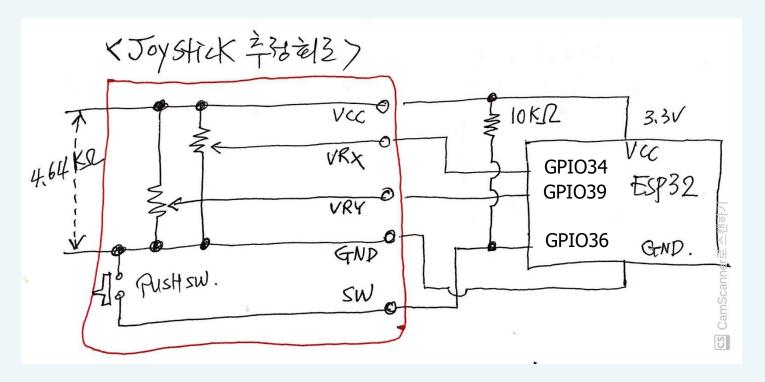
Analog Input - Joystick

- Joystick의 Analog Input .. analogRead(GPIO)
 - $VRx \rightarrow GPIO34 (ADC1_CH6)$
 - $VRy \rightarrow GPIO39 (ADC1_CH3)$
- Joystick의 Digital Input
 - Switch → GPIO36



Analog Input - Joystick

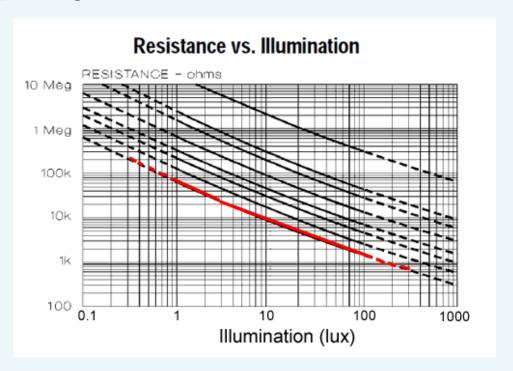
- Joystick에는 두개의 Potentiometer와 한 개의 Button이 있다
 - − 추정회로.. ESP32 연결 회로.. Pull-up or Pull-down ?



Analog Input - CdS Cell

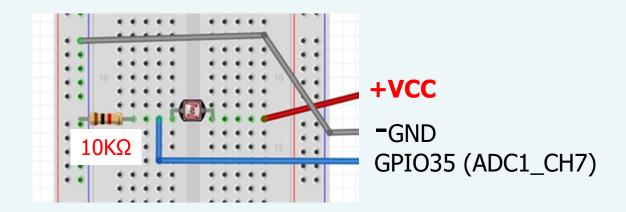
- CdS cell (Cadmium sulphide cell): 조도센서
 - CdS 셀은 가시광선의 양에 따라 저항도 변화
 - 광량이 증가할수록 저항은 감소
 - CdS 셀은 0.3~300 lux 범위에서 가장 밝은 300 lux일 때 저항의 크기가 약 700Ω
 - 가장 어두울 때인 0.3 lux일 때 저항의 크기는 200kΩ





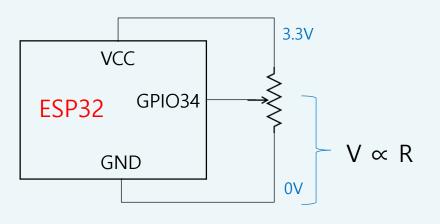
Analog Input – CdS Cell Circuit

- CdS의 저항의 변화에 따른 전압을 ADC로 입력
- GPIO35 → ADC1_CH7 .. analogRead(35)



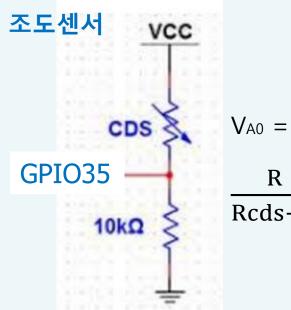
Analog Input- Potentiometer, CdS

■ 가변저항, 조도센서의 신호를 읽는 방법은 유사하다

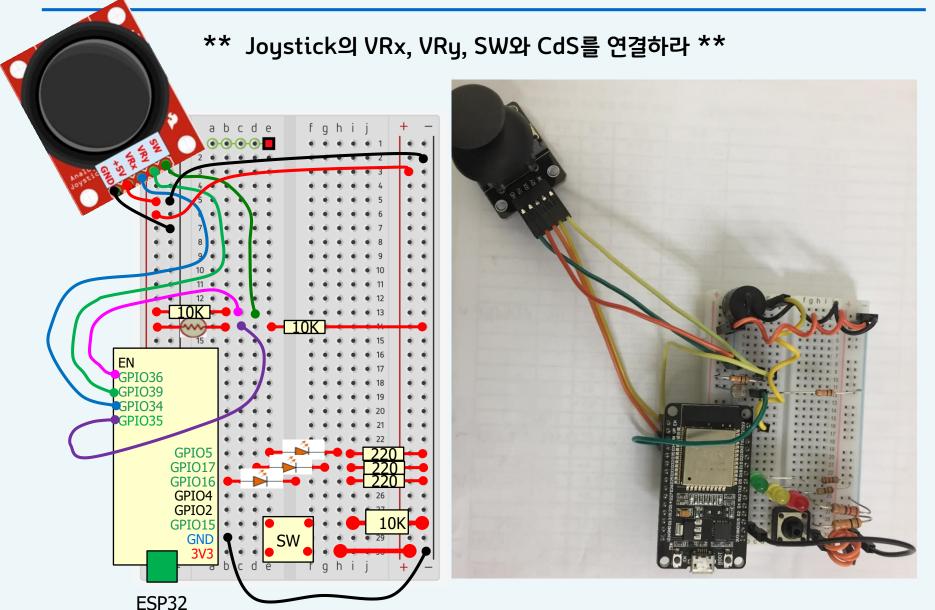


- GPIO34 전압은 GND~GPIO34 저항값에 비례
- analogRead(34) 는 12bit (0~4095) 입력 (ADC)
- 누설전류 (Leakage): 가변저항이 $10K\Omega$ 이면, $V \propto R$ I = 3.3 / 10000 = 0.33mA

가변저항 위치	GND~GPIO34 건압	analogRead	
0	0V	0	
30%	1V	1229	
50%	1.7V	2048	
100%	3.3V	4095	



Task04-A Analog Input- Joystick, CdS



Task04-A Reading Analog Inputs

<Task04-A>

```
// Joystick, CdS test
// Joystick is connected to GPIO 34/39 (Analog ADC1_CH6/3)
// Cds is connected to GPIO15 (Analog ADC1_CH7)
const int joyPinX = 34;
const int joyPinY = 39;
const int joySW = 36;
                                                     void loop() {
const int cdsPin = 35;
                                                     // Reading Joystick values
                                                      xValue = analogRead(joyPinX);
// variable for storing the Joystick values
                                                      yValue = analogRead(joyPinY);
int xValue = 0, yValue = 0, sValue = 0, cValue = 0;
                                                      cValue = analogRead(cdsPin);
                                                      sValue = digitalRead(joySW);
void setup() {
                                                      String str = (X,Y) = (" + String(xValue))
 Serial.begin(115200);
                                                                 + ',' + String(yValue) + ")\n";
 pinMode(joySW, INPUT);
                                                      Serial.print(str);
 delay(1000);
                                                       Serial.print("Switch = ");
                                                      Serial.println(sValue?"OFF":"ON"); //
                                                     pull-up circuit
                                                       Serial.print("Cds Value = ");
                                                      Serial.println(cValue);
                                                      delay(500);
```

Task04-A Reading Analog Inputs - result

- Check CdS value.. Change luminance
- Check Joystick value.. stick left, right, up, down
- Check Joystick switch.. Press button

```
COM3
Switch = OFF
Cds Value = 208
(X,Y) = (1798,1757)
Switch = OFF
Cds Value = 208
(X,Y) = (1803,1754)
Switch = OFF
Cds Value = 192
(X,Y) = (1805,1755)
Switch = OFF
Cds Value = 212
(X,Y) = (1802,1757)
Switch = OFF
Cds Value = 217
☑ 자동 스크롤 □ 타임스탬프 표시
```

```
** Explain the relationship
between CdS value and
brightness ?
** Why ?
```

** Change the circuit to get the reverse result

Task04-Step C Play station with PWM

Task04-4>를 수정하여 Music Player를 구현하라

```
- 입력: 시리얼모니터 사용
```

- 한 음을 <Note#> : 음의 높이 <Duration#> : 음의 길이 으로 표현 Ex)



	Note #		Duration#	t Delay
C4 262 - 도	0			Delay
CS4 277	1	0	0	2000
D4 294 - 레	2	Ī		
DS4 311	3	0.	1	1500
E4 330 - 🗆	4		2	1000
F4 349 - 파	5	-	∠	1000
FS4 370	6		3	750
G4 392 - 솔	7	1		, 50
GS4 415	8		4	500
A4 440 - 라	9	k	-	
AS4 466	a) .	5	375
B4 494 - 시	b	Ь	6	250
C5 523	С	•	0	250
	, 쉼표			

** 쉼표를 연주하기 위해서는 PWM의 Duty를 0로 한다

Task04-Step C Play station with PWM

■ 다음을 연주하라

